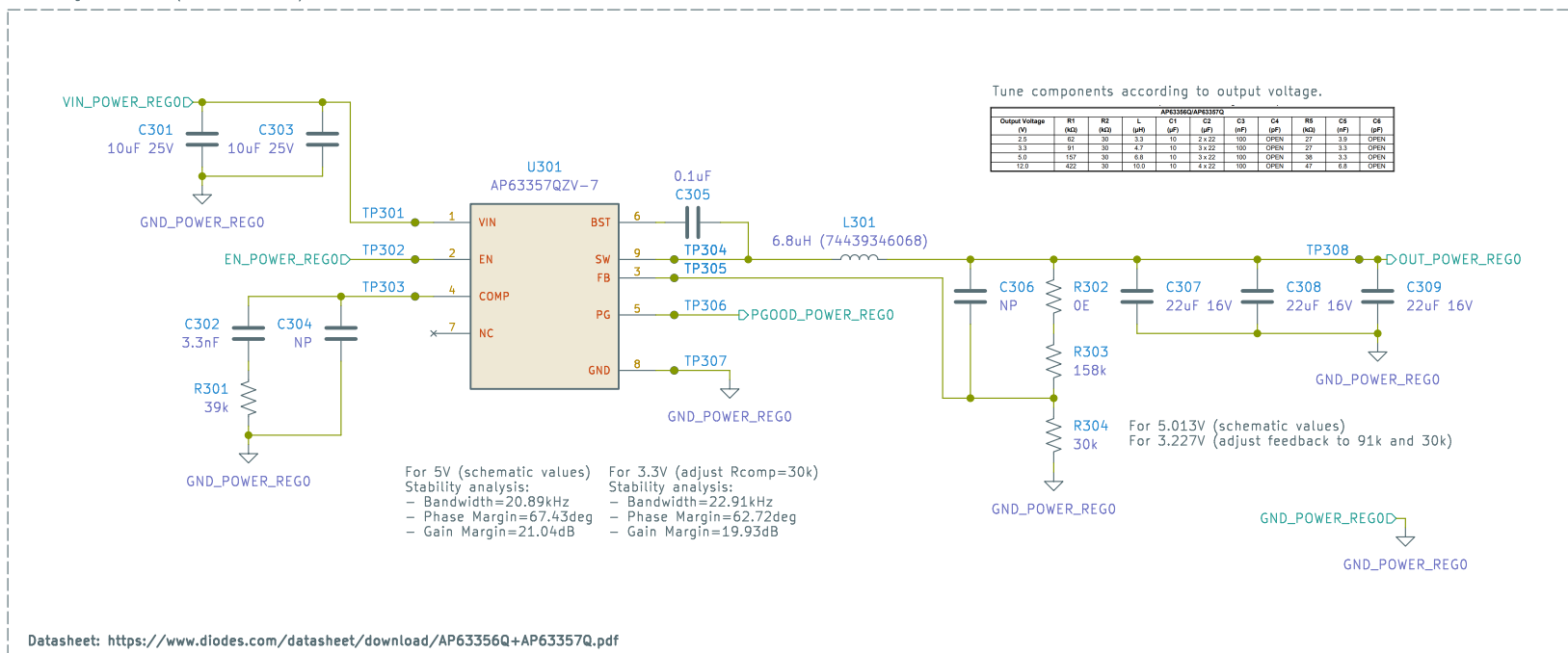


Power Regulator BUCK (Pi and MCU PSU)



Distributed Open-source as: CC BY-SA 4.0
Design implements a battery management system and power deliver for use with the developed autonomous robot platform powered by LEGO Technic HUB and Rasberry Pi

