

# **Autonomous Mobile Robots**

# LD Series

# Designed to automate material transport tasks in factories and indoor facilities.

• Natural-feature navigation:

Automatically plans efficient routes and prevents collisions

• Fleet management:

Supervises and coordinates the entire fleet of up to 100 vehicles

· Easy deployment:

Short installation time, no facility modifications



# **Ordering Information**

Product Name	Maximum Load	Docking Station Kit*1	Top Plate	Pendant (Joystick)	Part Number
			37032-00000		
LD-60		Yes	No		37032-00002
	60 kg		Yes		37032-10004
			No		37032-20000
LD-60 ESD*2		Yes		No	37032-20002
			Yes		37032-20004
			No		37042-00000
LD-90		Yes		No	37042-00002
			Yes		37042-10004
		No		37062-00000	
LD-90x*3		Yes No		37062-00002	
	90 kg	Yes		37062-10004	
	90 kg	No		37042-20000	
LD-90 ESD*2		Yes	No		37042-20002
		Yes			37042-20004
1 D 00 F0D*2*2			No		37062-20000
LD-90x ESD*2*3		Yes	Yes No		37062-20002
			Yes		37062-20004
		No			37222-00000
LD-250		Yes	No		37222-00002
	250 kg	Yes		37222-10004	
	230 kg	No			37222-20000
LD-250 ESD*2		Yes		No	37222-20002
			Yes		

<sup>\*1</sup> Includes Battery Power Cable.

Note: To ensure proper fleet management, please contact an OMRON representative before ordering AMRs to add to an existing fleet.

Note: The battery for the AMR must be ordered separately (part number 20452-000). Before ordering lithium-ion batteries, please verify local shipping regulations to ensure compliance with applicable laws and restrictions.

<sup>\*2</sup> For use in electrostatic-sensitive environments, compliant to the IEC 61340-5-1 standard.

<sup>\*3</sup> For use in cart transporter applications.

# Items Included With the AMR

Item	Description
HMI Jumper	HDB15 male plug
Wireless Antennas Two rubber duck antennas with SMA plugs	
Labels	Warning and product labels
USB drive Contains digital product documentation and software for operating the AMR	
Printed Documentation Printed manuals and guides for unpacking and operating the AMR	

# **Accessories and Optional Items**

	Item	Details	Part Number
	EM2100 Appliance	Appliance that runs any Fleet Operations Workspace Solutions software. 120 day factory trial license included. Refer to Fleet Operations Workspace (FLOW) Licenses below for more information.	20271-900 (Primary Fleet Manager) 20271-901 (Secondary Fleet Manager) 20271-903 (Bundle with Fleet Simulator License)
	Mobile I/O Box	Used with a Fleet Manager to summon an AMR to a goal or control connected devices with I/O	23419-802
	Mobile I/O Box Power Supply	Recommended for purchase with the Mobile I/O Box	23419-812
	High Accuracy Positioning System (HAPS) Single sensor	AMR Alignment using magnetic floor tape. Includes single HAPS sensor kit, one mounting bracket, cabling, hardware, and magnetic tape (254 mm wide, 49 m long)	LD-60/90: 13660-100 LD-250: 21374-100
*	High Accuracy Positioning System (HAPS) Double sensor	AMR Alignment using magnetic floor tape. Includes double HAPS sensor kit, two mounting brackets, cabling, hardware, and magnetic tape (254 mm wide, 49 m long)	LD-60/90: 13660-000 LD-250: 21374-000
	Magnetic tape	25 mm wide magnetic tape (South top side, 49 m roll)	14925-000
		Camera, mounting kit, cables, leveling kit	13700-000
	Acuity Localization	Camera, mounting kit, cables, no leveling kit	13700-100
	Side Laser Bundle	Includes two Lasers, mounting kit, and cable	13456-000
	Side Laser Kit	Includes two lasers, two mounting kits, two metal covers, and cable	13456-100
	Battery*	Removable and rechargeable power source for the AMR.	20452-000
and the same of th	Docking Station	Used to autonomously charge the battery inside an AMR or to charge an AMR battery outside of the AMR with a battery power cable (sold separately)	12477-000
	Battery Power Cable	Cable length: 0.45 m	12676-000L

Item	Details	Part Number
Pendant (Joystick)	Handheld device for manually driving an AMR and map creation, 3 m cable length	13558-000
Digital I/O Terminal Block Kit	Provides a terminal block for the Digital I/O connector on the Core. Includes a 0.76 m male to female cable, terminal block, and a mounting bracket	14165-000
Top Plate - LD-60, LD-90, LD-90x	Provides additional protection for the AMR.	12944-000
Top Plate - LD-250		20458-002
Top Plate - LD-250 ESD	Provides additional protection for the AMR.	20458-202
Rear Facing Laser Bundle	Provides CAPS functionality while the AMR is traveling in the reverse direction. Includes TiM laser and required cables.	21446-000

<sup>\*</sup>Before ordering lithium-ion batteries, please verify local shipping regulations to ensure compliance with applicable laws and restrictions.

