



Introduction to metamodels & Polynomial chaos expansions

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Outline

Metamodels

- Definition, construction and validation

- Use for sensitivity analysis

Polynomial chaos expansion

Applications in non-destructive testing

Conclusions

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Metamodels

- Definition, construction and validation

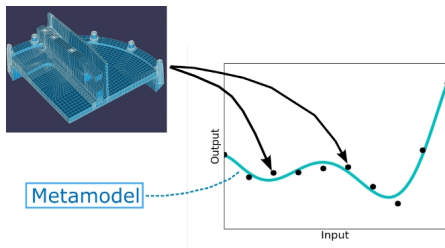
- Use for sensitivity analysis

Polynomial chaos expansion

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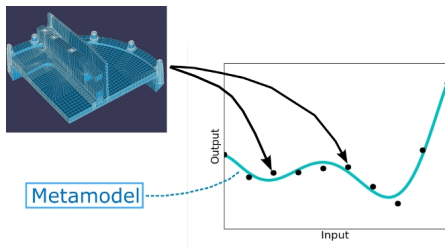
Metamodel - Definition



Meta : a prefix added to the name of something that consciously references or comments upon its own subject or features, e.g. metamodel : a model of another model

A metamodel is an approximation model that mimics the behaviour of a computationally expensive simulator by training on *observations (data)* of the latter.

Metamodel - Definition



Expensive simulator: $\mathbf{Y} = f(\mathbf{X})$

- ▶ \mathbf{X} , \mathbf{Y} are vectors of input and output,
- ▶ $\mathbf{X} = (X_1, \dots, X_M)$

Metamodel: $\tilde{\mathbf{Y}} = \hat{f}(\mathbf{X}, \boldsymbol{\theta})$, $\boldsymbol{\theta}$ being its vector of parameters

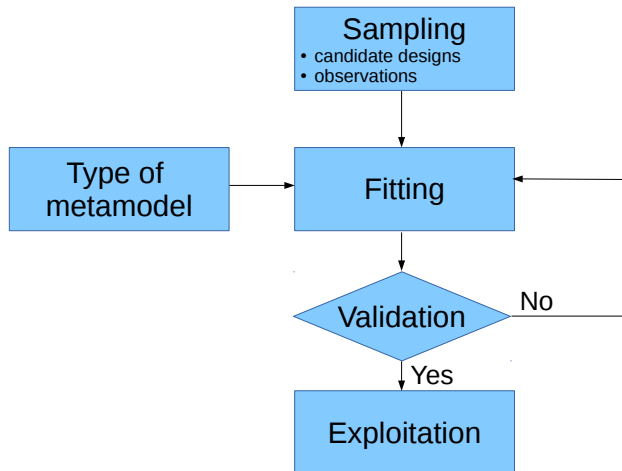
By definition, two requirements of a metamodel \hat{f} are:

- ▶ Usefully accurate when predicting away from known observation
- ▶ Being significantly cheaper to evaluate than the primary simulator

Metamodel - Objectives

- ▶ Show functional relationships between input parameters and the output quantity of interest: impacts of variables
- ▶ Augment results from single, expensive simulations: results can be predicted without use of the primary simulator; a continuous predictive function instead of discrete observations
- ▶ Optimize the output quantity of interest: determine configurations that maximize the response or achieve specifications or customer requirements
- ▶ Replace the primary simulator in uncertainty propagation (surrogate model): sensitivity analysis

Major steps for constructing a metamodel



Major steps for constructing a metamodel

Sampling (define an experimental design):

- ▶ A number of possible candidate designs are generated
- ▶ The designs are launched with the primary simulator

Constructing the metamodel:

- ▶ A type of metamodel is selected (among several available options)
- ▶ The metamodel is fitted to the available data
- ▶ The metamodel is validated (yes or no)
 - ▶ if yes: stop
 - ▶ if no, several solutions to be considered
 - ▶ change method for fitting: use advanced regression technique instead of least squares errors,
 - ▶ change metamodel parameters: increase polynomial degrees,
 - ▶ enrich the experimental design where the model is inaccurate or interesting behaviour is observed,
 - ▶ change the type of metamodel: polynomial chaos instead of second-order response surface

Some types of metamodels

Polynomial models: (response surface)

