

1 Numerical Method for dispersion error Break Down

To do the first analysis we first construct the update matrix F , which plays a similar role to λ I showed you in the space continuous case. We then diagonalise this so that we get back to just factors (basically). This also means I would like to update what we present in the table, I think we should present all the elements of the matrices, for $\mathcal{F}^{h,u}$ and $\mathcal{F}^{h,h}$ there is no change but for $\mathcal{F}^{u,u}$ and $\mathcal{F}^{u,h}$ this means also dividing it by \mathcal{G} as well as \mathcal{M} and Δx . Anyway onto the method.

1.1 F

F comes from the FVM update scheme which for us is

$$\bar{q}_j^{n+1} = \bar{q}_j^n - \frac{\Delta t}{\Delta x} \left[F_{j+\frac{1}{2}} - F_{j-\frac{1}{2}} \right]$$

This converts to (both analytical and numerical)

$$\mathcal{M}q_j^{n+1} = \mathcal{M}q_j^n - \frac{\Delta t}{\Delta x} [\mathcal{F}^{q,v}v_j + \mathcal{F}^{q,q}q_j - \mathcal{F}^{q,v}v_{j-1} - \mathcal{F}^{q,q}q_{j-1}]$$

$$\mathcal{M}q_j^{n+1} = \mathcal{M}q_j^n - \frac{\Delta t}{\Delta x} [\mathcal{F}^{q,v}v_j + \mathcal{F}^{q,q}q_j - \mathcal{F}^{q,v}e^{-ik\Delta x}v_j - \mathcal{F}^{q,q}e^{-ik\Delta x}q_j]$$

Defining $\mathcal{D}_x = 1 - e^{-ik\Delta x}$

$$\mathcal{M}q_j^{n+1} = \mathcal{M}q_j^n - \frac{\Delta t}{\Delta x} [\mathcal{D}_x \mathcal{F}^{q,v}v_j + \mathcal{D}_x \mathcal{F}^{q,q}q_j]$$

So we have

$$q_j^{n+1} = q_j^n - \frac{\mathcal{D}_x \Delta t}{\mathcal{M} \Delta x} [\mathcal{F}^{q,v}v_j + \mathcal{F}^{q,q}q_j]$$

Thus we have

$$\begin{bmatrix} h \\ \mathcal{G}u \end{bmatrix}_j^{n+1} = \begin{bmatrix} h \\ \mathcal{G}u \end{bmatrix}_j^n - \frac{\mathcal{D}_x \Delta t}{\mathcal{M} \Delta x} \begin{bmatrix} \mathcal{F}^{h,h} & \mathcal{F}^{h,u} \\ \mathcal{F}^{u,h} & \mathcal{F}^{u,u} \end{bmatrix} \begin{bmatrix} h \\ u \end{bmatrix}_j^n$$

$$\begin{bmatrix} h \\ u \end{bmatrix}_j^{n+1} = \begin{bmatrix} h \\ u \end{bmatrix}_j^n - \frac{\mathcal{D}_x \Delta t}{\mathcal{M} \Delta x} \begin{bmatrix} \mathcal{F}^{h,h} & \mathcal{F}^{h,u} \\ \frac{1}{\mathcal{G}} \mathcal{F}^{u,h} & \frac{1}{\mathcal{G}} \mathcal{F}^{u,u} \end{bmatrix} \begin{bmatrix} h \\ u \end{bmatrix}_j^n$$

Lets define

$$\begin{aligned} \mathbf{F} &= \frac{\mathcal{D}_x}{\mathcal{M} \Delta x} \begin{bmatrix} \mathcal{F}^{h,h} & \mathcal{F}^{h,u} \\ \frac{1}{\mathcal{G}} \mathcal{F}^{u,h} & \frac{1}{\mathcal{G}} \mathcal{F}^{u,u} \end{bmatrix} \\ \begin{bmatrix} h \\ u \end{bmatrix}_j^{n+1} &= \begin{bmatrix} h \\ u \end{bmatrix}_j^n - \Delta t \mathbf{F} \begin{bmatrix} h \\ u \end{bmatrix}_j^n \\ \begin{bmatrix} h \\ u \end{bmatrix}_j^{n+1} &= (\mathbf{I} - \Delta t \mathbf{F}) \begin{bmatrix} h \\ u \end{bmatrix}_j^n \end{aligned}$$

Thats our Euler Step, the difference between this and the previous version is we didn't divide that bottom Row by \mathcal{G} So we have to change our approximation stuff. Also we would like to know what the analytic value of \mathbf{F} is and approximations to it.

