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... solutions for robust engineering

Simulation and identification of non-Gaussian, non-stationary random processes using OpenTURNS

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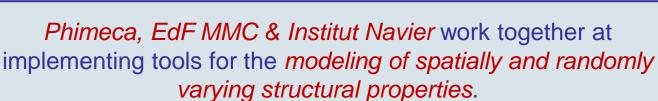


Introduction





- A group of partners around the problematique of ageing components in nuclear power plants.
- Means:
 - testing (subatomic scale microscope, non-destructive testing)
 - numerical simulation (HPC)
 - theoretical developments
 - courses







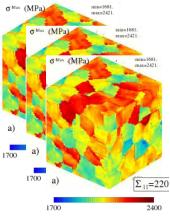
Introduction

Objective

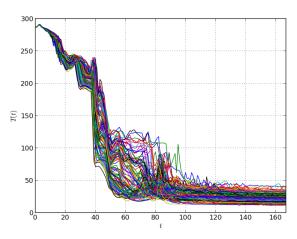
• Let suppose we have a sample of experimental data:

$$\boldsymbol{\mathcal{Y}} = \left\{ \left\{ \boldsymbol{y}^{(q)} \left(\boldsymbol{x}^{[i]}\right), i = 1, \dots, N^{(q)} \right\}, q = 1, \dots, Q \right\}, \qquad \boldsymbol{x} \in \mathbb{X} \subseteq \mathbb{R}^d$$

• <u>Ex</u>:



Stress field within polycristalline aggregates of 16MND5 steel (Code_Aster output)



Thermodynamic transient state in the vessel of a nuclear powerplant (Cathare output)

We aim at *building a model* representative of the spatial and/or temporal random variations of these properties





Introduction

- Available representation techniques (simulation and identification)
 - (Assumed) stationary and Gaussian random processes:
 - Spectral representation (periodogram analysis)
 - Optimal linear estimation, a.k.a. Kriging (variographic analysis)
 - Available in OpenTURNS (see the model_process submodule)
 - Non-stationary and non-Gaussian random processes:
 - Karhunen-Loève expansion
 - and that's all folks!... (yet, to my knowledge)
 - Not available (yet) in OpenTURNS

We assume the data is complete enough for estimating its non-stationarity and non-gaussianity.



- Definition of a random field
- The Karhunen-Loève representation of random fields
 - Theoretical and practical representations
 - Galerkin-based discretization of the autocovariance function
 - Global approaches
 - A word on local approaches
- Application to the simulation of random fields
 - Gaussian random fields
 - Translation fields
- Application to the identification of random fields
 - Estimating the mean and the covariance
 - Identification of the distribution of the KL coefficients
- Implementation
 - OpenTURNS-based Python implementation
 - Examples
- Conclusions & Perspectives



Definition

Random variables

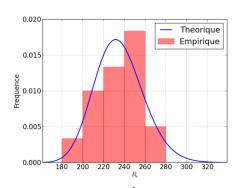
$$Y: \omega \to y = Y(\omega)$$

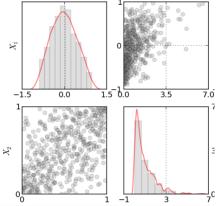
Random vectors

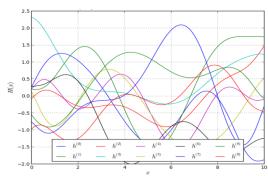
$$\mathbf{Y}: \omega \to \mathbf{y} = \mathbf{Y}(\omega) = \begin{bmatrix} Y_1(\omega) \\ \vdots \\ Y_n(\omega) \end{bmatrix}, \quad n \in \mathbb{N}$$

Scalar-valued random fields

$$Y: \omega \to y(\mathbf{x}) = Y(\mathbf{x}, \omega), \qquad \mathbf{x} \in \mathbb{X} \subset \mathbb{R}^d$$







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The Karhunen-Loève expansion

A naïve approach to the modelling of random fields

Let suppose we have some discretized sample paths:

$$\mathbf{y} = \{ \{ y^{(q)}(\mathbf{x}^{[i]}), i = 1, ..., N^{(q)} \}, q = 1, ..., Q \}, \qquad \mathbf{x} \in \mathbb{X}$$

