Master en Técnicas de conservación de la biodiversidad y ecología

Modelización: Modelos biofísicos en ecología

Juanvi G. Rubalcaba

Marie-Curie Fellow McGill & URJC

jg.rubalcaba@gmail.com

¿Si aumenta 1ºC la temperatura ambiente, cuánto cambia la temperatura del cuerpo?



Modelo biofísico

Modelo comportamental

Aumento esperado (nivel macroclimático)

Aumento real (microclima)

Aumento de temperatura corporal

+1.2 ºC (sol) +0.8 ºC (sombra)

Aumento de temperatura corporal

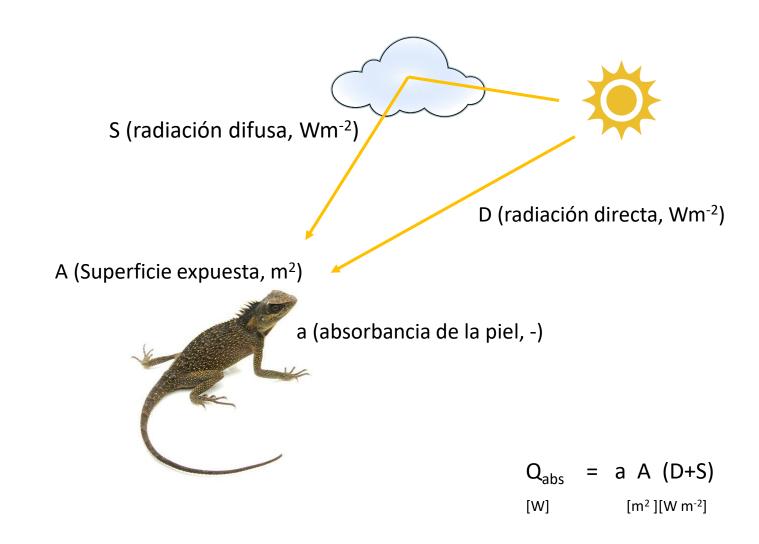
e.g., pasa más tiempo a la sombra

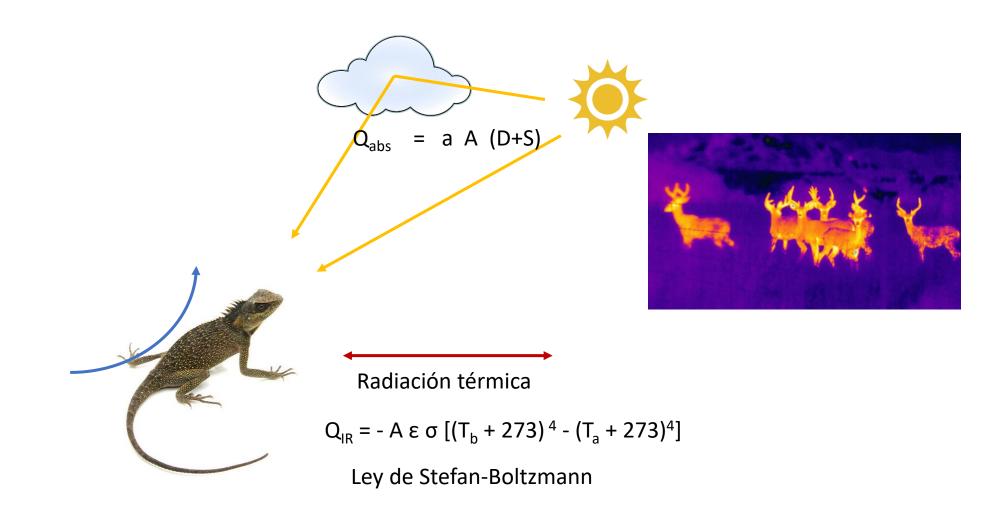
Modelo ectotermo

Modelo biofísico

$$C = \frac{d Tb}{dt}$$
 = Entrada de calor — Salida de calor





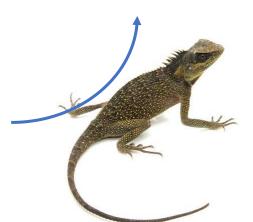


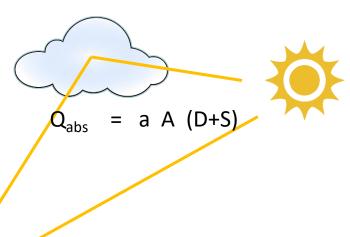
$$Q_{conv} = -Ah_c(T_b - T_a)$$

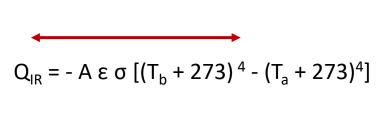
[W] [m²] [Wm-² ºC-1] [ºC]

