

Node



```
graph BT; A["ros2_wait_for_cloud_message.CloudSubscriber"] --> B["Node"]
```

A diagram illustrating a class inheritance relationship. At the bottom is a gray rectangular box with a black border containing the text `ros2_wait_for_cloud_message.CloudSubscriber`. A blue arrow points vertically upwards from the top center of this box to the bottom center of a white rectangular box with a gray border at the top. The white box contains the text `Node`.

`ros2_wait_for_cloud
_message.CloudSubscriber`