

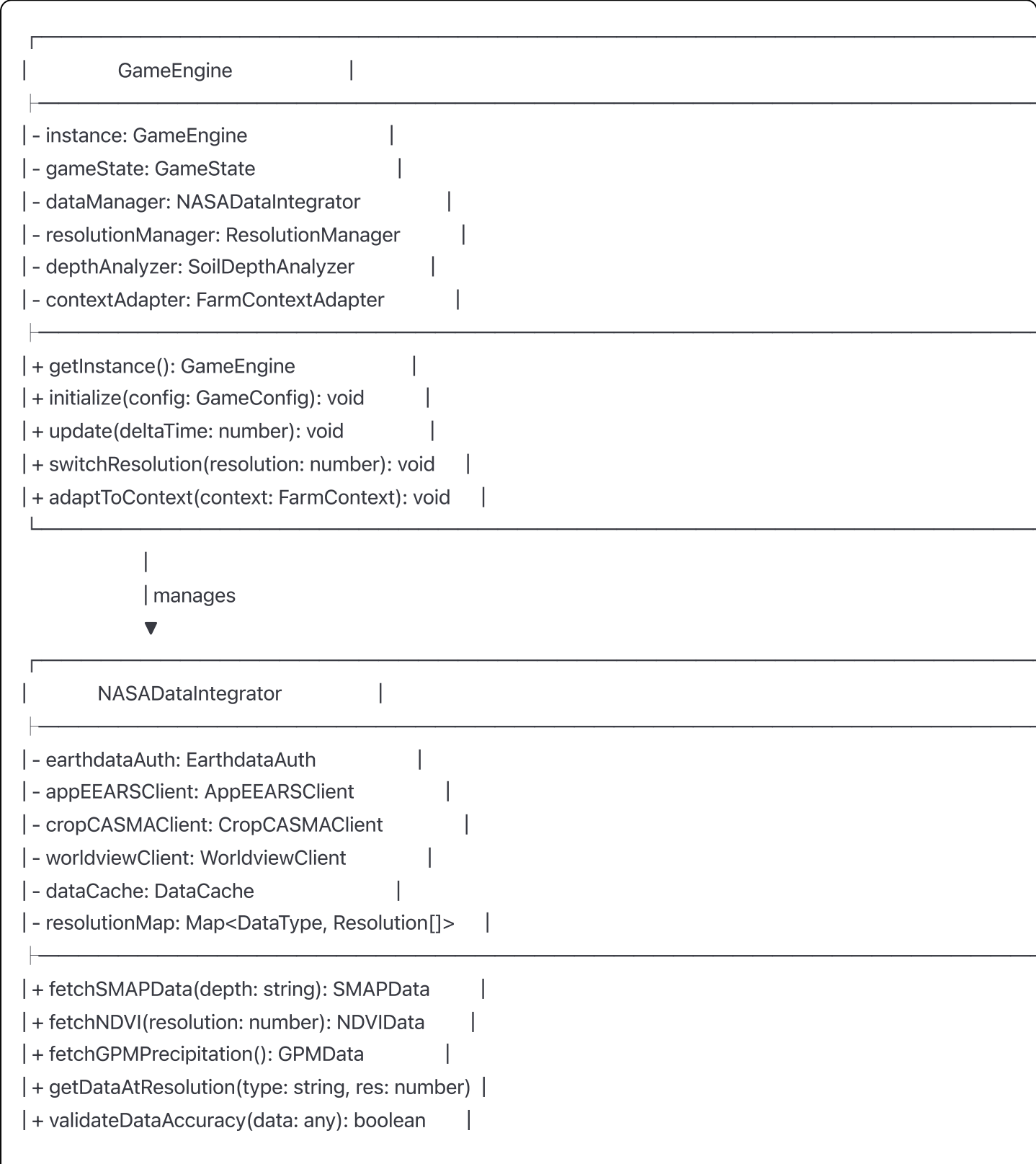
UML Design Documentation

NASA Farm Navigators

Version: 2.0

Date: September 2025

1. Class Diagram - Core System Architecture



| + explainDataLimitations(data: any): string[] |

|

| uses



ResolutionManager

| - availableResolutions: Resolution[] |

| - currentResolution: number |

| - resolutionImpacts: Map<number, Impact> |

| + switchResolution(meters: number): void |

| + compareResolutions(r1: number, r2: number) |

| + demonstratePixelSize(resolution: number) |

| + getDetectionCapability(res: number): string[] |

| + educateResolutionTrade offs(): Tutorial |

SoilDepthAnalyzer

| - surfaceData: SoilData (0-5cm) |

