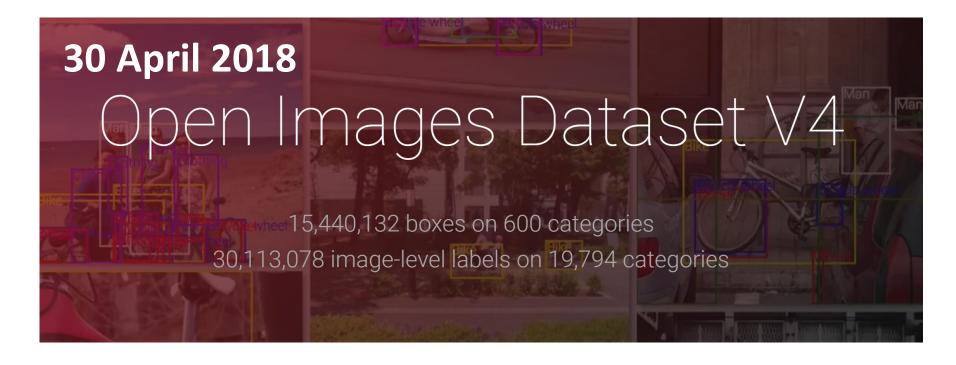
ML News

Patrycja Jakimów 07.05.2018



~9 million images

complex scenes with several objects

the largest existing dataset with object location annotations

Open Image Dataset V4

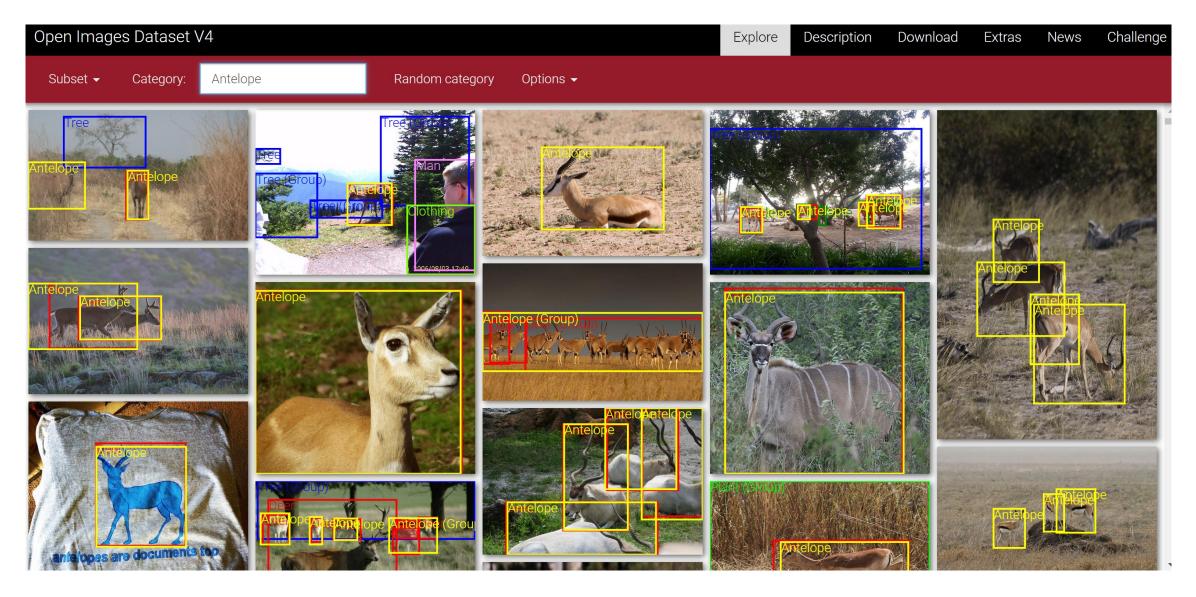


Image-level labels

Table 1: Image-level labels.

