

Semester best BERI 418 Test 3 - Memo
16 May 2014

Question 1

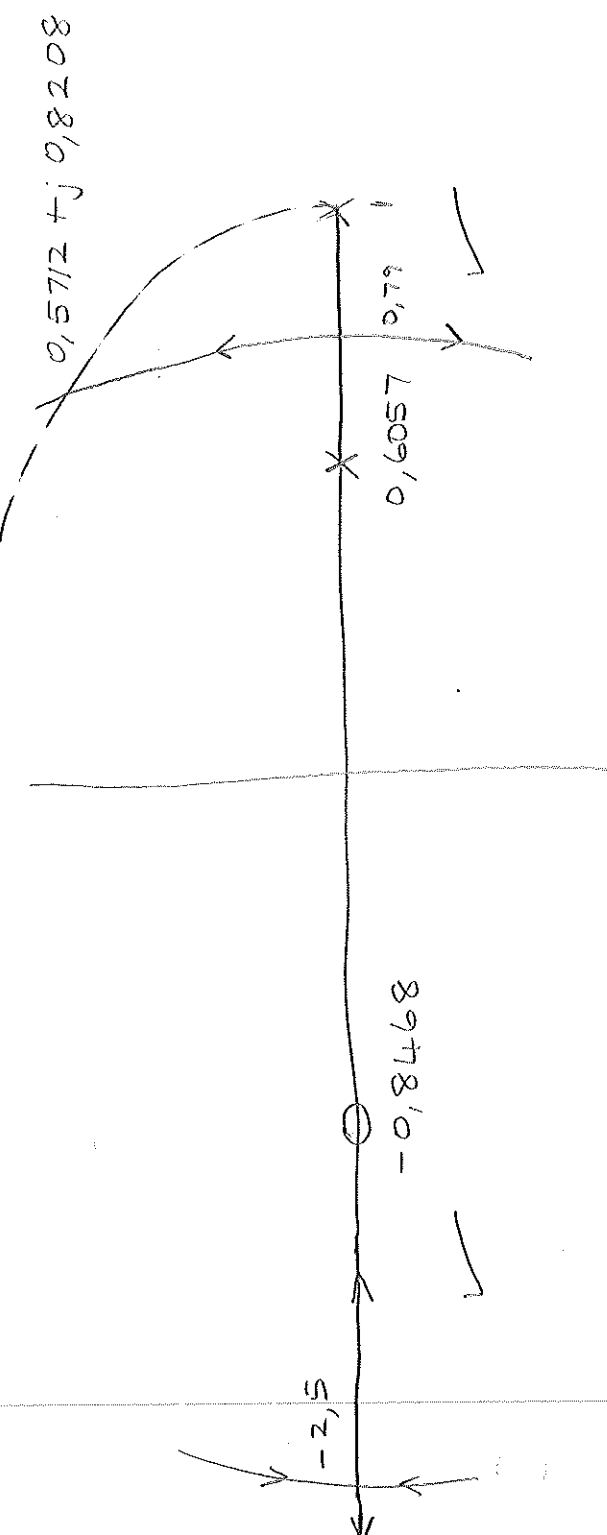
$$G_P(s) = \frac{10k}{s(s+4)}$$

$$G(z) = \frac{k(0,06658z + 0,05638)}{z^2 - 1,607z + 0,6065}$$

$$T = 0,125s$$

1.1 Wortellokus met $D(z) = 1$

$$G(z) = \frac{k \cdot 0,06658(z + 0,8468)}{(z - 1)(z - 0,6057)}$$



Breakaway point: $K = \frac{|z-1||z-0,6057|}{0,06658|(z+0,8468)|}$

K	0,3539	0,3544	0,3551	0,354
z	0,8029	0,8	0,79	0,78

K	807,67	314,84	168,9	121	101	100	109
z	-0,9	-1	-1,2	-1,5	-2	-3	-4

$$K = 98,9$$

$$z = -2,5$$

(2)