1.2 Analytic

$$\frac{\mathcal{D}_a}{\Delta x \mathcal{M}_a} \mathcal{F}_a^{h,u} = ikH$$

$$\frac{\mathcal{D}_a}{\Delta x \mathcal{M}_a} \mathcal{F}_a^{h,h} = 0$$

$$\frac{\mathcal{D}_a}{\mathcal{G}_a \Delta x \mathcal{M}_a} \mathcal{F}_a^{u,h} = \frac{ikgH}{H + \frac{H^3}{3}k^2} = i\frac{k}{H}gH \frac{3}{3 + H^2k^2}$$

$$\text{using } \omega = \pm k\sqrt{gH} \sqrt{\frac{3}{H^2k^2+3}}, \quad \omega^2 = k^2gH \frac{3}{H^2k^2+3}$$

$$\frac{\mathcal{D}_a}{\mathcal{G} \Delta x \mathcal{M}_a} \mathcal{F}_a^{u,h} = i\frac{k}{H} \frac{\omega^2}{k^2} = -i\frac{\omega^2}{kH}$$

$$\frac{\mathcal{D}_a}{\mathcal{G} \Delta x \mathcal{M}_a} \mathcal{F}_a^{u,u} = 0$$

So we have

$$\mathbf{F} = \begin{bmatrix} 0 & ikH \\ \frac{\omega^2}{ikH} & 0 \end{bmatrix} = \frac{1}{ikH} \begin{bmatrix} 0 & -k^2H^2 \\ \omega^2 & 0 \end{bmatrix}$$

We can diagonalise this ($A = SDS^{-1}$) with the following matrices

$$\mathbf{F} = \frac{1}{ikH} \begin{bmatrix} -\frac{ikH}{\omega} & \frac{ikH}{\omega} \\ 1 & 1 \end{bmatrix} \begin{bmatrix} -ikH\omega & 0 \\ 0 & ikH\omega \end{bmatrix} \begin{bmatrix} -\frac{ikH}{\omega} & \frac{ikH}{\omega} \\ 1 & 1 \end{bmatrix}^{-1}$$

$$\mathbf{F} = \begin{bmatrix} -\frac{ikH}{\omega} & \frac{ikH}{\omega} \\ 1 & 1 \end{bmatrix} \begin{bmatrix} -\omega & 0 \\ 0 & \omega \end{bmatrix} \begin{bmatrix} -\frac{ikH}{\omega} & \frac{ikH}{\omega} \\ 1 & 1 \end{bmatrix}^{-1}$$

We will use the following notation

$$\mathbf{W}_a = \begin{bmatrix} -\omega & 0 \\ 0 & \omega \end{bmatrix}$$

$$\mathbf{S}_a = \begin{bmatrix} -\frac{ikH}{\omega} & \frac{ikH}{\omega} \\ 1 & 1 \end{bmatrix}$$