	Train	Validation	Test	# Classes	# Trainable Classes
Images	9,011,219	41,620	125,436	-	-
Machine-Generated Labels	78,977,695	512,093	1,545,835	7,870	4,764
Human-Verified Labels	27,894,289 pos: 13,444,569 neg: 14,449,720	551,390 pos: 365,772 neg: 185,618	1,667,399 pos: 1,105,052 neg: 562,347	19,794	7,186

pos - certain object classes are present

neg - certain object classes are absent

Boxes

Table 2: Boxes.

	Train	Validation	Test	# Classes
Images	1,743,042	41,620	125,436	-
Boxes	14,610,229	204,621	625,282	600

90% of the boxes were manually drawn by professional annotators at Google using the efficient extreme clicking interface

We produced the remaining 10% semi-automatically

Data Formats

image-level labels

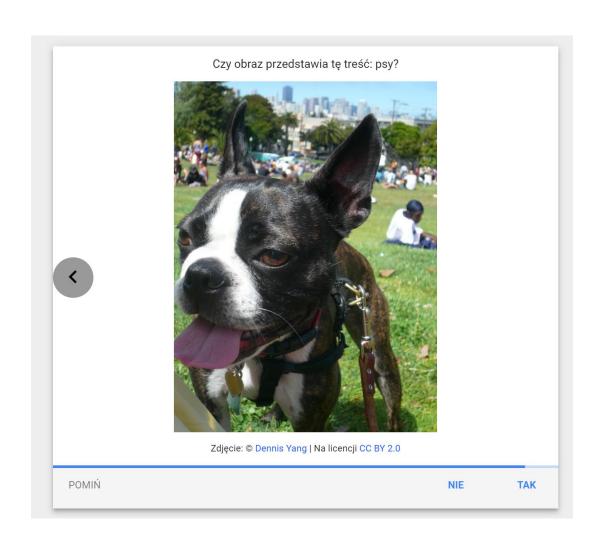
```
ImageID,Source,LabelName,Confidence
000026e7ee790996,verification,/m/04hgtk,0
000026e7ee790996,verification,/m/07j7r,1
000026e7ee790996,crowdsource-verification,/m/01bqvp,1
000026e7ee790996,crowdsource-verification,/m/0csby,1
000026e7ee790996,verification,/m/01_m7,0
000026e7ee790996,verification,/m/01cbzq,1
000026e7ee790996,verification,/m/01czv3,0
000026e7ee790996,verification,/m/01v4jb,0
000026e7ee790996,verification,/m/03d1rd,0
...
```

Source: indicates how the annotation was created:

- verification are labels verified by in-house annotators at Google.
- crowdsource-verification are labels verified from the Crowdsource app.
- machine are machine-generated labels.

Confidence: Labels that are human-verified to be present in an image have confidence = 1 (positive labels). Labels that are human-verified to be absent from an image have confidence = 0 (negative labels). Machine-generated labels have fractional confidences, generally >= 0.5. The higher the confidence, the smaller the chance for the label to be a false positive.