| - rootZoneData: SoilData (0-100cm) |

| - deepSoilData: SoilData (100cm+) |

| - cropRootDepths: Map<Crop, number> |

| + analyzeMoistureByDepth(depth: number): number |

| + recommendIrrigationDepth(crop: Crop): string |

| + visualizeDepthProfile(): DepthVisualization |

| + teachDepthImportance(): EducationalContent |

FarmContextAdapter

| - context: FarmingContext |

| - scale: FarmScale |

| - resources: ResourceAvailability |

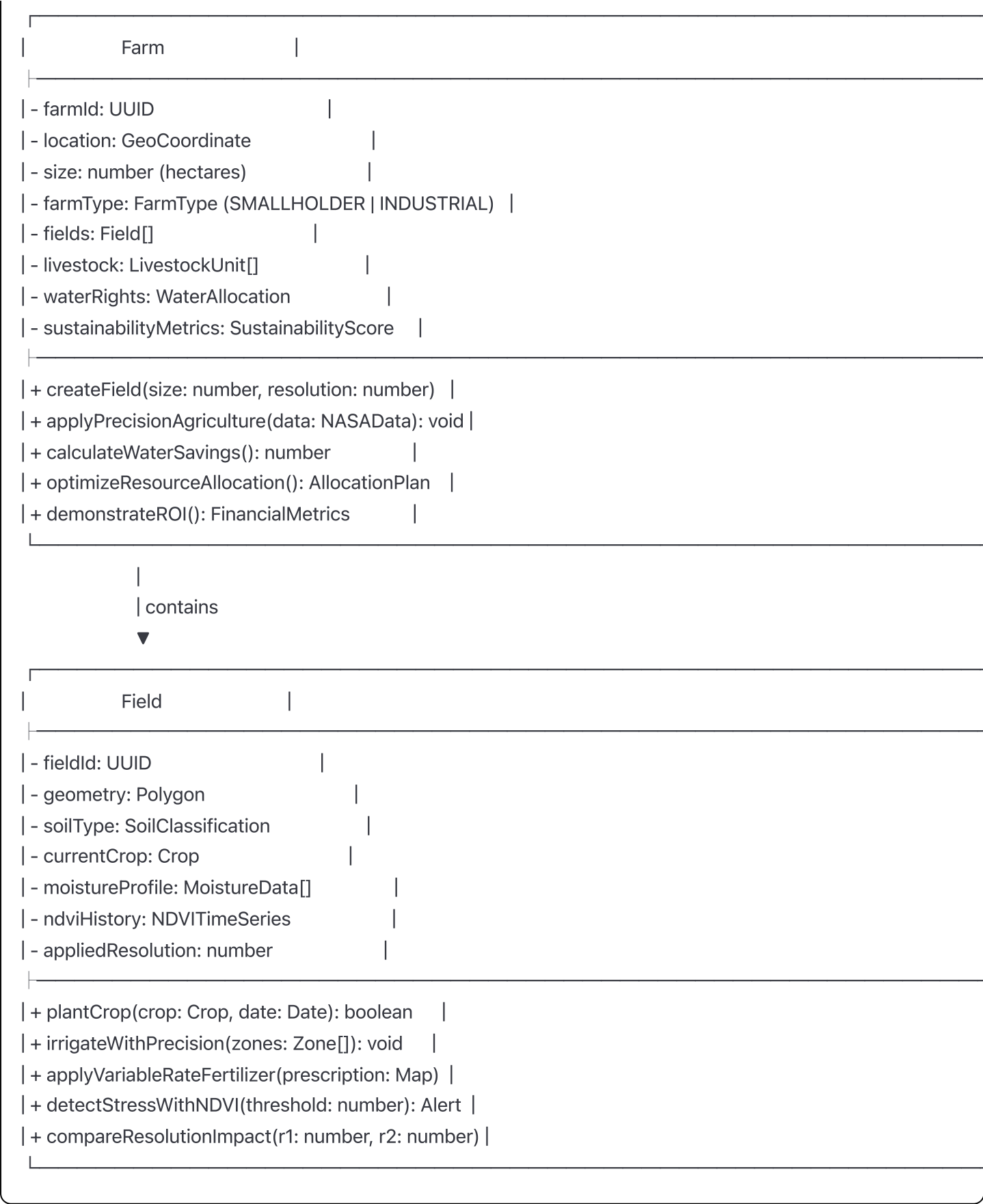
| - constraints: Constraint[] |

| + adaptToSmallholder(): GameplayModifiers |

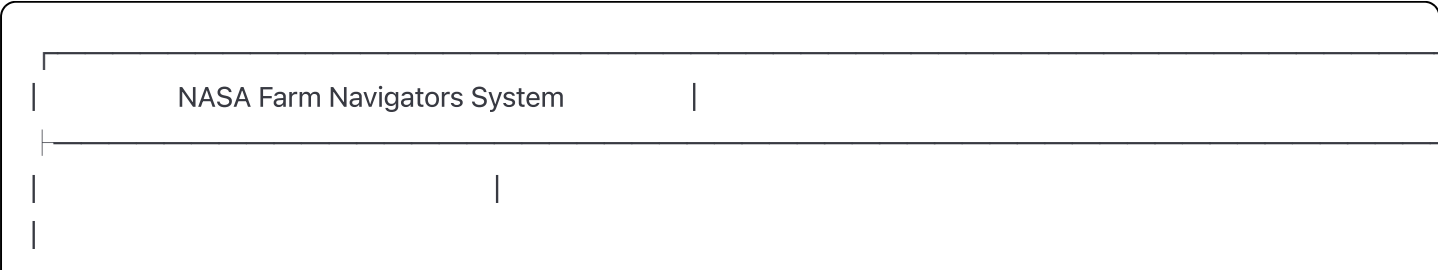
| + adaptToIndustrial(): GameplayModifiers |