 We can recast these sample paths to a common functional representation (using e.g. ordinary least-squares regression):

$$\mathcal{F} = \{ \varphi(\mathbf{x}; \boldsymbol{\xi}^{(q)}), q = 1, \dots, Q \}, \qquad \mathbf{x} \in \mathbb{X}$$

Ex:

$$\varphi(x; \boldsymbol{\xi}) = \sum_{k=1}^{K} \xi_k \cos\left(\frac{2\pi}{\overline{\mathbb{X}}}kx\right), \qquad x \in \mathbb{X}$$

- Eventually, we are back into « ordinary statistics »: what is the joint distribution of the vector £?
 - Marginal distributions
 - Complete the joint distribution by composing with copulas



The Karhunen-Loève expansion

There exists an optimal representation

(Loève, 1957)

The Karhunen-Loève expansion reads:

$$Y(x) = \mu_Y(x) + \sum_{k=1}^{+\infty} \sqrt{\lambda_k} \Xi_k \varphi_k(x), \qquad x \in X$$

where:

• the *infinite but countable set of 2-uples* $\{(\lambda_k, \varphi_k), k \in \mathbb{N}^*\}$ are solutions of the eigendecomposition of the field's autocovariance function C:

$$\int_{\mathbb{X}} C(x, x') \varphi_k(x') dx' = \lambda_k \varphi_k(x), \qquad x \in \mathbb{X}$$

$$C(x, x') = \mathbb{E} [(Y(x) - \mu_Y(x))(Y(x') - \mu_Y(x'))], \qquad (x, x') \in \mathbb{X} \times \mathbb{X}$$

the coefficients are zero-mean, unit-variance, non-correlated random variables:

$$\begin{cases} \mathbb{E}[\Xi_k] = 0, & \forall k \in \mathbb{N}^* \\ \mathbb{E}[\Xi_i \Xi_j] = \delta_{ij}, & (i, j) \in \mathbb{N}^* \times \mathbb{N}^* \end{cases}$$

« Optimality » holds in the mean square sense.



The Karhunen-Loève expansion

In practice

The *truncated* Karhunen-Loève expansion reads:

$$\hat{Y}_M(x) = \mu_Y(x) + \sum_{k=1}^M \sqrt{\lambda_k} \Xi_k \varphi_k(x), \qquad x \in \mathbb{X}, M \in \mathbb{N}^*$$

where:

• the infinite countable set of 2-uples $\{(\lambda_k, \varphi_k), k \in \mathbb{N}^*\}$ are ordered in decreasing order of eigenvalues:

$$\lambda_1 > \dots > \lambda_M > \lambda_{M+1} > \dots$$

the random coefficients are zero-mean, unit-variance, non-correlated random variables:

$$\begin{cases} \mathbb{E}[\Xi_k] = 0, & k = 1, ..., M \\ \mathbb{E}[\Xi_i \Xi_j] = \delta_{ij}, & i, j = 1, ..., M \end{cases}$$

 Truncation results in an approximation of the given autocovariance function (variance is underestimated).



Galerkin-based discretization

Numerical resolution of the Fredholm integral equation

$$\int_{\mathbb{X}} C(x, x') \varphi_k(x') dx' = \lambda_k \varphi_k(x), \qquad x \in \mathbb{X}$$

This equation admits analytical solutions for a (very?) few parametric covariance functions.

Ex: the absolute exponential (stationary) autocovariance function:

$$C(x, x') = \sigma^2 \exp\left(\sum_{i=1}^d \frac{|x_i - x_i'|}{\ell_i}\right), \quad (x, x') \in \mathbb{X} \times \mathbb{X}$$

Otherwise, we need to resort to numerical discretization using a Galerkin scheme (Ghanem & Spanos, 1993; Sudret, 2000).



