## ICSolar Model

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## 1 Steady Model

Consider the model of air and water interaction consisting of an initial inlet region (denoted by 0) and a pair of regions, an open region with pipe followed by a module, denoted by (1,2) satisfying

$$W_1: \quad \dot{m}_w C_{p,w} (T_{w,1} - T_{w,0}) - h_{wa} (T_{a,1} - T_{w,1}) = 0 \tag{1}$$

$$A_1: \quad \dot{m}_a C_{p,a} (T_{a,1} - T_{a,0}) - h_{wa} (T_{w,1} - T_{a,1}) - h_e (T_e - T_{a,1}) - h_i (T_i - T_{a,1}) = 0$$
 (2)

$$W_2: \quad \dot{m}_w C_{p,w} (T_{w,2} - T_{w,1}) - Q_w = 0 \tag{3}$$

$$A_2: \quad \dot{m}_a C_{p,a} (T_{a,2} - T_{a,1}) - Q_a = 0 \tag{4}$$

Where i and e are interior and exterior contributions. Each pair of these forms a 'module'. In this work, we use

$$C_{p,w} = 4.218kJ/(kgK) \tag{5}$$

$$\dot{m}_w = 0.0008483kg/s \tag{6}$$

$$C_{p,a} = 1.005kJ/(kgK) \tag{7}$$

$$\dot{m}_a = 0.384kg/s \tag{8}$$

$$h_{wa} = 4.823 \times 10^{-5} kW/(Km) \tag{9}$$

$$h_i = 1.572 \times 10^{-4} kW/(Km) \tag{10}$$

$$h_e = 4.837 \times 10^{-4} kW/(Km) \tag{11}$$

(12)

With Initial and Boundary Conditions of  $T_{a,0} = 20C$ ,  $T_i = 25.0C$ ,  $T_e = 22.5C$ . At this point, we set  $Q_a = 0$  as the surrounding air acts like a reservoir and its effect is currently minimal. Our inputs are  $T_{w,0}$  and  $Q_{w,i}$  from experimental data. We also occasionally have access to  $T_{a,0}$ , the ambient air temperature.

### 2 Unsteady Model

Consider the steady model in 4 and introduce the time derivative,  $mC_p \frac{\partial T}{\partial t}$  and rearrange to get

$$W_1: m_{w,1}C_{p,w}\frac{\partial T}{\partial t} + \dot{m}_wC_{p,w}(T_{w,1} - T_{w,0}) - h_{wa}(T_{a,1} - T_{w,1}) = 0 (13)$$

$$W_2: m_{w,2}C_{p,w}\frac{\partial T}{\partial t} + \dot{m}_wC_{p,w}(T_{w,2} - T_{w,1}) - Q_w(t) = 0 (14)$$

$$A_1: \qquad m_{a,1}C_{p,a}\frac{\partial T}{\partial t} + \dot{m}_aC_{p,a}(T_{a,1} - T_{a,0}) - h_{wa}(T_{w,1} - T_{a,1}) - h_e(T_e - T_{a,1}) - h_i(T_i - T_{a,1}) \neq 15$$

$$A_2: m_{a,2}C_{p,a}\frac{\partial T}{\partial t} + \dot{m}_aC_{p,a}(T_{a,2} - T_{a,1}) - Q_a = 0 (16)$$

To handle the mass term, we need the volume. We have a length of the first tube as  $L_1 = 0.15m$  and  $L_{3,5,...} = 0.3m$ . The cross sectional area of the tube is based on inner diameter, d = 0.003m and outer diameter of d = 0.0142m. The volume of the surrounding air we are interested in has a cross section of  $0.4m \times 0.4m$ . Using the density and the specific heat, we get that  $m_a = 0.0576kg$ ,  $m_w = 2.12 \times 10^{-3}kg$ .

For regions with modules, we can create a small volume,  $m_{a,2,4,6,...} \approx Cm_a$  and  $m_{w,2,4,6,...}Cm_w$ .

#### 3 Steady Model - Matrix Form

Lets write the equations in the form  $\mathbf{A}\mathbf{x} = \mathbf{b}$ 

$$W_1: \qquad (\dot{m}_w C_{p,w} + h_{wa}) T_{w,1} - h_{wa} T_{a,1} = \qquad \dot{m}_w C_{p,w} T_{w,0} \tag{17}$$

$$A_1: (\dot{m}_a C_{p,a} + h_{wa} + h_e + h_i) T_{a,1} - h_{wa} T_{w,1} = \dot{m}_a C_{p,a} T_{a,0} + h_e T_e + h_i T_i$$
(18)

$$W_2: \qquad \dot{m}_w C_{p,w} T_{w,2} - \dot{m}_w C_{p,w} T_{w,1} = Q_w \tag{19}$$

$$A_2: \qquad \dot{m}_a C_{p,a} T_{a,2} - \dot{m}_a C_{p,a} T_{a,1} = Q_a$$
 (20)