| + adjustDataGranularity(scale: FarmScale): void |

| + customizeObjectives(context: FarmingContext) |



2. Component Diagram - System Architecture



Presentation Layer

Game UI | Dashboard | Tutorial |
(Phaser.js) | (React) | System |

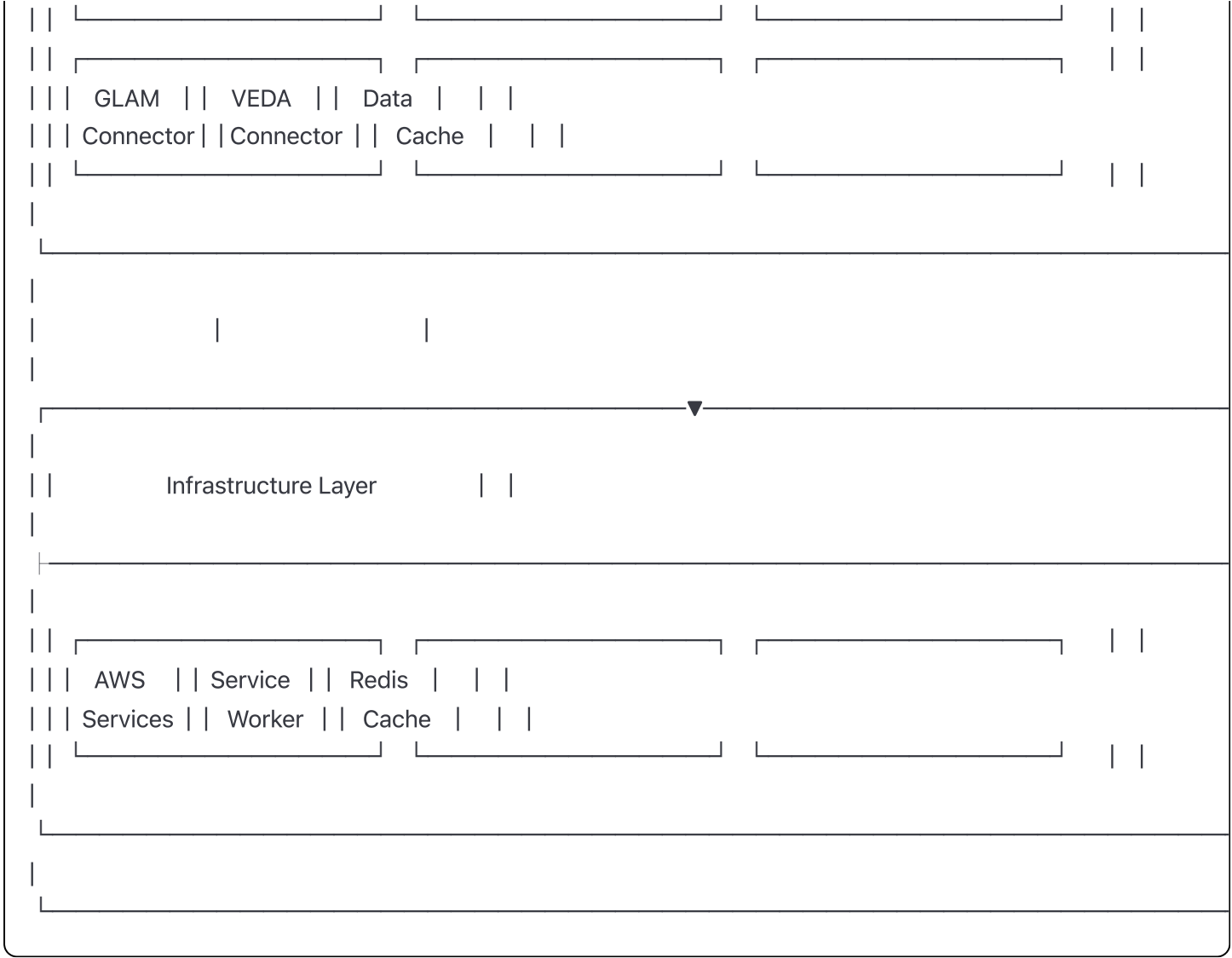
Game Logic Layer

Farm Manager | Data Processor | Education |
| | | Engine |

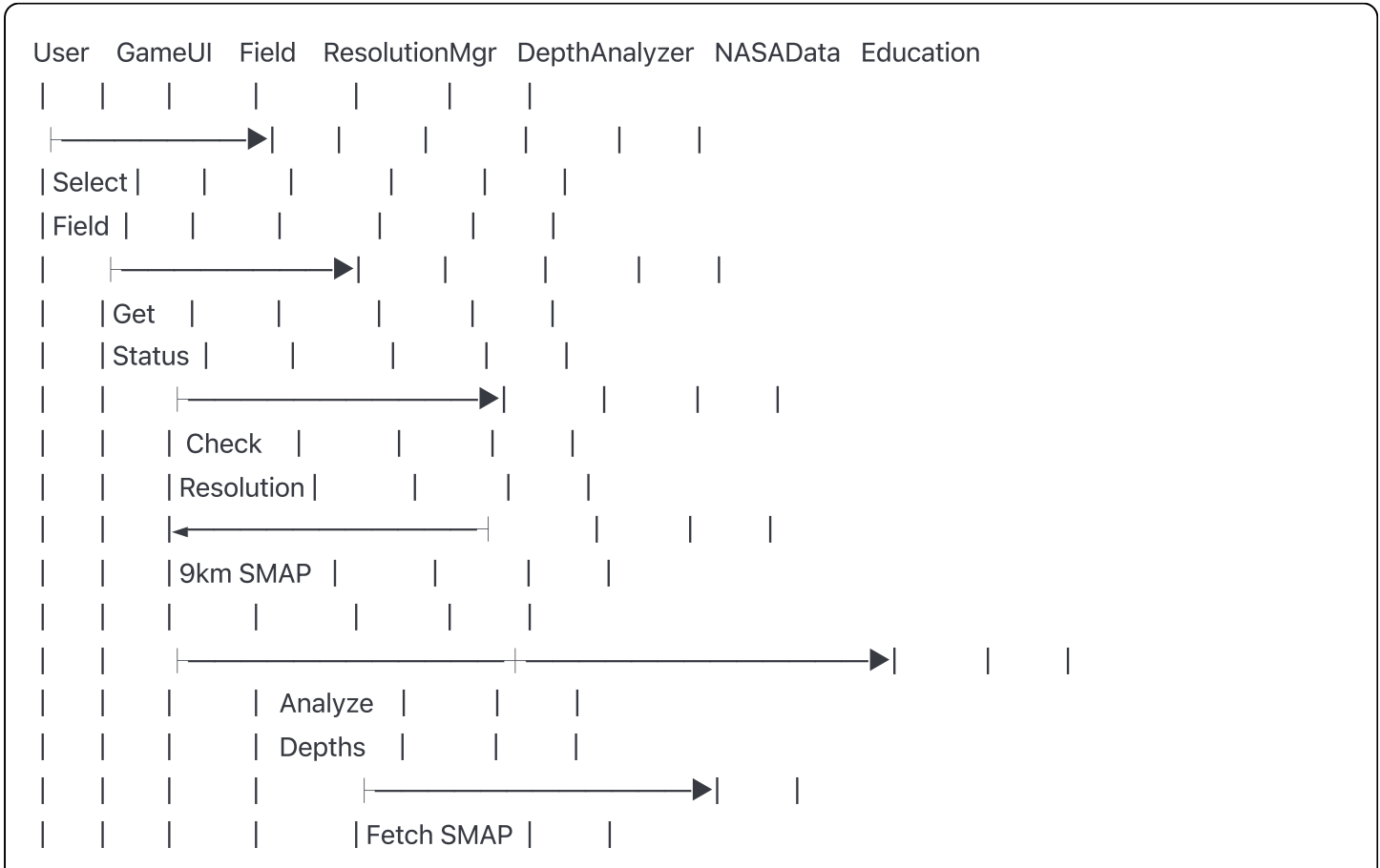
Resolution | Depth | Context |
Educator | Analyzer | Adapter |

