

1 Elliptic Equation

The linearised elliptic equation is

$$G = Hv - \frac{H^3}{3} \left(\frac{\partial^2 v}{\partial x^2} \right)$$

Taking the weak version of this we get that

$$\begin{aligned} \int_{\Omega} Gv \, dx &= H \int_{\Omega} vv \, dx - \frac{H^3}{3} \int_{\Omega} \frac{\partial^2 v}{\partial x^2} v \, dx \\ \int_{\Omega} Gv \, dx &= H \int_{\Omega} vv \, dx + \frac{H^3}{3} \int_{\Omega} \frac{\partial v}{\partial x} \frac{\partial v}{\partial x} \, dx \end{aligned}$$

In particular for the basis function ϕ_j we must have

$$\int_{\Omega} G\phi_j \, dx = H \int_{\Omega} v\phi_j \, dx + \frac{H^3}{3} \int_{\Omega} \frac{\partial v}{\partial x} \frac{\partial (\phi_j)}{\partial x} \, dx$$

We use the FEM discretisation from []

$$G = \sum_j G_{j-1/2}^+ \psi_{j-1/2}^+ + G_{j+1/2}^- \psi_{j+1/2}^-$$

and

$$v = \sum_j v_{j-1/2} \phi_{j-1/2} + v_j \phi_j + v_{j+1/2} \phi_{j+1/2} \quad (1)$$

Now for our evolution equations we only need to get the errors introduced from our calculation of $v_{j+1/2}$ and v_j , as we can get $v_{j-1/2}$ from just a shift. We previously demonstrated how the coefficient matrices are calculated for the FEM so we now just skip ahead to give the equations.

The FEM gives

$$\begin{aligned} \sum_j \frac{\Delta x}{2} \left[\begin{array}{c} \frac{1}{3} G_{j-1/2}^+ \\ \frac{2}{3} G_{j-1/2}^+ + \frac{2}{3} G_{j+1/2}^- \\ \frac{1}{3} G_{j+1/2}^- \end{array} \right] &= \\ \sum_j \left(H \frac{\Delta x}{2} \left[\begin{array}{ccc} \frac{4}{15} & \frac{2}{15} & -\frac{1}{15} \\ \frac{2}{15} & \frac{16}{15} & \frac{2}{15} \\ -\frac{1}{15} & \frac{2}{15} & \frac{4}{15} \end{array} \right] + \frac{2H^3}{3\Delta x} \left[\begin{array}{ccc} \frac{7}{6} & -\frac{4}{3} & \frac{1}{6} \\ -\frac{4}{3} & \frac{8}{3} & -\frac{4}{3} \\ \frac{1}{6} & -\frac{4}{3} & 7 \end{array} \right] \right) &\begin{bmatrix} u_{j-1/2} \\ u_j \\ u_{j+1/2} \end{bmatrix} \quad (2) \end{aligned}$$

$$\begin{aligned}
\sum_j \frac{\Delta x}{6} \begin{bmatrix} G_{j-1/2}^+ \\ 2G_{j-1/2}^+ + 2G_{j+1/2}^- \\ G_{j+1/2}^- \end{bmatrix} = \\
\sum_j \left(H \frac{\Delta x}{30} \begin{bmatrix} 4 & 2 & -1 \\ 2 & 16 & 2 \\ -1 & 2 & 4 \end{bmatrix} + \frac{H^3}{9\Delta x} \begin{bmatrix} 7 & -8 & 1 \\ -8 & 16 & -8 \\ 1 & -8 & 7 \end{bmatrix} \right) \begin{bmatrix} u_{j-1/2} \\ u_j \\ u_{j+1/2} \end{bmatrix} \quad (3)
\end{aligned}$$

$$\begin{aligned}
\sum_j \frac{\Delta x}{6} \begin{bmatrix} G_{j-1/2}^+ \\ 2G_{j-1/2}^+ + 2G_{j+1/2}^- \\ G_{j+1/2}^- \end{bmatrix} = \\
\sum_j \left(H \frac{\Delta x}{30} \begin{bmatrix} 4 & 2 & -1 \\ 2 & 16 & 2 \\ -1 & 2 & 4 \end{bmatrix} + \frac{H^3}{9\Delta x} \begin{bmatrix} 7 & -8 & 1 \\ -8 & 16 & -8 \\ 1 & -8 & 7 \end{bmatrix} \right) \begin{bmatrix} e^{-ik\frac{\Delta x}{2}} \\ 1 \\ e^{ik\frac{\Delta x}{2}} \end{bmatrix} u_j \quad (4)
\end{aligned}$$

