Skewness and Kurtosis

We want to show the structure of simple functions in R and Python. To illustrate how to create those functions (without exceptions or testing for data type), we will implement the formulas for skewness and kurtosis of a random sample and compare with inbuilt functions. The skewness, which is a measure of asymmetry, is defined as:

$$Skewness = \frac{\frac{1}{n} \sum_{i=1}^{n} (x_i - \bar{x})^3}{\frac{1}{n} \sum_{i=1}^{n} (x_i - \bar{x})^{(3/2)}}$$

The kurtosis is a measure of 'tailedness' (how fat a distribution is) and is defined as:

$$Kurtosis = \frac{\frac{1}{n} \sum_{i=1}^{n} (x_i - \bar{x})^4}{\left(\frac{1}{n} \sum_{i=1}^{n} (x_i - \bar{x})^2\right)^2}$$

Skewness and Kurtosis in R

```
1 library (moments)
 2
 3 # generate a vector x of Normal data
 4 x = rnorm(100, 4, 1.5)
 6 # skewness and kurtosis functions
 7 myskewness=function(x) {
 8 m = mean(x)
 9 \quad diff = (x-m)
10  num = mean(diff^3)
11 den = (mean(diff^2))^(3/2)
12 num/den
13 }
14
15 mykurtosis = function(x) {
16 \quad m = mean(x)
17 \quad diff = (x-m)
18 num = mean(diff^4)
19 den = mean(diff^2)^2
20 (num/den)
21 }
22
23 mvskewness(x) # [1] 0.03989365
24 skewness(x) # [1] 0.04009463
25 mykurtosis(x) # [1] 2.693733
26 kurtosis(x) # [1] 2.693733
```

Skewness and Kurtosis in Python

```
1 import numpy as np
2 from scipy.stats import skew, kurtosis
4 # Generate a vector v of Normal data
5 \times = np.random.normal(4, 1.5, 100)
    Skewness and Kurtosis function
8 def mvskewness(x):
  m = np.mean(x)
10
     diff = x - m
    num = np.mean(diff**3)
11
12 den = np.std(x, ddof=1)**3
13
     return num / den
14
15 def mvkurtosis(x):
16 \quad m = np.mean(x)
17
    diff = x - m
18    num = np.mean(diff**4)
19
      den = np.mean(diff**2)**2
20
      return num / den
21
22 print("Custom Skewness:", myskewness(x))
23 print("Scipy Skewness:", skew(x))
24 print("Custom Kurtosis:", mvkurtosis(x))
25 print("Scipy Kurtosis:", kurtosis(x))
```