

camera\_fisheye1\_optical\_frame

camera\_fisheye2\_optical\_frame

view\_frames Result

Recorded at time: 1677455565.452

robot\_1\_trajectory/lower0 robot\_1\_trajectory/lower1 robot\_1\_trajectory/lower2 robot\_1\_trajectory/body robot\_1\_trajectory/lower3 Broadcaster: /robot\_1/trajectory/robot\_state\_publisher Broadcaster: /robot 1/trajectory/robot state publisher | Broadcaster: /robot 1/trajectory/robot state publisher Broadcaster: /robot 1/trajectory/robot state publisher Broadcaster: /robot\_1/trajectory/robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec old) | Most recent transform: 0.000 ( 1677455565.452 sec o Buffer length: 0.000 sec robot\_1\_trajectory/toe1 robot\_1\_trajectory/toe2 robot\_1\_trajectory/toe3 robot\_1\_trajectory/text\_right robot\_1\_trajectory/toe0