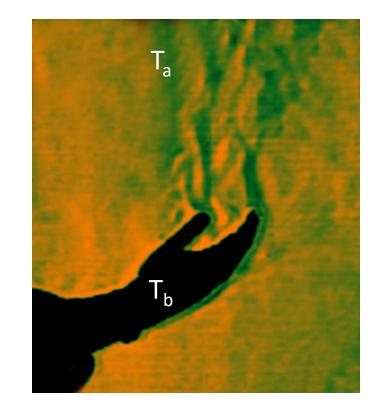
h_c: coeficiente de convección

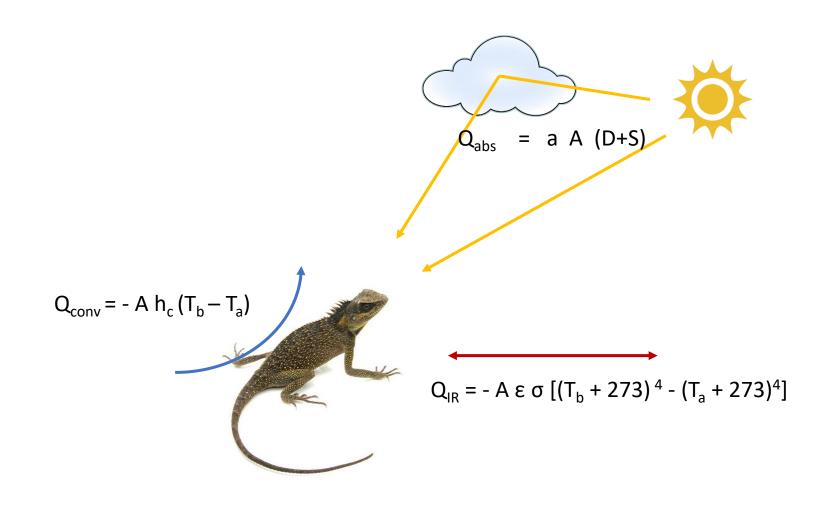
 $h_c = a \times velocidad viento^b \times longitud cuerpo^{-c}$











 $Q_{net} = Q_{abs} + Q_{IR} + Q_{conv}$

Transferencia de calor

$$Q_{net} = Q_{abs} + Q_{IR} + Q_{conv}$$

$$[W] = [J S^{-1}]$$

 $[W] = [J s^{-1}]$ Tasa de transferencia de calor

Temperatura corporal, T_b

$$\frac{dT_b}{dt} = \frac{1}{MC} Q_{net}$$

$$\frac{1}{MC} Q_{net} \qquad \frac{[^{9}C]}{[s]} = \frac{1}{[g][J g^{-1} {}^{9}C^{-1}]} \qquad \text{Tasa de cambio de temperatura}$$

$$M = masa(g)$$

 $C = capacidad calorífica (J g^{-1} \circ C^{-1})$

Temperatura corporal, T_b

$$\mathbf{Q}_{net} = \mathbf{Q}_{abs} + \mathbf{Q}_{IR} + \mathbf{Q}_{conv}$$

$$\mathbf{Q}_{abs} = \mathbf{A} \text{ a } (\mathbf{D} + \mathbf{S})$$

$$\mathbf{Q}_{IR} = -\mathbf{A} \varepsilon \sigma (\mathbf{T}_b^4 - \mathbf{T}_a^4)$$

