

Module 1

$$1) \sum_{k=0}^{\infty} \delta[n-k] = \delta[n] + \delta[n-1] + \delta[n-2] + \dots$$

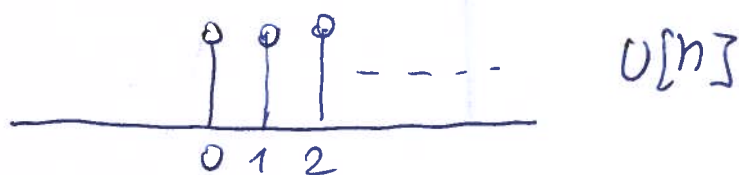
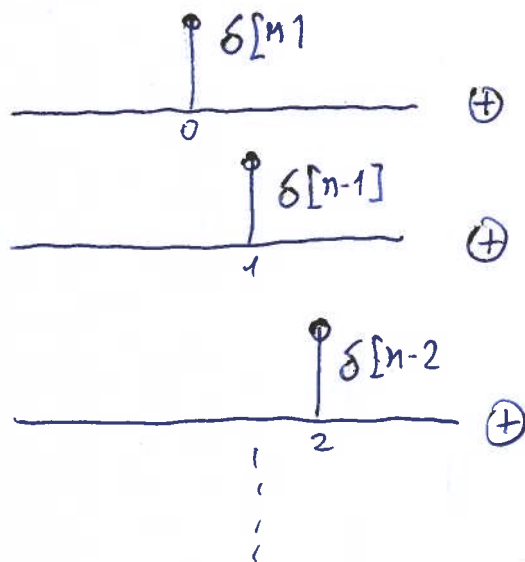
$$\delta[n] = 1 \quad \text{if } n=0$$

$$\delta[n-1] = 1 \quad \text{if } n=1 \quad \delta[n-k] = 0 \quad \text{if } n \neq k$$

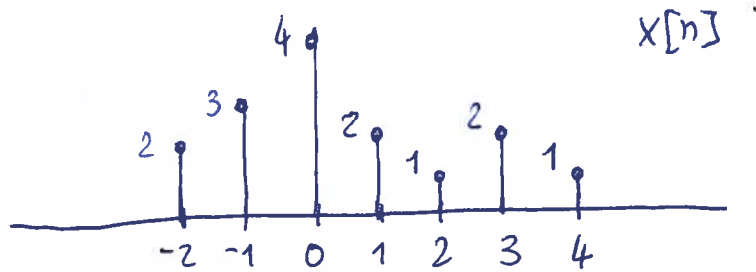
$$\delta[n-2] = 1 \quad \text{if } n=2$$

\vdots

$$\text{Since } u[n] = 1 \quad \text{if } n \geq 0 \rightarrow \delta[n] + \delta[n-1] + \delta[n-2] + \dots = u[n]$$

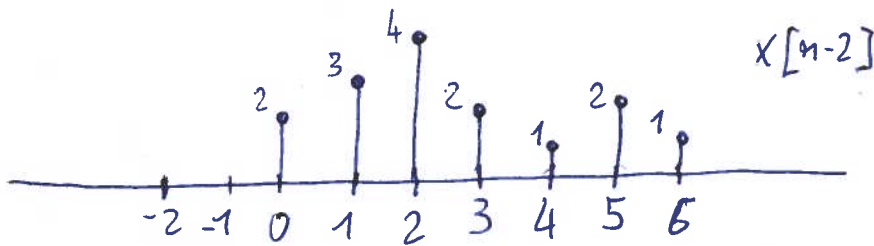


2)

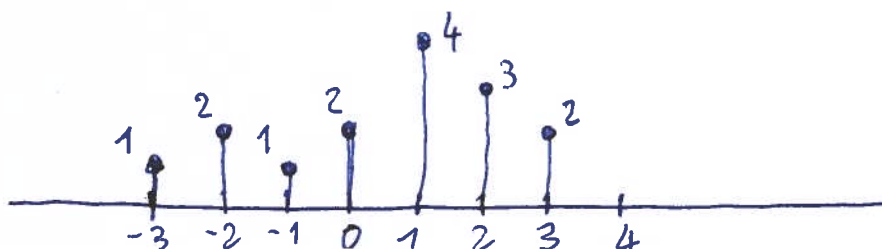


$$x[n] = 2\delta[n+2] + 3\delta[n+1] + 4\delta[n] + 2\delta[n-1] + \delta[n-2] + 2\delta[n-3] + \delta[n-4]$$

$$\begin{aligned} x[n-2] &= 2\delta[(n-2)+2] + 3\delta[(n-2)+1] + 4\delta[n-2] + 2\delta[(n-2)-1] + \\ &\quad + \delta[(n-2)-2] + 2\delta[(n-2)-3] + \delta[(n-2)-4] = \\ &= 2\delta[n] + 3\delta[n-1] + 4\delta[n-2] + 2\delta[n-3] + \delta[n-4] + \\ &\quad + 2\delta[n-5] + \delta[n-6] \end{aligned}$$