## **Software Licenses**

Product Name	Applicable For	Configuration	Part Number
Fleet Operations Workspace (FLOW) Core Fleet Manager License, 3 Year		Initial entitlement for a 3 year renewable FLOW Core license. Replace DW with 05, 10, 15, 20, 25, 30, 50 to indicate the number of AMRs licensed to connect, where 50 represents an unlimited number of AMRs.	30271-1□□*¹
Fleet Operations Workspace (FLOW) Core Fleet Upgrade	Virtual Fleet	Entitlement for fleet connection limit increase by one additional AMR (used for existing installations).	30271-001
Fleet Operations Workspace (FLOW) Core Renewal	Manager	Entitlement for a 1 year (verify) renewal of the FLOW Core license. Replace   □□ with a value of 05 to 30, or 50 to indicate the number of AMRs licensed to connect, where 50 represents an unlimited number of AMRs.	30271-2□□
Fleet Operations Workspace		Entitlement for a 1 year renewable FLOW iQ license.	30271-701
(FLOW) iQ License		Entitlement for a 3 year renewable FLOW iQ license.	30271-703
Primary Fleet Operations Workspace (FLOW) Core License, 1 Year		Entitlement for a 1 year renewable Primary FLOW Core license, runtime and development, per AMR connection	20271-800*2
Primary Fleet Operations Workspace (FLOW) Core License, 5 Year		Entitlement for a 5 year renewable Primary FLOW Core license, runtime and development, per AMR connection	20271-806*2
Secondary Fleet Operations Workspace (FLOW) Core License, 1 Year	EM2100	Entitlement for a 1 year renewable Secondary FLOW Core license per fleet, redundant runtime	20271-802*2
Secondary Fleet Operations Workspace (FLOW) Core License, 5 Year		Entitlement for a 5 year renewable Secondary FLOW Core license per fleet, redundant runtime	20271-807*2
License, Fleet Operations		Entitlement for a 1 year renewable FLOW iQ license	20271-701
Workspace iQ		Entitlement for a 5 year renewable FLOW iQ license	20271-705
Cell Alignment Positioning System (CAPS) License	AMR	AMR Alignment using software-defined target. Entitlement for a perpetual CAPS license	20271-805

<sup>\*1</sup> After expiration of a FLOW Core Fleet Manager license, all Virtual Fleet Manager functionality will continue to operate without requiring subscription renewals. An active subscription will still be required to access subsequent software releases, including bug fixes, feature upgrades, and performance improvements.

<sup>\*2</sup> Expiration of a 1 year subscription license without renewal will result in cessation of the EM2100 fleet management functions of the OMRON

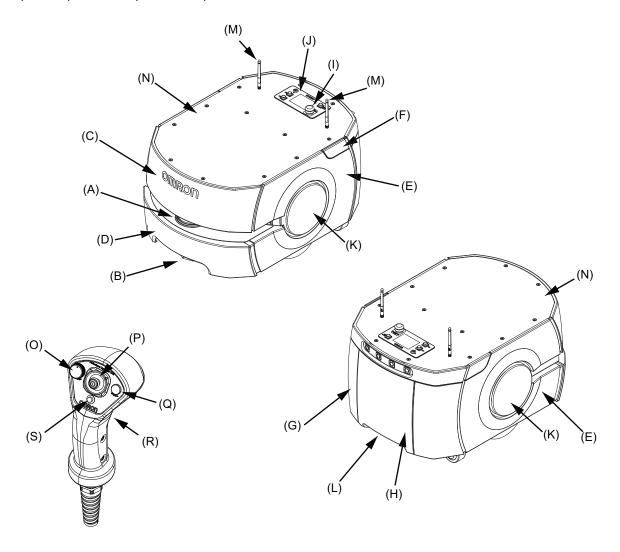
AMR solution until the license is renewed. This does not apply to Virtual Fleet Manager.