$$\mathbf{Q}_{conv} = -\mathbf{A} \mathbf{h}_c (\mathbf{T}_b - \mathbf{T}_a)$$

$$\Delta T_b = \frac{1}{MC} Q_{net}$$



Parámetros del lagarto (tamaño, forma y color)

$$A = 0.0029 \text{ m}^2$$

$$C = 3.7 \text{ J g}^{-1} \, {}^{\circ}\text{C}^{-1}$$

$$a = 0.9$$

Parámetros ambientales

$$D = 400 \text{ Wm}^{-2}$$

$$v = 0.8 \text{ m s}^{-1}$$



| Tb | \mathbf{Q}_{abs} | \mathbf{Q}_{IR} | \mathbf{Q}_{conv} |
|--------|--|--|--|
| 20.000 | 1.263 | 0.000 | 0.000 |
| 20.792 | 1.263 | -0.012 | -0.044 |
| 21.620 | 1.263 | -0.024 | -0.089 |
| 22.490 | 1.263 | -0.038 | -0.137 |
| 23.408 | 1.263 | -0.052 | -0.188 |
| 24.385 | 1.263 | -0.067 | -0.242 |
| 25.433 | 1.263 | -0.083 | -0.300 |
| 26.569 | 1.263 | -0.101 | -0.362 |
| 27.820 | 1.263 | -0.121 | -0.431 |
| 29.227 | 1.263 | -0.144 | -0.509 |
| | 20.000 20.792 21.620 22.490 23.408 24.385 25.433 26.569 27.820 | 20.000 1.263 20.792 1.263 21.620 1.263 22.490 1.263 23.408 1.263 24.385 1.263 25.433 1.263 26.569 1.263 27.820 1.263 | 20.000 1.263 0.000 20.792 1.263 -0.012 21.620 1.263 -0.024 22.490 1.263 -0.038 23.408 1.263 -0.052 24.385 1.263 -0.067 25.433 1.263 -0.083 26.569 1.263 -0.101 27.820 1.263 -0.121 |

Temperatura corporal, T_b

$$\mathbf{Q}_{net} = \mathbf{Q}_{abs} + \mathbf{Q}_{IR} + \mathbf{Q}_{conv}$$

$$\mathbf{Q}_{abs} = \mathbf{A} \text{ a } (\mathbf{D} + \mathbf{S})$$

$$\mathbf{Q}_{IR} = -\mathbf{A} \varepsilon \sigma (\mathbf{T}_b^4 - \mathbf{T}_a^4)$$

$$\mathbf{Q}_{conv} = -\mathbf{A} \mathbf{h}_c (\mathbf{T}_b - \mathbf{T}_a)$$

$$\Delta T_b = \frac{1}{MC} Q_{net}$$



Parámetros del lagarto (tamaño, forma y color)