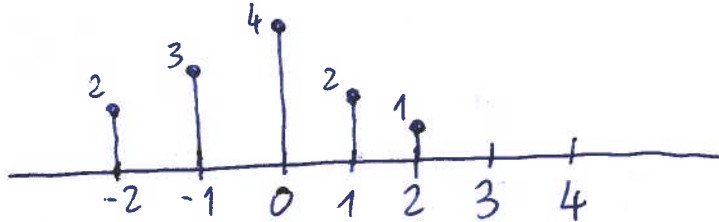
$$\begin{aligned} x[1-n] &= 2\delta[(1-n)+2] + 3\delta[(1-n)+1] + 4\delta[1-n] + 2\delta[(1-n)-1] + \\ &\quad + \delta[(1-n)-2] + 2\delta[(1-n)-3] + \delta[(1-n)-4] = \\ &= 2\delta[3-n] + 3\delta[2-n] + 4\delta[1-n] + 2\delta[-n] + \\ &\quad + \delta[-n-1] + 2\delta[-n-2] + \delta[-n-3] = \begin{cases} \delta[-n-x] \\ = \delta[n+x] \end{cases} \\ &= 2\delta[n-3] + 3\delta[n-2] + 4\delta[n-1] + 2\delta[n] + \\ &\quad + \delta[n+1] + 2\delta[n+2] + \delta[n+3] \end{aligned}$$



- $x[n] u[2-n]$

$$u[2-n] = \begin{cases} 1 & 2-n \geq 0 \rightarrow n \leq 2 \\ 0 & 2-n < 0 \rightarrow n > 2 \end{cases}$$

$$x[n] u[2-n] = 2\delta[n+2] + 3\delta[n+1] + 4\delta[n] + 2\delta[n-1] + \delta[n-2]$$

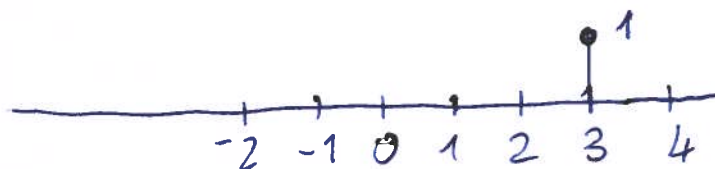


- $x[n-1] \delta[n-3]$

$$\delta[n-3] = \begin{cases} 1 & n=3 \\ 0 & n \neq 3 \end{cases}$$

$$x[n-1] = 2\delta[n+1] + 3\delta[n] + 4\delta[n-1] + 2\delta[n-2] + \delta[n-3] + 2\delta[n-4] + \delta[n-5]$$

$$x[n-1] \delta[n-3] = \delta[n-3]$$



$$3) \cdot T(x[n]) = e^{x[n]}$$

- linearity

Let us consider 2 sequences $x_1[n]$, $x_2[n]$

$$T(x_1[n]) = e^{x_1[n]} \quad T(x_2[n]) = e^{x_2[n]}$$

We define $\hat{x}[n] = ax_1[n] + bx_2[n]$

$$T(\hat{x}[n]) = e^{ax_1[n] + bx_2[n]} = e^{ax_1[n]} e^{bx_2[n]} \neq$$

$$\neq aT(x_1[n]) + bT(x_2[n])$$

non-linear!

- stability

if $|x[n]| \leq B_x < \infty$

$$|T(x[n])| = |e^{x[n]}| \leq e^{|x[n]|} \leq e^{B_x} < \infty$$

stable system!

- causality

The system does not depend on future values of $x[n]$, and is therefore causal

- time invariance

$$y[n-n_0] = e^{x[n-n_0]}$$

$$T(x[n-n_0]) = e^{x[n-n_0]} = y[n-n_0]$$

time invariant / system

- $T(x[n]) = ax + b$, $a, b < \infty$.

- linearity

$$x_1[n], x_2[n] \rightarrow \begin{aligned} T(x_1[n]) &= ax_1[n] + b \\ T(x_2[n]) &= ax_2[n] + b \end{aligned}$$

$$cT(x_1[n]) + dT(x_2[n]) = c(ax_1[n] + b) + d(ax_2[n] + b)$$

Let us define $\tilde{x}[n] = cx_1[n] + dx_2[n]$

$$T(\tilde{x}[n]) = T(cx_1[n] + dx_2[n]) = a(cx_1[n] + dx_2[n]) + b$$

$$\neq cT(x_1[n]) + dT(x_2[n])$$

not linear!

- causality

Since the system does not depend of future values of $x[n]$, it is causal

- stability

if $|x[n]| \leq B_x < \infty$

$$\rightarrow |T(x[n])| = |ax[n] + b| \leq |a|B_x + |b| < \infty$$

for $a, b < \infty$

stable system

- time invariance

$$y[n-n_0] = ax[n-n_0] + b$$

$$T(x[n-n_0]) = ax[n-n_0] + b = y[n-n_0]$$

time invariant system!