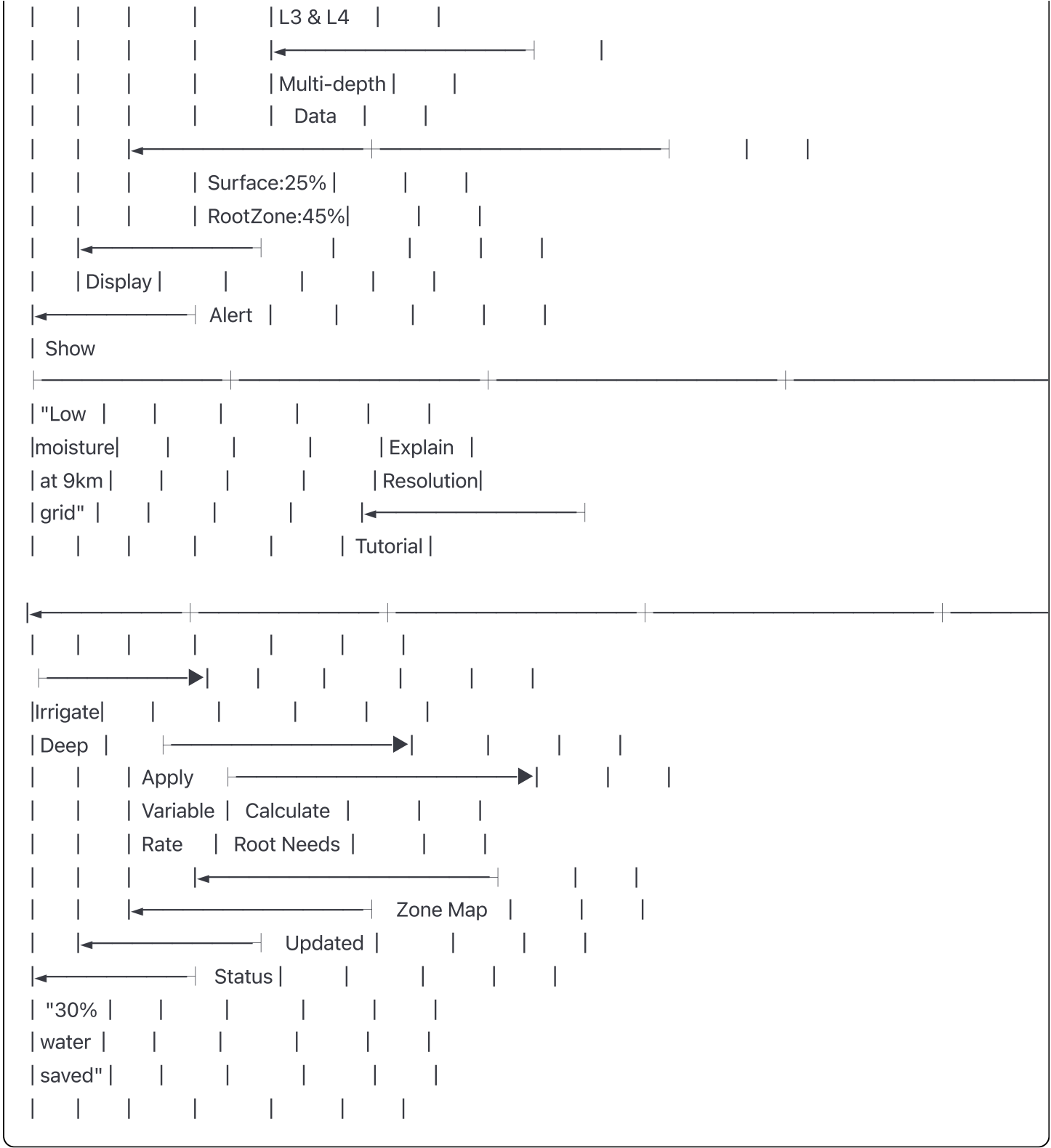
Data Integration Layer

AppEEARS | Crop-CASMA | Worldview |
Client | Client | Client |

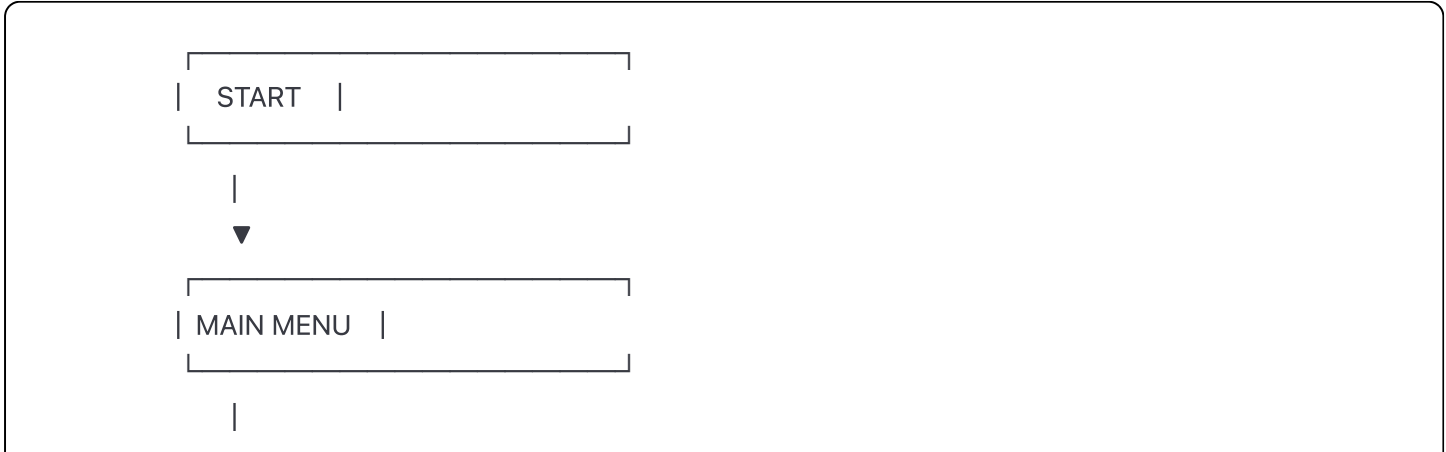


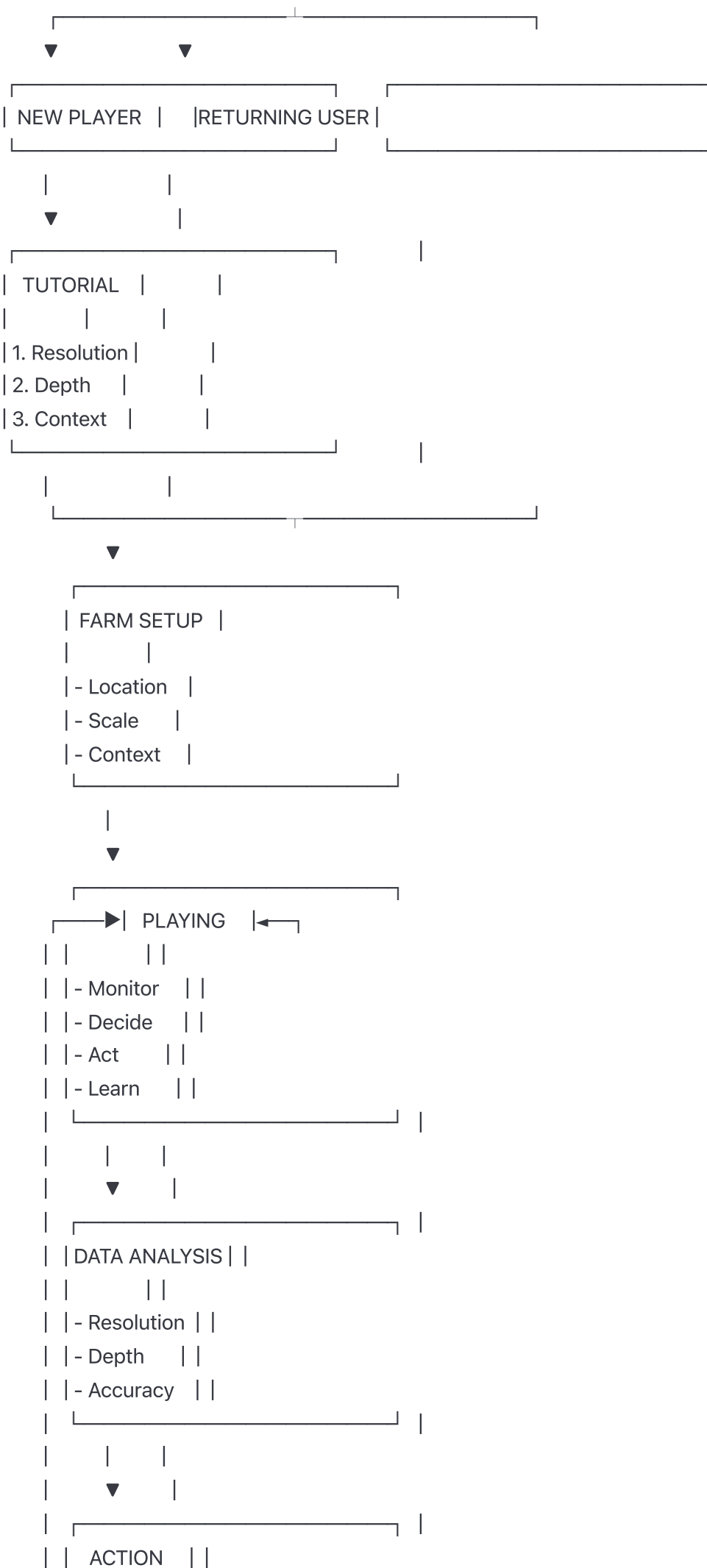