After five consecutively licensed years (either one 5 year license or five 1 year licenses), all EM2100 fleet management functions will continue to operate without requiring subsequent subscription renewals. An active subscription will still be required to access new software releases, including bug fixes, feature upgrades, and performance improvements.

**Note:** To upgrade to the latest version of the FLOW Core software, contact your local OMRON representative. Please note that an active subscription is required for access to software upgrades.

# **Features and Components**

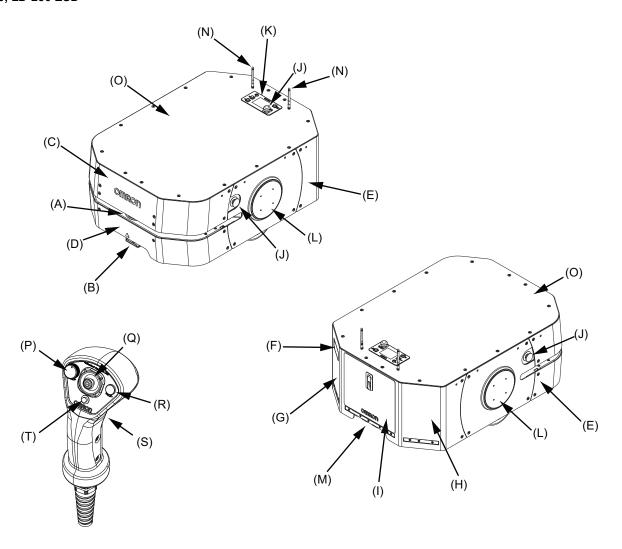
LD-60, LD-90, LD-90x, LD-60 ESD, LD-90 ESD, and LD-90x ESD



Item	Description	Item	Description
Α	Safety Laser Scanner	K	Light Disk
В	Low Laser	L	Charging Contacts
С	Upper Front Skin	М	Wireless Antennas
D	Bumper Skin	N	Payload Mounting Surface (Top Plate shown)
Е	Side Skin	0	Speed Control
F	Access Panel	Р	Directional Control Stick
G	Rear Skin	Q	Goal Button
Н	Battery Door Skin	R	Trigger
ı	E-STOP button	S	Indicator Light
J	Operator Panel		

# **Features and Components**

LD-250, LD-250 ESD



Item	Description	Item	Description
Α	Safety Laser Scanner	K	Operator Panel
В	Low Laser	L	Light Disk
С	Upper Front Skin	М	Charging Contacts
D	Bumper Skin	N	Wireless Antennas
Е	Side Skin	0	Payload Mounting Surface (Top Plate shown)
F	Access Panel	Р	Speed Control
G	Left Rear Skin	Q	Directional Control Stick
Н	Right Rear Skin	R	Goal Button
1	Battery Door Skin	S	Trigger
J	E-STOP button	Т	Indicator Light