Sheet: /POWER_SUPPLY/POWER_REGO/
File: regulator.kicad_sch

Title: Power delivery Board

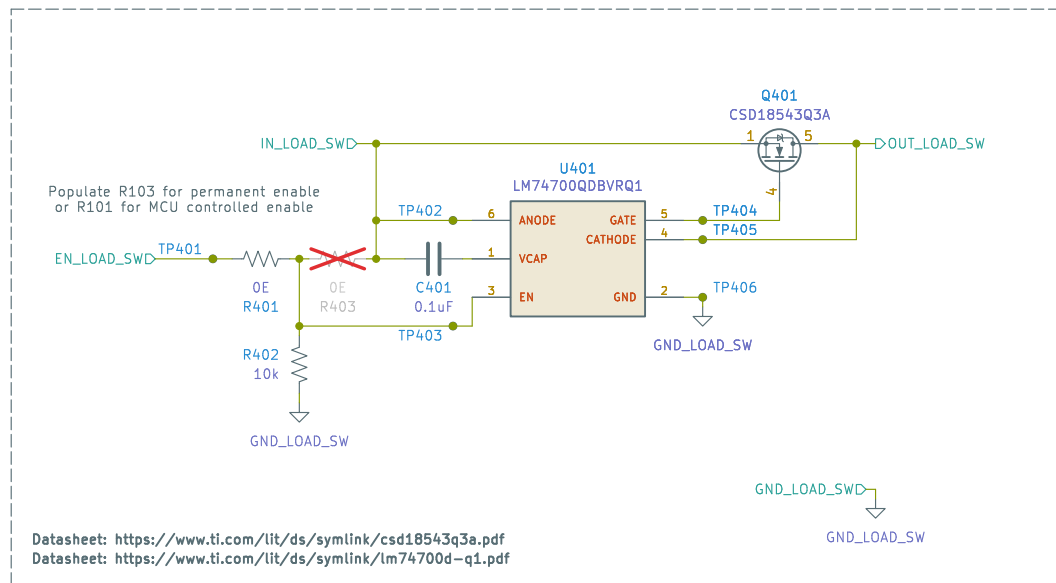
Size: A4 Date: 2025-06-25

KiCad E.D.A. 9.0.0

Rev: B

Id: 3/14

Load Switch with 2 Condition Enable



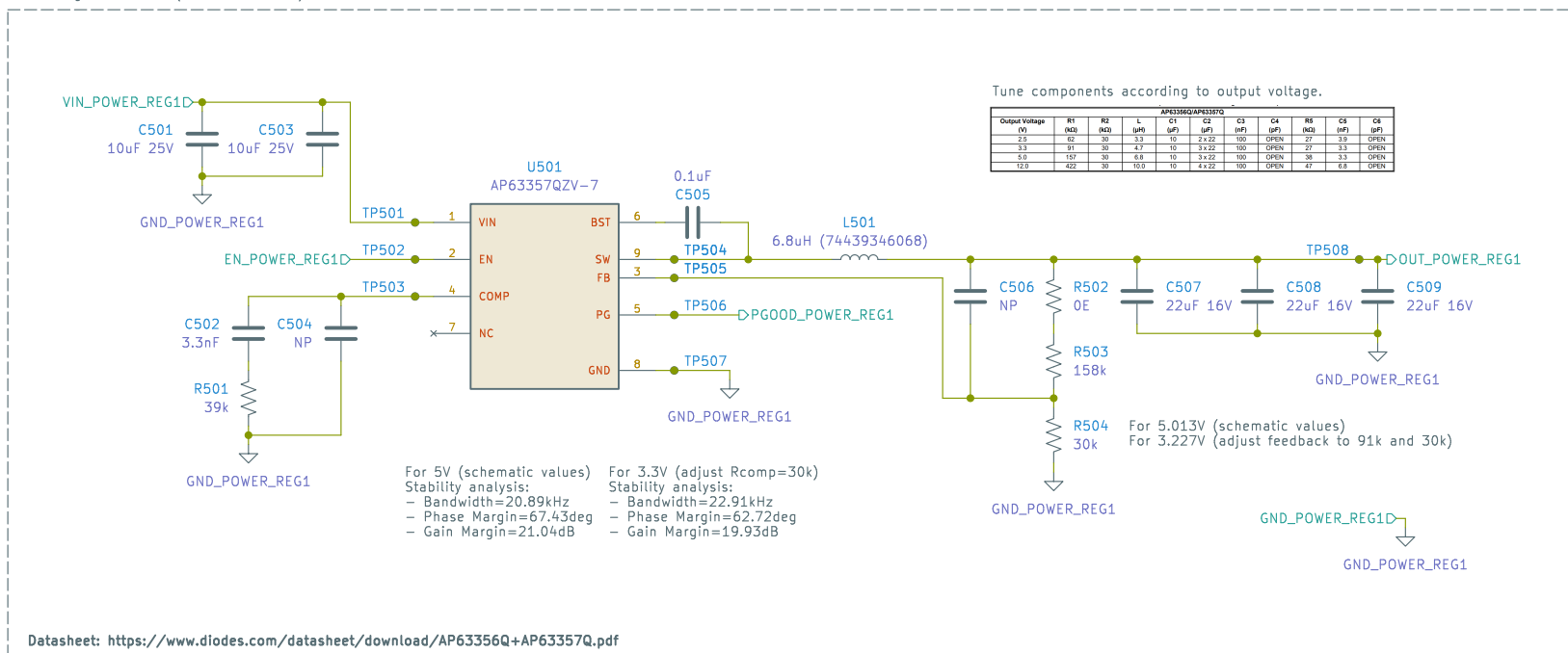
Distributed Open-source as: CC BY-SA 4.0
Design implements a battery management system and power deliver for use with the developed autonomous robot platform powered by LEGO Technic HUB and Raspberry Pi