So we have

$$\mathbf{F}_a = \mathbf{S}_a \mathbf{W}_a \mathbf{S}_a^{-1}$$

1.3 Third Order

$$\begin{bmatrix} h \\ u \end{bmatrix}^1 = (\mathbf{I} - \Delta t \mathbf{F}_3) \begin{bmatrix} h \\ u \end{bmatrix}^n$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^2 = (\mathbf{I} - \Delta t \mathbf{F}_3) \begin{bmatrix} h \\ u \end{bmatrix}^1$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^3 = \frac{3}{4} \begin{bmatrix} h \\ u \end{bmatrix}^n + \frac{1}{4} \begin{bmatrix} h \\ u \end{bmatrix}^2$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^4 = (\mathbf{I} - \Delta t \mathbf{F}_3) \begin{bmatrix} h \\ u \end{bmatrix}^3$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \frac{1}{3} \begin{bmatrix} h \\ u \end{bmatrix}^n + \frac{2}{3} \begin{bmatrix} h \\ u \end{bmatrix}^4$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^3 = \frac{3}{4} \begin{bmatrix} h \\ u \end{bmatrix}^n + \frac{1}{4} (\mathbf{I} - \Delta t \mathbf{F}_3)^2 \begin{bmatrix} h \\ u \end{bmatrix}^n$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^3 = \left(\frac{3}{4}\mathbf{I} + \frac{1}{4}(\mathbf{I} - \Delta t \mathbf{F}_3)^2 \right) \begin{bmatrix} h \\ u \end{bmatrix}^n$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \frac{1}{3} \begin{bmatrix} h \\ u \end{bmatrix}^n + \frac{2}{3}(\mathbf{I} - \Delta t \mathbf{F}_3) \left(\frac{3}{4}\mathbf{I} + \frac{1}{4}(\mathbf{I} - \Delta t \mathbf{F}_3)^2 \right) \begin{bmatrix} h \\ u \end{bmatrix}^n$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(\frac{1}{3}\mathbf{I} + \frac{2}{3}(\mathbf{I} - \Delta t \mathbf{F}_3) \left(\frac{3}{4}\mathbf{I} + \frac{1}{4}(\mathbf{I} - \Delta t \mathbf{F}_3)^2 \right) \right) \begin{bmatrix} h \\ u \end{bmatrix}^n$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(\frac{1}{3}\mathbf{I} + (\mathbf{I} - \Delta t \mathbf{F}_3) \left(\frac{1}{2}\mathbf{I} + \frac{1}{6}(\mathbf{I} - 2\Delta t \mathbf{F}_3 + \Delta t^2 \mathbf{F}_3^2) \right) \right) \begin{bmatrix} h \\ u \end{bmatrix}^n$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(\frac{1}{3}\mathbf{I} + (\mathbf{I} - \Delta t \mathbf{F}_3) \left(\frac{2}{3}\mathbf{I} - \frac{1}{3}\Delta t \mathbf{F}_3 + \frac{1}{6}\Delta t^2 \mathbf{F}_3^2 \right) \right) \begin{bmatrix} h \\ u \end{bmatrix}^n$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(\frac{1}{3}\mathbf{I} + \frac{2}{3}\mathbf{I} - \frac{1}{3}\Delta t \mathbf{F}_3 + \frac{1}{6}\Delta t^2 \mathbf{F}_3^2 + (-\Delta t \mathbf{F}_3) \left(\frac{2}{3}\mathbf{I} - \frac{1}{3}\Delta t \mathbf{F}_3 + \frac{1}{6}\Delta t^2 \mathbf{F}_3^2 \right) \right) \begin{bmatrix} h \\ u \end{bmatrix}^n$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(\mathbf{I} - \frac{1}{3}\Delta t \mathbf{F}_3 + \frac{1}{6}\Delta t^2 \mathbf{F}_3^2 - \frac{2}{3}\Delta t \mathbf{F}_3 + \frac{1}{3}\Delta t \mathbf{F}_3 \Delta t \mathbf{F}_3 - \frac{1}{6}\Delta t^2 \mathbf{F}_3^2 \Delta t \mathbf{F}_3 \right) \begin{bmatrix} h \\ u \end{bmatrix}^n$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(\mathbf{I} - \mathbf{F}_3 + \frac{1}{6}\Delta t^2 \mathbf{F}_3^2 + \frac{1}{3}\Delta t^2 \mathbf{F}_3^2 - \frac{1}{6}\Delta t^3 \mathbf{F}_3^3 \right) \begin{bmatrix} h \\ u \end{bmatrix}^n$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(\mathbf{I} - \Delta t \mathbf{F}_3 + \frac{1}{2}\Delta t^2 \mathbf{F}_3^2 - \frac{1}{6}\Delta t^3 \mathbf{F}_3^3 \right) \begin{bmatrix} h \\ u \end{bmatrix}^n$$