# **Specifications**

LD-60, LD-90, LD	-90x, LD-60 ESD, LD-90 ESD	, and LD-90x ESD					
	Item	LD-60	LD-90	LD-90x			
Weight (with Batte	ery)	62 kg					
	Ambient temperature	5 to 40°C					
	Ambient humidity	5 to 95% (non-condensing)					
Environment	Operating Environment		ssive dust, no corrosive gas o Direct sunlight may cause saf	or liquid. Floor must be free of ety laser false positives.			
	Ingress Protection Class	IP20					
	Cleanroom rating	ISO 5 / Class 100					
	Minimum floor flatness	F <sub>F</sub> 25 (ACI 117 standard)					
	Traversable step	15 mm max.*1	10 mm max.*1				
Floor Conditions	Traversable gap	15 mm max <sup>*2</sup>					
	Maximum Slope	Up to 60 kg: 4.8° / 8.3% inc Over 60 kg: Level floor only					
	Minimum floor compressive strength	5 Mpa					
	Routing	Autonomous routing by loca mapping	alizing with safety scanning la	ser based on environment			
Navigation	Environmental map making method	Scan by walking the AMR the MobilePlanner software	nrough the environment, and	upload the scan data to the			
	Low Front Laser	One Class 1 laser at front o	f AMR with a 126° field of vie	eW			
	Side Laser (optional)	Two Class 1 lasers with a 2 mounted	70° field of view on the sides	of payload structure, user-			
Visual Indicators		Light discs are located on the	ne sides of the AMR. Addition	nal indicators can be added.			
Payload	Maximum Weight	60 kg	90 kg				
	Run time (no payload)	15 h approx.		20 h approx.			
	Run Time (full payload)	12 h approx.		15 h approx.			
Mobility	Maximum Speed	1800 mm/s	1350 mm/s	900 mm/s			
	Maximum Rotation Speed	180 °/s					
	Stop Position Repeatability (single AMR) <sup>*3</sup>	<ul> <li>To a position: ±65 mm</li> <li>To standard target: ±25 mm, ±2°</li> <li>With CAPS: ±8 mm, ±0.5°</li> <li>With HAPS: ±8 mm, ±0.4°</li> </ul>					
	Stop Position Repeatability (Fleet)*3	<ul> <li>To a position: ±85 mm</li> <li>To standard target: ±35 mm, ±2°</li> <li>With CAPS: ±12 mm, ±0.5°</li> <li>With HAPS: ±10 mm, ±0.5°</li> </ul>					
Drive wheels	Materials	Solid aluminum with non-ma	arking, non-conductive, foam	-filled rubber tread			
Passive casters	Materials	Conductive thermoplastic ru	ıbber on polyolefin				
Auxiliary Power		5 VDC±5%, 1 A switched Aux power 12 VDC±5%, 1 A switched Aux power 20 VDC±5%, 1 A switched Aux power 22 to 30 VDC, 4 A switched 22 to 30 VDC, 10 A switched 22 to 30 VDC, 10 A safe, switched 10 A switched and 10 A safe switched are from the same source and pass through the same 10 A fuse, so the sum of their current must be less than 10 A.					
	AMR	EN ISO 12100, EN ISO 138 CSA Z434, EN 61000-6-2, I	49-1, EN 60204-1, EN 1525, EN 61000-6-4	ANSI B56.5, ISO 10218/			
Standards	Battery	EN ISO 12100, UN 38.3, EN	I 61000-6-2, EN 61000-6-4, l	JL 2271			
	Docking Station	EN ISO 12100, UL1012/CS/	A C22.2.107.2, IEC 60204-1,	EN 61000-6-2, EN 61000-6-4			
	Wireless	IEEE 802.11 a/b/g					
Safety Features	Safety Scanning Laser	One at front of AMR Class 1 PLd safety per ISO13849-1 240° field of view					
	E-STOP Buttons	One on Operator Panel, add structure	ditional E-STOP buttons can	be added to the payload			
	Rear Sonar	Two at rear of AMR, 2 m ran together.	ge. Each pair includes one en	nitter and one receiver working			
	Front Bumper	Two pairs of sensors at the	front of the AMR				
	Audible Indicators	Two speakers are included. Additional buzzers can be added.					

Item		LD-60	LD-90	LD-90x			
Operator	Display	8.89 cm diagonal TFT, 320 x 240 pixels, color screen					
Interface	Button	ON button, OFF button, Brake-release button, and keyed mode selection					
	Wireless	802.11 a/b/g					
	Ethernet	One TCP/UDP interface (maintenance LAN), Auto-MDIX					
User Interface	Serial	Two serial communication interfaces					
	Digital I/O	16 inputs, 16 outputs					
	Audio	Digital audio in / out					

<sup>\*1</sup> A speed of 250 mm/s is recommended for traversing steps, and routine driving over steps should be avoided. Lower speeds may not traverse the step. Faster or frequent driving over steps will shorten the lifespan of the drivetrain components. All steps should have smooth, rounded profiles.

