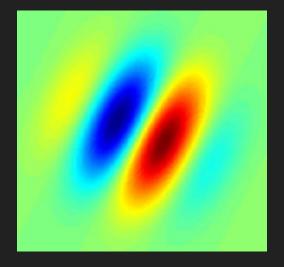
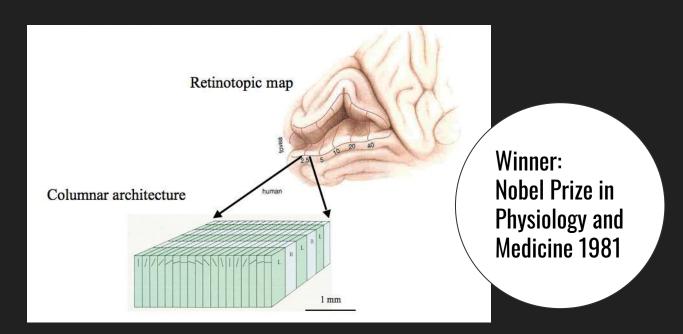
Convolutional Neural Networks

A Brief History of C.N.N.s

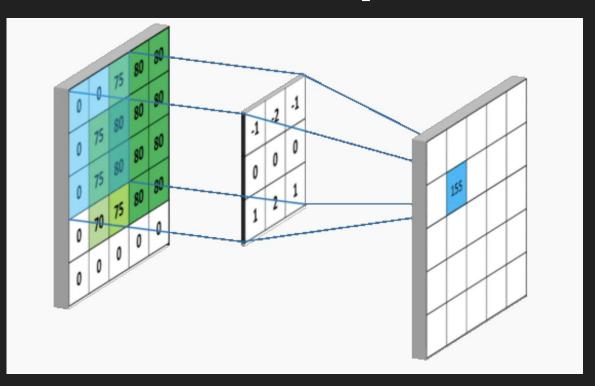




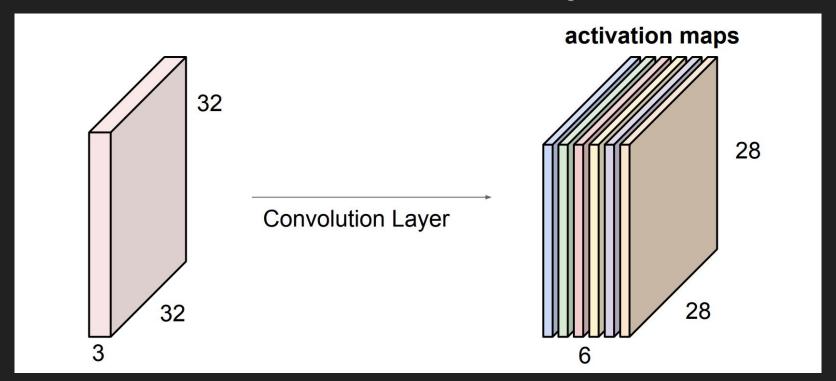
V1



Convolutional Operations



Convolutional Layer

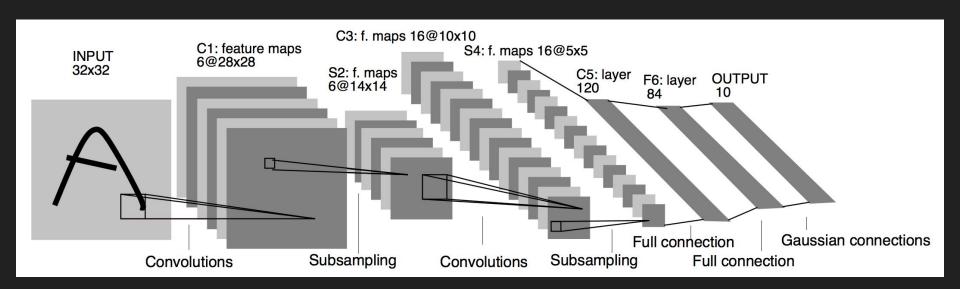








LeNet



Subsampling (Max Pooling)

12	20	30	0			
8	12	2	0	2×2 Max-Pool	20	30
34	70	37	4		112	37
112	100	25	12	reduce the number of parameters to be learned		

