Mathematics for Machine Learning - Solutions Chapter 2 - Linear Algebra

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2.1.

a) We first attempt to show the group properties:

1. Closure

For the set $\mathbb{R} \setminus \{-1\}$ to be closed under \star , the latter should take two of its elements and yield a number different from -1.

Let us assume that we can get -1 from applying the operator to some $a,b\in\mathbb{R}\setminus\{-1\}$. Then,

$$ab + a + b = -1 \iff ab + a + b + 1 = 0 \iff (a+1)(b+1) = 0,$$
 (1)

so either a=-1 or b=-1. We have reached a contradiction; recall that we introduced the assumption that $a\neq -1$ and $b\neq -1$. Therefore, $\mathbb{R}\setminus\{-1\}$ is closed under \star .

2. Associativity

$$(a \star b) \star c = (ab + a + b) \star c$$

$$= (ab + a + b)c + (ab + a + b) + c$$

$$= a + ab + abc + ac + b + bc + c$$

$$= (abc + ab + ac) + (bc + b + c) + a$$

$$= a(b \star c) + a + (b \star c)$$

$$= a \star (b \star c)$$
(2)

3. Neutral element

 $\forall a \in \mathbb{R} \setminus \{-1\} : a \star 0 = a \cdot 0 + a + 0 = a$, and $0 \star a = 0 \cdot a + 0 + a = a$, so 0 is the neutral element of $(\mathbb{R} \setminus \{-1\}, \star)$.

4. Inverse element We try to find some x for which $\forall a \in \mathbb{R} \setminus \{-1\} : a \star x = x \star a = 0$. We have

$$a \star x = 0$$

$$\iff ax + a + x = 0$$

$$\iff x = -\frac{a}{a+1}.$$
(3)

Since $a \neq -1$ necessarily, the solution for equation 3 always exists. Thus, x is the inverse element of $(\mathbb{R} \setminus \{-1\}, \star)$. This concludes proof that $(\mathbb{R} \setminus \{-1\}, \star)$ is a group.

5. Commutativity

$$\forall a, b \in \mathbb{R} \setminus \{-1\} : a \star b = ab + a + b = ba + b + a = b \star a.$$

Alternatively, we may observe that $a \star b = b \star a$, by the commutativity of addition and multiplication of real numbers.

We conclude that $(\mathbb{R} \setminus \{-1\}, \star)$ is an Abelian group. b)

$$3 \star x \star x = 15 \iff (3x + 3 + x) \star x = 15$$

$$\iff 3x^2 + 3x + x^2 + 3x + 3 + x + x = 15$$

$$\iff 4x^2 + 8x - 12 = 0$$

$$\iff x = 1 \lor x = -3$$

$$(4)$$

Therefore, $x \in \{-3, 1\}$.

2.2. HELP.

2.3. Let A, B be in \mathcal{G} such that

$$\boldsymbol{A} = \begin{bmatrix} 1 & x & z \\ 0 & 1 & y \\ 0 & 0 & 1 \end{bmatrix}, \ \boldsymbol{B} = \begin{bmatrix} 1 & a & c \\ 0 & 1 & b \\ 0 & 0 & 1 \end{bmatrix}, \text{ with } x, y, z, a, b, c \in \mathbb{R}$$

Then,

$$\mathbf{A} \cdot \mathbf{B} = \begin{bmatrix} 1 & a+x & c+bx+z \\ 0 & 1 & b+y \\ 0 & 0 & 1 \end{bmatrix}$$

1. Closure

Since $a + x, b + y, c + bx + z \in \mathbb{R}$, then $\mathbf{A} \cdot \mathbf{B} \in \mathcal{G}$. Therefore, \mathcal{G} is closed under \cdot (matrix multiplication).

2. Associativity

Let us ake A, B as defined above, and let C be in \mathcal{G} such that

$$oldsymbol{C} = egin{bmatrix} 1 & p & r \ 0 & 1 & q \ 0 & 0 & 1 \end{bmatrix}, ext{ with } p,q,r \in \mathbb{R}.$$

Then,

$$(\mathbf{A} \cdot \mathbf{B}) \cdot \mathbf{C} = \begin{bmatrix} 1 & a+x & c+bx+z \\ 0 & 1 & b+y \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & p & r \\ 0 & 1 & q \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & p+a+x & r+qa+qx+c+bx+z \\ 0 & 1 & q+b+y \\ 0 & 0 & 1 \end{bmatrix} .$$

$$(5)$$

Similarly, $A \cdot (B \cdot C)$ yields the same result. Therefore, \cdot is associative.

