

OTBENCHMARK: AN OPEN SOURCE PYTHON PACKAGE FOR BENCHMARKING AND VALIDATING UNCERTAINTY QUANTIFICATION ALGORITHMS

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Introduction

Industrial context

- In France, the EDF group operates
 - ▷ 56 nuclear power plants
 - ▷ 433 hydraulic power plants
 - ▷ thousands of wind turbines
 - ▷ thousands of photo-voltaic panels
- Industrial risk management through the treatment of uncertainties
- Over the past years, a panel of industrials, public research centers and academics:
 - ▷ jointly proposed a generic methodology for uncertainty management
 - ▷ developed OpenTURNS, a tool for the treatment of uncertainties [1]
- Need for a benchmark platform for uncertainty quantification

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OpenTURNS

An Open source initiative for the Treatment of Uncertainties, Risks'N Statistics

Plan

Motivations and objectives

Package architecture

Reliability example

Benchmark results

Conclusion

Motivations and objectives

Uncertainty propagation: problem definition

- Uncertain input random vector $\mathbf{X} \in \mathbb{R}^d$
- Model $g : \mathbb{R}^d \rightarrow \mathbb{R}^p$

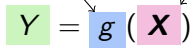
The equation $Y = g(X)$ is displayed with Y in a green box, g in a blue box, and X in a pink box. A curved arrow points from the text ' $\mathbf{X} \in \mathbb{R}^d$ ' in the list above to the pink box containing X .

$$Y = g(X)$$

- Output random variable $Y \in \mathbb{R}^p$

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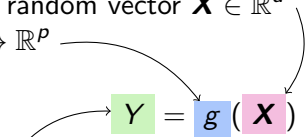
The diagram illustrates the uncertainty propagation problem. It shows a green square labeled Y on the left, followed by an equals sign, then a blue square labeled g , and finally a pink square labeled X enclosed in parentheses. Two curved arrows originate from the text above: one from the model g points to the blue square, and another from the input vector X points to the pink square.

$$Y = g(\mathbf{X})$$

- Output random variable $Y \in \mathbb{R}^p$

Uncertainty propagation: problem definition

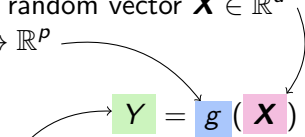
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Reliability analysis formulation:

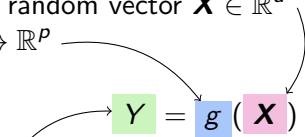
- Failure is characterized by a **threshold event** E
- The **failure probability**, denoted p_f , is given by:

$$p_f = \int_{\mathbb{R}^d} \mathbb{1}_E(\mathbf{x}) f_{\mathbf{X}}(\mathbf{x}) d\mathbf{x}$$

- Many standard or advanced algorithms for reliability analysis exist [2]

Uncertainty propagation: problem definition

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- Output random variable $Y \in \mathbb{R}^p$

Sensitivity analysis formulation:

- Compute **sensitivity indices** reflecting the influence of inputs on the output
- e.g., variance decomposition with the Sobol' indices [3]

$$S_i = \frac{\text{Var} [\mathbb{E}[Y|X_i]]}{\text{Var}[Y]} \quad S_{T_i} = \frac{\mathbb{E} [\text{Var}[Y|\mathbf{X}_{-i}]]}{\text{Var}[Y]}$$

- ▷ S_i is the first-order index, S_{T_i} the total-order index of X_i
- ▷ \mathbf{X}_{-i} stands for \mathbf{X} without the i -th component

OpenTURNS: www.openturns.org



AIRBUS

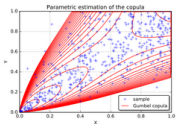


- First release: 2007
- Open source, LGPL licensed, C++/Python library
- Project size (2018): 720 classes, more than 6000 services
- Probabilistic programming paradigm for statistical modeling
- Numerical tools dedicated to the treatment of uncertainties
- Generic coupling to any type of physical model

```
user@user-desktop:~$ pip install openturns
```

