

MATH 367 - Week 1 Notes

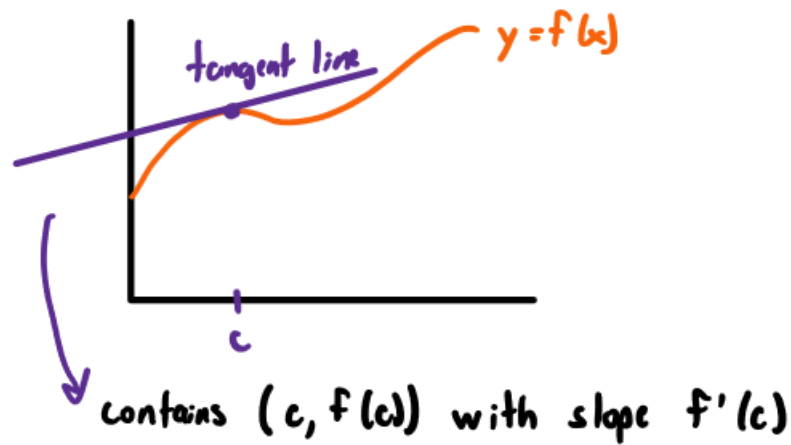
Jasraj Sandhu

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Introduction

What is a derivative?

- rate of change of y with respect to x .
- linearization



We write the linearization as $y - f(c) = f'(c) \cdot (x - c)$. With $y = L(x)$, we then get

$$L(x) = f(c) + f'(c) \cdot (x - c) .$$

$L(x)$ is the best linear approximation to $f(x)$ near $x = c$. That is, $f'(c)$ is the best minimizing quantity for

$$|f(x) - (f(c) + m(x - c))|$$

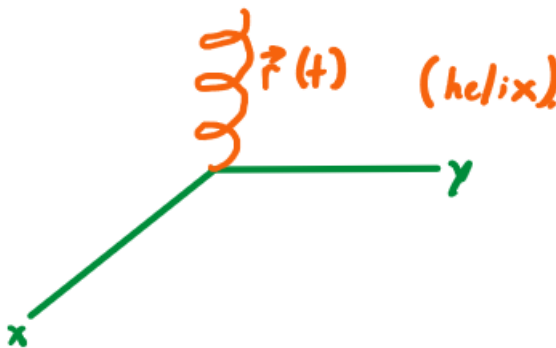
for x close to c .

In this course, we will look at functions with many input variables and many output variables. Consider the following examples.

(i) $f(x, y, z) = xy + z^2$ (scalar-valued function)

(ii) $\vec{r}(t) = \begin{pmatrix} \cos(t) \\ \sin(t) \\ t \end{pmatrix}$ (vector-valued function)

Note that the graph of the range of a vector-valued function is called a curve.



(iii) $\vec{f}(x, y) = \begin{pmatrix} -y \\ x \end{pmatrix}$ (vector field in 2D)

$\vec{f}(x, y, z) = \frac{1}{\sqrt{x^2 + y^2 + z^2}} \begin{pmatrix} -x \\ -y \\ -z \end{pmatrix}$ (vector field in 3D).

(# of inputs = # of outputs)

(iv) Suppose A is a an $m \times n$ matrix and define a function

$$\vec{f}(\vec{x}) = A\vec{x} + \vec{b} \in \mathbb{R}^m ,$$

where $\vec{b} \in \mathbb{R}^m$, and $\vec{x} \in \mathbb{R}^n$ is our input. This is a function from $\mathbb{R}^n \rightarrow \mathbb{R}^m$, called an **affine** function. (Note that this is a **linear transformation** **when** $\vec{b} = \vec{0}$).

What should be the derivative of \vec{f} ? We want it to be A . Note that the equation above is similar to the slope equation

$$y = mx + b ,$$

whose derivative evaluates to m .