Second-order model

$$\tilde{Y} = \theta_0 + \sum_{i=0}^M \theta_i X_i + \sum_{i=0}^M \theta_{ii} X_i^2 + \sum_{i < j} \sum_{j=2}^M \theta_{ij} X_i X_j$$

Polynomial chaos expansion:

$$\tilde{Y} = \sum_{0 \leq |\mathbf{k}| \leq p} \theta_{\mathbf{k}} \psi_{\mathbf{k}}(\mathbf{X})$$

where $\psi_{\mathbf{k}}()$ being polynomial chaos functions

Radial basis function:

$$\tilde{Y} = \sum_{k=1}^N \theta_k \psi(\|\mathbf{X} - \mathbf{X}_k\|)$$

where $\psi()$ being a radial basis function with its centers taken at \mathbf{X}_k ,
 $k = 1, \dots, N$ in the experimental design

Some types of metamodels

Kriging: (Gaussian process regression)

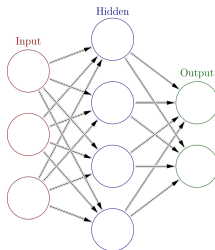
Deterministic trend: linear regression on a fixed basis

$$m(\mathbf{X}) = \mathbf{r}(\mathbf{X})^T \boldsymbol{\theta}$$

Random fluctuation: zero-mean stationary Gaussian process of covariance function

$$k(\mathbf{X}, \mathbf{X}') = \sigma^2 \rho(\|\mathbf{X} - \mathbf{X}'\|)$$

Artificial neural network: Radial basis function is a single layer neural network with radial coordinate neurons



Methods for fitting metamodels

Least square regression: minimize sum of squared errors of a linear regression model

$$\theta^* = \arg \min_{\theta} \sum_{i=1}^N \epsilon_i^2 = \arg \min_{\theta} \sum_{i=1}^N (Y_i - \hat{f}(\mathbf{X}_i, \theta))^2$$

Regularized regression methods: minimize sum of squared errors under a constraint

$$\theta^* = \arg \min_{\theta} \sum_{i=1}^N (Y_i - \hat{f}(\mathbf{X}_i, \theta))^2 + \lambda R(\theta)$$

- ▶ $R(\theta) = \|\theta\|_2$: Ridge regression,
- ▶ $R(\theta) = \|\theta\|_1$: LASSO regression,
- ▶ λ : non-negative regularization coefficient

Methods for fitting metamodels

Maximum likelihood estimation: e.g. assume that the errors ϵ are independently randomly distributed according to a normal distribution with standard deviation σ

$$\mathcal{L} = \frac{1}{(2\pi\sigma^2)^{N/2}} \prod_{i=1}^N \exp\left(-\frac{1}{2} \left(\frac{Y_i - \hat{f}(\mathbf{X}_i, \theta)}{\sigma}\right)^2\right)$$

$$\theta^* = \arg \max_{\theta} \mathcal{L}$$

K-fold cross-validation method:

$\mathcal{K} : \{1, \dots, N\} \mapsto \{1, \dots, K\}$ partition of N observations to K roughly equal-sized parts, $K = N$: leave-one-out

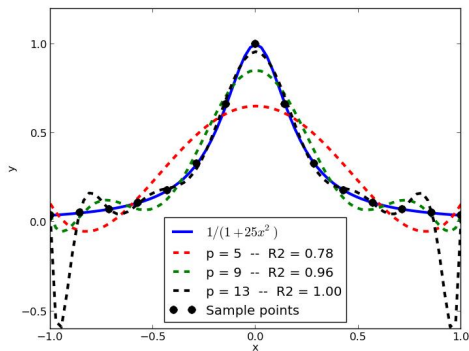
$\hat{f}^{-k}()$: fitted metamodel with k -th part of data set aside

Cross-validation estimate of prediction error:

$$CV(\hat{f}, \theta) = \frac{1}{N} \sum_{i=1}^N L(Y_i, \hat{f}^{-\mathcal{K}(i)}(\mathbf{X}_i))$$

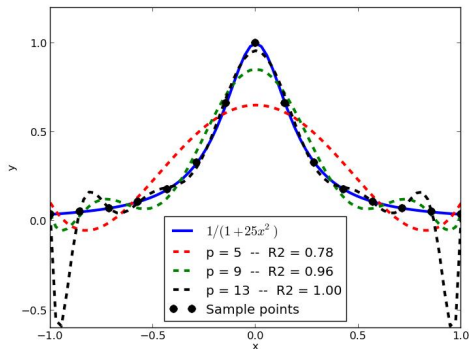
$$\theta^* = \arg \min_{\theta} CV(\hat{f}, \theta)$$