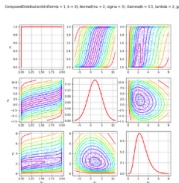
OpenTURNS: content

Data analysis



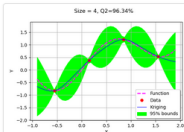
- Manage data and samples
- Sample analysis
- Distribution fitting
- Statistical hypothesis testing
- Estimate dependency and copulas
- Estimate stochastic processes
- Graphics

Probabilistic modeling



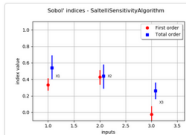
- Distributions
- Copulas
- Stochastic processes

Meta modeling



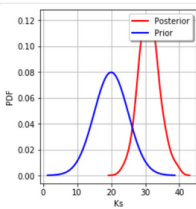
- General purpose metamodels
- Polynomial chaos metamodel
- Kriging metamodel
- Fields metamodels

Reliability, sensitivity



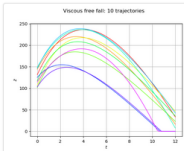
- Central dispersion
- Reliability
- Reliability: processes
- Sensitivity analysis
- Design of experiments

Calibration



Least squares and gaussian calibration
Bayesian calibration

Functional modeling



- Vectorial functions
- Field functions
- [Link to an external code](#)

otbenchmark: from benchmark repositories to a package

What is a benchmark?

“Something that can be measured and used as a standard that other things can be compared with.” The Oxford English dictionary

- Many existing benchmark packages for linear algebra, numerical analysis, optimization
- Some uncertainty quantification repositories of benchmark problems
 - ▷ Virtual Library of Simulation Experiments¹
 - ▷ GDR Mascot-Num research group benchmark repository²
- “Black-box Reliability Challenge”³ organized by TNO
 - ▷ Online submissions in 2019
 - ▷ Almost 30 reliability benchmark problems

¹<http://www.sfu.ca/ssurjano/index.html>

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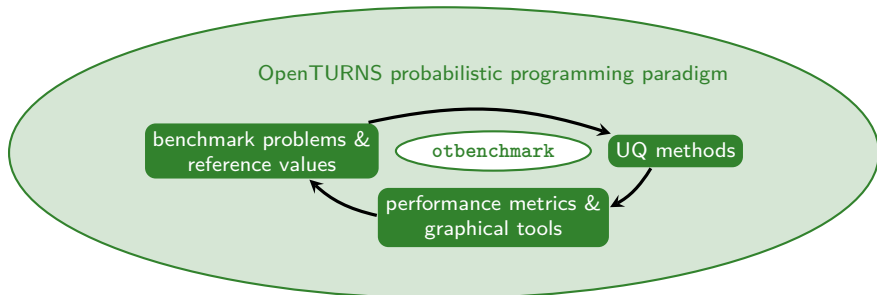
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otbenchmark: benchmark platform for UQ

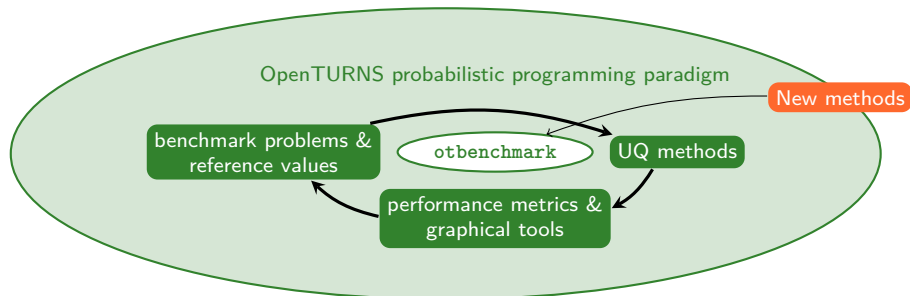
- 26 reliability problems and 4 sensitivity analysis problems so far
- Reference values either computed by exact quadrature methods or large Monte Carlo sampling



