Nicklas **Hansen** 📱 +1 (619) 375-9792 | 📧 hello@nicklashansen.com | 🏠 nicklashansen.com | 🗘 nicklashansen | 💆 @ncklashansen | 🛅 ncklas | 📍 San Diego, CA Education University of California, San Diego San Diego, CA, USA PhD student, Computer Science and Engineering, GPA: 3.85/4.0 Fall 2021 - present · Advised by Xiaolong Wang and Hao Su. NVIDIA Graduate Fellow. University of California, Berkeley Berkeley, CA, USA Visiting Student, GPA: 4.0/4.0 Spring 2020 · Spar Nord Fonden's FinTech scholarship recipient. SCET's Collider Cup finalist. **Technical University of Denmark** Kongens Lyngby, Denmark MSc Mathematical Modeling & Computation, GPA: 11.2/12.0 Feb 2019 - Jan 2021 · Special topics in machine learning. Advised by Ole Winther. **Technical University of Denmark** Kongens Lyngby, Denmark BSc Software Technology, GPA: 8.2/12.0, final year GPA: 10.8/12.0 Sep 2015 - Dec 2018 · Nanyang Technological University, Singapore - semester abroad, Fall 2017. Publications & Preprints (21) A Simulation Benchmark for Autonomous Racing with Large-Scale Human Data Under review Under review 2024 Adrian Remonda, Nicklas Hansen, Ayoub Raji, Nicola Musiu, Marko Bertogna, Eduardo E. Veas, Xiaolong Wang To be released

Policy Learning with Large World Models Preprint arXiv preprint 2024 Ignat Georgiev, Varun Giridhar, Nicklas Hansen, Animesh Garg https://arxiv.org/abs/2407.02466 Hierarchical World Models as Visual Whole-Body Humanoid Controllers Preprint arXiv preprint 2024 Nicklas Hansen, Jyothir S V, Vlad Sobal, Yann LeCun, Xiaolong Wang*, Hao Su* https://arxiv.org/abs/2405.18418 A Recipe for Unbounded Data Augmentation in Visual Reinforcement Learning Poster Reinforcement Learning Conference (RLC) 2024 Abdulaziz Almuzairee, **Nicklas Hansen**, Henrik I. Christensen https://arxiv.org/abs/2405.17416

TD-MPC2: Scalable, Robust World Models for Continuous Control
International Conference on Learning Representations (ICLR)

Nicklas Hansen, Hao Su*, Xiaolong Wang*

Best Conference Paper

2024

Open X-Embodiment: Robotic Learning Datasets and RT-X Models
International Conference on Robotics and Automation (ICRA)
Open X-Embodiment Collaboration, [...], Nicklas Hansen, [...] (173 authors)
https://arxiv.org/abs/2310.08864