Jury stability analysis:

$$Q(z) = 1 + G(z) = 0$$

$$\therefore 1 + \frac{k \cdot 0,06658(z + 0,8468)}{(z-1)(z-0,6057)} = 0$$

$$(z-1)(z-0,6057) + k \cdot 0,06658(z + 0,8468) = 0$$

$$\therefore z^2 - 1,607z + 0,6065 + k \cdot 0,06658z + k \cdot 0,05638$$

$$= z^2 + (0,06658k - 1,607)z + 0,05638k + 0,6065$$

$$\checkmark$$

$$① Q(1) > 0$$

$$1 + (0,06658k - 1,607) + 0,05638k + 0,6065 > 0$$

$$\therefore 0,123k > 0 \quad \therefore k > 0 \quad \checkmark$$

$$② (-1)^2 Q(-1) > 0$$

$$1 - (0,06658k - 1,607) + 0,05638k + 0,6065 > 0$$

$$3,2135 - 0,0102k > 0$$

$$\therefore -0,0102k > -3,2135$$

$$\therefore k < 315,05 \quad \checkmark$$

$$③$$

$$|a_0| < a_2$$

$$|0,05638k + 0,6055| < 1$$

$$\therefore k < 6,9794 \quad \checkmark$$

$$\therefore 0 < k < 6,9794 \quad \checkmark$$

Steady is marginal stable for $k = 6,9794$

$$\therefore z^2 - 1,1423z + 1 = 0 \quad \therefore z = 0,5712 \pm j 0,8208$$

$$= 1 \pm 0,9628 \quad \checkmark$$

(10)

Design a phase lead compensator
 Retain critically damped poles and reduce the
 time constant of the system by a factor 2.

The critically damped poles are at $z = 0,79$
 resulting in a time constant of

$$\therefore z = e^{\frac{-T}{\tau}} = e^{\frac{-1}{\tau}} \quad \checkmark$$

$$\therefore \tau = \frac{-1}{\ln z} = \frac{-0,125}{\ln 0,79} = 0,53035. \quad \checkmark$$

\therefore To reduce the time constant by a factor 2

$$\tau_{\text{new}} = \frac{0,5303}{2} \text{ s} = 0,2652 \quad \checkmark$$

$$\therefore z = e^{\frac{-T}{\tau}} = e^{\frac{-0,125}{0,2652}} = 0,6242 \quad \checkmark$$

$$\text{Choose } z_0 = 0,6057. \quad \checkmark$$

If we estimate the breakaway point, to be
 more or less half way between the pole at
 $z=1$ and the compensator pole at z_p .

$$\frac{z_p + 1}{2} = 0,6242$$

$$\therefore z_p \approx 0,2484 \quad \checkmark$$

$$\therefore D(z) = \frac{K_d(z - 0,6057)}{(z - 0,2484)}$$

$$D(1) = 1 \quad \therefore K_d = 1,906 \quad \checkmark$$

\therefore Now only the value of K_c needs to be determined

$$\therefore 1 + D(z) \cdot G(z) = 0 \quad \text{with } z = 0,6242 \quad \checkmark$$

$$\therefore 1 + \frac{1,906(z - 0,6057)}{(z - 0,2484)} \cdot \frac{K_c 0,06658(z + 0,8468)}{(z - 1)(z - 0,6057)} = 0$$

$$\therefore K_c = 0,7565 \quad \checkmark$$

(10)

1.2. $k = 3$.

Phase lag design for PM of 40°

(a) Determine ω_{w1} where $\phi = -180^\circ + \phi_m + 50^\circ$
 $= -180^\circ + 40^\circ + 50^\circ$
 $= -135^\circ \quad \checkmark$

$\therefore \omega_{w1} \approx 2,8 \text{ rad/s.} \quad \checkmark$

$G(j\omega_{w1}) = -3 \text{ dB} + 9,5 \text{ dB} = 6,5 \text{ dB} = 2,1135 \quad \checkmark$

Choose $\omega_{w0} = 0,1 \omega_{w1} = 0,28 \text{ rad/s.} \quad \checkmark$

$\omega_{wp} = \frac{0,1 \cdot \omega_{w1}}{0,28 |G(j\omega_{w1})|} = \frac{0,28}{1 \cdot 2,1135} = 0,1325 \text{ rad/s} \quad \checkmark$

$\therefore D(w) = \frac{1 + \frac{w}{0,28}}{1 + \frac{w}{0,1325}} \quad \checkmark$

$\therefore K_d = \frac{0,1325 (0,28 + \frac{z}{0,125})}{0,28 (0,1325 + \frac{z}{0,125})} = 0,4775 \quad \checkmark$

$z_0 = \frac{z/T - \omega_{w0}}{z/T + \omega_{w0}} = \frac{z/0,125 - 0,28}{z/0,125 + 0,28} = 0,9656 \quad \checkmark$

$z_p = \frac{z/T - \omega_{wp}}{z/T + \omega_{wp}} = \frac{z/0,125 - 0,1325}{z/0,125 + 0,1325} = 0,9836 \quad \checkmark$

$\therefore O(z) = \frac{0,4775 (z - 0,9656)}{(z - 0,9836)} \quad \checkmark$

(10)

[30]