3. Sequence Diagram - Precision Irrigation Decision Flow

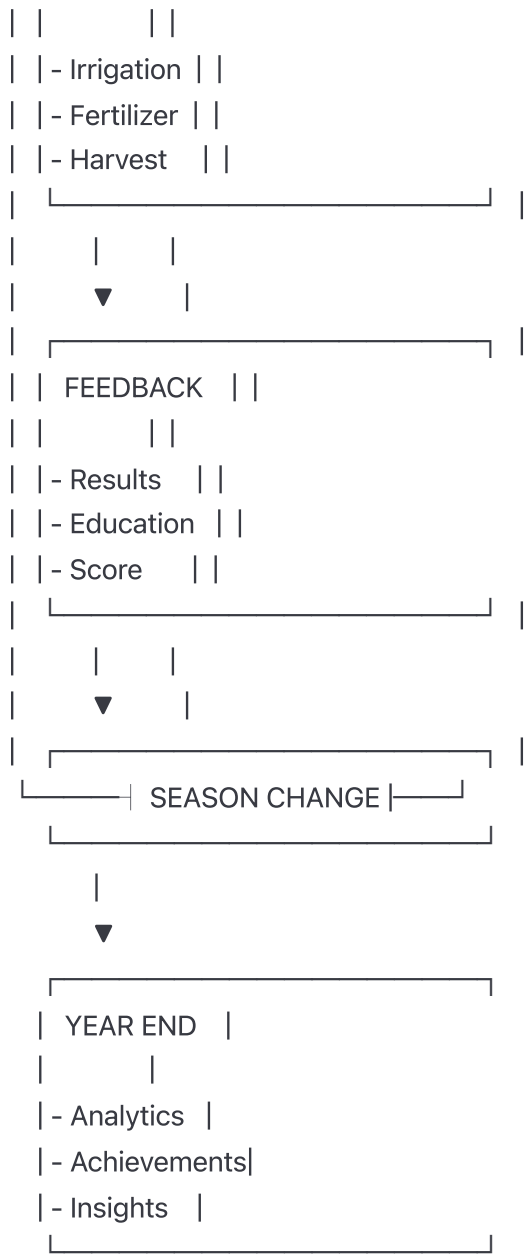




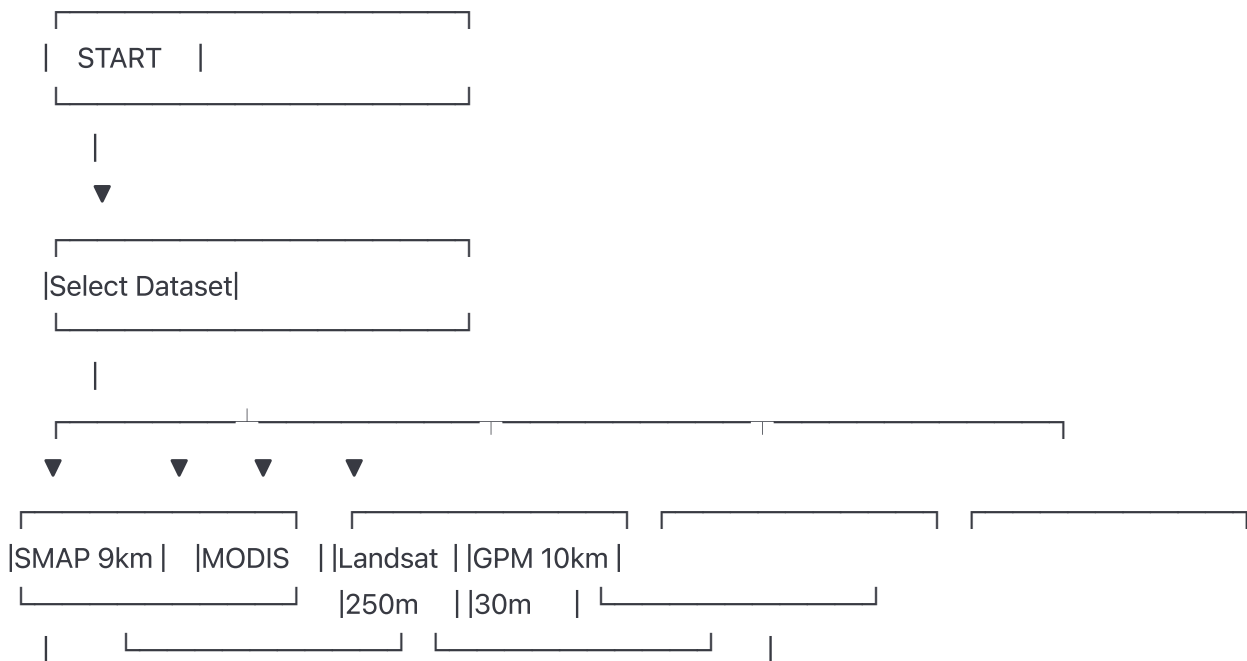
4. State Diagram - Game Progression States