lets say we have

$$\mathbf{F}_3 = \mathbf{S}_3 \mathbf{D}_3 \mathbf{S}_3^{-1}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(\mathbf{I} - \Delta t \mathbf{S}_3 \mathbf{D}_3 \mathbf{S}_3^{-1} + \frac{1}{2} \Delta t^2 \mathbf{S}_3 \mathbf{D}_3^2 \mathbf{S}_3^{-1} - \frac{1}{6} \Delta t^3 \mathbf{S}_3 \mathbf{D}_3^3 \mathbf{S}_3^{-1} \right) \begin{bmatrix} h \\ u \end{bmatrix}^n$$

$$\mathbf{S}_3^{-1} \begin{bmatrix} h \\ u \end{bmatrix}^{n+1} = \left(\mathbf{S}_3^{-1} - \Delta t \mathbf{D}_3 \mathbf{S}_3^{-1} + \frac{1}{2} \Delta t^2 \mathbf{D}_3^2 \mathbf{S}_3^{-1} - \frac{1}{6} \Delta t^3 \mathbf{D}_3^3 \mathbf{S}_3^{-1} \right) \begin{bmatrix} h \\ u \end{bmatrix}^n$$

$$\mathbf{S}_3^{-1} e^{i\omega \Delta t} \begin{bmatrix} h \\ u \end{bmatrix}^n = \left(\mathbf{I} - \Delta t \mathbf{D}_3 + \frac{1}{2} \Delta t^2 \mathbf{D}_3^2 - \frac{1}{6} \Delta t^3 \mathbf{D}_3^3 \right) \mathbf{S}_3^{-1} \begin{bmatrix} h \\ u \end{bmatrix}^n$$

$$e^{i\omega \Delta t} \mathbf{S}_3^{-1} \begin{bmatrix} h \\ u \end{bmatrix}^n = \left(\mathbf{I} - \Delta t \mathbf{D}_3 + \frac{1}{2} \Delta t^2 \mathbf{D}_3^2 - \frac{1}{6} \Delta t^3 \mathbf{D}_3^3 \right) \mathbf{S}_3^{-1} \begin{bmatrix} h \\ u \end{bmatrix}^n$$

$$e^{i\omega \Delta t} \mathbf{S}_3^{-1} \begin{bmatrix} h \\ u \end{bmatrix}^n = \begin{bmatrix} 1 - \Delta t \lambda_{3,-} + \frac{\Delta t^2}{2} \lambda_{3,-}^2 - \frac{\Delta t^3}{6} \lambda_{3,-}^3 & 0 \\ 0 & 1 - \Delta t \lambda_{3,+} + \frac{\Delta t^2}{2} \lambda_{3,+}^2 - \frac{\Delta t^3}{6} \lambda_{3,+}^3 \end{bmatrix} \mathbf{S}_3^{-1} \begin{bmatrix} h \\ u \end{bmatrix}^n \quad (1)$$

So $e^{i\omega \Delta t}$ an eigenvalue of this diagonal matrix, so it must be that

$$e^{i\omega \Delta t} = 1 - \Delta t \lambda_{3,\pm} + \frac{\Delta t^2}{2} \lambda_{3,\pm}^2 - \frac{\Delta t^3}{6} \lambda_{3,\pm}^3$$

$$i\omega \Delta t = \ln \left(1 - \Delta t \lambda_{3,\pm} + \frac{\Delta t^2}{2} \lambda_{3,\pm}^2 - \frac{\Delta t^3}{6} \lambda_{3,\pm}^3 \right)$$

$$\omega = \frac{1}{i\Delta t} \ln \left(1 - \Delta t \lambda_{3,\pm} + \frac{\Delta t^2}{2} \lambda_{3,\pm}^2 - \frac{\Delta t^3}{6} \lambda_{3,\pm}^3 \right)$$

Yes so its possible, now for the other methods. Where \mathbf{F}_3 is given by the following