Galerkin-based discretization

An optimal approximation of the unknown eigenfunctions

• We *approximate the eigenfunctions* with a linear combination of square-integrable functions:

$$\varphi_k(\mathbf{x}) = \sum_{i=1}^N d_i^{(k)} h_i(\mathbf{x}), \qquad \mathbf{x} \in \mathbb{X}$$

The k-th residual of the Fredholm integral equation reads:

$$\varepsilon_k(\mathbf{x}) = \sum_{i=1}^N d_i^{(k)} \left[\int_{\mathbb{X}} C(\mathbf{x}, \mathbf{x}') \varphi_k(\mathbf{x}') d\mathbf{x}' - \lambda_k h_i(\mathbf{x}) \right], \qquad \mathbf{x} \in \mathbb{X}, k = 1, \dots, K$$

 The Galerkin scheme consists in requiring that this residual is orthogonal to the approximation basis:

$$\int_{\mathbb{R}} \varepsilon_k(\mathbf{x}) h_i(\mathbf{x}) d\mathbf{x} = 0, \qquad k = 1, ..., M, i = 1, ..., N$$



Galerkin-based discretization

An optimal approximation of the unknown eigenfunctions (cont'd)

• Eventually, we obtain N + 1 unknowns for N equations for each 2-uples of eigensolutions, which can be put in the following matrix form:

$$CD = \Lambda BD$$

where:

$$C_{ij} = \int_{\mathbb{X}} \int_{\mathbb{X}} C(\boldsymbol{x}, \boldsymbol{x}') h_i(\boldsymbol{x}) h_j(\boldsymbol{x}') d\boldsymbol{x} d\boldsymbol{x}', \qquad i, j = 1, ..., N$$

$$B_{ij} = \int_{\mathbb{X}} h_i(\boldsymbol{x}) h_j(\boldsymbol{x}) d\boldsymbol{x}, \qquad i, j = 1, ..., N$$

• Then, we resort to a *numerical solver for finding the M* \leq *N solutions* of the generalized eigenvalue problem that have the *largest eigenvalues*:

$$\mathbf{\Lambda} = \text{diag} (\{\lambda_k, k = 1, ..., M\})$$

$$\mathbf{D} = \left[d_i^{(k)}, i = 1, ..., N, k = 1, ..., M \right]$$



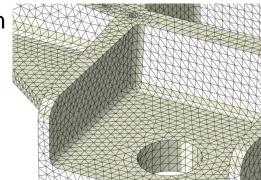
Global vs. local approximation

Global approximation

- We can choose any (square-integrable) functional basis with sympathetic properties:
 - Legendre polynomials (present implementation):
 - > so that C can be calculated using Gauss-Legendre quadrature
 - orthogonal, hence B is diagonal and norm is known analytically
 - Haar wavelets (Phoon, 2002), or any other wavelets family:
 - > so that C is the *discrete wavelet transform* of the autocovariance function
 - orthogonal, hence B is diagonal and norm is known analytically
- Or any other basis but with more pain!

Local approximation (Recek, 2007; Perrin, 2013)

- Shape functions over a finite element mesh
- Better suited for non-rectangular domains
- ... C and B can be dense though
- > FE-software-dependent





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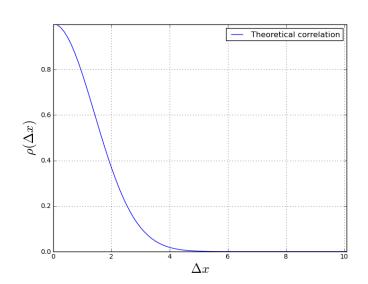
Simulation of random fields

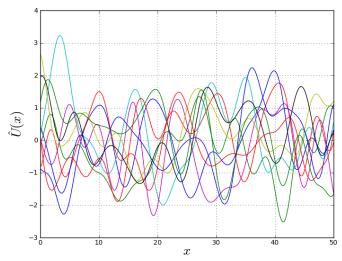
Simulation of Gaussian random fields

- Definition:
 - rectangular domain
 - mean function
 - autocovariance functions
- Numerical discretization using either global or local approximation
- The field being assumed Gaussian, the KL coefficients are jointly normally distributed:

