

Table 1. Properties of the z transform

Sequence	Transform
$e(k)$	$E(z) = \sum_{k=0}^{\infty} e(k)z^{-k}$
$a_1 e_1(k) + a_2 e_2(k)$	$a_1 E_1(z) + a_2 E_2(z)$
$e(k-n)u(k-n); \quad n \geq 0$	$z^{-n} E(z)$
$e(k+n)u(k); \quad n \geq 1$	$z^n \left[E(z) - \sum_{k=0}^{n-1} e(k)z^{-k} \right]$
$\epsilon^{ak} e(k)$	$E(z\epsilon^{-a})$
$ke(k)$	$-z \frac{dE(z)}{dz}$
$e_1(k) * e_2(k)$	$E_1(z)E_2(z)$
$e_1(k) = \sum_{n=0}^k e(n)$	$E_1(z) = \frac{z}{z-1} E(z)$
Initial value: $e(0) = \lim_{z \rightarrow \infty} E(z)$	
Final value: $e(\infty) = \lim_{z \rightarrow 1} (z-1)E(z)$, if $e(\infty)$ exists	

Table 2. z-transforms

Sequence	z-Transform
$\delta(k-n)$	z^{-n}
1	$\frac{z}{z-1}$
k	$\frac{z}{(z-1)^2}$
k^2	$\frac{z(z+1)}{(z-1)^3}$
a^k	$\frac{z}{z-a}$
ka^k	$\frac{az}{(z-a)^2}$
$\sin ak$	$\frac{z \sin a}{z^2 - 2z \cos a + 1}$
$\cos ak$	$\frac{z(z - \cos a)}{z^2 - 2z \cos a + 1}$
$a^k \sin bk$	$\frac{az \sin b}{z^2 - 2az \cos b + a^2}$
$a^k \cos bk$	$\frac{z^2 - az \cos b}{z^2 - 2az \cos b + a^2}$

Table 3. z-transforms

Laplace transform $E(s)$	Time function $e(t)$	z-Transform $E(z)$	Modified z-transform $E(z, m)$
$\frac{1}{s}$	$u(t)$	$\frac{z}{z-1}$	$\frac{1}{z-1}$
$\frac{1}{s^2}$	t	$\frac{Tz}{(z-1)^2}$	$\frac{mT}{z-1} + \frac{T}{(z-1)^2}$
$\frac{1}{s^3}$	$\frac{t^2}{2}$	$\frac{T^2 z(z+1)}{2(z-1)^3}$	$\frac{T^2}{2} \left[\frac{m^2}{z-1} + \frac{2m+1}{(z-1)^2} + \frac{2}{(z-1)^3} \right]$
$\frac{(k-1)!}{s^k}$	t^{k-1}	$\lim_{a \rightarrow 0} (-1)^{k-1} \frac{\partial^{k-1}}{\partial a^{k-1}} \left[\frac{z}{z - \epsilon^{-aT}} \right]$	$\lim_{a \rightarrow 0} (-1)^{k-1} \frac{\partial^{k-1}}{\partial a^{k-1}} \left[\frac{\epsilon^{-amT}}{z - \epsilon^{-aT}} \right]$
$\frac{1}{s+a}$	ϵ^{-at}	$\frac{z}{z - \epsilon^{-aT}}$	$\frac{\epsilon^{-amT}}{z - \epsilon^{-aT}}$
$\frac{1}{(s+a)^2}$	$t\epsilon^{-at}$	$\frac{Tz\epsilon^{-aT}}{(z - \epsilon^{-aT})^2}$	$\frac{T\epsilon^{-amT}[\epsilon^{-aT} + m(z - \epsilon^{-aT})]}{(z - \epsilon^{-aT})^2}$
$\frac{(k-1)!}{(s+a)^k}$	$t^k \epsilon^{-at}$	$(-1)^k \frac{\partial^k}{\partial a^k} \left[\frac{z}{z - \epsilon^{-aT}} \right]$	$(-1)^k \frac{\partial^k}{\partial a^k} \left[\frac{\epsilon^{-amT}}{z - \epsilon^{-aT}} \right]$
$\frac{a}{s(s+a)}$	$1 - \epsilon^{-at}$	$\frac{z(1 - \epsilon^{-aT})}{(z-1)(z - \epsilon^{-aT})}$	$\frac{1}{z-1} - \frac{\epsilon^{-amT}}{z - \epsilon^{-aT}}$
$\frac{a}{s^2(s+a)}$	$t - \frac{1 - \epsilon^{-at}}{a}$	$\frac{z[(aT - 1 + \epsilon^{-aT})z + (1 - \epsilon^{-aT} - aT\epsilon^{-aT})]}{a(z-1)^2(z - \epsilon^{-aT})}$	$\frac{T}{(z-1)^2} + \frac{amT-1}{a(z-1)} + \frac{\epsilon^{-amT}}{a(z - \epsilon^{-aT})}$
$\frac{a^2}{s(s+a)^2}$	$1 - (1+at)\epsilon^{-at}$	$\frac{z}{z-1} - \frac{z}{z - \epsilon^{-aT}} - \frac{aT\epsilon^{-aT}z}{(z - \epsilon^{-aT})^2}$	$\frac{1}{z-1} - \left[\frac{1+amT}{z - \epsilon^{-aT}} + \frac{aT\epsilon^{-aT}}{(z - \epsilon^{-aT})^2} \right] \epsilon^{-amT}$
$\frac{b-a}{(s+a)(s+b)}$	$\epsilon^{-at} - \epsilon^{-bt}$	$\frac{(e^{-aT} - \epsilon^{-bT})z}{(z - \epsilon^{-aT})(z - \epsilon^{-bT})}$	$\frac{\epsilon^{-amT}}{z - \epsilon^{-aT}} - \frac{\epsilon^{-bmT}}{z - \epsilon^{-bT}}$
$\frac{a}{s^2 + a^2}$	$\sin(at)$	$\frac{z \sin(aT)}{z^2 - 2z \cos(aT) + 1}$	$\frac{z \sin(amT) + \sin(1-m)aT}{z^2 - 2z \cos(aT) + 1}$
$\frac{s}{s^2 + a^2}$	$\cos(at)$	$\frac{z(z - \cos(aT))}{z^2 - 2z \cos(aT) + 1}$	$\frac{z \cos(amT) - \cos(1-m)aT}{z^2 - 2z \cos(aT) + 1}$
$\frac{1}{(s+a)^2 + b^2}$	$\frac{1}{b} \epsilon^{-at} \sin bt$	$\frac{1}{b} \left[\frac{z\epsilon^{-aT} \sin bT}{z^2 - 2z\epsilon^{-aT} \cos(bT) + \epsilon^{-2aT}} \right]$	$\frac{1}{b} \left[\frac{\epsilon^{-amT}[z \sin bmT + \epsilon^{-aT} \sin(1-m)bT]}{z^2 - 2z\epsilon^{-aT} \cos bT + \epsilon^{-2aT}} \right]$
$\frac{s+a}{(s+a)^2 + b^2}$	$\epsilon^{-at} \cos bt$	$\frac{z^2 - z\epsilon^{-aT} \cos bT}{z^2 - 2z\epsilon^{-aT} \cos bT + \epsilon^{-2aT}}$	$\frac{\epsilon^{-amT}[z \cos bmT + \epsilon^{-aT} \sin(1-m)bT]}{z^2 - 2z\epsilon^{-aT} \cos bT + \epsilon^{-2aT}}$
$\frac{a^2 + b^2}{s[(s+a)^2 + b^2]}$	$1 - \epsilon^{-at} \left(\cos bt + \frac{a}{b} \sin bt \right)$	$\frac{z(Az + B)}{(z-1)(z^2 - 2z\epsilon^{-aT} \cos bT + \epsilon^{-2aT})}$ $A = 1 - \epsilon^{-aT} \left(\cos bT + \frac{a}{b} \sin bT \right)$ $B = \epsilon^{-2aT} + \epsilon^{-aT} \left(\frac{a}{b} \sin bT - \cos bT \right)$	$\frac{1}{z-1}$ $-\frac{\epsilon^{-amT}[z \cos bmT + \epsilon^{-aT} \sin(1-m)bT]}{z^2 - 2z\epsilon^{-aT} \cos bT + \epsilon^{-2aT}}$ $+\frac{a}{b} \{ \epsilon^{-amT}[z \sin bmT - \epsilon^{-aT} \sin(1-m)bT] \}$ $\frac{z^2 - 2z\epsilon^{-aT} \cos bT + \epsilon^{-2aT}}$
$\frac{1}{s(s+a)(s+b)}$	$\frac{1}{ab} + \frac{\epsilon^{-at}}{a(a-b)} + \frac{\epsilon^{-bt}}{b(b-a)}$	$\frac{(Az + B)z}{(z - \epsilon^{-aT})(z - \epsilon^{-bT})(z-1)}$	$A = \frac{b(1 - \epsilon^{-aT}) - a(1 - \epsilon^{-bT})}{ab(b-a)}$ $B = \frac{a\epsilon^{-aT}(1 - \epsilon^{-bT}) - b\epsilon^{-bT}(1 - \epsilon^{-aT})}{ab(b-a)}$