5. Activity Diagram - Data Resolution Education Flow





Show Pixel Grid
on Farm Map



◆ Can detect feature? ◆

Yes No



Show Feature | Explain Why Not |
Detected | "Feature smaller |
than pixel" |



Compare Multiple |
Resolutions |



Interactive Quiz |
"Which resolution |
for this task?" |



◆ Correct Answer? ◆

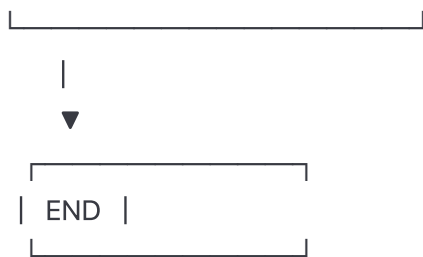
Yes No



Award XP | Explain |
Progress | Concept |



Save Learning
Progress



6. Use Case Diagram - System Actors and Functions

NASA Farm Navigators System

Manage Farm with NASA Data

Student Farmer Educator

Learn Data Apply Precision
Resolution Agriculture

Understand Compare Farm
Soil Depths Contexts

Practice Track
Irrigation Sustainability

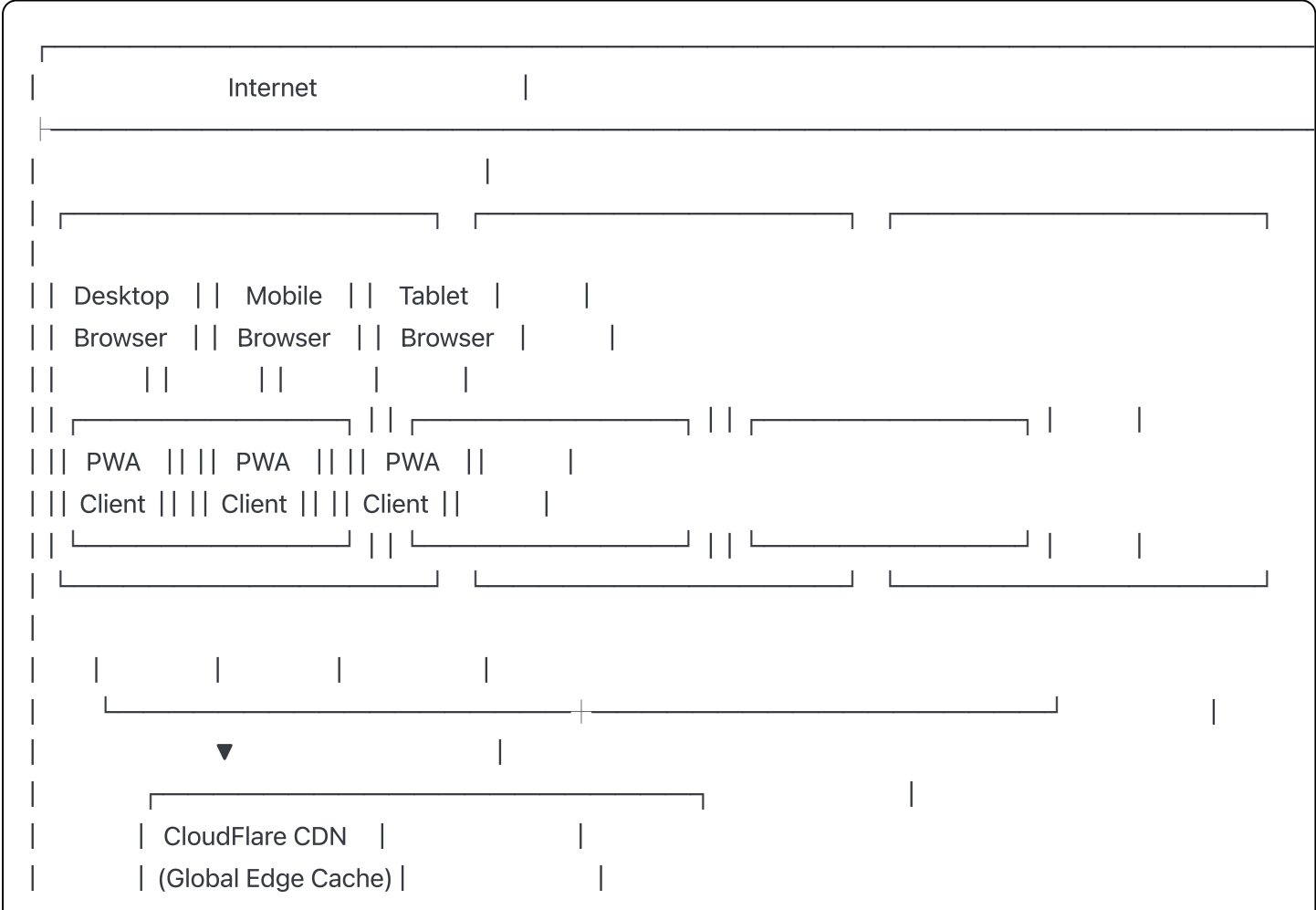
NASA Data Sources

• AppEEARS

• Crop-CASMA



7. Deployment Diagram - Infrastructure Architecture



AWS Application Load
Balancer (ALB)