Sheet: /POWER_SUPPLY/LOAD_SW/
File: switch.kicad_sch

Title: Power delivery Board

Size: A4	Date: 2025-06-25	Rev: B
KiCad E.D.A. 9.0.0		Id: 4/14

Power Regulator BUCK (Pi and MCU PSU)



Distributed Open-source as: CC BY-SA 4.0
Design implements a battery management system and power delivery for use with the developed autonomous robot platform powered by LEGO Technic HUB and Raspberry Pi

Sheet: /POWER_SUPPLY/POWER_REG1/
File: regulator.kicad_sch

Title: Power delivery Board

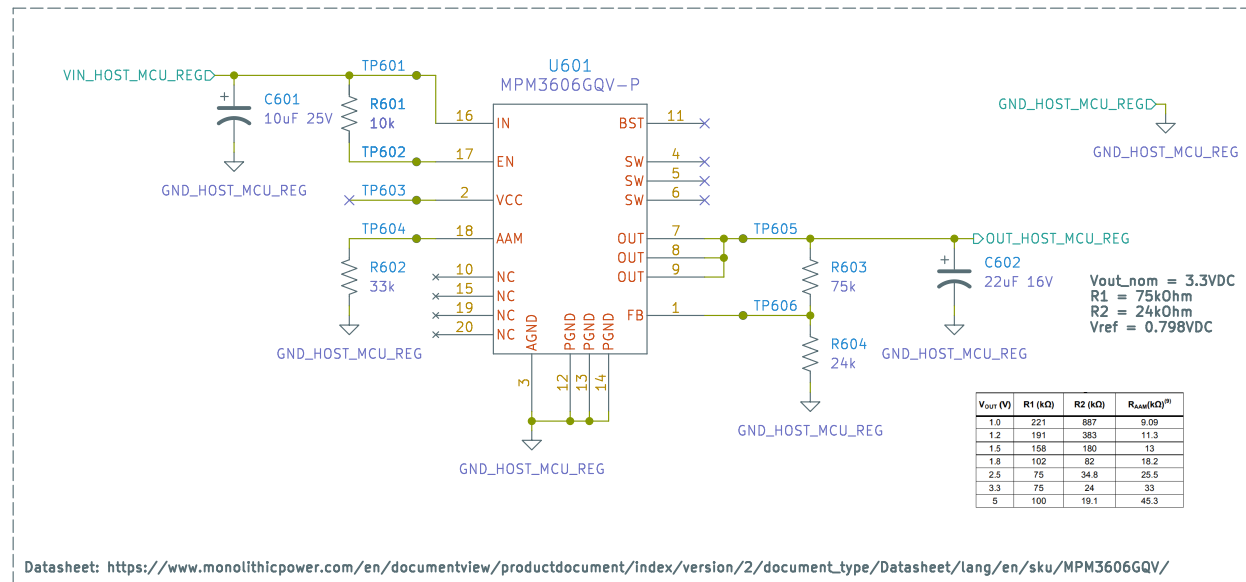
Size: A4 Date: 2025-06-25

KiCad E.D.A. 9.0.0

Rev: B

Id: 5/14

Power Regulator 3.3V 2V (MCU and sensors)