#### LD-250, LD-250 ESD Specifications

	Item	LD-250
Weight (with ba	attery)	148 kg
	Ambient temperature	5 to 40°C
	Ambient humidity	5 to 95% (non-condensing)
Environment	Operating Environment	Indoor usage only, no excessive dust, no corrosive gas or liquid. Floor must be free of water, oil, dirt, and debris. Direct sunlight may cause safety laser false positives.
	Ingress Protection Class	IP20
	Cleanroom rating	ISO 5 / Class 100
	Minimum floor flatness	F <sub>F</sub> 25 (ACI 117 standard)
	Traversable step	10 mm max.*1
Floor	Traversable gap	15 mm max.*2
Conditions	Maximum Slope	Max. 1.7° / 3% incline
	Minimum floor compressive strength	5 Mpa
Navigation	Routing	Autonomous routing by localizing with safety scanning laser based on environment mapping
	Environmental map making method	Scan by manually driving the AMR through the environment, and upload the scan data to the MobilePlanner for map creation.
	Low Front Laser	One Class 1 laser at front of AMR with a 126° field of view
	Side Laser (optional)	Two Class 1 lasers with a 270° field of view on the sides of payload structure, user-mounted
Visual Indicator	rs	Light discs are located on the sides of the AMR. Additional indicators can be added.
Payload	Maximum Weight	250 kg
	Run time (no payload)	13 h approx.
	Run Time (full payload)	10 h approx.
	Maximum Speed	1200 mm/s
	Maximum Rotation Speed	120 °/s
Mobility	Stop Position Repeatability (single AMR) <sup>-3</sup>	<ul> <li>To a position: ±75 mm</li> <li>To standard target: ±25 mm, ±2°</li> <li>With CAPS: ±8 mm, ±0.5°</li> <li>With HAPS: ±8 mm, ±0.4°</li> </ul>
	Stop Position Repeatability (Fleet) <sup>'3</sup>	<ul> <li>To a position: ±100 mm</li> <li>To standard target: ±35 mm, ±2°</li> <li>With CAPS: ±14 mm, ±0.6°</li> <li>With HAPS: ±10 mm, ±0.6°</li> </ul>
Drive wheel	Materials	Aluminum with polyurethane tread
Passive caster	Materials	Elastomer (Polyurethane)
Auxiliary Power		5 VDC±5%, 1 A switched Aux power 12 VDC±5%, 1 A switched Aux power 20 VDC±5%, 1 A switched Aux power 22 to 30 VDC, 4 A switched ´2 22 to 30 VDC, 10 A switched 22 to 30 VDC, 10 A safe, switched 10 A switched and 10 A safe switched are drawn from the same source, and pass through the same 10 A fuse, so the sum of their current must be less than 10 A.

<sup>\*2</sup> AMR maximum speed is recommended for traversing gaps, and routine driving over gaps should be avoided. Lower speeds may not traverse the gap. Faster or frequent driving over gaps will shorten the lifespan of the drivetrain components.

<sup>\*3</sup> Stop position repeatability values were obtained using default AMR parameters and a map created by the LD-series AMR.

	Item	LD-250					
	AMR	EN ISO 12100, EN ISO 13849-1, EN 60204-1, EN 1525, ANSI B56.5, ISO 10218/CSA Z434, EN 61000-6-2, EN 61000-6-4					
Standards	Battery	EN ISO 12100, UN 38.3, EN 61000-6-2, EN 61000-6-4, UL 2271					
	Docking Station	N ISO 12100, UL1012/CSA C22.2.107.2, IEC 60204-1, EN 61000-6-2, EN 61000-6-4					
	Wireless	IEEE 802.11 a/b/g					
Safety	Safety Scanning Laser	One at front of AMR Class 1 PLd safety per ISO13849-1 240° field of view					
Features	E-STOP Buttons	One at Operator Panel, one on each side. Additional E-STOP buttons can be added to the payloa structure					
	Rear Sensing	Time of flight (TOF) sensors					
	Audible Indicators	Two speakers are included. Additional buzzers can be added					
Operator	Display	3.5 inch TFT, 320 x 240 pixels, color screen					
Interface	Button	ON button, OFF button, Brake-release button, and keyed mode selection					
	Wireless	802.11 a/b/g					
	Ethernet	One TCP/UDP interface (maintenance LAN), Auto-MDIX					
User Interface	Serial	Two serial communication interfaces					
	Digital I/O	16 inputs, 16 outputs					
	Audio	Digital audio in / out					

<sup>\*1</sup> A speed of 600 mm/s is recommended for traversing steps, and routine driving over steps should be avoided. Lower speeds may not traverse the step. Faster or frequent driving over steps and gaps will shorten the lifespan of the drivetrain components. All steps should have smooth, rounded profiles.

<sup>\*2</sup> AMR maximum speed is recommended for traversing gaps, and routine driving over gaps should be avoided. Lower speeds may not traverse the gap. Faster or frequent driving over gaps will shorten the lifespan of the drivetrain components.

<sup>\*3</sup> Stop position repeatability values were obtained using default AMR parameters and a map created by the LD-series AMR.

