

E11.3 - Observability and controllability

A system is described by the matrix equations

$$\dot{\mathbf{x}} = \begin{bmatrix} 0 & 1 \\ 0 & -3 \end{bmatrix} \mathbf{x} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u$$

$$y = \begin{bmatrix} 0 & 2 \end{bmatrix} \mathbf{x} + [0] u.$$

Determine whether the system is controllable and observable.

For controllability: $P_c = \begin{bmatrix} B & A^1 B & A^2 B & \dots & A^{n-1} B \end{bmatrix}$ and $\det(P_c) \neq 0$

$$\begin{aligned} n=2 \quad : \quad P_c &= \begin{bmatrix} B & A^1 B \end{bmatrix} \quad \begin{matrix} 2 \times 2 & 2 \times 1 & \Rightarrow & 2 \times 1 \end{matrix} \\ &= \begin{bmatrix} 0 & 1 \\ 0 & -3 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} (0 \times 0) + (1 \times 1) & \\ (0 \times 0) + (-3 \times 1) & \end{bmatrix} = \begin{bmatrix} 1 & \\ & -3 \end{bmatrix} \end{aligned}$$

$$\therefore P_c = \begin{bmatrix} 0 & 1 \\ 1 & -3 \end{bmatrix}$$

$$\det \begin{bmatrix} 0 & 1 \\ 1 & -3 \end{bmatrix} = (0 \times -3) - (1 \times 1) = 0 - 1 = -1 \neq 0 \quad \therefore \text{controllable}$$

For observability: $\mathcal{P}_o = \begin{bmatrix} \mathcal{C} \\ \mathcal{C}A \\ \vdots \\ \mathcal{C}A^{n-1} \end{bmatrix}$ $\det(\mathcal{P}_o) \neq 0$

$$\begin{aligned} n=2: \quad \mathcal{C}A &= \begin{matrix} 1 \times 2 & 2 \times 2 & 2 \times 2 \end{matrix} \begin{bmatrix} 0 & 2 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & -3 \end{bmatrix} \\ &= \begin{bmatrix} (0 \times 0) + (2 \times 0) & (0 \times 1) + (2 \times -3) \end{bmatrix} \\ &= \begin{bmatrix} 0 & -6 \end{bmatrix} \end{aligned}$$

$$\mathcal{P}_o = \begin{bmatrix} 0 & 2 \\ 0 & -6 \end{bmatrix} \quad \det \mathcal{P}_o = (0 \times -6) - (2 \times 0) = 0$$

\therefore Not observable.

E11.5 - Observability and controllability

A system is described by the matrix equations

$$\dot{\mathbf{x}} = \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix} \mathbf{x} + \begin{bmatrix} 1 \\ -2 \end{bmatrix} u$$

$$y = \begin{bmatrix} 1 & 0 \end{bmatrix} \mathbf{x} + [0] u.$$

Determine whether the system is controllable and observable.

Test for controllability:

$$\begin{aligned} n=2 \quad \mathcal{P}_c &= \begin{bmatrix} \mathcal{B} & A\mathcal{B} \end{bmatrix} \\ &= \begin{bmatrix} 1 & -2 \\ -2 & 3 \end{bmatrix} \end{aligned}$$

$$\det \mathcal{P}_c = (1 \times 3) - (-2 \times -2)$$

$$= 3 - 4 = -1 \neq 0$$

\therefore controllable

$$\begin{aligned} A\mathcal{B} &= \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} 1 \\ -2 \end{bmatrix} = \begin{bmatrix} (0 \times 1) + (1 \times -2) \\ (-1 \times 1) + (-2 \times -2) \end{bmatrix} \\ &= \begin{bmatrix} -2 \\ +3 \end{bmatrix} \end{aligned}$$

Observability.

$$P_O = \begin{bmatrix} C \\ CA \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\det P_O = (1 \times 1) - (0 \times 0)$$

$$= 1 \neq 0$$

\therefore observable.

$$C \times A = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix}$$

$$= \begin{bmatrix} (1 \times 0) + (0 \times -1) & (1 \times 1) + (0 \times -2) \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 1 \end{bmatrix}$$