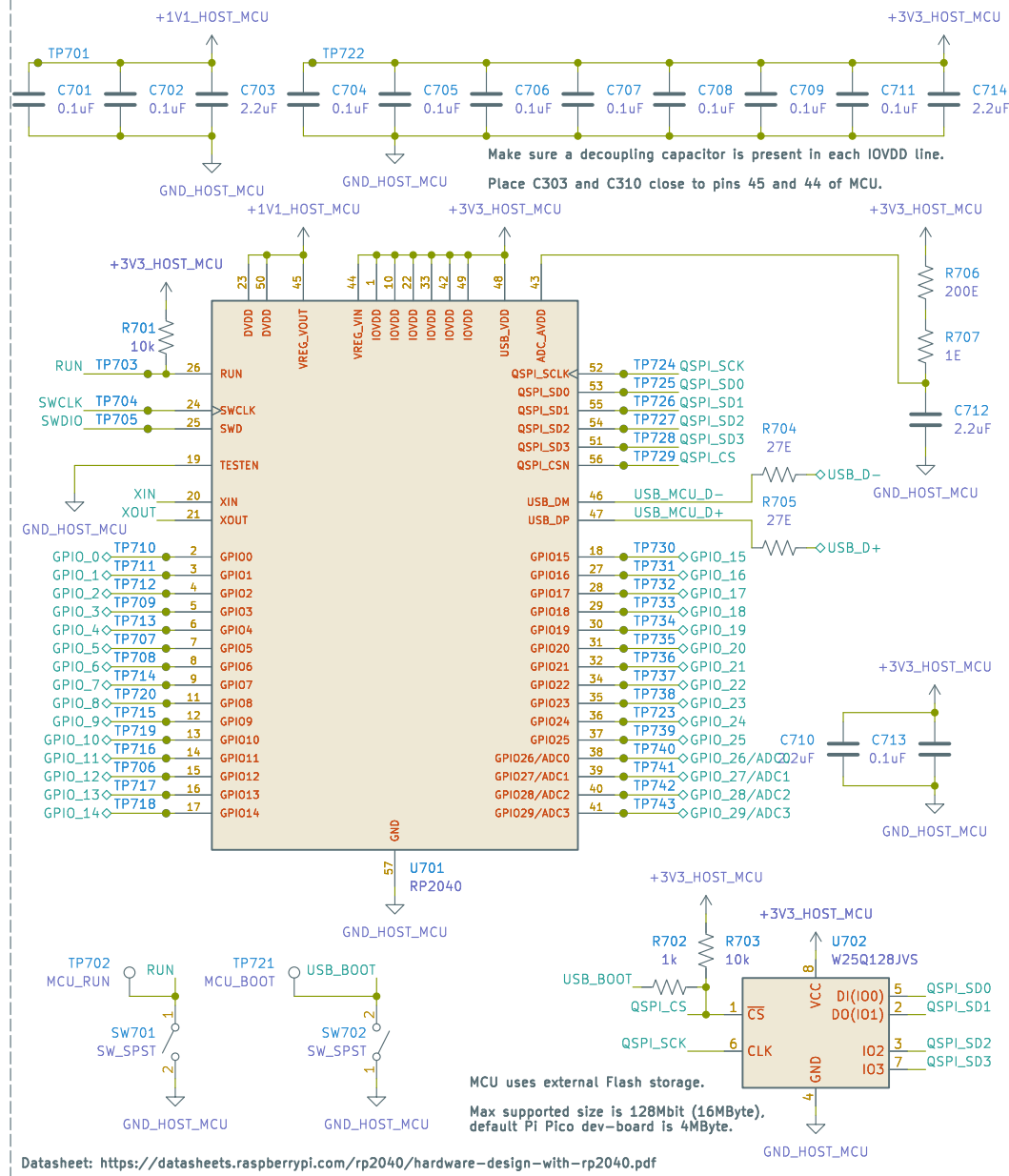
Distributed Open-source as: CC BY-SA 4.0
Design implements a battery management system and power deliver for use with the developed autonomous robot platform powered by LEGO Technic HUB and Rasberry Pi

Sheet: /POWER_SUPPLY/HOST_MCU_REG/
File: host_mcu_regulator.kicad_sch

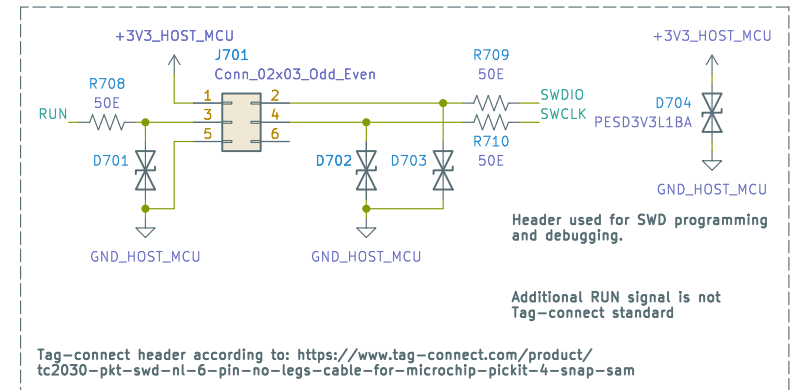
Title: Power delivery Board

Size: A4	Date: 2025-06-25	Rev: B
KiCad E.D.A. 9.0.0		Id: 6/14

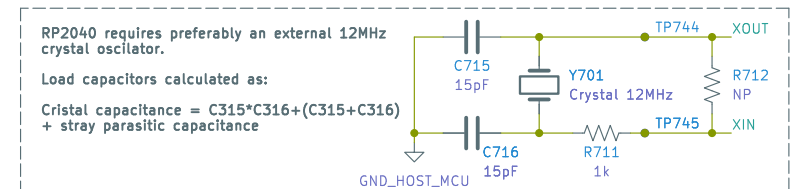
RP2040 Main MCU



SWD programming header



Crystal oscillator



Distributed Open-source as: CC BY-SA 4.0
Design implements a battery management system and power deliver for use with the developed autonomous robot platform powered by LEGO Technic HUB and Rasberry Pi