$$\boldsymbol{\mathcal{Z}} \sim \mathcal{N}_{M}(\mathbf{0},\mathbf{1})$$

<u>Ex</u>: Zero-mean, unit-variance with a square exponential autocovariance







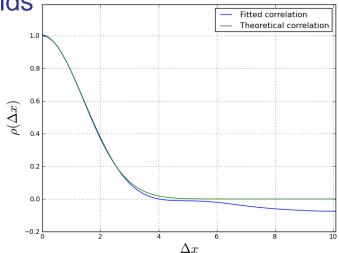
Simulation of random fields

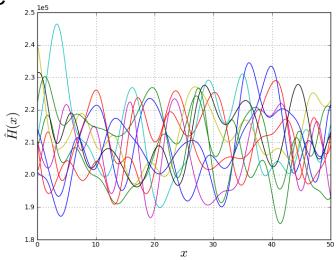
Simulation of non-Gaussian random fields

- Definition:
 - rectangular domain
 - mean function
 - autocovariance function
 - « pointwise distribution »
- Numerical discretization using either global or local approximation
- Simulation of a zero-mean, unit-variance Gaussian process
- Translation into the targeted non-Gaussian randomfield using a pointwise isoprobabilistic transformation:

$$Y(x) = T(U(x), x), \qquad x \in X$$

Ex: A lognormal translation field





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Simulation of random fields

Simulation of non-Gaussian random fields

- Premise of a number of authors:
 - « I can't get the autocorrelation and the distribution! »
 - The translation alters the given autocovariance function
 - Workaround: well, let us try to solve our favorite problem:

$$\rho(\mathbf{x}, \mathbf{x}') = \int_{\mathbb{R}} \int_{\mathbb{R}} \frac{\left(F_{Y(\mathbf{x})}^{-1}(\Phi(z)) - \mu_{Y}(\mathbf{x})\right) \left(F_{Y(\mathbf{x}')}^{-1}(\Phi(z')) - \mu_{Y}(\mathbf{x}')\right) \times \cdots}{\ldots \times \varphi_{2}(z, z'; \rho_{0}(\mathbf{x}, \mathbf{x}')) dz dz'}, \quad (\mathbf{x}, \mathbf{x}') \in \mathbb{X} \times \mathbb{X}$$

- > Pearson stroke again! (Lebrun & Dutfoy, 2009a,b,c; Lebrun, 2013)
- What you can get though is:
 - a pointwise distribution and a *fractile autocorrelation* (Phoon, 2004)

$$\rho_0(\mathbf{x}, \mathbf{x}') = 2\sin\left(\frac{\pi}{6}\rho_{\rm S}(\mathbf{x}, \mathbf{x}')\right)$$

... and, between the lines: an assumed Gaussian copula parameterized with a Spearman rank autocorrelation function!



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Identification of random fields

Identification of non-stationary, non-Gaussian random fields

- Interpolation of the sample paths (e.g. linear)
- Pointwise *empirical estimation* of the mean and autocovariance functions:

$$\hat{\mu}_Y(\mathbf{x}) = \frac{1}{Q} \sum_{q=1}^{Q} y^{(q)}(\mathbf{x}), \qquad \mathbf{x} \in \mathbb{X}$$

$$\hat{C}(x,x') = \frac{1}{Q-1} \sum_{q=1}^{Q} (y^{(q)}(x) - \hat{\mu}_{Y}(x)) (y^{(q)}(x') - \hat{\mu}_{Y}(x')), (x,x') \in \mathbb{X} \times \mathbb{X}$$

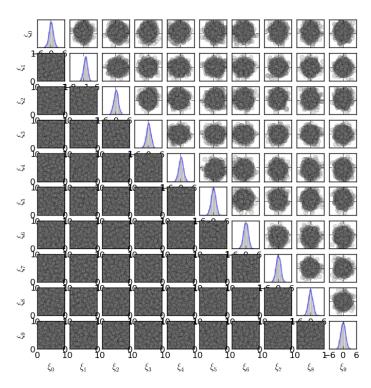
- Numerical discretization using either global or local approximation
- Compute the sample of KL coefficients associated to the set of sample paths by exploiting the property of orthogonality of eigenfunctions:

$$\xi_k^{(q)} = \frac{1}{\sqrt{\lambda_k}} \int_{\mathbb{X}} \varphi_k(\mathbf{x}) (y^{(q)}(\mathbf{x}) - \mu_Y(\mathbf{x})) d\mathbf{x}, \qquad k = 1, ..., M, q = 1, ..., Q$$



Identification of random fields

Identification of the KL coefficients' joint distribution



- Parametric or non-parametric models:
 - for the marginal distributions
 - for the (composed) copula(s)
- Despite the number of KL coefficients is optimal (minimal), it can remain quite large!