1.4 Second Order

$$\begin{bmatrix} h \\ u \end{bmatrix}_j^{n+1} = (\mathbf{I} - \Delta t \mathbf{F}_1) \begin{bmatrix} h \\ u \end{bmatrix}_j^n$$

lets say we have

$$\mathbf{F}_1 = \mathbf{S}_1 \begin{bmatrix} \lambda_{1,-} & 0 \\ 0 & \lambda_{1,+} \end{bmatrix} \mathbf{S}_1^{-1}$$

$$\begin{bmatrix} h \\ u \end{bmatrix}_j^{n+1} = \left(\mathbf{I} - \Delta t \mathbf{S}_1 \begin{bmatrix} \lambda_{1,-} & 0 \\ 0 & \lambda_{1,+} \end{bmatrix} \mathbf{S}_1^{-1} \right) \begin{bmatrix} h \\ u \end{bmatrix}_j^n$$

$$\mathbf{S}_1^{-1} \begin{bmatrix} h \\ u \end{bmatrix}_j^{n+1} = \left(\mathbf{S}_1^{-1} - \Delta t \begin{bmatrix} \lambda_{1,-} & 0 \\ 0 & \lambda_{1,+} \end{bmatrix} \mathbf{S}_1^{-1} \right) \begin{bmatrix} h \\ u \end{bmatrix}_j^n$$

$$e^{i\omega\Delta t} \mathbf{S}_1^{-1} \begin{bmatrix} h \\ u \end{bmatrix}_j^n = \left(\mathbf{I} - \Delta t \begin{bmatrix} \lambda_{1,-} & 0 \\ 0 & \lambda_{1,+} \end{bmatrix} \right) \mathbf{S}_1^{-1} \begin{bmatrix} h \\ u \end{bmatrix}_j^n$$

$$e^{i\omega\Delta t} \mathbf{S}_1^{-1} \begin{bmatrix} h \\ u \end{bmatrix}_j^n = \begin{bmatrix} 1 - \Delta t \lambda_{1,-} & 0 \\ 0 & 1 - \Delta t \lambda_{1,+} \end{bmatrix} \mathbf{S}_1^{-1} \begin{bmatrix} h \\ u \end{bmatrix}_j^n$$

So we have

$$e^{i\omega\Delta t} = 1 - \Delta t \lambda_{1,-}$$

$$\omega = \frac{1}{i\Delta t} \ln(1 - \Delta t \lambda_{1,-})$$

1.5 Second Order

$$\begin{bmatrix} h \\ u \end{bmatrix}_j^1 = (\mathbf{I} - \Delta t \mathbf{F}) \begin{bmatrix} h \\ u \end{bmatrix}_j^n$$

$$\begin{bmatrix} h \\ u \end{bmatrix}_j^2 = (\mathbf{I} - \Delta t \mathbf{F}) \begin{bmatrix} h \\ u \end{bmatrix}_j^1$$

$$\begin{bmatrix} h \\ u \end{bmatrix}_j^{n+1} = \frac{1}{2} \left(\begin{bmatrix} h \\ u \end{bmatrix}_j^n + \begin{bmatrix} h \\ u \end{bmatrix}_j^2 \right)$$

$$\begin{aligned}
\begin{bmatrix} h \\ u \end{bmatrix}_j^{n+1} &= \frac{1}{2} \left(\begin{bmatrix} h \\ u \end{bmatrix}_j^n + (\mathbf{I} - \Delta t \mathbf{F})^2 \begin{bmatrix} h \\ u \end{bmatrix}_j^n \right) \\
&= \frac{1}{2} (\mathbf{I} + (\mathbf{I} - \Delta t \mathbf{F})^2) \begin{bmatrix} h \\ u \end{bmatrix}_j^n \\
&= \frac{1}{2} (\mathbf{I} + \mathbf{I} - 2\Delta t \mathbf{F} + \Delta t^2 \mathbf{F}^2) \begin{bmatrix} h \\ u \end{bmatrix}_j^n \\
&= \frac{1}{2} (2\mathbf{I} - 2\Delta t \mathbf{F} + \Delta t^2 \mathbf{F}^2) \begin{bmatrix} h \\ u \end{bmatrix}_j^n
\end{aligned}$$