The first CNN



0.95% error rate



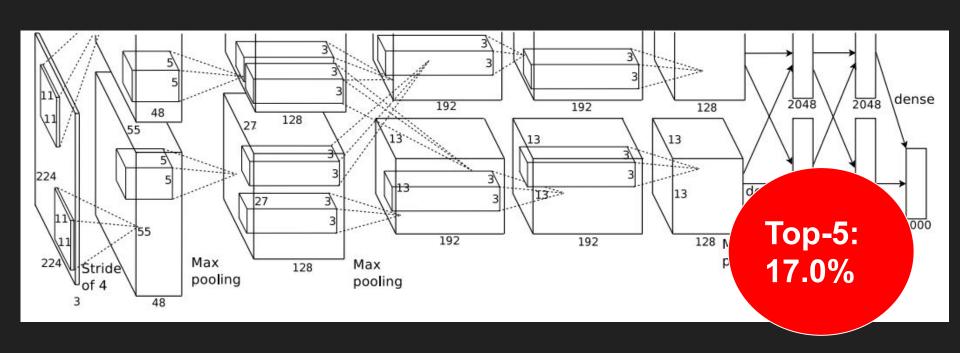




Large Scale Visual Recognition Challenge.

2012 AlexNet

2012 WINNER



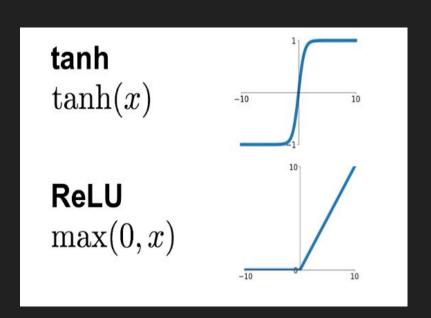
ReLu - accelerate training

2 parallel GPUs communicating between certain layers

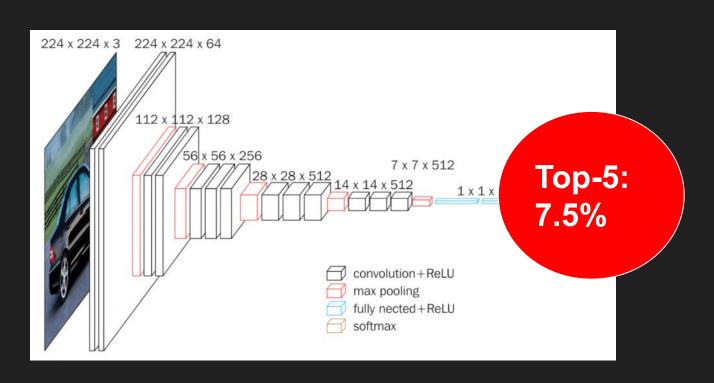
Local Response Normalization

Overlapping Pooling

Dropout - to reduce overfitting

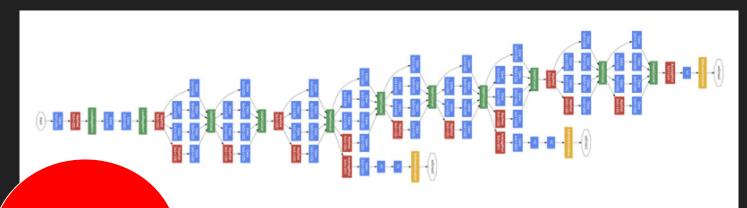


2014 V.G.G.



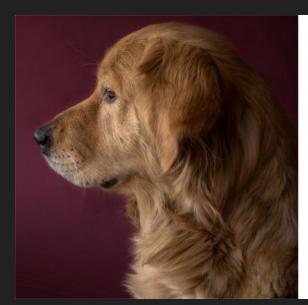
2015 GoogLeNet

2014 WINNER

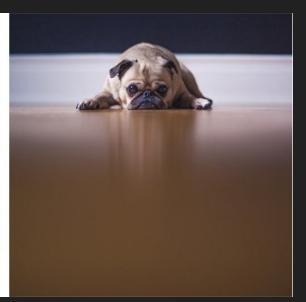


Top-5: 6.67%

Convolution Pooling Softmax Other