$$M = 5g$$

$$A = 0.0029 \text{ m}^2$$

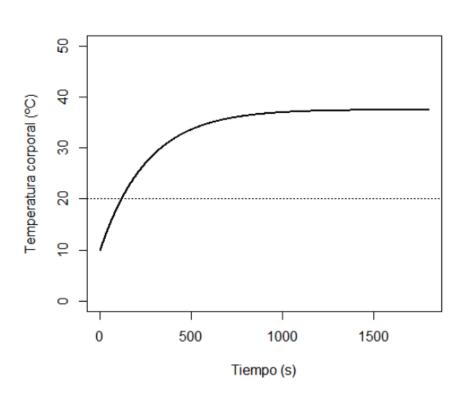
$$a = 0.9$$

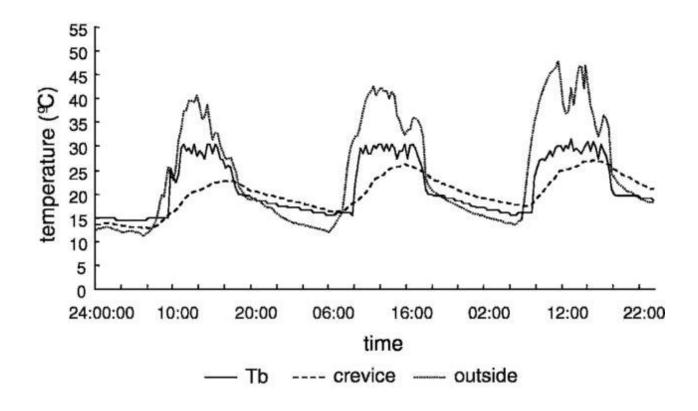
Parámetros ambientales

$$D = 400 \text{ Wm}^{-2}$$

$$v = 0.8 \text{ m s}^{-1}$$









Pseudocordylus melanotus

Técnicas de conservación de la biodiversidad y ecología

Modelos biofísicos: Práctica

Modelo de ectotermo

Juanvi G. Rubalcaba

jg.rubalcaba@gmail.com





modelo transitorio de transferencia de calor

$$\frac{dT_b}{dt} = \frac{1}{cM}(Q_{abs} + Q_{IR} + Q_{conv})$$

$$T_b(t) = T_b(t-1) + \Delta t \frac{1}{cM} (Q_{abs} + Q_{IR} + Q_{conv})$$
 Solución numérica (método de Euler)

Solución numérica por iteración



modelo transitorio de transferencia de calor

$$\frac{dT_b}{dt} = \frac{1}{cM}(Q_{abs} + Q_{IR} + Q_{conv})$$

$$\frac{dT_b}{Q_{abs} + Q_{IR} + Q_{conv}} = \frac{1}{cM}dt$$

$$\int \frac{dT_b}{Q_{abs} + Q_{IR} + Q_{conv}} = \int \frac{1}{cM} dt$$

•••

$$T_b(t) = \cdots \exp(\dots tiempo)$$

$$cM\frac{dT_b}{dt} = Q_{abs} + Q_{IR} + Q_{conv}$$

$$cM\frac{dT_b}{dt} = Aa(D+S) - A\varepsilon\sigma(T_b^4 - T_a^4) - Ah_c(T_b - T_a)$$



$$cM\frac{dT_b}{dt} = Q_{abs} + Q_{IR} + Q_{conv}$$

$$cM\frac{dT_b}{dt} = Aa(D+S) - A\varepsilon\sigma(T_b^4 - T_a^4) - Ah_c(T_b - T_a)$$
$$A4\varepsilon\sigma T_a^3(T_b - T_a)$$



$$cM\frac{dT_b}{dt} = Q_{abs} + Q_{IR} + Q_{conv}$$

$$cM\frac{dT_b}{dt} = Aa(D+S) - A\varepsilon\sigma(T_b^4 - T_a^4) - Ah_c(T_b - T_a)$$

$$A4\varepsilon\sigma T_a^3(T_b - T_a)$$

$$AR(T_b - T_a)$$



$$cM\frac{dT_b}{dt} = Q_{abs} + Q_{IR} + Q_{conv}$$

$$cM\frac{dT_b}{dt} = Aa(D+S) - AR(T_b - T_a) - Ah_c(T_b - T_a)$$



$$cM\frac{dT_b}{dt} = Q_{abs} + Q_{IR} + Q_{conv}$$

$$cM\frac{dT_b}{dt} = Aa(D+S) - AR(T_b - T_a) - Ah_c(T_b - T_a)$$

$$\frac{dT_b}{dt} = \frac{Aa}{cM}(D+S) - \frac{AR}{cM}(T_b - T_a) + \frac{Ah_c}{cM}(T_b - T_a)$$



$$\frac{dT_b}{dt} = \frac{Aa}{cM}(D + S) - \left(\frac{A(R + h_c)}{cM}\right)(T_b - T_a)$$