Sheet: /POWER_SUPPLY/HOST_MCU/
File: host_mcu.kicad_sch

Title: Power delivery Board

Size: A4	Date: 2025-06-25	Rev: B
KiCad E.D.A. 9.0.0		Id: 7/14

Current Limit Switch with Reverse Current Blocking and Output Over-voltage Clamp

Minimum input voltage set in VLIM
 $V_{INMIN} = 1.2 \times (R_H + R_L) / R_L$

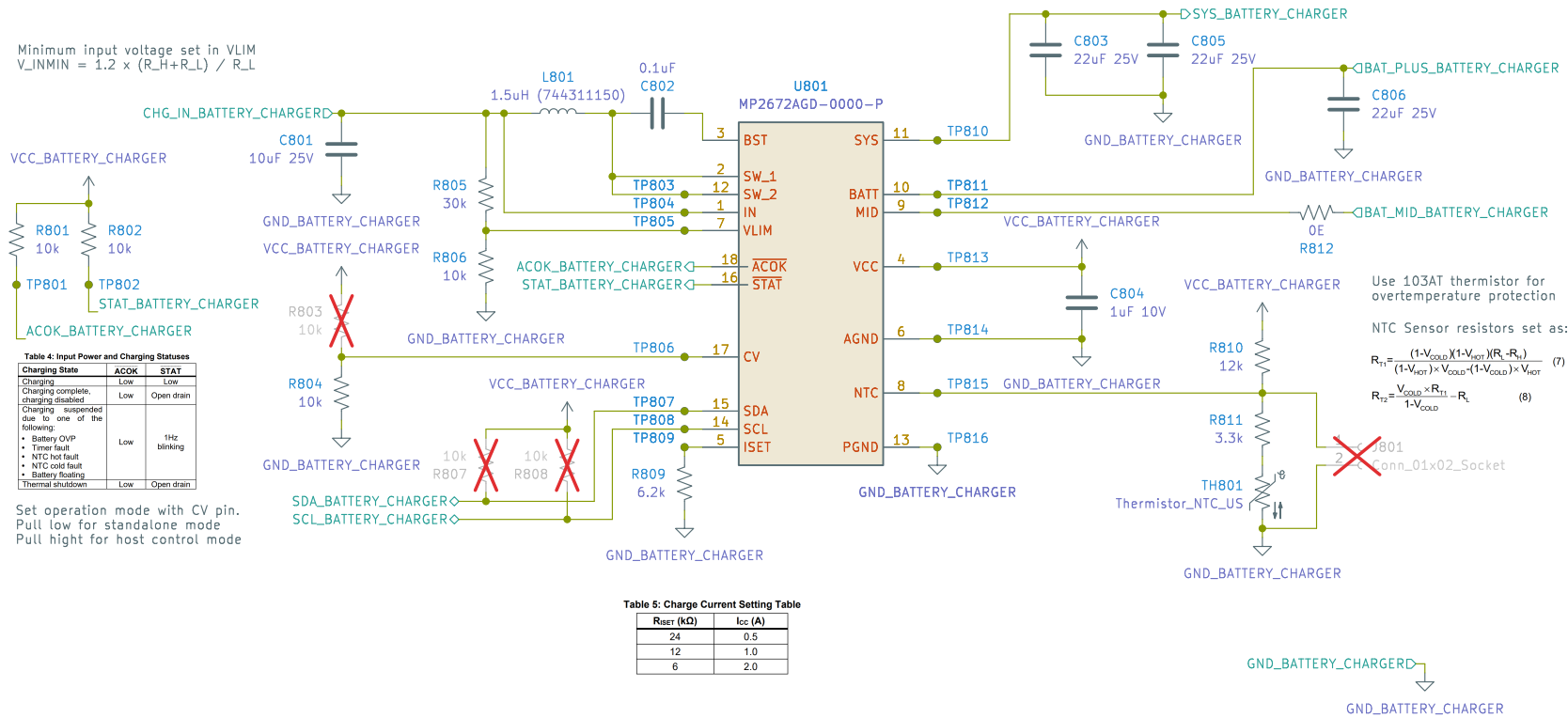


Table 4: Input Power and Charging Statuses

Charging State	ACOK	STAT
Charging	Low	Low
Charging complete, charging disabled	Low	Open drain
Charging suspended due to one of the following:		
• Battery OVP	Low	1Hz blinking
• Timer fault		
• NTC hot fault		
• NTC cold fault		
• Battery floating		
Thermal shutdown	Low	Open drain