3. Neutral element

$$\mathbb{I} \cdot \mathbf{A} = \mathbf{A} = \mathbf{A} \cdot \mathbb{I}, \forall \mathbf{A} \in \mathcal{G}.$$

Therefore, I is the neutral element.

4. Inverse element

We need to find the inverse such that

$$\mathbf{A} \cdot \mathbf{A}^{-1} = \mathbb{I}$$
 (neutral element), and $\mathbf{A}^{-1} \cdot \mathbf{A} = \mathbb{I}$.

To find the *right* inverse A_r^{-1} of A, which needs to satisfy $A \cdot A_r^{-1} = \mathbb{I}$, we solve the linear system $A \cdot X = \mathbb{I}$. We write the system in augmented notation $[A|\mathbb{I}]$ and solve using Gaussian Elimination (G.E.), which yields

$$[\boldsymbol{A}|\mathbb{I}] \overset{G.E.}{=} \begin{bmatrix} 1 & 0 & 0 & 1 & -x & xy-z \\ 0 & 1 & 0 & 0 & 1 & -y \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}, \text{ so } \boldsymbol{A}_r^{-1} = \begin{bmatrix} 1 & -x & xy-z \\ 0 & 1 & -y \\ 0 & 0 & 1 \end{bmatrix} \in \mathcal{G}.$$

Since the inverse element is unique, if there is a left inverse \boldsymbol{A}_l^{-1} (i.e., such that $\boldsymbol{A}_l^{-1}\boldsymbol{A}=\mathbb{I}$), then it is equal to the right inverse \boldsymbol{A}_r^{-1} . However, since matrix multiplication is not commutative, we need to check that $\boldsymbol{A}_r^{-1}\boldsymbol{A}=\mathbb{I}$ indeed:

$$\mathbf{A}_{r}^{-1}\mathbf{A} = \begin{bmatrix} 1 & -x & xy - z \\ 0 & 1 & -y \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & x & z \\ 0 & 1 & y \\ 0 & 0 & 1 \end{bmatrix} \\
= \begin{bmatrix} 1 & x - x & z - xy + xy - z \\ 0 & 1 & y - y \\ 0 & 0 & 1 \end{bmatrix} \\
= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \mathbb{I}.$$
(6)

Thus, every element of $\mathcal G$ has an inverse. This concludes proof that $(\mathcal G,\,\cdot)$ is a group.

5. Commutativity

We need only find some $A, B \in \mathcal{G}$ for which $A \cdot B \neq B \cdot A$ to show that \cdot is not commutative. Using A, B as defined above, we have

$$\boldsymbol{B} \cdot \boldsymbol{A} = \begin{bmatrix} 1 & x + a & z + ax + c \\ 0 & 1 & y + b \\ 0 & 0 & 1 \end{bmatrix},$$

which differs from $A \cdot B$ in the element in the position 1, 3. In particular,

e.g., for
$$A = \begin{bmatrix} 1 & 3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
, $B = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$, we have

$$\mathbf{A} \cdot \mathbf{B} = \begin{bmatrix} 1 & 4 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \neq \mathbf{B} \cdot \mathbf{A} = \begin{bmatrix} 1 & 4 & 3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Therefore, \cdot is not commutative, and thus (\mathcal{G}, \cdot) is a non-Abelian group.

2.4

a) The matrices have dimensions (3×2) and (3×3) , respectively. Therefore, the matrix product is not defined for these two matrices.

b)

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 4 & 3 & 5 \\ 10 & 9 & 11 \\ 16 & 15 & 17 \end{bmatrix}$$

c)

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} = \begin{bmatrix} 5 & 7 & 9 \\ 11 & 13 & 15 \\ 8 & 10 & 12 \end{bmatrix}$$

 $\mathbf{d})$

$$\begin{bmatrix} 1 & 2 & 1 & 2 \\ 4 & 1 & -1 & -4 \end{bmatrix} \begin{bmatrix} 0 & 2 \\ 1 & -1 \\ 2 & 1 \\ 5 & 2 \end{bmatrix} = \begin{bmatrix} 14 & 6 \\ -21 & 2 \end{bmatrix}$$

e)

$$\begin{bmatrix} 0 & 3 \\ 1 & -1 \\ 2 & 1 \\ 5 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 & 2 \\ 4 & 1 & -1 & 4 \end{bmatrix} = \begin{bmatrix} 12 & 3 & -3 & -12 \\ -3 & 1 & 2 & 6 \\ 6 & 5 & 1 & 0 \\ 13 & 12 & 3 & 2 \end{bmatrix}$$