The Basic Topology of \mathbb{R}^n

Definition (Open Ball)

The open ball centered at \vec{x}_0 with radius $r > 0$ is the set

$$B_r(\vec{x}_0) = \{\vec{x} \in \mathbb{R}^n : \|\vec{x} - \vec{x}_0\| < r\} \subseteq \mathbb{R}^n ,$$

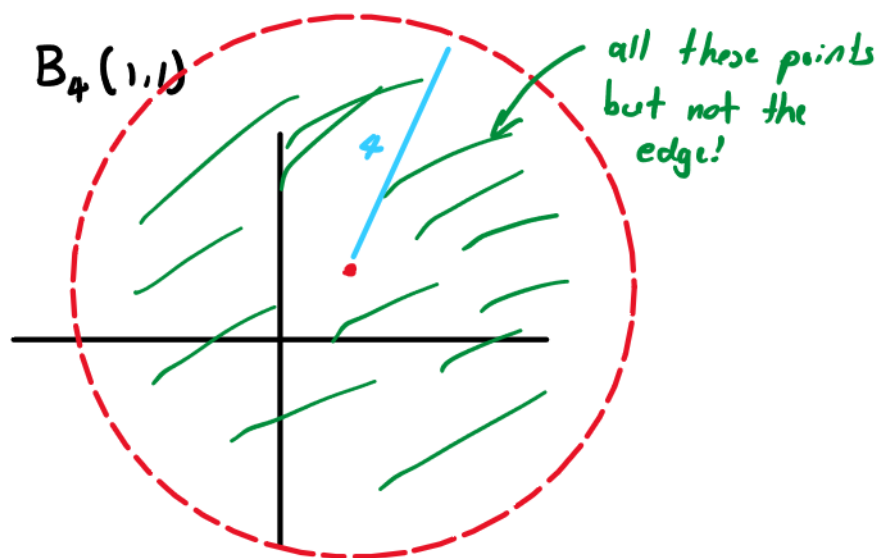
where $\|\vec{x} - \vec{x}_0\|$ is the Euclidean distance between \vec{x} and \vec{x}_0 .

For example, let $\vec{v} = \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}$ and $\vec{w} = \begin{pmatrix} w_1 \\ \vdots \\ w_n \end{pmatrix}$. Then the euclidean distance between \vec{v} and \vec{w} is given by

$$\|\vec{v} - \vec{w}\| = \sqrt{\sum_{j=1}^n |v_j - w_j|^2} .$$

Essentially, an open ball is the set of all vectors $< r$ distance away from the vector \vec{x}_0 , where \vec{x}_0 is the center of the ball whose radius is r .

Consider $B_4(1,1)$ in \mathbb{R}^2 . This is the ball of radius 4 centered at $(1,1)$.



Definition (Closed Ball)

The closed ball of radius r centered at \vec{x}_0 is the set

$$\overline{B}_r(\vec{x}_0) = \{\vec{x} \in \mathbb{R}^n : \|\vec{x} - \vec{x}_0\| \leq r\}$$

If we consider $\overline{B}_4(1,1)$, which is the closed ball of radius 4 centered at $(1,1)$, the image is the same as the one for the open ball $B_4(1,1)$, but with the edge included.

In one variable:

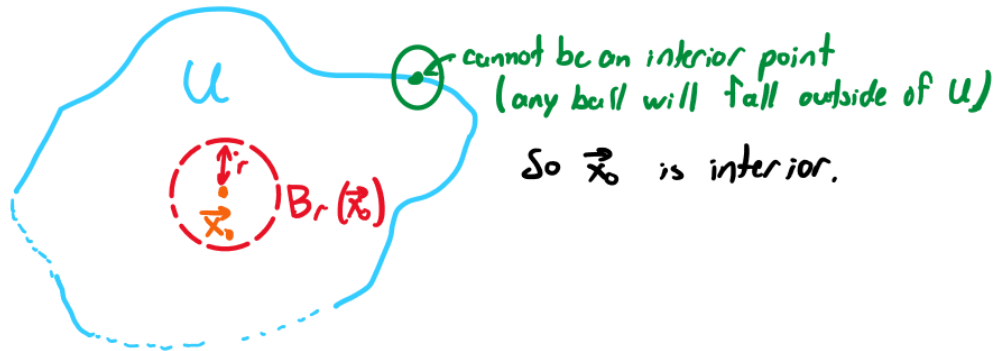
$$\begin{aligned} B_r(x_0) &= (x_0 - r, x_0 + r) \\ \overline{B}_r &= [x_0 - r, x_0 + r] \end{aligned}$$

Note that these are intervals, not matrices.

Definition (Interior Point)

Suppose $U \subseteq \mathbb{R}^n$. We say that \vec{x}_0 in U is an **interior point** for U if there is some $r > 0$ with $B_r(\vec{x}_0) \subseteq U$.