lets say we have

$$\mathbf{F}_2 = \mathbf{S}_2 \begin{bmatrix} \lambda_{2,-} & 0 \\ 0 & \lambda_{2,+} \end{bmatrix} \mathbf{S}_2^{-1}$$

$$\begin{aligned}
\begin{bmatrix} h \\ u \end{bmatrix}_j^{n+1} &= \frac{1}{2} \left(2\mathbf{I} - 2\Delta t \mathbf{S}_2 \begin{bmatrix} \lambda_{2,-} & 0 \\ 0 & \lambda_{2,+} \end{bmatrix} \mathbf{S}_2^{-1} + \Delta t^2 \mathbf{S}_2 \begin{bmatrix} \lambda_{2,-}^2 & 0 \\ 0 & \lambda_{2,+}^2 \end{bmatrix} \mathbf{S}_2^{-1} \right) \begin{bmatrix} h \\ u \end{bmatrix}_j^n \\
\mathbf{S}_2^{-1} \begin{bmatrix} h \\ u \end{bmatrix}_j^{n+1} &= \frac{1}{2} \left(2\mathbf{S}_2^{-1} - 2\Delta t \begin{bmatrix} \lambda_{2,-} & 0 \\ 0 & \lambda_{2,+} \end{bmatrix} \mathbf{S}_2^{-1} + \Delta t^2 \begin{bmatrix} \lambda_{2,-}^2 & 0 \\ 0 & \lambda_{2,+}^2 \end{bmatrix} \mathbf{S}_2^{-1} \right) \begin{bmatrix} h \\ u \end{bmatrix}_j^n \\
\mathbf{S}_2^{-1} \begin{bmatrix} h \\ u \end{bmatrix}_j^{n+1} &= \frac{1}{2} \left(2\mathbf{S}_2^{-1} + \begin{bmatrix} \Delta t^2 \lambda_{2,-}^2 - 2\Delta t \lambda_{2,-} & 0 \\ 0 & \Delta t^2 \lambda_{2,+}^2 - 2\Delta t \lambda_{2,-} \end{bmatrix} \mathbf{S}_2^{-1} \right) \begin{bmatrix} h \\ u \end{bmatrix}_j^n \\
e^{i\omega \Delta t} \left(\mathbf{S}_2^{-1} \begin{bmatrix} h \\ u \end{bmatrix}_j^n \right) &= \frac{1}{2} \left(2 + \begin{bmatrix} \Delta t^2 \lambda_{2,-}^2 - 2\Delta t \lambda_{2,-} & 0 \\ 0 & \Delta t^2 \lambda_{2,+}^2 - 2\Delta t \lambda_{2,-} \end{bmatrix} \right) \left(\mathbf{S}_2^{-1} \begin{bmatrix} h \\ u \end{bmatrix}_j^n \right) \\
e^{i\omega \Delta t} \left(\mathbf{S}_2^{-1} \begin{bmatrix} h \\ u \end{bmatrix}_j^n \right) &= \frac{1}{2} \begin{bmatrix} 2 + \Delta t^2 \lambda_{2,-}^2 - 2\Delta t \lambda_{2,-} & 0 \\ 0 & 2 + \Delta t^2 \lambda_{2,+}^2 - 2\Delta t \lambda_{2,-} \end{bmatrix} \left(\mathbf{S}_2^{-1} \begin{bmatrix} h \\ u \end{bmatrix}_j^n \right)
\end{aligned}$$

So we have

$$\begin{aligned}
e^{i\omega \Delta t} &= 1 + \frac{1}{2} \Delta t^2 \lambda_{2,\pm}^2 - \Delta t \lambda_{2,\pm} \\
\omega &= \frac{1}{i\Delta t} \ln \left(1 + \frac{1}{2} \Delta t^2 \lambda_{2,\pm}^2 - \Delta t \lambda_{2,\pm} \right)
\end{aligned}$$