https://arxiv.org/abs/2310.16828

MoDem-V2: Visuo-Motor World Models for Real-World Robot Learning International Conference on Robotics and Automation (ICRA) Patrick Lancaster, Nicklas Hansen, Aravind Rajeswaran, Vikash Kumar https://arxiv.org/abs/2309.14236	Poster 2024
Finetuning Offline World Models in the Real World Conference on Robot Learning (CoRL) Yunhai Feng*, Nicklas Hansen*, Ziyan Xiong*, Chandramouli Rajagopalan, Xiaolong Wang https://arxiv.org/abs/2310.16029	Oral 2023
Multi-Task Real Robot Learning with Generalizable Neural Feature Fields Conference on Robot Learning (CoRL) Yanjie Ze, Ge Yan, Yueh-Hua Wu, Annabella Macaluso, Yuying Ge, Jianglong Ye, Nicklas Hansen, Li Erran Li, Xiaolong Wang https://arxiv.org/abs/2308.16891	Oral 2023
On Pre-Training for Visuo-Motor Control: Revisiting a Learning-from-Scratch Baseline International Conference on Machine Learning (ICML) Nicklas Hansen*, Zhechen Yuan*, Yanjie Ze*, Tongzhou Mu*, Aravind Rajeswaran^, Hao Su^, Huazhe Xu^, Xiaolong Wang^ https://arxiv.org/abs/2212.05749	Poster 2023
MoDem: Accelerating Visual Model-Based Manipulation with Demonstrations International Conference on Learning Representations (ICLR) Nicklas Hansen, Yixin Lin, Hao Su, Xiaolong Wang, Vikash Kumar, Aravind Rajeswaran https://arxiv.org/abs/2212.05698	Poster 2023
On the Feasibility of Cross-Task Transfer with Model-Based Reinforcement Learning International Conference on Learning Representations (ICLR) Yifan Xu*, Nicklas Hansen*, Zirui Wang, Yung-Chieh Chan, Hao Su, Zhouwen Tu https://arxiv.org/abs/2210.10763	Poster 2023
Visual Reinforcement Learning with Self-Supervised 3D Representations IEEE Robotics and Automation Letters (RA-L) International Conference on Intelligent Robots and Systems (IROS) Yanjie Ze*, Nicklas Hansen*, Yinbo Chen, Mohit Jain, Xiaolong Wang https://arxiv.org/abs/2210.07241	Journal & Poster 2023
Graph Inverse Reinforcement Learning from Diverse Videos Conference on Robot Learning (CoRL) Sateesh Kumar, Jonathan Zamora*, Nicklas Hansen*, Rishabh Jangir, Xiaolong Wang https://arxiv.org/abs/2207.14299	Oral 2022
Temporal Difference Learning for Model Predictive Control International Conference on Machine Learning (ICML) Nicklas Hansen, Xiaolong Wang*, Hao Su* https://arxiv.org/abs/2203.04955	Short Presentation 2022
Look Closer: Bridging Egocentric and Third-Person Views with Transformers for Robotic Man IEEE Robotics and Automation Letters (RA-L) International Conference on Robotics and Automation (ICRA) Rishabh Jangir*, Nicklas Hansen*, Sambaran Ghosal, Mohit Jain, Xiaolong Wang https://arxiv.org/abs/2201.07779	ipulation Journal & Poster 2022
Learning Vision-Guided Quadrupedal Locomotion with Cross-Modal Transformers International Conference on Learning Representations (ICLR) Ruihan Yang*, Minghao Zhang*, Nicklas Hansen, Hauzhe Xu, Xiaolong Wang https://arxiv.org/abs/2107.03996	Spotlight 2022

Poster 2021
Poster 2021
Spotlight 2021
Poster 2020
Teaching Assistant Spring 2024
Co-organizer Jan 2021 eks of full-time study.
Teaching Assistant Fall 2019, Fall 2020 ement learning. Fall 2019
2020 - 2022 2020 - 2022 2021 - 2022 2021 - 2023 2021 - 2023 2021 - 2023 2022 - 2023 2022 - 2023 2021 - 2023 2021 - 2023

2022 - 2024

2023 -

Chandramouli Rajagopalan (MS, UCSD)

Jyothir S V (MS, NYU)

Invited Talks

HuggingFace BeNeRL Seminar TILOS Institute Univ. Michigan Georgia Tech Tech. Univ. Denmark Tsinghua IIIS MILA/ServiceNow Georgia Tech Meta AI (FAIR) TU Delft UCSD RoboGrads Generally Intelligent	"TD-MPC, TD-MPC2, and beyond" "Data-Driven World Models for Robots" "Large Datasets and Models for Robots in the Real World" "Robot Learning with (Generalist) World Models" "Building Generalist World Models" "Data-Driven World Models at Scale: Why, What, and How?" "The Next Generation of World Models" "World Models with Behavioral Priors" "Towards Sample-Efficient Robot Learning with World Models" "Pretraining for Control: Current Challenges and Solutions" "Model-Based Reinforcement Learning: A Path Towards Generalist Agents?" "Model-Based Reinforcement Learning: A Path Towards Generalist Agents?" Podcast: https://generallyintelligent.com/podcast/2022-12-16-podcast-episode-25-nicklas-hansen/	June 2024 June 2024 May 2024 Jan 2024 Jan 2024 Dec 2023 Mar 2023 Feb 2023 Jan 2023 Jan 2023 Oct 2022 Oct 2022 September 2022
Generally Intelligent Intel Al	Podcast: https://generallyintelligent.com/podcast/2022-12-16-podcast-episode-25-nicklas-hansen/ "Temporal Difference Learning for Model Predictive Control"	September 2022 April 2022
Intel Al	"Robots that Generalize"	August 2021
G-Research	"Agents that Generalize and Adapt"	February 2021
Neural Al	"An Introduction to Reinforcement Learning"	June 2019