- *Scenario #1*: test a **new UQ algorithm** on a panel of problems and analyze its performances
- *Scenario #2*: apply and compare several UQ algorithms available on a given **benchmark problem**

otbenchmark: benchmark platform for UQ

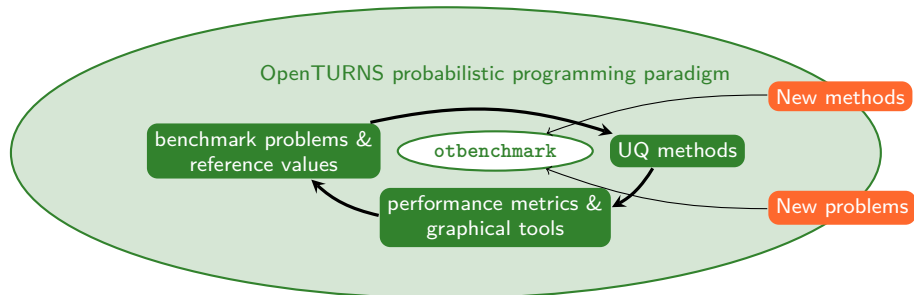
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Package architecture

Package architecture

- **Generic classes** `ReliabilityBenchmarkProblem` and `SensitivityBenchmarkProblem`
- Problem-specific classes inheriting methods from the generic classes
- `ReliabilityBenchmarkResult` to manage the result of a benchmark
- `ReliabilityBenchmarkProblemList` to perform a benchmark on list of problems
- `DrawEvent` to provide high-dimension graphical analysis tools (e.g., cross-cuts)

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Reliability example

RP 57: problem definition

Considering the threshold event:

$$E = \{g(\mathbf{X}) < 0, \quad \mathbf{X} \in \mathbb{R}^2\}$$

with the system limit-state function:

$$g(\mathbf{X}) = \min(\max(g_1(\mathbf{X}), g_2(\mathbf{X})), g_3(\mathbf{X}))$$

$$\begin{cases} g_1(\mathbf{X}) = -X_1^2 + X_2^3 + 3 \\ g_2(\mathbf{X}) = 2 - X_1 - 8X_2 \\ g_3(\mathbf{X}) = (X_1 + 3)^2 + (X_2 + 3)^2 - 4 \end{cases}$$

Where $\mathbf{X} \in \mathbb{R}^2$ has independent Gaussian marginals:

$$X_1 \sim \mathcal{N}(\mu_1 = 0, \sigma_1 = 1), \quad X_2 \sim \mathcal{N}(\mu_2 = 0, \sigma_2 = 1).$$

For these parameters, the reference probability is:

$$p_{f,\text{ref}} = 0.0284$$

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RP57: otbenchmark demonstration

Reliability problem definition

```

1  # Import packages
2  import openturns as ot
3  import otbenchmark as otb
4  problem = otb.ReliabilityProblem57()
5  event = problem.getEvent()
6  g = event.getFunction()
7  print("Reference failure probability = %.4f" % (problem.getProbability()))

Reference failure probability = 0.0284

```

FORM approximation

```

8  meta_algo = otb.ReliabilityBenchmarkMetaAlgorithm(problem)
9  bench_results = meta_algo.runFORM(ot.AbdoRackwitz())
10 pf = bench_results.computedProbability
11 nb_digits = bench_results.numberOfCorrectDigits
12 nb_simu = bench_results.numberOfFunctionEvaluations
13 print("FORM failure probability = %.4f" % (pf))
14 print("FORM nb. good digits = %.4f" % (nb_digits))
15 print("FORM nb. function calls = %d" % (nb_simu))

FORM failure probability = 0.4504
FORM nb. correct digits = -1.1719
FORM nb. function calls = 1004

```

FORM **performs poorly** on a system limit-state function (as foreseen here)

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RP57: otbenchmark demonstration

Monte Carlo simulation

```

16 sample_size = 1000
17 bench_results = meta_algo.runMonteCarlo(sample_size)
18 pf = bench_results.computedProbability
19 nb_digits = bench_results.numberOfCorrectDigits
20 nb_simu = bench_results.numberOfFunctionEvaluations
21 print("MC failure probability = %.4f" % (pf))
22 print("MC nb. correct digits = %.4f" % (nb_digits))
23 print("MC nb. function calls = %d" % (nb_simu))

MC failure probability = 0.0260
MC nb. good digits = 1.0731
MC nb. function calls = 1000

