Centro de Investigación en Matemáticas, A.C.

Reconocimiento de Patrones

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Examen 2. Ejercicio 1

In [1]: from PIL import Image
 import numpy as np

Sea θ^* el minimizador de la función

$$f(\theta) = \sum_{i} |y_i - \theta|,$$

donde y_i son observaciones de una v.a. Y.

Sea θ^n el n-ésimo estimador de θ^* , entonces:

$$h_i(heta \mid heta^n) = 0.5 rac{(y_i - heta)^2}{|y_i - heta^n|} + 0.5 |y_i - heta^n|$$

mayoriza $|y_i - \theta|$ para todo θ .

Demostración: Supongamos que $y_i
eq \theta^n$, entonces

$$egin{aligned} &rac{1}{2|y_i- heta^n|}(|y_i- heta|-|y_i- heta^n|)^2 \geq 0, \ &rac{1}{2|y_i- heta^n|}\Big(|y_i- heta|^2-2|y_i- heta||y_i- heta^n|+|y_i- heta^n|^2\Big) \geq 0 \ &rac{1}{2}\Bigg(rac{|y_i- heta|^2}{|y_i- heta^n|}-2|y_i- heta|+|y_i- heta^n|\Bigg) \geq 0 \ &0.5rac{|y_i- heta|^2}{|y_i- heta^n|}-|y_i- heta|+0.5|y_i- heta^n| \geq 0 \ &0.5rac{(y_i- heta)^2}{|y_i- heta^n|}+0.5|y_i- heta^n| \geq |y_i- heta| \end{aligned}$$

Por lo tanto, $h_i(\theta \mid \theta^n) \geq |y_i - \theta|$.

Además, evaluando en $\theta = \theta^n$ tenemos que

$$h_i(heta^n \mid heta^n) = 0.5 rac{(y_i - heta^n)^2}{|y_i - heta^n|} + 0.5 |y_i - heta^n| = |y_i - heta^n|,$$

de forma que $h_i(\theta \mid \theta^n)$ mayoriza $|y_i - \theta^n|$.

Ahora, el algoritmo MM para encontrar la mediana de un conjunto de datos X, también conocido como algoritmo de Weiszfeld es el siguiente:

```
In [ ]: def mm_median(X, m=None, max_iters=20, tol=1e-4, random_state=None):
            MM method for computing the median of a dataset X.
            Parameters:
            - X: array-like, shape (n samples, n features)
                 The input data.
            - m: array-like, shape (n_features,), optional
                 Initial guess for the median. If None, it will be initialized to the mean o
            - max iters: int, optional
                 Maximum number of iterations for convergence.
            - tol: float, optional
                 Tolerance for convergence.
             - random state: int, optional
                 Random seed for reproducibility.
            X = np.asarray(X)
            if random state is not None:
                 np.random.seed(random_state)
            n_samples, n_features = X.shape
            # Initialize median
            if m is None:
                 m = np.mean(X, axis=0)
            elif len(m) != n features:
                 raise ValueError(f"Expected median with {n_features} features, but got {len
            else:
                 m = np.asarray(m)
            u = np.ones(n_samples)
            for _ in range(max_iters):
                # Compute weights inversely proportional to distance from current median
                w = np.linalg.norm(X - m, axis=1)
                w = 1 / (w + tol)
                 # Update median as weighted mean
                new_m = np.dot(w, X) / np.dot(w, u)
                 if np.linalg.norm(new_m - m) < tol:</pre>
                    break
                m = new_m
             return m
```

A continuación, el algoritmo de k-medianas que utiliza las medianas calculadas por el algoritmo MM anterior:

```
In [ ]: def kmedians(X, k, max_iters = 30, tol=1e-4, random_state=None, medians=None):
            K-medians clustering algorithm using the MM method for computing medians.
            Parameters:
             - X: array-like, shape (n_samples, n_features)
                 The input data.
             - k: int
                The number of clusters.
            - max_iters: int, optional
                 Maximum number of iterations for convergence.
            - tol: float, optional
                 Tolerance for convergence.
            - random state: int, optional
                 Random seed for reproducibility.
             - medians: array-like, shape (k, n features), optional
                 Initial medians for the clusters. If None, they will be randomly initialize
            X = np.asarray(X)
            if random_state is not None:
                 np.random.seed(random state)
            n samples, n features = X.shape
            # Initialize medians
            if medians is None:
                 indices = np.random.choice(n_samples, size=k, replace=False)
                 medians = X[indices]
            elif len(medians) != k:
                 raise ValueError(f"Expected {k} medians, but got {len(medians)}")
            elif np.asarray(medians).shape[1] != n_features:
                 raise ValueError(f"Expected medians with {n features} features, but got {np
            else:
                 medians = np.array(medians, copy=True)
            for _ in range(max_iters):
                 # Compute distances from each point to each centroid
                 distances = np.linalg.norm(X[:, np.newaxis] - medians, axis=2)
                 # Assign each point to the nearest centroid
                 labels = np.argmin(distances, axis=1)
                 new_medians = medians.copy()
                 for j in range(k):
                    mask = (labels == j)
                     if np.any(mask):
                         # Update centroid as the weighted median of its cluster
                         new_medians[j] = mm_median(X[mask], m=medians[j])
                 # Check for convergence
                 if np.linalg.norm(new_medians - medians) < tol:</pre>
                     break
                 medians = new_medians.copy()
             return medians, labels
```

Definimos funciones auxiliares para convertir la imagen a datos, y la función inversa:

```
In [3]: def image_to_features(image_path):
    # Load an image and convert it to RGB format
    img = Image.open(image_path).convert('RGB')
    img_np = np.array(img)
    n, m, c = img_np.shape
```

```
# Reshape image array to a 2D array where each row is a pixel's RGB values
features = img_np.reshape(-1, 3)
# Return the features and the original image shape (rows, columns)
return features, (n, m)

def features_to_image(features, shape):
# Reshape the 2D feature array back to the original image shape
n, m = shape
return features.reshape(n, m, 3).astype(np.uint8)
```

Para los 4 valores de k, (2, 3, 5 y 10), se ejecuta el algoritmo de k-medianas para colorear la imagen:

```
In []: # Quantize image for different numbers of clusters using k-medians
K = [2, 3, 5, 10]

features, shape = image_to_features("Figures/foto.jpg") # Convert image to feature

for k in K:
    medians, labels = kmedians(features, k=k, random_state=2025) # Cluster pixels
    output = np.zeros_like(features) # Prepare array for quantized image
    for i in range(shape[0] * shape[1]):
        output[i] = medians[labels[i]] # Assign each pixel the median color of its
    reconstructed_img = features_to_image(output, shape) # Convert features back t
    Image.fromarray(reconstructed_img).save(f"kmedians_{k}.png") # Save quantized
```

Las imágenes resultantes se encuentran guardadas con el nombre 'kmedians_x.png', donde x es el número de medianas utilizadas.