Overfitting



A metamodel that fits closely or exactly a specific set of data (training set) but fails to *predict* future data reliably

Validation of metamodels

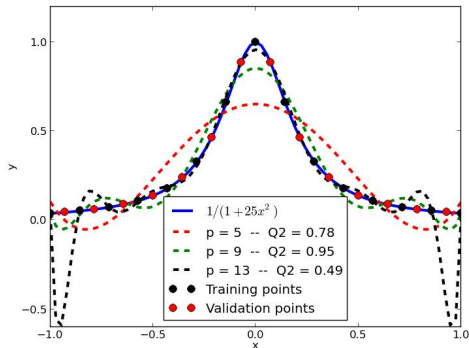


Coefficient of determination R^2

$$R^2 = 1 - Err \quad , \quad Err \propto \sum_{i=1}^N \left(f(\xi^{(i)}) - \tilde{f}_a(\xi^{(i)}) \right)^2$$

R^2 does not detect over-fitting and overestimates *predictive* performance

Validation of metamodels



Equivalent of R^2 on an independent validation set:

$$Q^2 = 1 - Err \quad , \quad Err \propto \sum_{i=1}^{N_{val}} \left(f(\xi^{(i)}) - \hat{f}_a(\xi^{(i)}) \right)^2$$

Validation on an independent validation set is necessary

Validation of metamodels

Cross-validation consists in dividing the data sample into two sub-samples.

- ▶ A metamodel is built with the first sub-sample (training set)
- ▶ Its performance is assessed by comparing its predictions with the second sub-sample (test set)

Data are often scarce. Partition in training and validation set is a luxury.

K -fold cross-validation: the data sample is divided into K sub-samples of roughly equal size.

$K = N$: leave-one-out error

Variance-based sensitivity analysis

Consider the model $Y = f(\mathbf{X})$ with random inputs $\mathbf{X} = \{X_1, \dots, X_M\}$

- ▶ The output dispersion is characterized by its variance $\mathbb{V}\text{ar}[Y]$
- ▶ Partial variance due to X_i :

$$\mathbb{V}\text{ar}_{X_i} [\mathbb{E}_{\mathbf{X} \sim X_i} [Y|X_i]]$$

$\mathbf{X} \sim X_i$: set of all variables except X_i

- ▶ Sobol index, interpretable as a variance percentage:

$$S_i = \frac{\mathbb{V}\text{ar}_{X_i} [\mathbb{E}_{\mathbf{X} \sim X_i} [Y|X_i]]}{\mathbb{V}\text{ar}[Y]}$$

- ▶ Sobol indices to interactions can also be defined:

$$S_{ij} = \frac{\mathbb{V}\text{ar}_{X_{ij}} [\mathbb{E}_{\mathbf{X} \sim X_{ij}} [Y|X_{ij}]]}{\mathbb{V}\text{ar}[Y]}$$

PROBLEM: Estimating the partial variances may require many (costly) model evaluations

Solution: Use an analytic approximation of the model – **Metamodel**

Outline

Metamodels

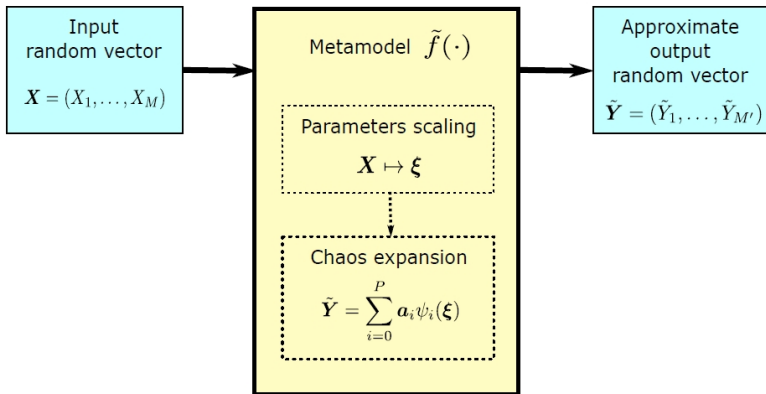
Polynomial chaos expansion

Applications in non-destructive testing

Conclusions

Polynomial chaos expansion

Let us consider the model : $\mathbf{Y} = f(\mathbf{X})$, \mathbf{X}, \mathbf{Y} are random vectors