Crowdsource



Data Formats

bounding box

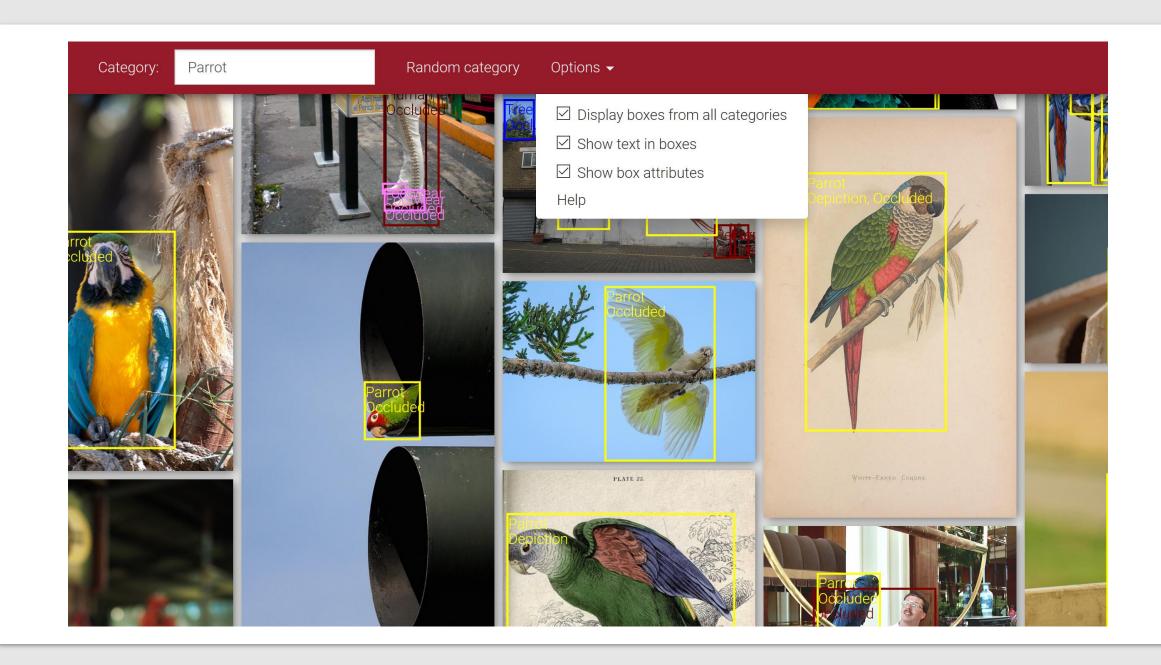
```
ImageID, Source, LabelName Confidence XMin, XMax, YMin, YMax, IsOccluded, IsTruncated, IsGroupOf, IsDepiction, IsInside 000026e7ee790996, freeform, /m/07j7r, 1, 0.071905, 0.145346, 0.200591, 0.391300, 0, 1, 1, 0, 0 000026e7ee790996, freeform, /m/07j7r, 1, 0.439756, 0.572466, 0.264153, 0.435122, 0, 1, 1, 0, 0 000026e7ee790996, freeform, /m/07j7r, 1, 0.668455, 1.000000, 0.000000, 0.552825, 0, 1, 1, 0, 0 000062a39995e348, freeform, /m/015p6, 1, 0.205719, 0.849912, 0.154144, 1.000000, 0, 0, 0, 0 000062a39995e348, freeform, /m/05s2s, 1, 0.137133, 0.377634, 0.000000, 0.884185, 1, 1, 0, 0, 0 0000c64e1253d68f, freeform, /m/07yv9, 1, 0.000000, 0.973850, 0.000000, 0.043342, 0, 1, 1, 0, 0 0000c64e1253d68f, freeform, /m/0k4j, 1, 0.000000, 0.513534, 0.321356, 0.689661, 0, 1, 0, 0, 0 0000c64e1253d68f, freeform, /m/0k4j, 1, 0.016515, 0.268228, 0.299368, 0.462906, 1, 0, 0, 0, 0 0000c64e1253d68f, freeform, /m/0k4j, 1, 0.481498, 0.904376, 0.232029, 0.489017, 1, 0, 0, 0, 0, 0 0000c64e1253d68f, freeform, /m/0k4j, 1, 0.481498, 0.904376, 0.232029, 0.489017, 1, 0, 0, 0, 0, 0 0000c64e1253d68f, freeform, /m/0k4j, 1, 0.481498, 0.904376, 0.232029, 0.489017, 1, 0, 0, 0, 0, 0 0000c64e1253d68f, freeform, /m/0k4j, 1, 0.481498, 0.904376, 0.232029, 0.489017, 1, 0, 0, 0, 0, 0 0000c64e1253d68f, freeform, /m/0k4j, 1, 0.481498, 0.904376, 0.232029, 0.489017, 1, 0, 0, 0, 0, 0 0000c64e1253d68f, freeform, /m/0k4j, 1, 0.481498, 0.904376, 0.232029, 0.489017, 1, 0, 0, 0, 0, 0 0000c64e1253d68f, freeform, /m/0k4j, 1, 0.481498, 0.904376, 0.232029, 0.489017, 1, 0, 0, 0, 0 000c64e1253d68f, freeform, /m/0k4j, 1, 0.481498, 0.904376, 0.232029, 0.489017, 1, 0, 0, 0, 0 000c64e1253d68f, freeform, /m/0k4j, 1, 0.481498, 0.904376, 0.232029, 0.489017, 1, 0, 0, 0, 0 000c64e1253d68f, freeform, /m/0k4j, 1, 0.481498, 0.904376, 0.232029, 0.489017, 1, 0, 0, 0, 0 000c64e1253d68f, freeform, /m/0k4j, 1, 0.481498, 0.904376, 0.232029, 0.489017, 1, 0, 0, 0 000c64e1253d68f, freeform, /m/0k4j, 1, 0.481498, 0.904376, 0.232029, 0.489017, 1, 0, 0, 0, 0 000c64e1253d68f, freeform, /m/0k4
```

