```
In [26]: import numpy as np
import matplotlib.pyplot as plt
# from mpl_toolkits.mplot3d import Axes3D
%matplotlib inline
```

Q2

```
In [2]: def Q(x):
     x1 = x[0]
     x2 = x[1]
     return 0.5 * x1**2 + 0.5 * x2**2 - x1*x2
```

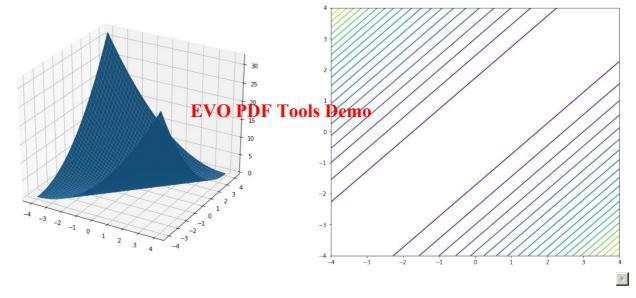
```
In [28]: LB = -4
    UB = 4
    x = np.linspace(LB, UB, 50)
    y = np.linspace(LB, UB, 50)
    X, Y = np.meshgrid(x, y)

Z = Q([X, Y])

fig = plt.figure(figsize=(20,8))
    ax1 = fig.add_subplot(121, projection='3d')
    ax1.plot_surface(X, Y, Z)

ax2 = fig.add_subplot(122)
    ax2.contour(X, Y, Z, levels=30)

plt.show()
```



Q3

```
In [18]: def F(x):
    x1 = x[0]
    x2 = x[1]
    return (x1**2 + x2 -11)**2 + (x1 + x2**2 - 7)**2
```

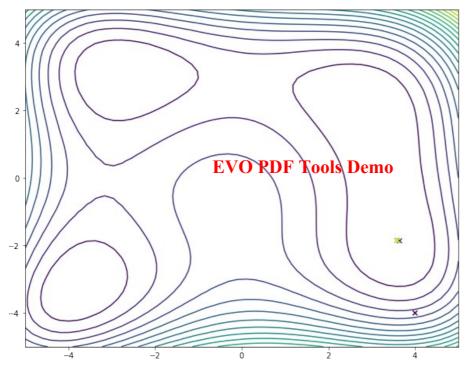
```
In [33]: from scipy.optimize import minimize
             #Powell's method
             x0 = np.array([4, -4])
             res = minimize(F, x0, method='Powell', options={'disp':True, 'return_all':True})
             xs = res.allvecs
            LB = -5
             UB = 5
             x = np.linspace(LB, UB, 50)
             y = np.linspace(LB, UB, 50)
             X, Y = np.meshgrid(x, y)
             Z = F([X, Y])
             fig = plt.figure(figsize=(10,8))
             ax1 = fig.add subplot(111)
             ax1.contour(X, Y, Z, levels=20)
              \texttt{ax1.scatter}([\texttt{x}[\texttt{0}] \ \textbf{for} \ \texttt{x} \ \textbf{in} \ \texttt{xs}], \ [\texttt{x}[\texttt{1}] \ \textbf{for} \ \texttt{x} \ \textbf{in} \ \texttt{xs}], \ \texttt{c=list}(\texttt{range}(\texttt{len}(\texttt{res.allvecs}))), \ \texttt{marker='x'}) 
             plt.show()
             print (res.x)
```

Optimization terminated successfully.

Current function value: 0.000000

Iterations: 6

Function evaluations: 151



[3.58442834 -1.84812653]

```
In [34]: #Conjugate Gradient
             x0 = np.array([4, -4])
             res = minimize(F, x0, method='CG', options={'disp':True, 'return_all':True})
             xs = res.allvecs
             LB = -5
             UB = 5
             x = np.linspace(LB, UB, 50)
             y = np.linspace(LB, UB, 50)
             X, Y = np.meshgrid(x, y)
             Z = F([X, Y])
             fig = plt.figure(figsize=(10,8))
             ax1 = fig.add_subplot(111 )
             ax1.contour(X, Y, Z, levels=20)
              \texttt{ax1.scatter}([\texttt{x}[\texttt{0}] \ \textbf{for} \ \texttt{x} \ \textbf{in} \ \texttt{xs}], \ [\texttt{x}[\texttt{1}] \ \textbf{for} \ \texttt{x} \ \textbf{in} \ \texttt{xs}], \ \texttt{c=list}(\texttt{range}(\texttt{len}(\texttt{res.allvecs}))), \ \texttt{marker='x'}) 
             plt.show()
             print (res.x)
```

Function evaluations: 88
Gradient evaluations: 22

[2.99999999 2.]

Optimization terminated successfully.

Iterations: 11

Current function value: 0.000000

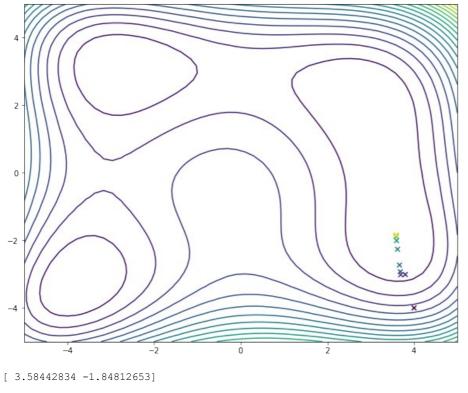
Optimization terminated successfully.

Current function value: 0.000000

Iterations: 11

Function evaluations: 60

Gradient evaluations: 15



In []:

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