# Virtual Fleet Manager Software Minimum Hardware Requirements

Fleet Size / AMR Count	Small / ≤ 5	Medium ≤ 15	Large ≤ 30	X-Large ≤ 100
Virtual CPU	2 cores		4 cores	
Clockspeed	4GHz	8 GHz	12 GHz	16 GHz
Virtual RAM	8 GB	16 GB	24 GB	32 GB
Virtual Disk	512 GB 1 TB			1 TB
FLOW software version	Minimum FLOW Core 4.0			

Note: The PC/IPC/Server is supplied by the user.

#### EM2100 Appliance

Ем2 100 Аррнансе	
9.1 kg	
1U rack mount in a standard 19-inch equipment rack	
100 to 240 VAC (typical 100 W)	
200 W max.	
10 to 35°C	
-25 to 60°C	
8 to 90%, non-condensing	
5 to 95%, non-condensing	
IP20	
Intel® Xeon® CPU	
32 GB DDR3	
60 GB SSD	
4 TB HDD	
Four 10/100/1000 Ethernet Four USB One VGA	
One vort	

#### High Accuracy Positioning System (HAPS)

High Accuracy Positioning System (HAPS)		
	Depth	30 mm
Sensor	Width	160 mm
	Ingress Protection Class	IP64
	Environment	-40 to 85°C
	LEDs	Power, tape present, left marker, right marker
Magnetic Tape	Width	25 mm
Magnetic Tape	Orientation	South up
	Width	25 mm
Markers	Length	300 mm min. for 500 mm/s drive speed
(Magnetic Tape)	Orientation	North up
ι αρογ	Separation From Tape	15 to 30 mm
	Front Sensor	RS232-1 (/dev/ttyUSB9) on the core
Connections	nnections Rear Sensor	RS232-2 (/dev/ttyUSB10) on the core
	Power, Both Sensors	Aux power using the included splitter cable
Stop Position	Single AMR	±8 mm position, 0.4° rotation
Repeatability, LD-60, LD-90*	Fleet	±10 mm position, 0.5° rotation
Stop Position	Single AMR	±8 mm position, 0.4° rotation
Repeatability, LD-250*	Fleet	±10 mm position, 0.6° rotation

<sup>\*</sup> Stop position repeatability values were obtained using default AMR parameters and a map created by the LD-series AMR.

#### **Cell Alignment Positioning System (CAPS)**

<b>Stop Position</b>	Single AMR	±8 mm position, 0.5° rotation
Repeatability, LD-60, LD-90, LD-90x*	Fleet	±12 mm position, 0.5° rotation
<b>Stop Position</b>	Single AMR	±8 mm position, 0.5° rotation
Repeatability, LD-250*	Fleet	±14 mm position, 0.6° rotation
Туре		Software license

<sup>\*3</sup> Stop position repeatability values were obtained using default AMR parameters and a map created by the LD-series AMR.

#### **Battery**

Battory	
Туре	Lithium-Ion (LiFePO4)
Weight	19 kg
Voltage	22 to 30 VDC (25.6 VDC nominal)
Capacity	72 Ah (battery cell nominal)
Recharge Time	2 hrs. 10 min. for 20% to 80% charge
Ingress Protection Class	IP20
Recharge Cycles	Approximately 2000 cycles*
Charging Method	Automatic or manual

<sup>\*</sup> Approximately 80% of nominal battery capacity will be available after using the battery at 90% depth of discharge at temperatures between 15°C to 35°C, charging and discharging at a 1C rate.

#### **Docking Station**

booking Gtation	
Current	8 A*
Power	100 to 240 VAC, 50 to 60 Hz
Power Consumption	800 W
Humidity	5 to 95L%, non-condensing
Temperature	5 to 40° C
Dimensions (W´D´H)	349 ´ 369 ´ 315 mm 495 ´ 495.5 ´ 317 mm (with floor plate)
Weight	8.2 kg
Mounting	Wall bracket, directly to floor, or on floor with floor plate
Indicators	Power on: blue Charging: yellow
Connector	For out-of-AMR battery charging

<sup>\*</sup> Circuit breaker built into AC power switch

#### Joystick (Pendant)

J	
Weight	0.55 kg
IP Rating	IP56

#### **Acuity Localization**

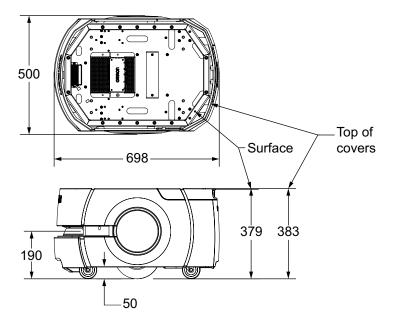
Field of View	140°
Power Input	12 VDC (±10%) supplied from AMR through power connector
Power Consumption	3.3 W maximum