$$C_w = \dot{m}_w C_{p,w} \tag{21}$$

$$C_a = \dot{m}_a C_{p,a} \tag{22}$$

$$h_{win} = h_e + h_i (23)$$

$$Q_{win} = h_e T_e + h_i T_i (24)$$

We can write this by defining  $2 \times 2$  and  $4 \times 4$  matrices along with a state vector

$$\mathbf{x}_{i} = [T_{w,i}, T_{a,i}, T_{w,i+1}, T_{a,i+1}]^{T}$$
(25)

for  $i = 1, \dots, n-1$ , which corresponds to a tube/module pair, as

$$\mathbf{A}_0 = \begin{bmatrix} C_w & 0 \\ 0 & C_a \end{bmatrix} \tag{26}$$

$$\mathbf{A}_{1} = \begin{bmatrix} h_{wa} & -h_{wa} \\ -h_{wa} & h_{wa} + h_{win} \end{bmatrix}$$
 (27)

$$\mathbf{B}_0 = \begin{bmatrix} \mathbf{A}_0 + \mathbf{A}_1 & \mathbf{0} \\ -\mathbf{A}_0 & \mathbf{A}_0 \end{bmatrix}$$
 (28)

$$\mathbf{B}_{-1} = \begin{bmatrix} \mathbf{0} & -\mathbf{A}_{\mathbf{0}} \\ \mathbf{0} & \mathbf{0} \end{bmatrix} \tag{29}$$

and writing the boundary condition as  $\mathbf{b}_0 = [\mathbf{x}_0^T \mathbf{A}_0, 0, 0]^T$ ,  $\mathbf{x}_0 = [T_{w,0}, T_{a,0}]^T$  and  $\mathbf{b}_i = [0, Q_{win}, Q_{w,i+1}, Q_{a,i+1}]^T$ to get  $\mathbf{A}_n \mathbf{x} = \mathbf{b}$ 

$$\begin{bmatrix} \mathbf{B}_0 \\ \mathbf{B}_{-1} & \mathbf{B}_0 \\ \mathbf{B}_{-1} & \mathbf{B}_0 \\ & & \ddots & \ddots \end{bmatrix} \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_3 \\ \mathbf{x}_5 \\ \vdots \end{bmatrix} = \begin{bmatrix} \mathbf{b}_1 \\ \mathbf{b}_3 \\ \mathbf{b}_5 \\ \vdots \end{bmatrix} + \begin{bmatrix} \mathbf{b}_0 \\ \mathbf{0} \\ \mathbf{0} \\ \vdots \end{bmatrix}$$
(30)

The eigenvalues of the system can be obtained from  $\mathbf{B}_0$ , itself, with algebraic multiplicity of n for  $\mathbf{A}_n$  as

$$\lambda = C_w, C_a, \frac{1}{2}(C_a + C_w + h_{win} + 2h_{wa}) \pm \frac{1}{2}\sqrt{(C_a - C_w)^2 + 2h_{win}(C_a - C_w + h_{win}) + 4h_{win}}$$
(31)

and an obvious defectiveness of the eigenvalues leading to 4 linearly independent eigenvectors. To calculate the inverse of the system, introduce the matrix product

$$C = B_{-1}B_0^{-1} (32)$$

We have that

$$\mathbf{B}_{0}^{-1} = \begin{bmatrix} (\mathbf{A}_{0} + \mathbf{A}_{1})^{-1} & \mathbf{0} \\ (\mathbf{A}_{0} + \mathbf{A}_{1})^{-1} & \mathbf{A}_{0}^{-1} \end{bmatrix}$$
(33)

$$\mathbf{C} = \begin{bmatrix} -\mathbf{A}_0(\mathbf{A}_0 + \mathbf{A}_1)^{-1} & -\mathbf{I} \\ \mathbf{0} & \mathbf{0} \end{bmatrix}$$
 (34)

$$\mathbf{C} = \begin{bmatrix} -\mathbf{A}_{0}(\mathbf{A}_{0} + \mathbf{A}_{1}) & \mathbf{A}_{0} & \mathbf{I} \\ -\mathbf{A}_{0}(\mathbf{A}_{0} + \mathbf{A}_{1})^{-1} & -\mathbf{I} \\ \mathbf{0} & \mathbf{0} \end{bmatrix}$$

$$\mathbf{B}_{0}^{-1}\mathbf{C} = \begin{bmatrix} -(\mathbf{A}_{0} + \mathbf{A}_{1})^{-1}\mathbf{A}_{0}(\mathbf{A}_{0} + \mathbf{A}_{1})^{-1} & -(\mathbf{A}_{0} + \mathbf{A}_{1})^{-1} \\ -(\mathbf{A}_{0} + \mathbf{A}_{1})^{-1}\mathbf{A}_{0}(\mathbf{A}_{0} + \mathbf{A}_{1})^{-1} & -(\mathbf{A}_{0} + \mathbf{A}_{1})^{-1} \end{bmatrix}$$