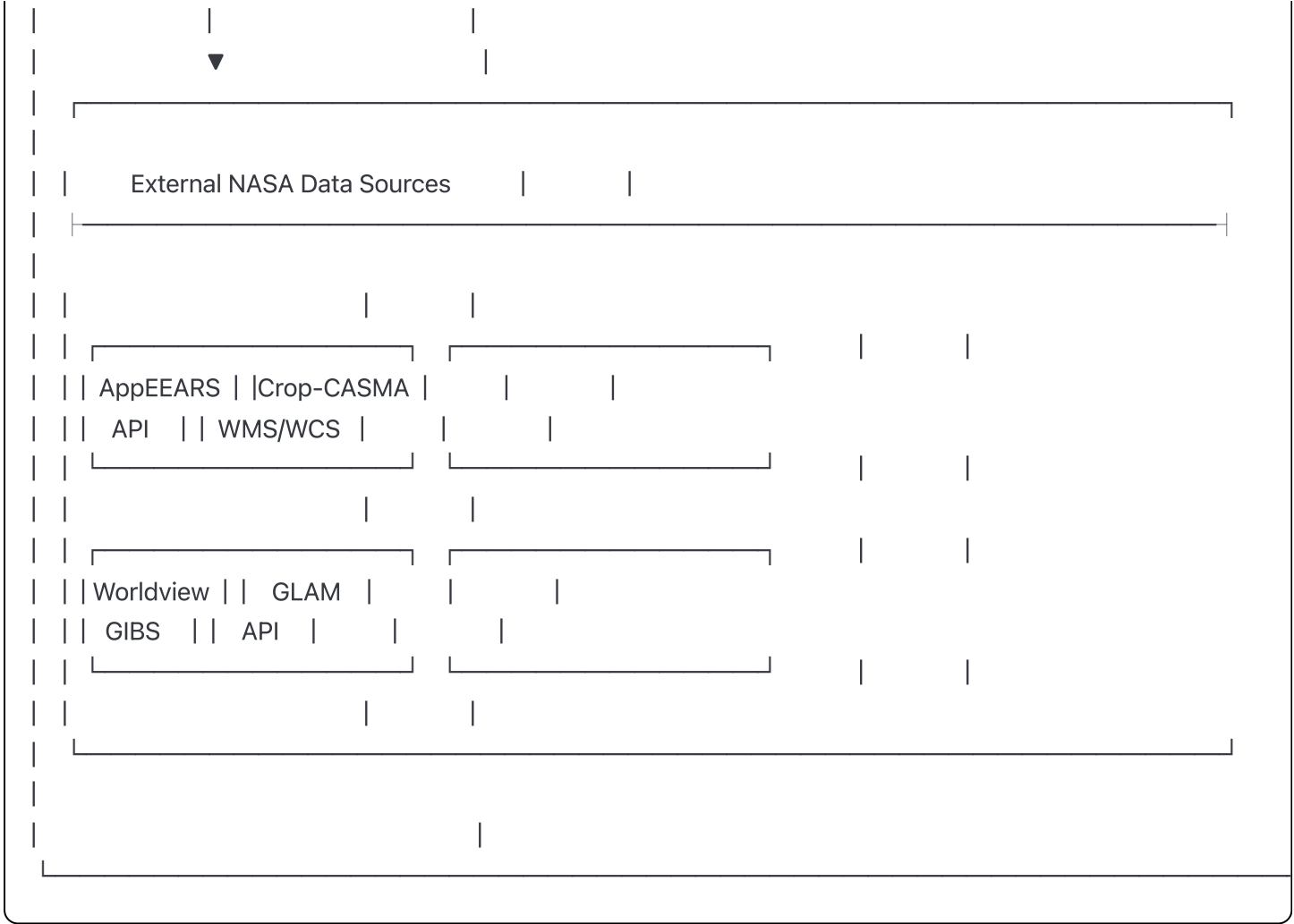
AWS ECS | | AWS ECS | | AWS ECS |
Container | | Container | | Container |
Node.js | | Node.js | | Node.js |
App | | App | | App |

AWS Services Layer

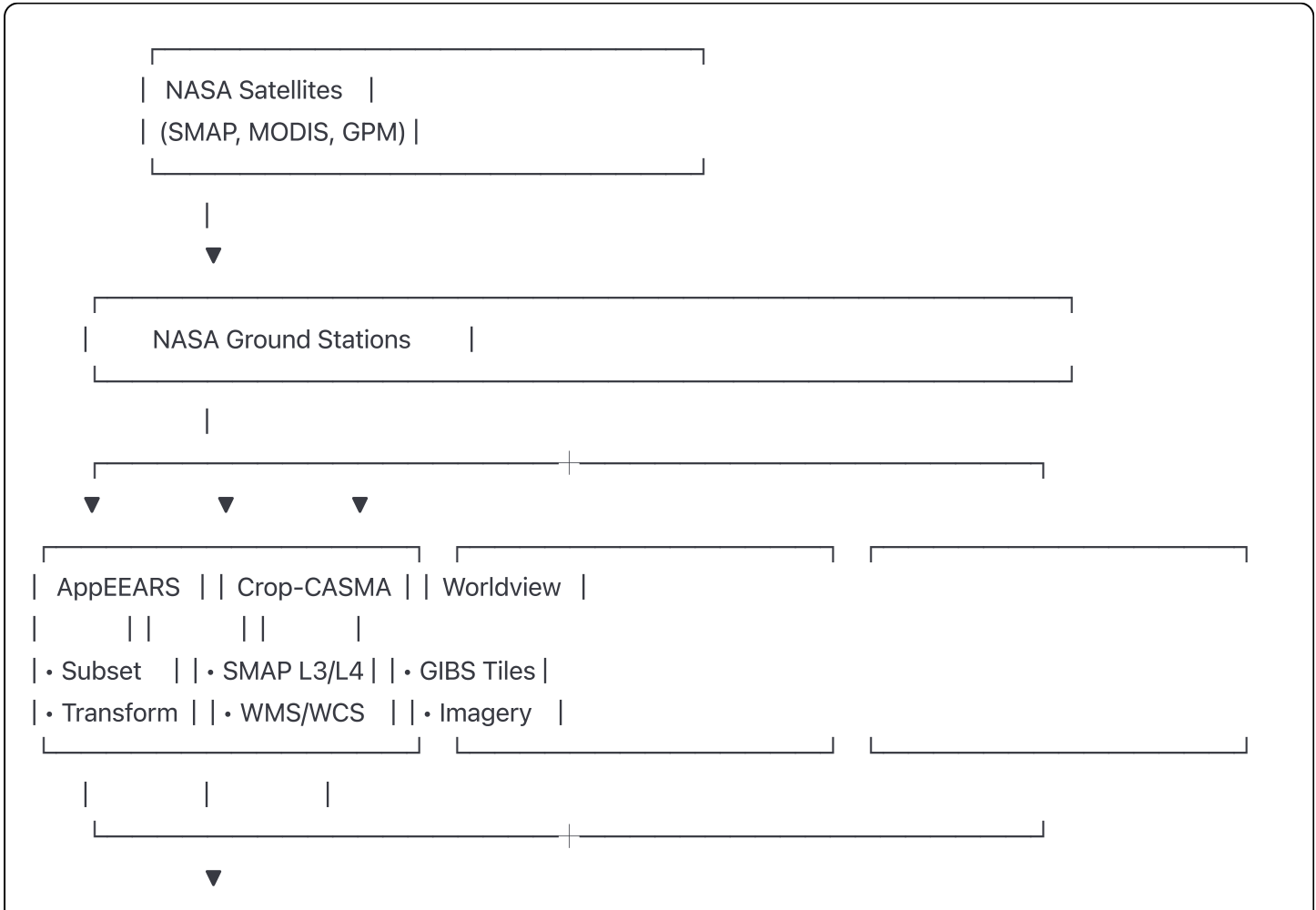
RDS | TimescaleDB |
PostgreSQL | Time Series |