$$cM\frac{dT_b}{dt} = Q_{abs} + Q_{IR} + Q_{conv}$$

$$cM\frac{dT_b}{dt} = Aa(D+S) - AR(T_b - T_a) - Ah_c(T_b - T_a)$$

$$\frac{dT_b}{dt} = \frac{Aa}{cM}(D+S) - \frac{AR}{cM}(T_b - T_a) + \frac{Ah_c}{cM}(T_b - T_a)$$



$$\frac{dT_b}{dt} = \frac{Aa}{cM}(D + S) - \left(\frac{A(R + h_c)}{cM}\right)(T_b - T_a)$$

$$\frac{dT_b}{dt} = \frac{Aa}{cM}(D + S) - \left(\frac{A(R + h_c)}{cM}\right)T_b - \left(\frac{A(R + h_c)}{cM}\right)T_a$$

$$\frac{dT_b}{dt} + \left(\frac{A(R + h_c)}{cM}\right)T_b = \frac{Aa}{cM}(D + S) - \left(\frac{A(R + h_c)}{cM}\right)T_a$$

$$\frac{dy}{dt} + \theta y = j$$



$$\frac{dT_b}{dt} + \left(\frac{A(R+h_c)}{cM}\right)T_b = \frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right)T_a$$

$$\frac{dy}{dt} \qquad \theta y \qquad j$$

$$\frac{dy}{dt} + \theta y = j$$



modelo transitorio de transferencia de calor

$$\frac{dT_b}{dt} + \left(\frac{A(R+h_c)}{cM}\right)T_b = \frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right)T_a$$

$$\frac{dy}{dt} \qquad \theta y \qquad j$$

$$\frac{dy}{dt} + \theta y = j$$

$$\frac{dy}{dt} + \theta y = j y = y_{equilibrio} + y_{transición}$$

 $y_{transición}$

$$\frac{dy}{dt} + \theta y = 0$$

$$\frac{dy}{dt} = -\theta y$$



modelo transitorio de transferencia de calor

$$\frac{dT_b}{dt} + \left(\frac{A(R+h_c)}{cM}\right)T_b = \frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right)T_a$$

$$\frac{dy}{dt} \qquad \theta y \qquad j$$

$$\frac{dy}{dt} + \theta y = j$$

$$\frac{dy}{dt} + \theta y = j y = y_{equilibrio} + y_{transición}$$

 $y_{transición}$

$$\frac{dy}{dt} + \theta y = 0$$

$$\frac{dy}{dt} = -\theta y$$

$$y_{transición}(t) = C_1 e^{-\theta t}$$



modelo transitorio de transferencia de calor

$$\begin{bmatrix} \frac{dT_b}{dt} \\ \frac{dT_b}{dt} \\ \end{bmatrix} + \begin{bmatrix} \frac{A(R+h_c)}{cM} \\ \end{bmatrix} T_b = \begin{bmatrix} \frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right) T_a \\ \frac{dy}{dt} \\ \end{bmatrix}$$

$$\frac{dy}{dt} + \theta y = j$$

$$\frac{dy}{dt} + \theta y = j y = y_{equilibrio} + y_{transición}$$

$$y_{transición}(t) = C_1 e^{-\theta t}$$

 $y_{equilibrio}$



modelo transitorio de transferencia de calor

$$\begin{bmatrix} \frac{dT_b}{dt} + \left(\frac{A(R+h_c)}{cM} \right) T_b = \frac{Aa}{cM} (D+S) - \left(\frac{A(R+h_c)}{cM} \right) T_a \end{bmatrix}$$