$$\begin{aligned}
\sum_j \frac{\Delta x}{6} \begin{bmatrix} e^{-ik\Delta x} \mathcal{R}_2^+ \\ 2e^{-ik\Delta x} \mathcal{R}_2^+ + 2\mathcal{R}_2^- \\ \mathcal{R}_2^- \end{bmatrix} G_j = \\
\sum_j \left(H \frac{\Delta x}{30} \begin{bmatrix} -5i \sin(k\frac{\Delta x}{2}) + 3 \cos(k\frac{\Delta x}{2}) + 2 \\ 16 + 4 \cos(k\frac{\Delta x}{2}) \\ 5i \sin(k\frac{\Delta x}{2}) + 3 \cos(k\frac{\Delta x}{2}) + 2 \end{bmatrix} \right. \\
\left. + \frac{H^3}{9\Delta x} \begin{bmatrix} -6i \sin(k\frac{\Delta x}{2}) + 8 \cos(k\frac{\Delta x}{2}) - 8 \\ 32 \sin^2(k\frac{\Delta x}{4}) \\ 6i \sin(k\frac{\Delta x}{2}) + 8 \cos(k\frac{\Delta x}{2}) - 8 \end{bmatrix} \right) u_j \quad (5)
\end{aligned}$$

assemble into complete matrices so we get, change notation to denote we sum the corresponding matrices together

$$\begin{aligned}
\sum_j \frac{\Delta x}{6} \begin{bmatrix} e^{-ik\Delta x} \mathcal{R}_2^+ + e^{-ik\Delta x} \mathcal{R}_2^- \\ 2e^{-ik\Delta x} \mathcal{R}_2^+ + 2\mathcal{R}_2^- \\ \mathcal{R}_2^- + \mathcal{R}_2^+ \end{bmatrix} G_j = \\
\sum_j \left(H \frac{\Delta x}{30} \begin{bmatrix} e^{-ik\frac{\Delta x}{2}} (4 \cos(\frac{k\Delta x}{2}) - 2 \cos(k\Delta x) + 8) \\ 16 + 4 \cos(k\frac{\Delta x}{2}) \\ e^{ik\frac{\Delta x}{2}} (4 \cos(\frac{k\Delta x}{2}) - 2 \cos(k\Delta x) + 8) \end{bmatrix} \right. \\
\left. + \frac{H^3}{9\Delta x} \begin{bmatrix} e^{-ik\frac{\Delta x}{2}} (-16 \cos(\frac{k\Delta x}{2}) + 2 \cos(k\Delta x) + 14) \\ 32 \sin^2(\frac{k\Delta x}{4}) \\ e^{ik\frac{\Delta x}{2}} (-16 \cos(\frac{k\Delta x}{2}) + 2 \cos(k\Delta x) + 14) \end{bmatrix} \right) u_j \quad (6)
\end{aligned}$$

$$\begin{aligned}
\sum_j \frac{\Delta x}{6} \begin{bmatrix} \mathcal{R}_2^+ + \mathcal{R}_2^- \\ 2 \\ \mathcal{R}_2^- + \mathcal{R}_2^+ \end{bmatrix}^T \begin{bmatrix} e^{-ik\Delta x} \\ 1 \\ 1 \end{bmatrix} G_j = \\
\sum_j \left(H \frac{\Delta x}{30} \begin{bmatrix} 4 \cos(\frac{k\Delta x}{2}) - 2 \cos(k\Delta x) + 8 \\ 16 + 4 \cos(k\frac{\Delta x}{2}) \\ 4 \cos(\frac{k\Delta x}{2}) - 2 \cos(k\Delta x) + 8 \end{bmatrix} \right. \\
\left. + \frac{H^3}{9\Delta x} \begin{bmatrix} -16 \cos(\frac{k\Delta x}{2}) + 2 \cos(k\Delta x) + 14 \\ 32 \sin^2(\frac{k\Delta x}{4}) \\ -16 \cos(\frac{k\Delta x}{2}) + 2 \cos(k\Delta x) + 14 \end{bmatrix} \right) \begin{bmatrix} e^{-ik\frac{\Delta x}{2}} \\ 1 \\ e^{ik\frac{\Delta x}{2}} \end{bmatrix} u_j \quad (7)
\end{aligned}$$

The equation for $u_{j+1/2}$ is then

$$\begin{aligned}
\frac{\Delta x}{6} (\mathcal{R}_2^+ + \mathcal{R}_2^-) G_j = \\
\left(H \frac{\Delta x}{30} \left(4 \cos\left(\frac{k\Delta x}{2}\right) - 2 \cos(k\Delta x) + 8 \right) \right. \\
\left. + \frac{H^3}{9\Delta x} \left(-16 \cos\left(\frac{k\Delta x}{2}\right) + 2 \cos(k\Delta x) + 14 \right) \right) e^{ik\frac{\Delta x}{2}} u_j. \quad (8)
\end{aligned}$$