```

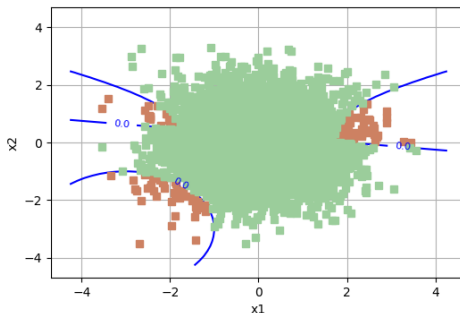
Monte Carlo **performs well** since p_f is not too rare

RP57: otbenchmark demonstration

Graphical analysis through cross-cuts

```
24 sample_size = 2000
25 drawEvent = otb.DrawEvent(event)
26 cloud = drawEvent.drawSampleCrossCut(sample_size)
27 bounds = ot.Interval([-4, -4], [4, 4])
28 graph = drawEvent.drawLimitStateCrossCut(bounds)
29 graph.add(cloud)
30 graph
```

Limit state surface



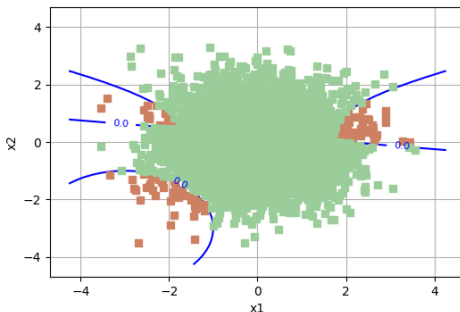
RP57: otbenchmark demonstration

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Limit state surface



otbenchmark can also **cross algorithms and problems** and compare performances

Benchmark results

Benchmark results: crossing problems and algorithms

Table: Estimation of p_f for all the problems using 5 algorithms ($n_{\max} = 10^4$ calls).

	$p_{f,\text{ref}}$	Monte Carlo	FORM	SORM	FORM-IS	Subset
RP8	7.840e-04	9.000e-04	6.599e-04	7.837e-04	7.737e-04	8.863e-04
RP14	7.520e-03	9.000e-04	7.003e-04	6.988e-04	7.598e-04	8.720e-04
RP22	4.160e-03	3.500e-03	6.210e-03	4.391e-03	4.259e-03	4.117e-03
RP24	2.860e-03	3.600e-03	6.209e-03	6.209e-03	2.749e-03	2.486e-03
RP25	6.140e-06	1.000e-04	2.105e-03	1.064e-05	4.644e-05	3.415e-05
RP28	1.460e-07	–	2.850e-08	0.000e+00	1.332e-07	1.756e-07
RP31	1.800e-04	2.300e-03	2.275e-02	2.275e-02	3.319e-03	3.919e-03
RP33	2.570e-03	1.600e-03	1.350e-03	1.350e-03	2.322e-03	2.718e-03
RP35	3.540e-03	3.000e-03	1.350e-03	2.134e-03	2.377e-03	3.430e-03
RP38	8.100e-03	8.500e-03	7.902e-03	8.029e-03	8.146e-03	7.848e-03
RP53	3.130e-02	3.260e-02	1.180e-01	2.986e-02	3.143e-02	2.971e-02
RP55	5.600e-01	5.660e-01	5.000e-01	1.093e-05	5.645e-01	5.655e-01
RP54	9.980e-04	1.100e-03	5.553e-02	3.552e-03	9.767e-04	9.611e-04
RP57	2.840e-02	2.950e-02	4.504e-01	0.000e+00	2.746e-02	2.772e-02
RP75	1.070e-02	1.030e-02	0.000e+00	0.000e+00	0.000e+00	9.409e-03
RP89	5.430e-03	5.000e-03	2.009e-09	2.009e-09	9.002e-05	5.460e-03
RP107	2.920e-07	–	2.867e-07	2.867e-07	2.896e-07	2.337e-07
RP110	3.190e-05	–	3.167e-05	3.167e-05	3.078e-05	7.116e-06
RP111	7.650e-07	–	0.000e+00	0.000e+00	0.000e+00	7.308e-07
RP63	3.790e-04	1.000e-04	1.000e+00	0.000e+00	0.000e+00	4.063e-04
RP91	6.970e-04	1.000e-03	6.984e-04	7.001e-04	6.964e-04	6.838e-04
RP60	4.560e-02	4.860e-02	4.484e-02	4.484e-02	4.503e-02	4.230e-02
RP77	2.870e-07	–	6.687e-02	6.687e-02	4.002e-07	3.683e-07
Four-branch serial system	2.186e-03	2.900e-03	0.000e+00	0.000e+00	0.000e+00	2.428e-03
R-S	7.865e-02	7.870e-02	7.865e-02	7.865e-02	7.792e-02	7.633e-02
Axial stressed beam	2.920e-02	2.690e-02	2.998e-02	2.933e-02	2.867e-02	2.936e-02