Decomposition of \mathbf{Y} onto an orthonormal polynomial basis

Polynomial chaos basis

Assumption: Independent input random variables X_1, \dots, X_M

Componentwise transform: $\xi_i = \mathcal{T}_i(X_i)$ (often based on CDFs, i.e.

$$\mathcal{T}_i(\cdot) \equiv \mathcal{F}_{\xi_i}^{-1}(\mathcal{F}_{X_i}(\cdot)))$$

- Several possible choices for each (ξ_i, \mathcal{T}_i)
- A given ξ_i dictates the choice of a family $(\pi_k^{(i)})_{k \geq 0}$ of orthonormal polynomials

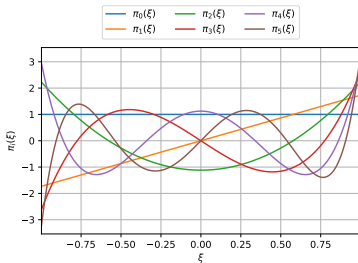
Given a uniform random variable $X \sim \mathcal{U}([0, 10])$, the transform $\xi = X/5 - 1$ leads to $\xi \sim \mathcal{U}([-1, 1])$ for which Legendre polynomials are used:

$$\pi_0(\xi) = 1 \quad , \quad \pi_1(\xi) = \sqrt{3}\xi \quad , \quad \pi_2(\xi) = \frac{\sqrt{5}}{2}(3\xi^2 - 1) \quad , \quad \dots$$

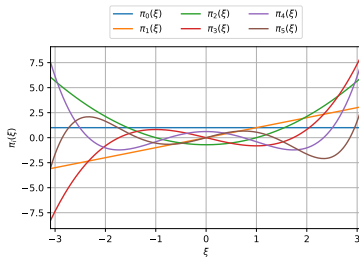
Given a normal random variable $X \sim \mathcal{N}(5, 1)$, the transform $\xi = X - 5$ leads to a standard normal RV $\xi \sim \mathcal{N}(0, 1)$ and Hermite polynomials:

$$\pi_0(\xi) = 1 \quad , \quad \pi_1(\xi) = \xi \quad , \quad \pi_2(\xi) = \frac{\sqrt{2}}{2}(\xi^2 - 1) \quad , \quad \dots$$

Polynomial chaos basis



Legendre polynomials



Hermite polynomials

Properties: $\pi_0^{(i)} = 1$, $\mathbb{E}[\pi_k^{(i)}(\xi_i)] \equiv \int_{\mathcal{D}_\xi} \pi_k^{(i)}(u) f_{\xi_i}(u) du = 0 \quad \forall k \geq 1$

$\mathbb{E}[\pi_k^{(i)}(\xi_i) \pi_l^{(i)}(\xi_i)] \equiv \int_{\mathcal{D}_\xi} \pi_k^{(i)}(u) \pi_l^{(i)}(u) f_{\xi_i}(u) du = 1 \quad \text{if } k = l \quad \text{else } 0$

Relevant for analytical estimation of first-order moments and Sobol' sensitivity indices

Polynomial chaos basis

Multivariate orthonormal polynomials:

$$\psi_{\mathbf{k}}(\xi) = \pi_{k_1}^{(1)}(\xi_1) \times \cdots \times \pi_{k_M}^{(M)}(\xi_M)$$

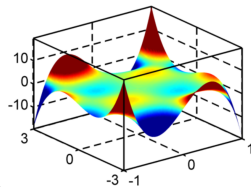
$\xi = (\xi_1, \dots, \xi_M)$: input vector; $\mathbf{k} = (k_1, \dots, k_M)$: indices vector

Bivariate Legendre-Hermite polynomials:

$$\psi_{0,0}(\xi_1, \xi_2) = \pi_0^{(1)}(\xi_1) \times \pi_0^{(2)}(\xi_2) = 1$$

$$\psi_{1,0}(\xi_1, \xi_2) = \pi_1^{(1)}(\xi_1) \times \pi_0^{(2)}(\xi_2) = \sqrt{3}\xi_1$$

$$\psi_{1,2}(\xi_1, \xi_2) = \pi_1^{(1)}(\xi_1) \times \pi_2^{(2)}(\xi_2) = \frac{\sqrt{6}}{2}\xi_1(\xi_2^2 - 1)$$