For example,



Definition (Interior)

The set of all interior points for U is called the **interior** of U (often written as U° or $\text{int}(U)$).

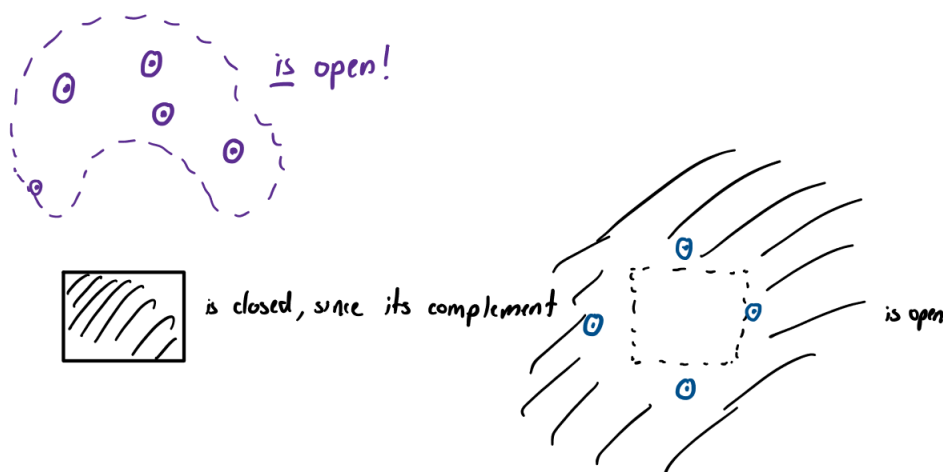
Definition (Open Set)

U is **open** if $U^\circ = U$ (that is, every point is interior).

Definition (Closed Set)

U is **closed** if $\mathbb{R}^n \setminus U$ (the complement of U) is open.

Consider the following examples.

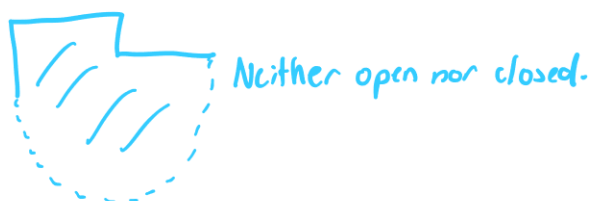


This makes sense.

- For the first example above, the set U is the inside of the strange shape, and so since every point is an interior point, we say that U is indeed an open set (by the definition of open set).
- For the second example above, U is closed. If we consider the complement of the second image (the rectangle), which is the the third image, we see that the complement of U , which we'll call U^c , is the outside of the rectangle. Since every point is indeed part of U^c (outside the rectangle), we say that U is indeed a closed set.

Remarks:

- A set is open if and only if it contains **no** boundary points.
- A set is closed if and only if it contains **all** boundary points.



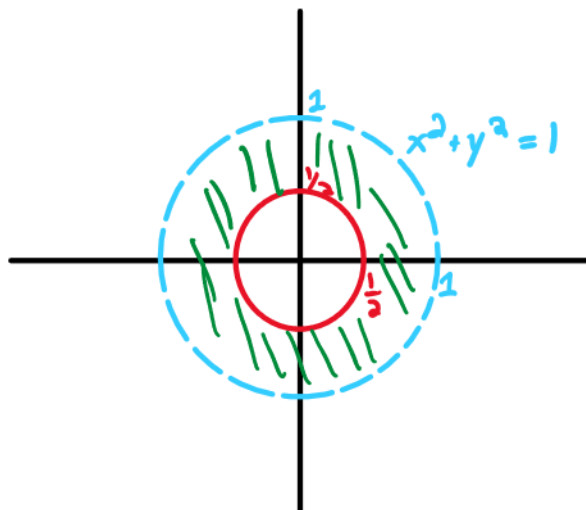
Ex: Find and sketch the domain of

$$\vec{f}(x, y) = \begin{pmatrix} \ln(1 - x^2 - y^2) \\ \sqrt{x^2 + y^2 - \frac{1}{4}} \end{pmatrix}.$$

