

## Oct 14 notes

### Activity 2.6.2:

$$\vec{e}_1 = \hat{i} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \vec{e}_2 = \hat{j} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \vec{e}_3 = \hat{k} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

a)  $\vec{v}$  can be expressed as a linear combination of  $\vec{e}_1$ ,  $\vec{e}_2$ , and  $\vec{e}_3$  because we have a pivot in every row, we can set i, j, and k to be any scalar to get any values of  $\vec{v}$

b) If  $\vec{w} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ ,  $\vec{v}$  can't be expressed as a linear combination of  $\vec{e}_1$ ,  $\vec{e}_2$ , and  $\vec{e}_3$  because we don't have a pivot in row 3, so not spanning set.

c) All vectors in  $\mathbb{R}^3$  can be written as linear combinations of  $\vec{e}_1$ ,  $\vec{e}_2$ , and  $\vec{e}_3$  because we have a pivot in every row and column - linearly independent vectors that span the set

**Observation 2.6.3:** A basis is a linearly independent set that spans a vector space. In example 2.6.2,  $\vec{e}_1$ ,  $\vec{e}_2$ , and  $\vec{e}_3$  is an example of the standard basis vectors of  $\mathbb{R}^3$ .

**Observation 2.6.4** A basis may be thought of as a collection of building blocks for a vector space, since every vector in the space can be expressed as a unique linear combination of basis vectors.

### Observation 2.5.8 says:

- A set of vectors is **linearly independent** if and only if the RREF has all pivot columns.
- A set of  $\mathbb{R}^m$  vectors **spans**  $\mathbb{R}^m$  if the RREF has all pivot rows

### Definition 2.6.3 says:

- A basis is a linearly independent set that spans a vector space. (This means it should have pivots in every row and column.)

### Activity 2.6.5

Label each of the sets as: spanning  $\mathbb{R}^4$ , linearly independent, or a basis for  $\mathbb{R}^4$

$$A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}, B = \begin{bmatrix} 2 & 2 & 4 & -3 \\ 3 & 0 & 3 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & 3 & 2 & 3 \end{bmatrix}, C = \begin{bmatrix} 2 & 2 & 3 & -1 & 4 \\ 3 & 0 & 13 & 10 & 3 \\ 0 & 0 & 7 & 7 & 0 \\ -1 & 3 & 16 & 14 & 2 \end{bmatrix}$$

$$D = \begin{bmatrix} 2 & 4 & -3 & 3 \\ 3 & 3 & 0 & 6 \\ 0 & 0 & 1 & 1 \\ -1 & 2 & 3 & 5 \end{bmatrix}, E = \begin{bmatrix} 5 & -2 & 4 \\ 3 & 1 & 5 \\ 0 & 0 & 1 \\ -1 & 3 & 3 \end{bmatrix}$$

```

B=Matrix(QQ,[ [2,2,4,-3],[3,0,3,0],[0,0,0,1],[-1,3,2,3] ])
B.rref()
C=Matrix(QQ,[ [2,2,3,-1,4],[3,0,13,10,3],[0,0,7,7,0],[-1,3,16,14,2] ])
C.rref()
D=Matrix(QQ,[ [2,4,-3,3],[3,3,0,6],[0,0,1,1],[-1,2,3,5] ])
D.rref()
E=Matrix(QQ,[ [5,-2,4],[3,1,5],[0,0,1],[-1,3,3] ])
E.rref()

```

$$\begin{aligned}
RREF(A) &= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}, RREF(B) = \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \\
RREF(C) &= \begin{bmatrix} 1 & 0 & 0 & -1 & 1 \\ 0 & 1 & 0 & -1 & 1 \\ 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \\
RREF(D) &= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}, RREF(E) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}
\end{aligned}$$

Span (all pivot rows in the RREF): A, D

Linearly Independent (RREF has all pivot columns): A, D, E

Basis (all pivot rows and columns in the RREF): A, D

None of the above: B, C

### Activity 2.6.6

If  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3, \vec{v}_4\}$  is a basis for  $R^4$  that means RREF would be:

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

This would be the identity matrix, with pivots in all rows and columns.

### Fact 2.6.7

A basis for  $R^n$  must have n vectors and its square matrix must reduce to the identity matrix containing all 0s except for 1 along the diagonal pointing down and to the right.

**Observation 2.7.1** - subspace of a vector space is a subset that is itself a vector space.

One easy way to construct a subspace is to take the span of set, but a linearly dependent set contains “redundant” vectors. For example, only two of the three vectors in the following image are needed to span the planar subspace.

**Activity 2.7.2** Consider the subspace of  $\mathbb{R}^4$  given by:

$$W = \text{span} = \left\{ \begin{bmatrix} 2 \\ 3 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -3 \\ 2 \\ -3 \end{bmatrix}, \begin{bmatrix} 2 \\ -3 \\ 2 \\ -3 \end{bmatrix}, \begin{bmatrix} 1 \\ 5 \\ -1 \\ 0 \end{bmatrix} \right\}$$

(a) Mark the parts of the RREF of the matrix to show what parts show that W’s spanning set is linearly dependent.

```
W=Matrix(QQ,[ [2,2,2,1],[3,0,-3,5],[0,1,2,-1],[1,-1,-3,0] ])
W.rref()
```

RREF(W):

$$\begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Linearly Independent means RREF has all pivot columns, but column 3 does not have a pivot so this is a linearly dependent system.

(b) Find a basis for W by removing a vector from its spanning set to make it linearly independent.

Drop 3rd vector because it isn’t a pivot column.

```
W=Matrix(QQ,[ [2,2,1],[3,0,5],[0,1,-1],[1,-1,0] ])
W.rref()
```

RREF(W):

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

**Fact 2.7.3:** To compute a basis for the subspace, simply remove the vectors corresponding to the non-pivot columns of the RREF.