Table 4. Laplace transform properties

Name	Theorem
Derivative	$\mathcal{L}\left[\frac{df}{dt}\right] = sF(s) - f(0^+)$
n th-order derivative	$\mathcal{L}\left[\frac{d^n f}{dt^n}\right] = s^n F(s) - s^{n-1} f(0^+) - \dots - f^{(n-1)}(0^+)$
Integral	$\mathcal{L}\left[\int_0^t f(\tau) d\tau\right] = \frac{F(s)}{s}$
Shifting	$\mathcal{L}[f(t - t_0)u(t - t_0)] = e^{-t_0 s} F(s)$
Initial value	$\lim_{t \rightarrow 0^+} f(t) = \lim_{s \rightarrow \infty} sF(s)$
Final value	$\lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} sF(s)$
Frequency shift	$\mathcal{L}[e^{-at} f(t)] = F(s + a)$
Convolution integral	$\mathcal{L}^{-1}[F_1(s)F_2(s)] = \int_0^t f_1(t - \tau)f_2(\tau) d\tau$ $= \int_0^t f_1(\tau)f_2(t - \tau) d\tau$

Table 5 Optimum coefficients of T(s) Based on the ITAE Criterion for a Step Input

$$\begin{aligned}
 & s + \omega_n \\
 & s^2 + 1.4\omega_n s + \omega_n^2 \\
 & s^3 + 1.75\omega_n s^2 + 2.15\omega_n^2 s + \omega_n^3 \\
 & s^4 + 2.1\omega_n s^3 + 3.4\omega_n^2 s^2 + 2.7\omega_n^3 s + \omega_n^4 \\
 & s^5 + 2.8\omega_n s^4 + 5.0\omega_n^2 s^3 + 5.5\omega_n^3 s^2 + 3.4\omega_n^4 s + \omega_n^5 \\
 & s^6 + 3.25\omega_n s^5 + 6.60\omega_n^2 s^4 + 8.60\omega_n^3 s^3 + 7.45\omega_n^4 s^2 + 3.95\omega_n^5 s + \omega_n^6
 \end{aligned}$$