$$\frac{dy}{dt} \qquad \theta y \qquad j$$

$$\frac{dy}{dt} + \theta y = j$$

$$\frac{dy}{dt} + \theta y = j y = y_{equilibrio} + y_{transición}$$

$$y_{transición}(t) = C_1 e^{-\theta t}$$

 $y_{equilibrio}$

$$0 + \theta y = j$$

$$\theta y = j$$

$$y_{equilibrio} = \frac{\dot{J}}{\theta}$$



$$\begin{bmatrix} \frac{dT_b}{dt} \\ \frac{dT_b}{dt} \end{bmatrix} + \begin{bmatrix} \frac{A(R+h_c)}{cM} \\ \frac{dS}{dt} \end{bmatrix} T_b = \begin{bmatrix} \frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right)T_a \\ \frac{dS}{dt} \end{bmatrix}$$

$$\frac{dy}{dt} + \theta y = j$$

$$\frac{dy}{dt} + \theta y = j y = y_{equilibrio} + y_{transición}$$

$$y_{transición}(t) = C_1 e^{-\theta t}$$

$$y_{equilibrio} = \frac{j}{\theta}$$



$$\begin{bmatrix} \frac{dT_b}{dt} \\ \frac{dT_b}{dt} \\ \end{bmatrix} + \begin{bmatrix} \frac{A(R+h_c)}{cM} \\ \frac{dy}{dt} \end{bmatrix} T_b = \begin{bmatrix} \frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right)T_a \\ \frac{dy}{dt} \\ \end{bmatrix}$$

$$\frac{dy}{dt} + \theta y = j$$

$$\frac{dy}{dt} + \theta y = j y = y_{equilibrio} + y_{transición}$$

$$y_{transición}(t) = C_1 e^{-\theta t}$$

$$y_{equilibrio} = \frac{j}{\theta}$$

$$y = \frac{j}{\theta} + C_1 e^{-\theta t}$$



modelo transitorio de transferencia de calor

$$\frac{dT_b}{dt} + \left(\frac{A(R+h_c)}{cM}\right)T_b = \frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right)T_a$$

$$\frac{dy}{dt} \qquad \theta y \qquad j$$

$$y_{transición}(t) = C_1 e^{-\theta t}$$

$$y_{equilibrio} = \frac{j}{\theta}$$

$$y_{equilibrio} = \frac{j}{\theta}$$
$$y = \frac{j}{\theta} + C_1 e^{-\theta t}$$



Condiciones iniciales

modelo transitorio de transferencia de calor

$$\frac{dT_b}{dt} + \left(\frac{A(R+h_c)}{cM}\right)T_b = \frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right)T_a$$

$$\frac{dy}{dt} \qquad \theta y \qquad j$$

$$y_{transición}(t) = C_1 e^{-\theta t}$$

$$y_{equilibrio} = \frac{\dot{J}}{\theta}$$

$$y = \frac{j}{\theta} + C_1 e^{-\theta t}$$



Condiciones iniciales

$$y(t=0) = y_0 = \frac{j}{\theta} + C_1 e^{-\theta t}$$

$$C_1 = y_0 - \frac{j}{\theta}$$

modelo transitorio de transferencia de calor

$$\frac{dT_b}{dt} + \left(\frac{A(R+h_c)}{cM}\right)T_b = \frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right)T_a$$

$$\frac{dy}{dt} \qquad \theta y \qquad j$$

$$y_{transición}(t) = C_1 e^{-\theta t}$$

$$y_{equilibrio} = \frac{j}{\theta}$$

$$y = \frac{j}{\theta} + C_1 e^{-\theta t}$$



Condiciones iniciales

$$y(t=0) = y_0 = \frac{j}{\theta} + C_1 e^{-\theta t}$$

$$C_1 = y_0 - \frac{j}{\theta}$$

$$y(t) = \frac{j}{\theta} + \left(y_0 - \frac{j}{\theta}\right)e^{-\theta t}$$

$$\frac{dT_b}{dt} + \left(\frac{A(R+h_c)}{cM}\right)T_b = \frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right)T_a$$

$$\frac{dy}{dt} \qquad \theta y \qquad j$$

$$y(t) = \frac{j}{\theta} + \left(y_0 - \frac{j}{\theta}\right)e^{-\theta t}$$



$$\frac{dT_b}{dt} + \left(\frac{A(R+h_c)}{cM}\right)T_b = \frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right)T_a$$