additional attributes

The attributes have the following definitions:

- IsOccluded: Indicates that the object is occluded by another object in the image.
- IsTruncated: Indicates that the object extends beyond the boundary of the image.
- IsGroupOf: Indicates that the box spans a group of objects (e.g., a bed of flowers or a crowd of people). We asked annotators to use this tag for cases with more than 5 instances which are heavily occluding each other and are physically touching.
- IsDepiction: Indicates that the object is a depiction (e.g., a cartoon or drawing of the object, not a real physical instance).
- IsInside: Indicates a picture taken from the inside of the object (e.g., a car interior or inside of a building).

XMin, XMax, YMin, YMax: coordinates of the box, in normalized image coordinates.



Open Images Challenge 2018

broad case: clothing

The challenge has two tracks:

- 1. Object Class Detection: predicting a tight bounding box around all instances of the 500 classes.
- 2. Visual Relationship Detection: detecting pairs of objects in particular relations, e.g. "woman playing guitar".

Dates

- April 30th 2018: training set for object detection track released (with bounding box annotations).
- May 10 2018: visual relationship detection annotations on the training set will be released.
- May 31 2018: evaluation metric protocols and implementation will be released (as a part of the TF Object Detection API).
- July 1st 2018: a test set of 100k images will be released by Kaggle.
- September 1st 2018: deadline for submission of results.

Prize money

The Challenge has a total prize fund of USD 50,000, sponsored by Google.

Tuning the hyper-parameters of an estimator

Article on Data Science PL

sklearn.model_selection.GridSearchCV

sklearn.model selection.RandomizedSearchCV

best_params_ : dict **best_score_** : float

Example

```
params_gs = {'criterion':('entropy', 'gini'),
    'splitter':('best', 'random'),
    'max_depth':np.arange(1,6),
    'min_samples_split':np.arange(3,8),
    'min_samples_leaf':np.arange(1,5)}

gs = GridSearch(V(tree(), cv = 10, param_grid = params_gs, scoring = 'accuracy', n_jobs = -1)
    gs.fit(x_tr, y_tr)

model_1 = tree(**gs.best_params_)
    model_1.fit(x_tr, y_tr)
params_rs = {'criterion':('entropy', 'gini'),
    'splitter':('best', 'random'),
    'max_depth':randint(1,6),
    'min_samples_split':randint(3,8),
    'min_samples_leaf':randint(1.5)}

model_1 = tree(**gs.best_params_)
model_1.fit(x_tr, y_tr)
```

Resources

Google Research Blog

https://research.googleblog.com/

Open Images Dataset v4

https://storage.googleapis.com/openimages/web/index.html

Crowdsource

https://crowdsource.google.com/

Data Science PL Group on Facebook

https://www.facebook.com/groups/datasciencepl/

2 proste i skuteczne metody optymalizacji parametrów modelu

https://mateuszgrzyb.pl/2-proste-i-skuteczne-metody-optymalizacji-parametrow-modelu/

RandomizedSearchCV

http://scikit-learn.org/stable/modules/generated/sklearn.model_selection.RandomizedSearchCV.html

GridSearchCV

http://scikit-learn.org/stable/modules/generated/sklearn.model_selection.GridSearchCV.html

Thank you