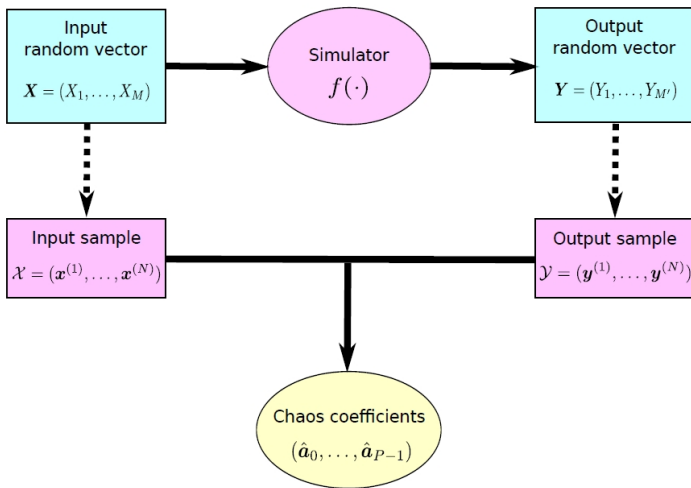


$\psi_{3,3}(\xi_1, \xi_2)$

Polynomial chaos expansion:

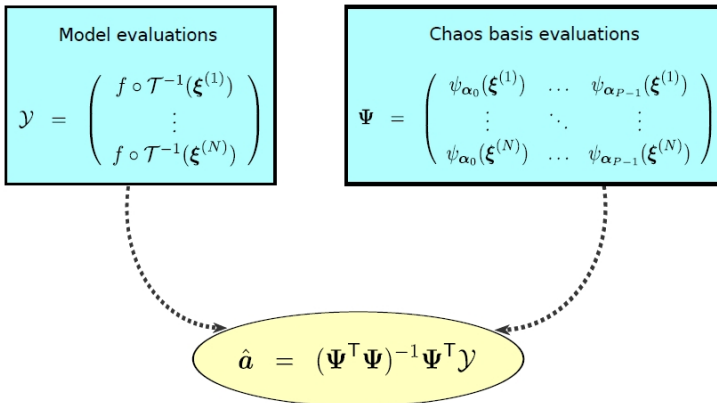
$$\tilde{\mathbf{Y}} = \sum_{0 \leq |\mathbf{k}| \leq p} a_{\mathbf{k}} \psi_{\mathbf{k}}(\xi) = \sum_{0 \leq |\mathbf{k}| \leq p} a_{\mathbf{k}} \pi_{k_1}^{(1)}(\xi_1) \times \cdots \times \pi_{k_M}^{(M)}(\xi_M)$$

Estimation of polynomial chaos coefficients



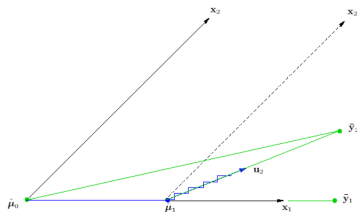
Caution: the input sample \mathcal{X} must respect the PDF of \mathbf{X}

Least squares



Well-posed problem if $N > P$

Least angle regression



Least angle regression

In each iteration:

- Find the vector ψ_{α_j} which is as correlated with the current residual as active vectors
- Move jointly coefficients until another vector is equi-correlated with the current residual

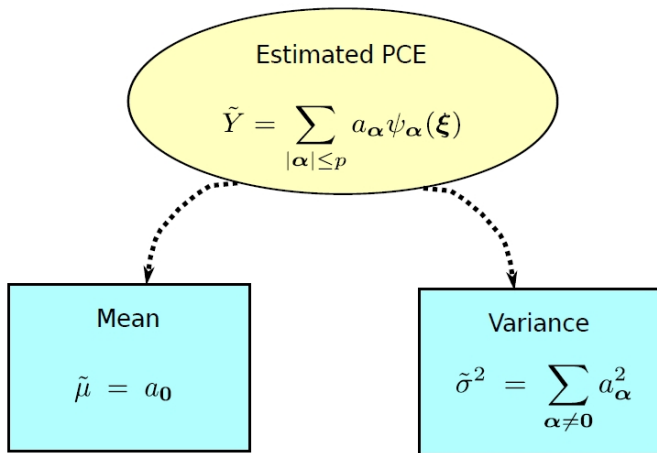
Error indicator

- ▶ Q^2 cross-validation on independent test data set
- ▶ Due to its linear-regression form, leave-one-out error for polynomial chaos expansions can be obtained without calculating N metamodels:

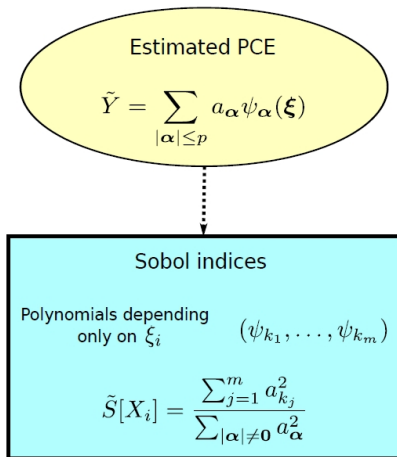
$$Err_{L00} = \frac{1}{N} \sum_{i=1}^N \left(\frac{f(\xi^{(i)}) - \hat{f}_a(\xi^{(i)})}{1 - h_i} \right)^2$$

where \hat{f}_a is the metamodel computed on the entire data set, h_i is i -th diagonal term of the matrix $\Psi (\Psi^T \Psi)^{-1} \Psi^T$

Post-processing: closed-form mean and variance



Post-processing: closed-form Sobol indices



Interaction indices can also be derived!

Outline

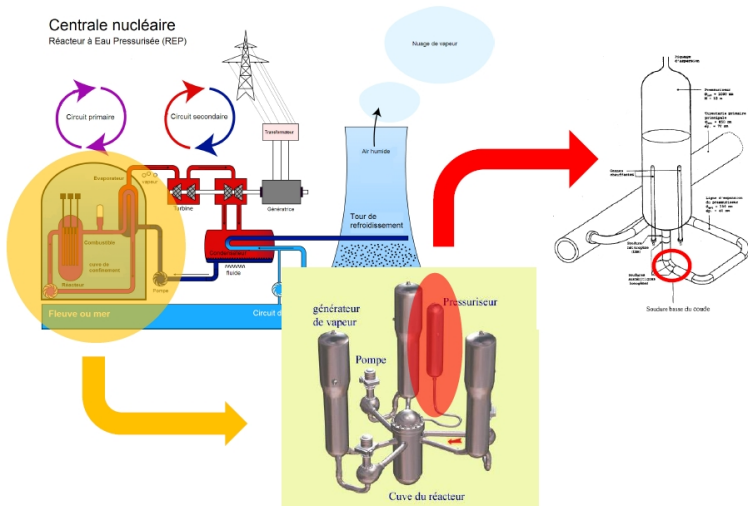
Metamodels

Polynomial chaos expansion

Applications in non-destructive testing

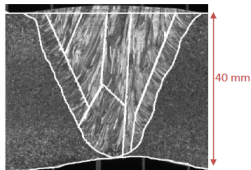
Conclusions

Primary circuit - Bent tube weld



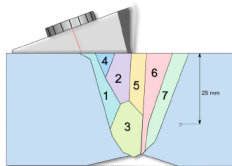
Inspection configuration and modelling

Weld description with
7 homogeneous domains



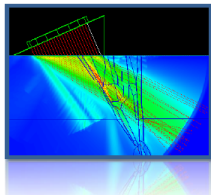
Chassignole et al. , QNDE, 1999 &
Chassignole et al., Ultrasonics, 2009

Inspection configuration



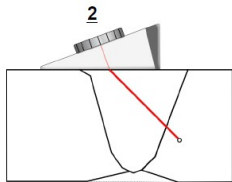
- L 45° waves
- Detection of a sided drilled hole after passing through the weld

Finite element model
(Athena 2D code)