Set operation mode with CV pin.
 Pull low for standalone mode
 Pull high for host control mode

Table 5: Charge Current Setting Table

R _{SET} (kΩ)	I _{CC} (A)
24	0.5
12	1.0
6	2.0

Datasheet: https://www.monolithicpower.com/en/documentview/productdocument/index/version/2/document_type/Datasheet/lang/en/sku/MP2672AGD/document_id/9059/

Distributed Open-source as: CC BY-SA 4.0

Design implements a battery management system and power deliver for use with the developed autonomous robot platform powered by LEGO Technic HUB and Raspberry Pi

Sheet: /POWER_SUPPLY/BATTERY_CHARGER/

File: battery.kicad_sch

Title: Power delivery Board

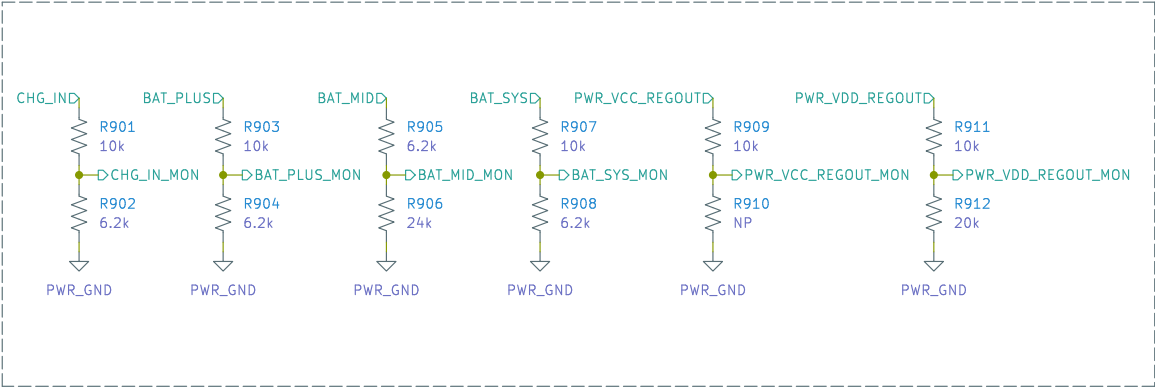
Size: A4 Date: 2025-06-25

KiCad E.D.A. 9.0.0

Rev: B

Id: 8/14

Power Monitoring Voltage Dividers



Distributed Open-source as: CC BY-SA 4.0
Design implemets a battery management system and power delivert for use with
the developed autonomous robot platform powered by LEGO Technic HUB and Rasberry Pi

Sheet: /POWER_SUPPLY/MONITORS/
File: vmonitor.kicad_sch

Title: Power delivery Board

Size: A4	Date: 2025-06-25	Rev: B
KiCad E.D.A. 9.0.0		Id: 9/14

The image contains two circuit diagrams, each showing a 2-to-1 multiplexer implemented using a 74AHC1G08 hex inverter. The left diagram shows a 2-to-1 multiplexer for IN1A and IN2A, with outputs OUTA and OUTB. The right diagram shows a 2-to-1 multiplexer for IN1B and IN2B, with outputs OUTB and OUTC. Both diagrams include VCC and GND connections for the regulators and the multiplexer.