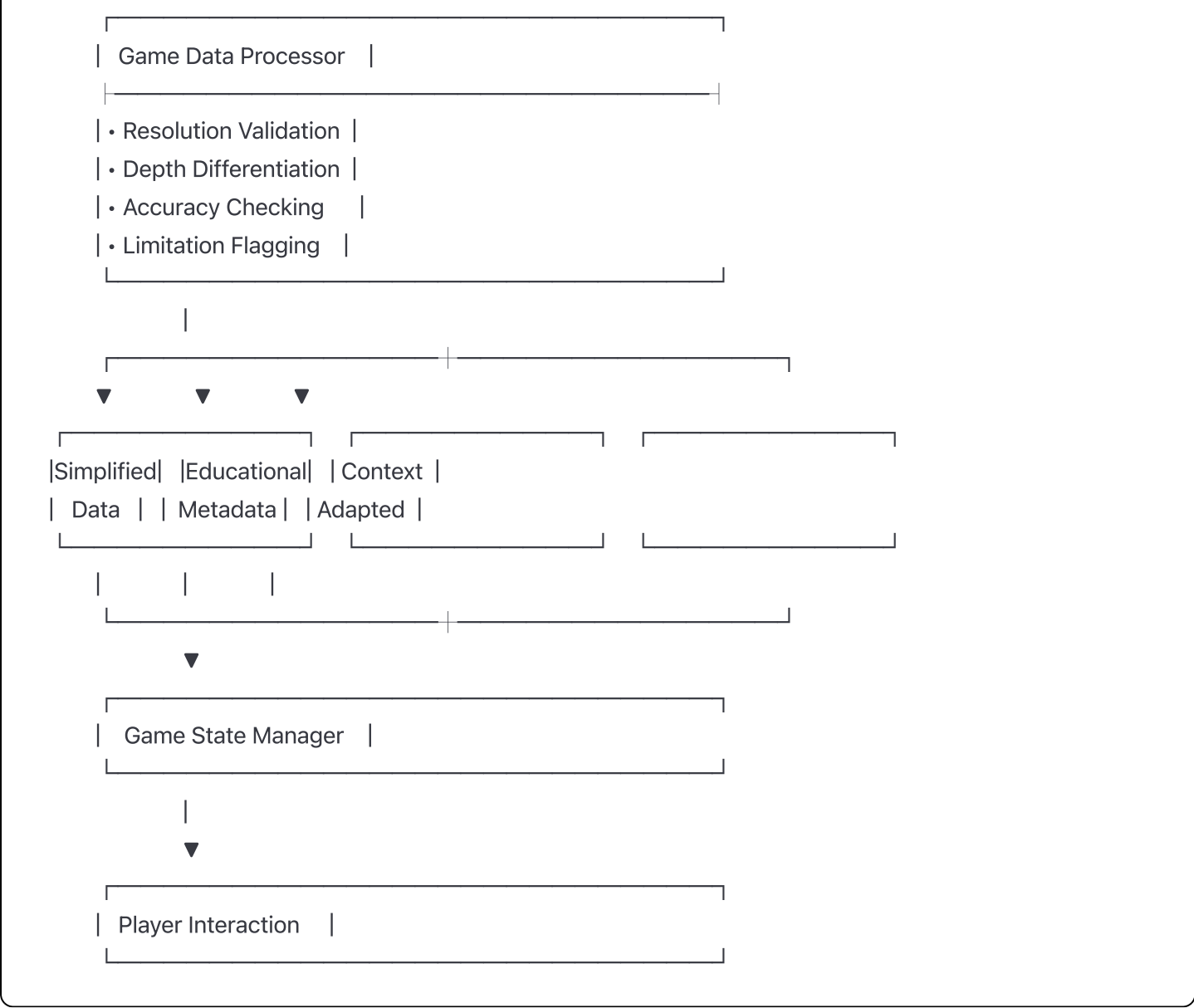
ElastiCache | Lambda |
Redis | Functions |

S3 | SQS |
Storage | Queue |



8. Data Flow Diagram - NASA Data Processing Pipeline





9. Package Diagram - System Modules



	• CropCASMClient			
	• WorldviewClient			
	• DataValidator			
	@nfn/resolution-engine			
	• ResolutionManager			
	• PixelCalculator			
	• DetectionAnalyzer			
	• ComparisonVisualizer			
	@nfn/depth-analysis			
	• SoilDepthProfiler			
	• RootZoneCalculator			
	• IrrigationOptimizer			
	• DepthEducator			
	@nfn/context-adapter			
	• SmallholderAdapter			
	• IndustrialAdapter			
	• ResourceConstraints			
	• ScaleAdjuster			
	@nfn/education			
	• TutorialSystem			
	• ProgressTracker			
	• AssessmentEngine			
	• CertificationManager			
	@nfn/offline			
	• ServiceWorker			
	• CacheManager			
	• SyncEngine			

```
graph TD;
    CR[ConflictResolver] --- L1(( ));
    L1 --- L2(( ));
    L2 --- L3(( ));
```