Benchmark results: performance metrics

Figure: Log relative error using 5 algorithms ($n_{\max} = 10^4$ calls).

	Monte Carlo	FORM	SORM	FORM-IS	Subset
RP8	0.83	0.80	3.43	1.88	0.88
RP14	0.06	0.04	0.04	0.05	0.05
RP22	0.80	0.31	1.26	1.62	1.59
RP24	0.59	0.07	0.07	1.41	0.88
RP25	1.18	2.53	0.14	0.82	0.66
RP28	0.00	0.09	0.00	1.06	0.69
RP31	1.07	2.10	2.10	1.24	1.32
RP33	0.42	0.32	0.32	1.02	1.24
RP35	0.82	0.21	0.40	0.48	1.51
RP38	1.31	1.61	2.06	2.25	1.51
RP53	1.38	0.44	1.34	2.38	1.29
RP55	1.97	0.97	0.00	2.10	2.01
RP54	0.99	1.74	0.41	1.67	1.43
RP57	1.41	1.17	0.00	1.48	1.62
RP75	1.43	0.00	0.00	0.00	0.92
RP89	1.10	0.00	0.00	0.01	2.26
RP107	0.00	1.74	1.74	2.08	0.70
RP110	0.00	2.14	2.14	1.45	0.11
RP111	0.00	0.00	0.00	0.00	1.35
RP63	0.13	3.42	0.00	0.00	1.14
RP91	0.36	2.70	2.35	3.04	1.72
RP60	1.18	1.78	1.78	1.91	1.14
RP77	0.00	5.37	5.37	0.40	0.55
Four-branch serial system	0.49	0.00	0.00	0.00	0.85

Performance metrics

For a reference value $p_{f,\text{ref}}$ and its approximation $p_{f,\text{apx}}$

- Absolute error: $\epsilon = |p_{f,\text{ref}} - p_{f,\text{apx}}|$
- Relative error: $\eta = \frac{|p_{f,\text{ref}} - p_{f,\text{apx}}|}{|p_{f,\text{ref}}|}$
- Log relative error: $N = \log_{10} \left(\frac{1}{\eta} \right)$

Conclusion

Conclusion: otbenchmark, a benchmark platform for UQ

- otbenchmark's ambition: gather and standardize UQ problems in a single Python package
- Any user can bring, either his new UQ algorithm or new use-case (with reference values!)
- Wide variety of reliability and sensitivity analysis problems
- Performance metrics and graphical tools for a smart analysis
- Agile development workflow to ensure a robust benchmark
- More problems to come, and more fields of uncertainty quantification to analyze (e.g., central tendency, calibration)

Welcome to participate!

- GitHub public repository¹
- Unit-tests and continuous integration using Circle-CI
- otbenchmark 0.1.1 package available on PyPI



¹Official repository: <https://github.com/mbaudin47/otbenchmark>

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```
user@user-desktop:~$ pip install otbenchmark
```

¹Official repository: <https://github.com/mbaudin47/otbenchmark>

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- [3] B. Iooss and P. Lemaître. A Review on Global Sensitivity Analysis Methods. In G. Dellino and C. Meloni, editors, *Uncertainty Management in Simulation-Optimization of Complex Systems: Algorithms and Applications*, chapter 5, pages 101–122. Springer US, Boston, MA, 2015.

Thank you