Sheet: /POWER_SUPPLY/REGULATOR_SEQ/
File: regulator_enable.kicad_sch

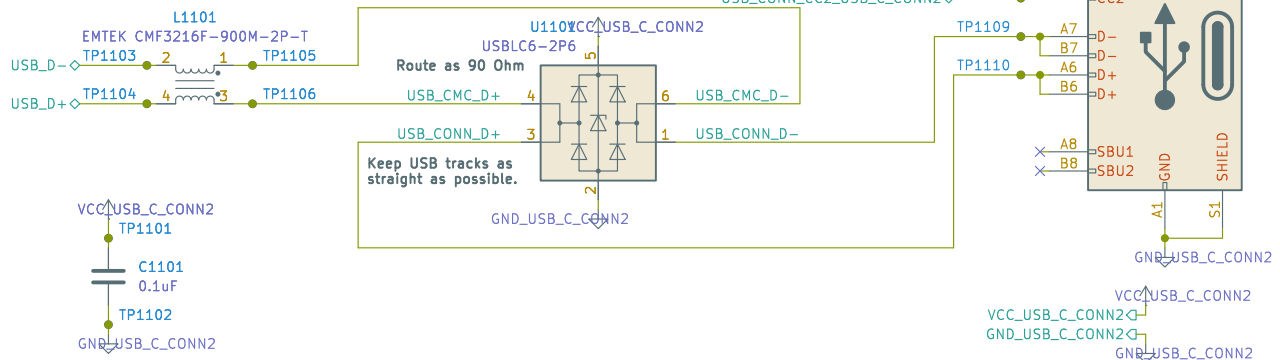
KiCad E.D.A. 9.0.0

Id: 10/14

USB power and data through type C port

ESD protection and data line filtering
for better EMC compliance.

Place USB port close to MCU
and away from power supply.



Distributed Open-source as: CC BY-SA 4.0
Design implements a battery management system and power deliver for use with
the developed autonomous robot platform powered by LEGO Technic HUB and Rasberry Pi