$$\frac{dy}{dt} \qquad \theta y \qquad j$$

$$y(t) = \frac{j}{\theta} + \left(y_0 - \frac{j}{\theta}\right)e^{-\theta t}$$

$$\frac{j}{\theta} = \frac{\frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right)T_a}{\frac{A(R+h_c)}{cM}}$$

$$\frac{j}{\theta} = T_a + \frac{a(D+S)}{R+h_c}$$

$$\begin{bmatrix} \frac{dT_b}{dt} \\ \frac{dS}{dt} \end{bmatrix} + \begin{bmatrix} \frac{A(R+h_c)}{cM} \\ \frac{dS}{dt} \end{bmatrix} T_b = \begin{bmatrix} \frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right)T_a \\ \frac{dS}{dt} \end{bmatrix}$$

$$y(t) = \frac{j}{\theta} + \left(y_0 - \frac{j}{\theta}\right)e^{-\theta t}$$

$$\frac{j}{\theta} = \frac{\frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right)T_a}{\frac{A(R+h_c)}{cM}}$$



$$\frac{j}{\theta} = T_a + \frac{a(D+S)}{R+h_c} = T_e$$

$$\frac{dT_b}{dt} + \left(\frac{A(R+h_c)}{cM}\right)T_b = \frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right)T_a$$

$$\frac{dy}{dt} \qquad \theta y \qquad j$$

$$\frac{j}{\theta} = T_a + \frac{a(D+S)}{R+h_c} = T_e$$

$$y(t) = \frac{j}{\theta} + \left(y_0 - \frac{j}{\theta}\right)e^{-\theta t}$$

$$\theta = \frac{A(R + h_c)}{cM}$$



$$\frac{dT_b}{dt} + \left(\frac{A(R+h_c)}{cM}\right)T_b = \frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right)T_a$$

$$\frac{dy}{dt} \qquad \theta y \qquad j$$

$$y(t) = \frac{j}{\theta} + \left(y_0 - \frac{j}{\theta}\right)e^{-\theta t}$$

$$\frac{j}{\theta} = T_a + \frac{a(D+S)}{R+h_c} = T_e$$

$$\theta = \frac{A(R + h_c)}{cM}$$



$$\begin{bmatrix} \frac{dT_b}{dt} \\ \frac{dS}{dt} \end{bmatrix} + \begin{bmatrix} \frac{A(R+h_c)}{cM} \\ \frac{dS}{dt} \end{bmatrix} T_b = \begin{bmatrix} \frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right)T_a \\ \frac{dS}{dt} \end{bmatrix}$$

$$y(t) = \frac{j}{\theta} + \left(y_0 - \frac{j}{\theta}\right)e^{-\theta t}$$

$$\frac{j}{\theta} = T_a + \frac{a(D+S)}{R+h_c} = T_e$$

$$\theta = \frac{A(R + h_c)}{cM}$$

$$y(t) = T_e + (T_0 - T_e)e^{-\frac{A(R+h_c)}{cM}t}$$



$$\frac{\frac{dT_b}{dt}}{dt} + \left(\frac{A(R+h_c)}{cM}\right)T_b = \frac{Aa}{cM}(D+S) - \left(\frac{A(R+h_c)}{cM}\right)T_a$$

$$\frac{dy}{dt} \qquad \theta y \qquad j$$

$$y(t) = \frac{j}{\theta} + \left(y_0 - \frac{j}{\theta}\right)e^{-\theta t}$$

$$\frac{j}{\theta} = T_a + \frac{a(D+S)}{R+h_c} = T_e$$

$$\theta = \frac{A(R + h_c)}{cM}$$

$$y(t) = T_e + (T_0 - T_e)e^{-\frac{A(R+h_c)}{cM}t}$$



$$T_e = T_a + \frac{a(D+S)}{R+h_c}$$