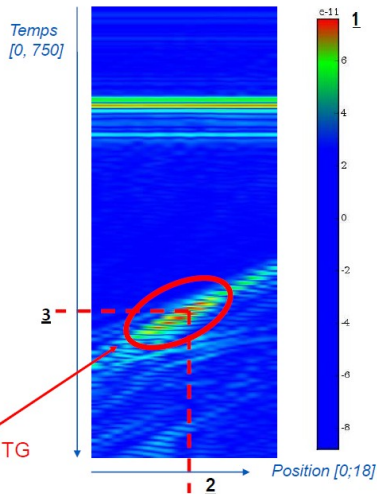


Quantities of interest : inspection results

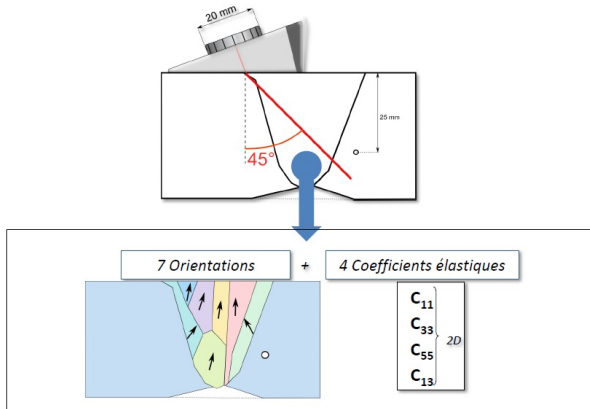
- Amplitude de l'écho max **(1)**
- La position du capteur au max **(2)**
- Le temps de vol du max **(3)**



Écho provenant du TG



Uncertain input data

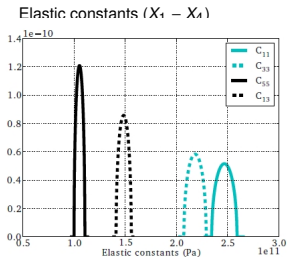
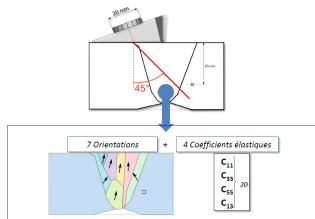


Problem : What is the sensitivity of the NDT output to each input parameter?

Strategy: Evaluate the Sobol sensitivity indices

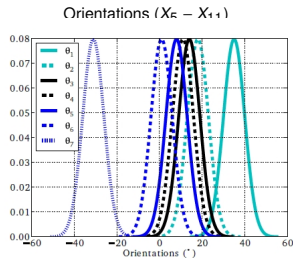
Specification of the input PDFs and chaos basis

Input variables: X_1, \dots, X_8
(independent)



Beta PDFs

$\xi_i \sim \mathcal{U}(-1, 1) \rightarrow$ Legendre poly.

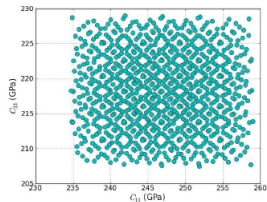


Normal PDFs

$\xi_i \sim \mathcal{N}(0, 1) \rightarrow$ Hermite poly.

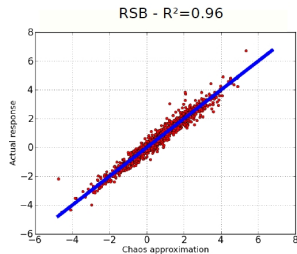
Construction of the polynomial chaos

- ▶ Design of experiments: quasi-random sample of size $N = 2000$

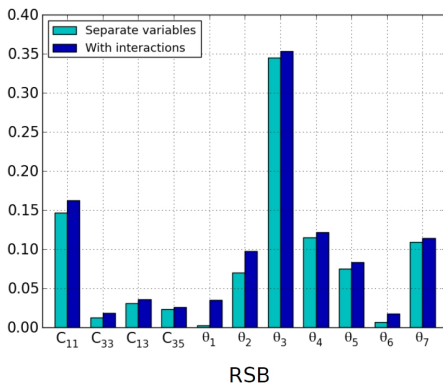
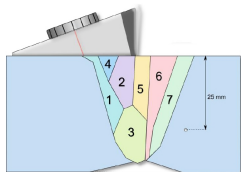


- ▶ Distributed calls to the FE model (cluster)

- ▶ Fit of chaos proxies with varying degree (70% of the sample points)
→ optimal degree $p = 3$
- ▶ Validation with the 30% remaining points



Sensitivity analysis – Signal-to-noise ratio



Almost no interaction effect (additive structure)

Variability mostly due to the orientations (plus C_{11})

θ_3 plays a major role here → Check a finer weld description

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Conclusions

Metamodels & Polynomial chaos

- ▶ For a given problem, ideally test several types of metamodels
- ▶ Polynomial chaos expansion and Kriging are in OpenTurns
- ▶ It is worth assessing carefully the metamodel quality prior to going further

Thank you