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OpenTURNS-based Python implementation

The KarhunenLoeveExpansion object

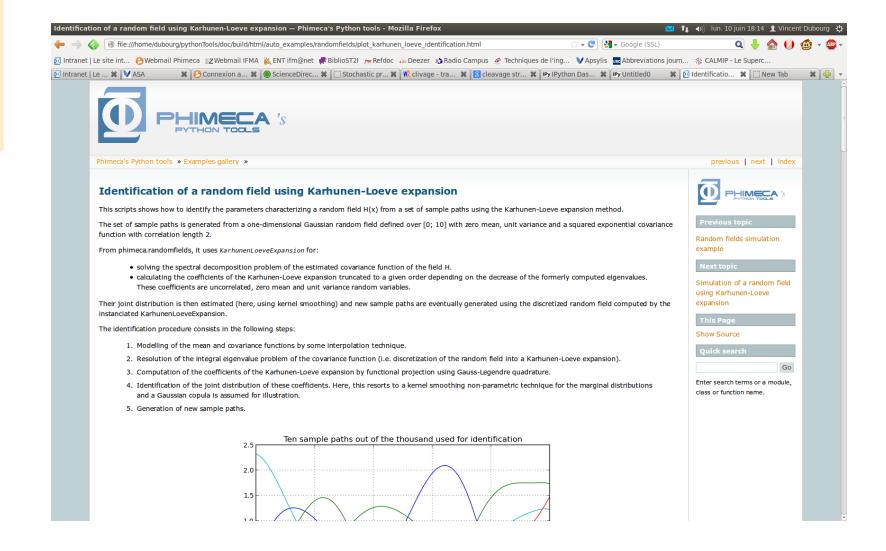
- ___init___:
 - The constructor discretizes the random field using *Gauss-Legendre* quadrature and tensorized Legendre polynomials from OpenTURNS
 - It takes μ, C, the bounds of the rectangular domain and the truncation order
 M as arguments
 - It also features a set of keyword arguments:
 - ightharpoonup the order of the *tensorized Legendre* approximation basis $(N = {d+p \choose p} > M)$
 - \triangleright the quadrature order for calculating **C** and ξ 's
- __call__:
 - The object is callable and takes x's and ξ 's as input, it calculates the required sample paths values.
- _eigenvalues, _eigenfunctions
- _compute_approximated_covariance:
 - It calculates the covariance of the truncated expansion for comparison:

$$\hat{C}(\mathbf{x}, \mathbf{x}') = \sum_{k=1}^{M} \lambda_k \, \varphi_k^2(\mathbf{x}) = f(\mathbf{x}, \mathbf{M}, \mathbf{N})$$

_compute_coefficients (uses Gauss-Legendre quadrature)



OpenTURNS-based Python implementation





Conclusions & Perspectives

Conclusions

- OpenTURNS has made a long way towards scientific Python:
 - Less typing (ot.Distribution(ot.Normal()) → ot.Normal())
 - Better casting from Sample/Point to Numpy Array (and vice-versa)
- But it still lacks:
 - Easy typing (remaining ot.Indices types in e.g. getMarginalDistribution)
 - Docstrings
- Features request:
 - a built-in method for computing integrals using Gauss-* quadrature
 - completing quadrature schemes such as Gauss-Kronrod (?)

Perspectives

- Implementation of the Karhunen-Loève representation of random fields within OpenTURNS:
 - Global approach: definitely go for wavelets!
 - Local approach: using Vtk? Code_Aster?
- Some literature about vector-valued KL expansions: Perrin, 2013.