- $T(X[n]) = X[-n]$

- linearity

$$x_1[n], x_2[n] \rightarrow T(x_1[n]) = x_1[-n]$$

$$T(x_2[n]) = x_2[-n]$$

let us define $\hat{x}[n] = ax_1[n] + bx_2[n]$

$$T(\hat{x}[n]) = T(ax_1[n] + bx_2[n]) = ax_1[-n] + bx_2[-n] =$$

$$= aT(x_1[n]) + bT(x_2[n])$$

linear system

- causality

if $n < 0$, the system depends on future values of $x[n]$

→ non causal

- stability

if $|x[n]| \leq B_x < \infty$

$$|T(x[n])| = |x[-n]| \leq B_x \quad \text{stable system}$$

- time invariance

$$y[n-n_0] = x[-n+n_0]$$

$$T(x[n-n_0]) = x[-n-n_0] \neq y[n-n_0]$$

non time invariant

- $T(x[n]) = x[n] + u[n+1]$

$$u[n+1] = \begin{cases} 1 & n \geq -1 \\ 0 & n < -1 \end{cases}$$

- linearity

$$x_1[n], x_2[n] \rightarrow T(x_1[n]) = x_1[n] + u[n+1]$$

$$T(x_2[n]) = x_2[n] + u[n+1]$$

$$a T(x_1[n]) + b T(x_2[n]) = a(x_1[n] + u[n+1]) + b(x_2[n] + u[n+1])$$

$$\hat{x}[n] = a x_1[n] + b x_2[n]$$

$$T(\hat{x}[n]) = T(a x_1[n] + b x_2[n]) = a x_1[n] + b x_2[n] + u[n+1]$$

$$\neq a T(x_1[n]) + b T(x_2[n])$$

non linear system!

- causality

The system does not depend on future values of $x[n]$, and is therefore causal

- stability

$$\text{if } |x[n]| \leq B_x < \infty$$

$$|T(x[n])| \leq B_{x+1} \quad \text{if } n \geq -1 \text{ and}$$

$$|T(x[n])| \leq B_x \quad \text{if } n < -1 \quad \text{stable system}$$

- time invariance

$$y[n-n_0] = x[n-n_0] + u[n-n_0+1]$$

$$T(x[n-n_0]) = x[n-n_0] + u[n+1] \neq y[n-n_0]$$

non-time invariant!

- $T(X[n]) = \sum_{k=n-1}^{n+1} X[k] = X[n-1] + X[n] + X[n+1]$

- linearity

$$x_1[n], x_2[n] \rightarrow T(x_1[n]) = \sum_{k=n-1}^{n+1} x_1[k]$$

$$T(x_2[n]) = \sum_{k=n-1}^{n+1} x_2[k]$$

$$aT(x_1[n]) + bT(x_2[n]) = a \sum_{k=n-1}^{n+1} x_1[k] + b \sum_{k=n-1}^{n+1} x_2[k]$$

$$\hat{x}[n] = ax_1[n] + bx_2[n]$$

$$T(\hat{x}[n]) = \sum_{k=n-1}^{n+1} (ax_1[k] + bx_2[k]) = a \sum_{k=n-1}^{n+1} x_1[k] + b \sum_{k=n-1}^{n+1} x_2[k]$$

$$= aT(x_1[n]) + bT(x_2[n]) \quad \text{linear!}$$

- causality

the system depends on future values of $X[n]$, and is therefore not causal

- stability

$$\text{if } |X[n]| \leq B_x < \infty$$

$$\rightarrow |T(X[n])| = |T(X[n-1] + X[n] + X[n+1])| \leq 3B_x$$

stable system



• time invariance

$$y[n-n_0] = \sum_{k=n-n_0-1}^{n-n_0+1} x[k]$$

$$T(x[n-n_0]) = \sum_{k=n-1}^{n+1} x[k-n_0] = \sum_{q=n-n_0-1}^{n-n_0+1} x[q] = y[n-n_0]$$

\uparrow
 $k-n_0=q$

time invariant!

- $T(x[n]) = x[n^2]$

- linearity

$$x_1[n], x_2[n] \rightarrow \begin{aligned} T(x_1[n]) &= x_1[n^2] \\ T(x_2[n]) &= x_2[n^2] \end{aligned}$$

$$aT(x_1[n]) + bT(x_2[n]) = ax_1[n^2] + bx_2[n^2]$$

$$\tilde{x}[n] = ax_1[n] + bx_2[n]$$

$$\begin{aligned} T(\tilde{x}[n]) &= T(ax_1[n] + bx_2[n]) = ax_1[n^2] + bx_2[n^2] = \\ &= aT(x_1[n]) + bT(x_2[n]) \end{aligned}$$

linear system

- causality

The system does depend on future values of $x[n]$, and is therefore non causal.

- stability

$$\text{if } |x[n]| \leq B_x < \infty \Rightarrow |x[n^2]| \leq B_x < \infty$$

stable system

- time invariance

$$y[n-n_0] = x[(n-n_0)^2] = x[n^2 + n_0^2 - 2nn_0]$$

$$T(x[n-n_0]) = x[n^2 - n_0] \neq y[n-n_0]$$

non time-invariant!