## **MobilePlanner Software**

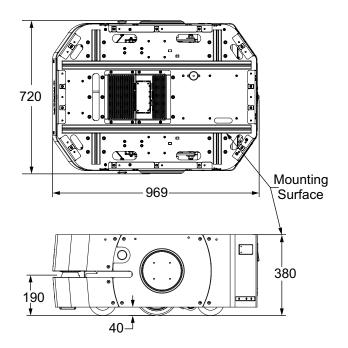
CPU	1.5 GHz dual-core CPU recommended
Main Memory	1.5 GB min. (4 GB min. recommended)
Hard Disk	At least 200 MB of available space
Video Memory	256 MB min.
Display	XGA 1024 ´ 768, 16 million colors
Supported Languages	English, Japanese, German, French, Italian, Korean, Spanish, Polish, Simplified Chinese, Traditional Chinese

(Unit: mm)

## LD-60, LD-90, LD-90x, LD-60 ESD, LD-90 ESD and LD-90x ESD

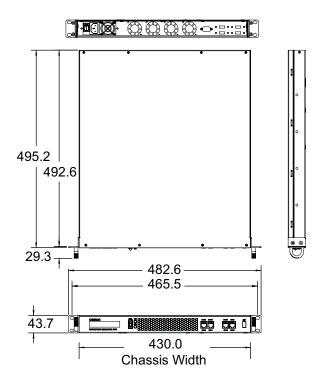


## LD-250, LD-250 ESD

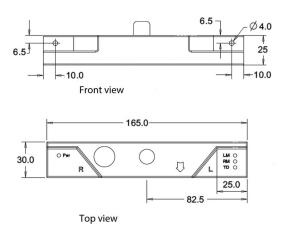


**Dimensions** (Unit: mm)

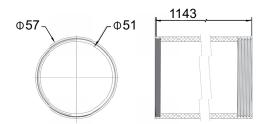
## EM2100 Appliance



## High Accuracy Positioning System (HAPS)

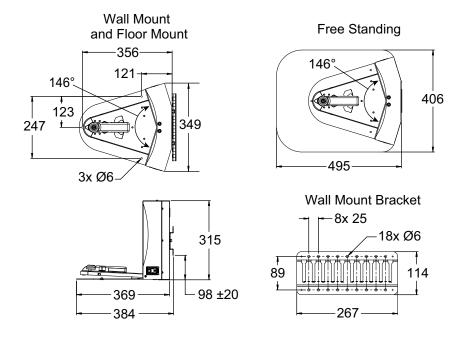


## **Acuity Localization**

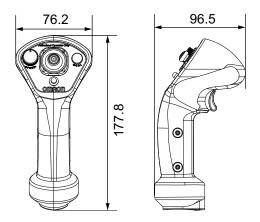


**Dimensions** (Unit: mm)

## **Docking Station**



## Joystick (Pendant)



# **Related Manuals**

Catalog Number	Manual Title
I611	LD-60/90 Platform User's Manual
I613	LD Platform Peripherals User's Guide
I614	Mobile Robot Software Suite User's Guide
I615	Enterprise Manager User Guide (this covers the EM1100, not the EM2100)
I616	Mobile Robot LD Safety Guide
I617	Advanced Robotics Command Language Reference Guide
I618	Advanced Robotics Command Language Fleet Manager - Mobile Robots Integration Guide
1634	EM2100 Installation Guide
1635	Fleet Operations Workspace Core User's Manual
1636	Fleet Operations Workspace Core Migration Guide
1637	Fleet Operations Workspace Core Integration Toolkit User Guide
1665	Fleet Operations Workspace iQ User's Manual
1649	Fleet Simulator User's Manual
1695	Virtual Fleet Manager Installation Guide
1642	LD-250 Platform User's Manual
1677	Mobile I/O Box User's Manual
1680	LD-Series Integration Guide

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# **Terms and Conditions Agreement**

## Read and understand this catalog.

Please read and understand this catalog before purchasing the products. Please consult your OMRON representative if you have any questions or comments.

#### Warranties.

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Note: Do not use this document to operate the Unit. This document describes AMR functionality supported with FLOW v2.0.7.

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