2.5. For each of the systems of linear equations, we start by writing them in augmented matrix notation and perform Gaussian Elimination to obtain reduced row-echelon form.

a)

$$\begin{bmatrix} 1 & 1 & -1 & -1 & 1 \\ 2 & 5 & -7 & -5 & -2 \\ 2 & -1 & 1 & 3 & 4 \\ 5 & 2 & -4 & 2 & 6 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & -1 & -1 & 1 \\ 0 & 3 & -5 & -3 & -4 \\ 0 & 0 & -2 & 2 & -2 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

We can see from the last row that the equation system is inconsistent and thus has no solution. Therefore, $S=\emptyset$.

b)

$$\begin{bmatrix} 1 & -1 & 0 & 0 & 1 & 3 \\ 1 & 1 & 0 & -3 & 0 & 6 \\ 2 & -1 & 0 & 1 & -1 & 5 \\ -1 & 2 & 0 & -2 & -1 & -1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & 0 & -1 & 3 \\ 0 & 0 & 0 & 1 & -1 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & -2 & 0 \end{bmatrix}$$

The third row is a tautology, and therefore redundant in the system. We remove it, rearrange the rows, and apply the "minus 1 trick":

$$\begin{bmatrix} 1 & 0 & 0 & 0 & -1 & 3 \\ 0 & 1 & 0 & 0 & -2 & 0 \\ 0 & 0 & -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & -1 & -1 \\ 0 & 0 & 0 & 0 & -1 & 0 \end{bmatrix}$$

The right-hand side of the system is a particular solution, while the two columns with -1 on the diagonal show the directions of the solution space. The solution set is thus

$$S = \left\{ oldsymbol{x} \in \mathbb{R}^5 : oldsymbol{x} = egin{bmatrix} 3 \\ 0 \\ 0 \\ -1 \\ 0 \end{bmatrix} + \lambda_1 egin{bmatrix} 0 \\ 0 \\ -1 \\ 0 \end{bmatrix} + \lambda_2 egin{bmatrix} 3 \\ 0 \\ 0 \\ -1 \\ 0 \end{bmatrix}, \lambda_1, \lambda_2 \in \mathbb{R}
ight\}$$

2.6.

We start by writing the system of linear equations in augmented matrix form and apply Gaussian Elimination to obtain reduced row-echelon form:

$$\begin{bmatrix} 0 & 1 & 0 & 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 1 & 1 & 0 & -1 \\ 0 & 1 & 0 & 0 & 0 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 & 1 & -1 & 1 \end{bmatrix}$$

Applying the "minus 1 trick", we get

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & 0 & 0 & -1 & 0 \end{bmatrix}$$

The right-hand side of the system is a particular solution, while the three columns with -1 on the diagonal show the directions of - and thys span - the solution space. The solution set is then

$$S = \left\{ \boldsymbol{x} \in \mathbb{R}^6 : \boldsymbol{x} = \begin{bmatrix} 0 \\ 1 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix} + \lambda_1 \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + \lambda_2 \begin{bmatrix} 0 \\ 0 \\ -1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + \lambda_3 \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \\ -1 \\ -1 \end{bmatrix}, \lambda_1, \lambda_2, \lambda_3 \in \mathbb{R} \right\}.$$

2.7. We have $Ax = 12x \iff Ax - 12x = 0 \iff (A - 12\mathbb{I})x = 0$. Writing this system of linear equations in augmented form, we have

$$\begin{bmatrix} -6 & 4 & 3 & 0 \\ 6 & -12 & 9 & 0 \\ 0 & 8 & -12 & 0 \end{bmatrix}$$

We can also write the constraint $\sum_{i=1}^{3} x_i = 1 \iff x_1 + x_2 + x_3 = 1$ as another row (equation) in the above matrix, which we also solve to reduced row-echelon form:

$$\begin{bmatrix} -6 & 4 & 3 & 0 \\ 6 & -12 & 9 & 0 \\ 0 & 8 & -12 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 2 \end{bmatrix}$$

Therefore, we have a unique solution $\begin{bmatrix} 3 & 3 & 2 \end{bmatrix}^{\top}$. **2.8.** IN PROGRESS...