Sheet: /USB_C_CONN2/
File: usb.kicad_sch

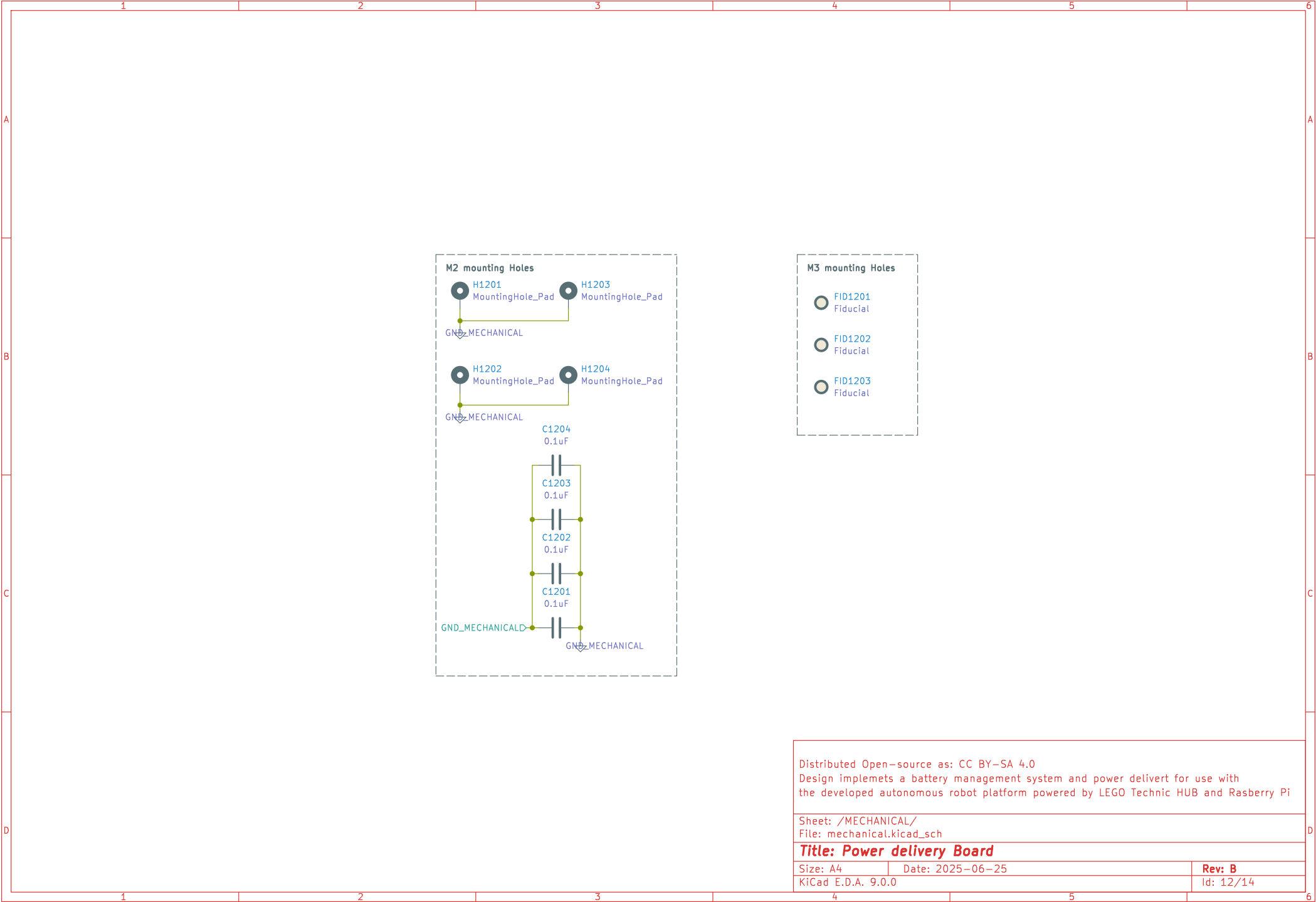
Title: Power delivery Board

Size: A4 Date: 2025-06-25

KiCad E.D.A. 9.0.0

Rev: B

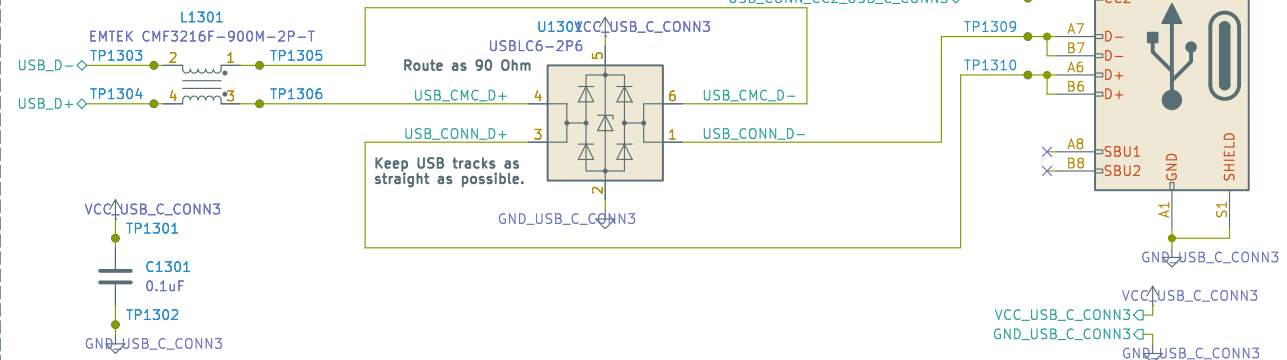
Id: 11/14



USB power and data through type C port

ESD protection and data line filtering
for better EMC compliance.

Place USB port close to MCU
and away from power supply.



Distributed Open-source as: CC BY-SA 4.0
Design implements a battery management system and power deliver for use with
the developed autonomous robot platform powered by LEGO Technic HUB and Rasberry Pi

Sheet: /USB_C_CONN3/
File: usb.kicad_sch

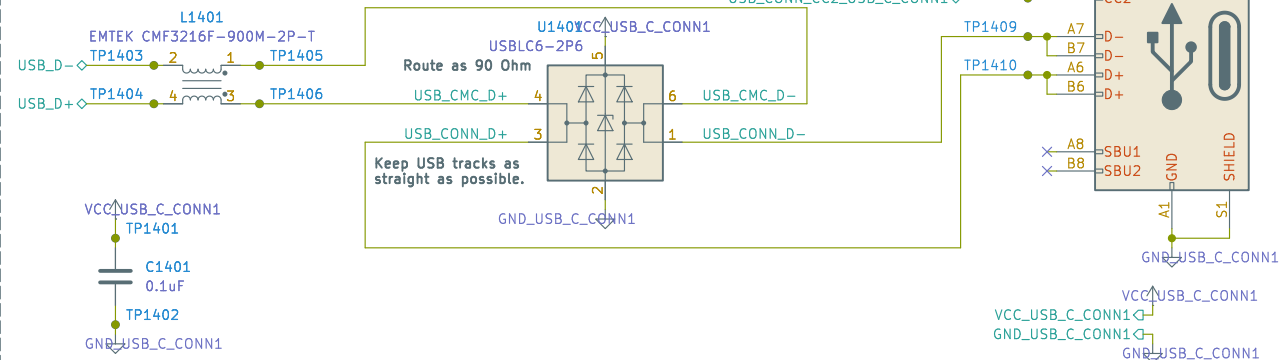
Title: Power delivery Board

Size: A4	Date: 2025-06-25	Rev: B
KiCad E.D.A. 9.0.0		Id: 13/14

USB power and data through type C port

ESD protection and data line filtering
for better EMC compliance.

Place USB port close to MCU
and away from power supply.



Distributed Open-source as: CC BY-SA 4.0
Design implements a battery management system and power deliver for use with
the developed autonomous robot platform powered by LEGO Technic HUB and Rasberry Pi

Sheet: /USB_C_CONN1/
File: usb.kicad_sch

Title: Power delivery Board

Size: A4 Date: 2025-06-25

KiCad E.D.A. 9.0.0

Rev: B

Id: 14/14