CasADi for solution of a Nonlinear Program Lecture 01C CasADi and the Himmelblau Optimization Problem

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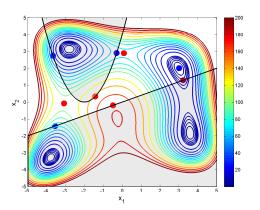
02612 Constrained Optimization

The Himmelblau Optimization Problem

$$\min_{x} \quad f(x) = (x_1^2 + x_2 - 11)^2 + (x_1 + x_2^2 - 7)^2$$
 (1a)

$$c_1(x) = (x_1 + 2)^2 - x_2 \ge 0$$
 (1b)

$$c_2(x) = -4x_1 + 10x_2 \ge 0 \tag{1c}$$



The Himmelblau Optimization Problem

► Himmelblau's optimization problem

$$\min_{x} \quad f(x) = (x_1^2 + x_2 - 11)^2 + (x_1 + x_2^2 - 7)^2$$
 (2a)

$$c_1(x) = (x_1 + 2)^2 - x_2 \ge 0$$
 (2b)

$$c_2(x) = -4x_1 + 10x_2 \ge 0 (2c)$$

► CasADi interface (ipopt interface)

$$\min_{x} \quad f(x) \tag{3a}$$

$$s.t. x_{lb} \le x \le x_{ub} (3b)$$

$$g_{lb} \le g(x) \le g_{ub} \tag{3c}$$

CasADi script

```
% example 4 casadi
   import casadi.*
3
  % Symbols/expressions
  x1 = MX.svm('x1');
   x2 = MX.sym('x2');
9 t1 = x1*x1 + x2 - 11;
10 t2 = x1 + x2*x2 - 7;
11
   f = t1*t1 + t2*t2;
12
13
14 c1 = (x1+2)^2 - x2;
15 c2 = -4 \times x1 + 10 \times x2;
16
  q = [c1; c2];
17
18 nlp = struct; % NLP declaration
19 nlp.x = [x1; x2]; % decision vars
20 nlp.f = f;
                         % objective
21
   nlp.q = q;
                         % constraints
22
23 % Create solver instance
24
   F = nlpsol('F', 'ipopt', nlp);
25
26
   % Solve the problem using a guess
27
   res = F('x0', [0.0 \ 0.0], 'ubg', 1e8, 'lbg', 0, 'lbx', [-5; -5], 'ubx', [5; 5])
28
29
   res.x
```