$$(34)$$

$$\mathbf{B}_{0}^{-1}\mathbf{C}^{n} = \begin{bmatrix} -(\mathbf{A}_{0} + \mathbf{A}_{1})^{-1}[\mathbf{A}_{0}(\mathbf{A}_{0} + \mathbf{A}_{1})^{-1}]^{n} & -(\mathbf{A}_{0} + \mathbf{A}_{1})^{-1}[\mathbf{A}_{0}(\mathbf{A}_{0} + \mathbf{A}_{1})^{-1}]^{n-1} \\ -(\mathbf{A}_{0} + \mathbf{A}_{1})^{-1}[\mathbf{A}_{0}(\mathbf{A}_{0} + \mathbf{A}_{1})^{-1}]^{n} & -(\mathbf{A}_{0} + \mathbf{A}_{1})^{-1}[\mathbf{A}_{0}(\mathbf{A}_{0} + \mathbf{A}_{1})^{-1}]^{n-1} \end{bmatrix}$$
(36)

Choosing row (or column) i = 1, 2, ..., n, the general formula for  $\mathbf{A}_n^{-1}$  is

$$\mathbf{A}_{n}^{-1} = \begin{bmatrix} \mathbf{B}_{0}^{-1} & & & & & & \\ -\mathbf{B}_{0}^{-1}\mathbf{C} & & \mathbf{B}_{0}^{-1} & & & & \\ \mathbf{B}_{0}^{-1}\mathbf{C}^{2} & & -\mathbf{B}_{0}^{-1}\mathbf{C} & & \mathbf{B}_{0}^{-1} & & & \\ \vdots & & \ddots & & \ddots & & & \\ (-1)^{i-1}\mathbf{B}_{0}^{-1}\mathbf{C}^{i-1} & & \dots & -\mathbf{B}_{0}^{-1}\mathbf{C} & \mathbf{B}_{0}^{-1} & & & \\ \vdots & & & & \ddots & \ddots & & \\ (-1)^{n-1}\mathbf{B}_{0}^{-1}\mathbf{C}^{n-1} & & & \dots & -\mathbf{B}_{0}^{-1}\mathbf{C} & \mathbf{B}_{0}^{-1} \end{bmatrix}$$

$$(37)$$

The solution to the system is then

$$\mathbf{x} = \mathbf{A}_n^{-1} \mathbf{b} \tag{38}$$

# Uncertainty Quantification

To do basic uncertainty quantification, lets define the heat generated as a uncorrelated gaussian random variable

$$Q_{w,i+1} = \bar{Q}_{w,i+1} + \tilde{Q}_{w,i+1} \tag{39}$$

where  $\tilde{Q}_{w,i+1}$  is a gaussian PDF with mean 0 and variance  $\sigma_{i+1}^2$  as

$$\tilde{Q}_{w,i+1} = \frac{1}{\sigma_{i+1}\sqrt{2\pi}} \exp\left[\frac{x^2}{2\sigma_{i+1}^2}\right]$$
(40)

The covariance matrix of **b** is block diagonal, with each block containing

$$\begin{bmatrix}
0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 \\
0 & 0 & \sigma_i^2 & 0 \\
0 & 0 & 0 & 0
\end{bmatrix}$$
(41)

The system can be written as

$$\mathbf{A}_{n}\mathbf{x} = \mathbf{b} + \tilde{\mathbf{b}} \tag{42}$$

and the solution can be written as a gaussian PDF with mean  $\mathbf{A}_n^{-1}\bar{\mathbf{x}}$  and variance  $\Sigma_x = \mathbf{A}_n^{-1}\Sigma_b\mathbf{A}_n^{-T}$ . Using our equation for  $\mathbf{A}_n^{-1}$  and noting that this is a Cholesky decomposition, and maintaining block form,

$$\Sigma_x = \mathbf{A}_n^{-1} \Sigma_b \mathbf{A}_n^{-T} \tag{43}$$

$$\Sigma_x = \mathbf{A}_n^{-1} \Sigma_b^{\frac{1}{2}} (\mathbf{A}_n^{-1} \Sigma_b^{\frac{1}{2}})^T \tag{44}$$

$$\Sigma_{x,ii} = \Sigma_{b,i} + \sum_{j=1}^{i-1} \mathbf{A}_{n,ij}^{-1} \Sigma_{b,j} \mathbf{A}_{n,ij}^{-T}$$

$$\tag{45}$$

$$\Sigma_{x,ij} = \mathbf{A}_{n,ij}^{-1} \Sigma_{b_j} + \sum_{k=1}^{j-1} \mathbf{A}_{n,ik}^{-1} \Sigma_{b,k} \mathbf{A}_{n,jk}^{-T}$$
(46)

The diagonals of this matrix are

$$\Sigma_{x,ii} = \Sigma_{b,i} + \sum_{j=1}^{i-1} \mathbf{A}_{n,ij}^{-1} \Sigma_{b,j} \mathbf{A}_{n,ij}^{-T}$$
(47)

(48)