

## Joshua Marr

Local: 2024 Unity Place, Louisville, KY 40208 Permanent: 459 Oakview Drive, Shelbyville, Ky, 40065

Phone: 502-202-9423 Email: jtmarr02@louisville.edu

**OBJECTIVE** First Computer Science Internship Position May 3<sup>rd</sup> - August 16<sup>th</sup>, 2023

**EDUCATION Bachelor of Arts in Computer Science**  **Expected May 2025** 

J.B. Speed School of Engineering, University of Louisville, Louisville, Kentucky

GPA 3.57/4.0 Hours Completed: 49

## SKILLS/COURSEWORK

#### **Technical Skills/Relevant Coursework**

- Python Programming
- C, C++
- Java programming\*
- SQL (novice level)\*
- Linux Terminal
- \*Fall 2022

- Discrete Structures
- Data Structures
- Calculus I
- Computer Systems
- Intro to Database

#### **APPLIED EXPERIENCE**

## **Course Projects:**

C: Created an insertion sort algorithm implementing macro programming

C: Created a phonebook, allowing the user to add, delete, and save phone numbers to a file

C++: Created a 3D tic-tac-toe game using object-oriented programming

Python: Created a program that produces a college campus database using object

oriented programming. **Independent Projects:** 

Website Design: Used HTML and templates to create my own website hosted on GitHub (Please see

https://jtm-uofl.github.io/)

Robotics Design and Programming: Designed, built, tested, and programmed both remote controlled and

autonomously controlled robots in High School and University

#### **WORK EXPERIENCE**

# **United Parcel Service (UPS)**

Package Handler

May 2022 - October 2022

Louisville, KY

- Work with others to load packages into feeder trucks and air cans

## **ACTIVITIES/HONORS**

Member, Association for Computing Machinery (ACM), August 2022 – Present

- Member, ACM Cyber Security Group, August 2022 Present
- Member, ACM Competitive Programming, August 2022 Present

Member, Redbird Robotics, August 2021 – Present

- Programed autonomous aerial robot using ROS environment in Linux to compete in a competition

Vice President, Vex Robotics, August 2018 – May 2021

Led a team of 4 that designed, built, and programmed an autonomous and manually controlled robot to compete in various games