# Jean Nassar | Résumé

Interests: Automation, robotics, AI, astronomy, anatomy, astrodynamics, space

#### Education

# Candidate, MS Mechanical Engineering Science2014–PresentKyoto University, Mechatronics LaboratoryKyoto, Japan

- $\circ\,$  Researching a third-person view for teleoperated drones using ROS and OpenGL
- Assisting labmates with programming (including swarm robotics)
- Was software lead for the lab's teleoperation robot; participated in RoboCup Japan

Research student2013–2014Kyoto University, Mechatronics LaboratoryKyoto, JapanBASc, Honours Mechatronics Engineering2008–2013

University of Waterloo

- Waterloo, ON
- Final project was a portable water purification system
- o Automated an assembly line robot (Allen-Bradley PLCs)
- Built an autonomous boat using Arduino
- o Cofounder of Engineering Ambassador program
- o Director of the Mental Health Awareness directorship
- Secretary of Club for Undergraduate Bioengineers; organized international symposium

### Languages

Fluent: English, French, Lebanese, Japanese

**Intermediate**: Spanish, Arabic

Beginner: German, Mandarin, Russian, Krio

#### Technical skills

- Python (incl. SciPy stack), C++, C, ROS, Matlab, gnuplot, LATEX
- Linux (Arch, Fedora, Ubuntu), Microsoft Windows (XP to 10)
- o Raspberry Pi, Arduino, mbed, AVR, Allen Bradley PLC
- Solidworks, Autodesk Inventor, AutoCAD, Sketchup
- o Vim, Git, Gimp, Inkscape, LibreOffice, Microsoft Office

#### **Selected courses**

- Modern control theory
- Automatic control systems
- Electromechanical machine design
- Computer structures and RT systems
- Digital control applications
- Microproc. systems and interfacing
- Mechatronic system integration
- o Algorithms and data structures

## Co-op experience

#### Starquip Integrated Systems, Ltd

Spring 2012

Junior Engineer

Toronto, ON

- Assisted in the mechanical design of custom pneumatic lift-assist devices
- Created modular assemblies and circuits
- Reduced design time for new systems
- Converted 2D drawings to 3D assemblies
- Produced ASME-compliant drawings

#### Kevin Quan Studios, Ltd

Fall 2011

Junior Project Engineer

Toronto, ON

- o Completed basic and intermediate Solidworks instruction
- Created assemblies and drawings of mountain and racing bicycles
- Wrote airfoil generator and exporter using LibreOffice Calc, Python
- o Performed 2D and 3D Computational Fluid Dynamics analysis of airfoils and bicycles
- o Determined the optimum configuration for several racing bicycles
- o Designed tooling molds and parts for various bicycle components

#### **Intelligent Mechatronics Systems, Inc**

Winter 2011

Hardware Associate

Waterloo, ON

- o Prototyped hardware solutions for future products using Altium Designer
- Programmed microcontrollers using C and C++
- Provided general assistance to lead design engineers

#### University of Waterloo

Spring 2010

Research Assistant, Multiscale Additive Manufacturing Lab

Waterloo, ON

- Designed, procured, and built essential parts for the enclosure, printhead assembly, and environmental isolation system for a solid freeform fabrication workstation
- $\circ~$  Workstation produces 3D scaffolds for bone and cartilage regrowth
- o Performed image processing on electron micrographs using Octave

#### American University of Beirut

Fall 2009

Research Assistant, Computer Vision and Mobile Robotics Lab

Beirut, Lebanon

- Researched and developed a positional navigation system for robots using C++
- o Quantized Inertial Measurement Unit (IMU) error

#### Sierra Construction Systems, Ltd

Winter 2009

Engineer in Training

Freetown, Sierra Leone

- Computerized payroll and significantly saved time and resources using Microsoft Excel, Word, and VBA programming
- Payroll productivity increased by approximately 6000%
- o Performed cost and time estimation for various construction projects

#### **Certifications**

o CPR HCP, 2012