Answer: In order for $(x, y) \in \text{dom}(\vec{f})$, it must be the case that $(x, y) \in \text{dom}(\ln(1 - x^2 - y^2))$ and $(x, y) \in \text{dom}\left(\sqrt{x^2 + y^2 - \frac{1}{4}}\right)$. So, using the fact that the domain of $\ln(x)$ is $(0, \infty)$ and the domain of \sqrt{x} is $[0, \infty)$, we get that

$$\begin{aligned} \text{dom}(\vec{f}) &= \left\{ (x, y) \in \mathbb{R}^2 : 1 - x^2 - y^2 > 0 \text{ and } x^2 + y^2 - \frac{1}{4} \geq 0 \right\} \\ &= \left\{ (x, y) \in \mathbb{R}^2 : x^2 + y^2 < 1 \text{ and } x^2 + y^2 \geq \frac{1}{4} \right\} \\ &= \left\{ (x, y) \in \mathbb{R}^2 : \frac{1}{4} \leq x^2 + y^2 < 1 \right\} \end{aligned}$$

Recall that $x^2 + y^2 = r^2$ is the circle of radius r centered at $(0, 0)$. The following is the sketch of $x^2 + y^2 = 1$ and $x^2 + y^2 = \frac{1}{4}$, the circle centered at $(0, 0)$ with radii 1 and $\frac{1}{2}$, respectively.



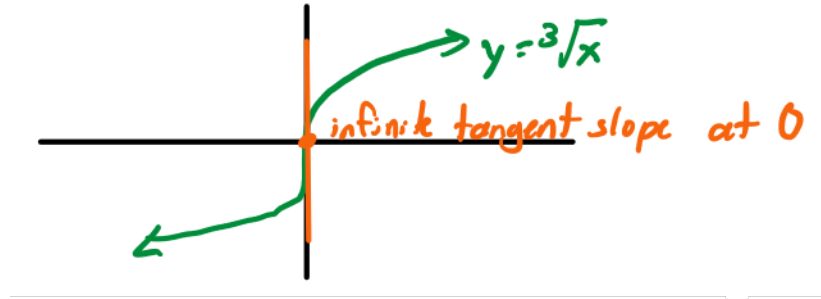
In single variable calculus, we generally define derivatives on the interior of the domain of f (or a subset of the interior). For example,

$$f(x) = \sqrt{x}, \quad \text{dom}(f) = [0, \infty)$$

$$f'(x) = \frac{1}{2\sqrt{x}}, \quad \text{dom}(f') = (0, \infty) = [0, \infty)^\circ$$

$$g(x) = \sqrt[3]{x}, \quad \text{dom}(g) = \mathbb{R}$$

$$g'(x) = \frac{1}{3\sqrt[3]{x^2}}, \quad \text{dom}(g') = (-\infty, 0) \cup (0, \infty)$$



The Derivative

Definition (Derivative)

Suppose $\vec{f} : U \rightarrow \mathbb{R}^m$ where $U \subseteq \mathbb{R}^n$. We say that f is differentiable at $\vec{x}_0 \in U^\circ$ if there is an $m \times n$ matrix A such that

$$\lim_{\vec{x} \rightarrow \vec{x}_0} \frac{\|\vec{f}(\vec{x}) - \vec{f}(\vec{x}_0) - A(\vec{x} - \vec{x}_0)\|}{\|\vec{x} - \vec{x}_0\|} = 0 ,$$

where the numerator is the Euclidean distance in \mathbb{R}^m and the denominator is the Euclidean distance in \mathbb{R}^n . When this is the case, A must be unique. We call this matrix the derivative of \vec{f} at \vec{x}_0 and write it as

$$D\vec{f}(\vec{x}_0) = A .$$

We can compare this definition to the single variable derivative definition:

$$f'(x_0) = \lim_{x \rightarrow x_0} \frac{f(x) - f(x_0)}{x - x_0} .$$

We can get this limit definition of a derivative of a single variable in a form similar to that of our definition above.

$$\begin{aligned} f'(x_0) &= \lim_{x \rightarrow x_0} \frac{f(x) - f(x_0)}{x - x_0} \\ 0 &= \lim_{x \rightarrow x_0} \frac{f(x) - f(x_0)}{x - x_0} - f'(x_0) \\ 0 &= \lim_{x \rightarrow x_0} \frac{f(x) - f(x_0)}{x - x_0} - \frac{f'(x_0)(x - x_0)}{x - x_0} \\ 0 &= \lim_{x \rightarrow x_0} \left| \frac{f(x) - f(x_0) - f'(x_0)(x - x_0)}{x - x_0} \right| . \end{aligned}$$