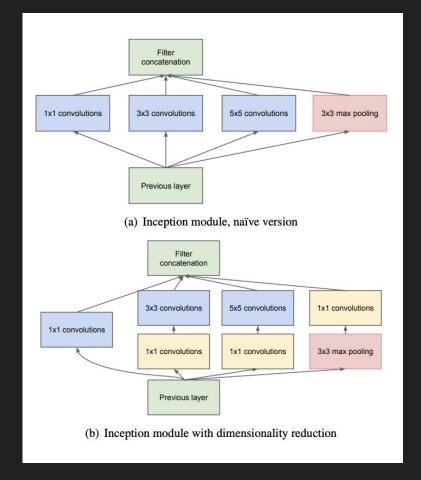




Inception Module

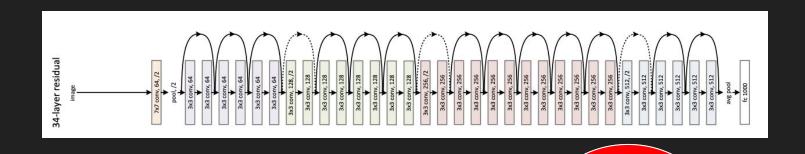
At each layer make a choice: Pooling or perform a convolution.

Why not perform all and concatenate.

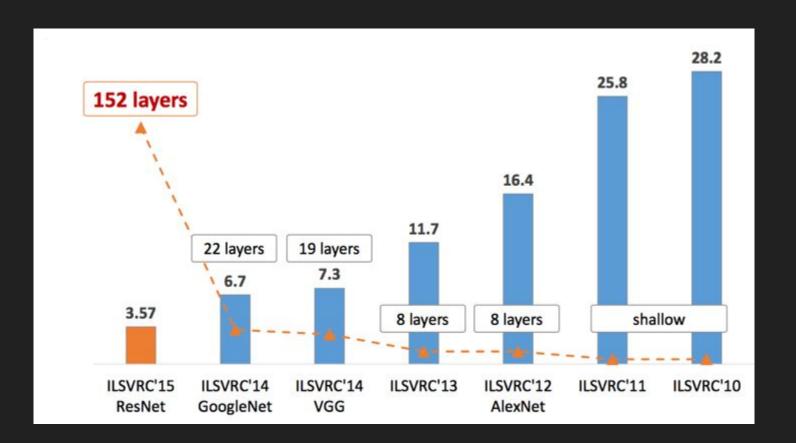


2015 ResNet

2015 WINNER



Top-5: 3.57%

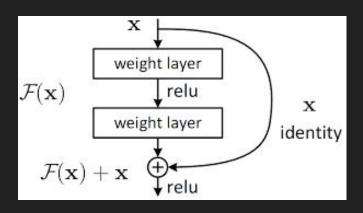


Deep Residual Learning

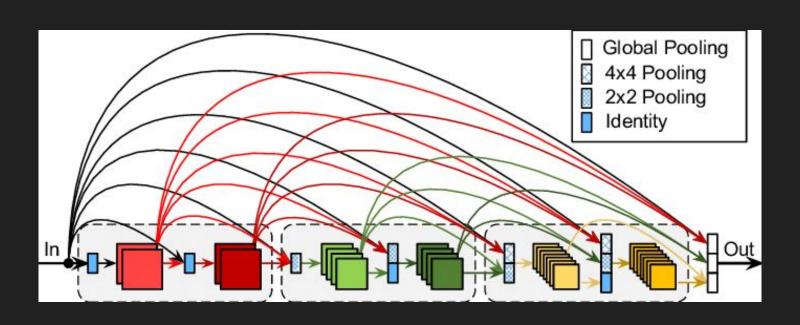
Solution to Degradation

Append current output to the output n convolutional layers later.

Much deeper network

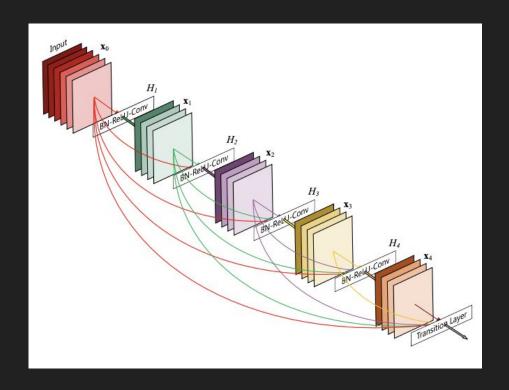


2017 DenseNet



Dense Blocks

At each layer in the block take all preceding feature maps



Questions