Academic Service

2024		Reviewer
2024	European Conference on Computer Vision (ECCV)	Reviewer
2024	International Conference on Machine Learning (ICML)	Reviewer
2024	Conference on Computer Vision and Pattern Recognition (CVPR)	Reviewer
2024	International Conference on Learning Representations (ICLR)	Reviewer
2024	IEEE International Conference on Robotics & Automation (ICRA)	Reviewer
2023	Foundation Models for Decision-Making, Workshop @ NeurIPS	Reviewer
2023	Self-Supervised Learning - Theory and Practice, Workshop @ NeurIPS	Reviewer
2023	Journal of Machine Learning Research (JMLR)	Reviewer
2023	International Journal of Computer Vision (IJCV)	Reviewer
2023	Conference on Neural Information Processing Systems (NeurIPS)	Top Reviewer
2023	Learning Dexterous Manipulation, Workshop @ RSS	Reviewer
2023	International Conference on Computer Vision (ICCV)	Reviewer
2023	Structural and Compositional Learning on 3D data, Workshop @ CVPR	Reviewer
2023	IEEE Robotics and Automation Letters (RA-L)	Reviewer
2023	International Conference on Intelligent Robots and Systems (IROS)	Reviewer
2023	International Conference on Machine Learning (ICML)	Reviewer
2023	Conference on Computer Vision and Pattern Recognition (CVPR)	Reviewer
2023	International Conference on Representation Learning (ICLR)	Assisted review
2023	IEEE International Conference on Robotics & Automation (ICRA)	Reviewer
2022	Self-Supervised Learning - Theory and Practice, Workshop @ NeurlPS	Reviewer
2022	Conference on Neural Information Processing Systems (NeurIPS)	Reviewer
2022	European Conference on Computer Vision (ECCV)	Reviewer
2022	IEEE Robotics and Automation Letters (RA-L)	Reviewer
2022	Generalizable Policy Learning in the Physical World, Workshop @ ICLR	Reviewer
2022	International Conference on Machine Learning (ICML)	Reviewer
2022	Conference on Computer Vision and Pattern Recognition (CVPR)	Reviewer
2022	IEEE Robotics and Automation Letters (RA-L)	Reviewer
2021	Association for the Advancement of Artificial Intelligence (AAAI)	Reviewer
2021	International Conference on Machine Learning (ICML)	Assisted review
2020	Annual Conference of the Association for Computational Linguistics (ACL)	Assisted review
2020	SIGNLL Conference on Computational Natural Language Learning (CoNLL)	Assisted review

Workshop Presentations

TD-MPC2: Scalable, Robust World Models for Continuous Control Foundation Models for Decision-Making @ NeurIPS Robot Learning @ NeurIPS Pre-Training Robot Learning @ CoRL	Poster 2023 2023 2023
On Pre-Training for Visuo-Motor Control: Revisiting a Learning-from-Scratch Baseline Pre-Training Robot Learning @ CoRL	Poster 2022
On the Feasibility of Cross-Task Transfer with Model-Based Reinforcement Learning Pre-Training Robot Learning @ CoRL Foundation Models for Decision Making @ NeurIPS Deep RL Workshop @ NeurIPS	Poster 2022 2022 2022
MoDem: Accelerating Visual Model-Based Reinforcement Learning with Demonstrations Pre-Training Robot Learning @ CoRL Deep RL Workshop @ NeurIPS	Poster 2022 2022
Look Closer: Bridging Egocentric and Third-Person Views with Transformers for Robotic Manipulation Workshop on Deployable Decision Making in Embodied Systems @ NeurIPS Deep RL Workshop @ NeurIPS	Poster 2021 2021
Learning Vision-Guided Quadrupedal Locomotion End-to-End with Cross-Modal Transformers Deep RL Workshop @ NeurIPS Visual Learning and Reasoning for Robotics Workshop @ RSS	Poster 2021 2021
Stabilizing Deep Q-Learning with ConvNets and Vision Transformers under Data Augmentation Unsupervised RL Workshop @ ICML Visual Learning and Reasoning for Robotics Workshop @ RSS	Poster 2021 2021
Self-Supervised Policy Adaptation During Deployment Microsoft Research RL Day Deep RL Workshop @ NeurIPS Workshop on Robot Learning @ NeurIPS	Poster 2021 2020 2020
Work Even evidence	

Work Experience

NVIDIA Research Seattle, WA, USA Research Intern June 2024 -

· Robot Learning. Mentored by Yashraj Narang and Dieter Fox.

Meta AI (FAIR) Menlo Park, CA, USA Research Intern June 2022 - Dec 2022

· Model-Based Reinforcement Learning. Mentored by Aravind Rajeswaran.

raffle.ai Copenhagen, Denmark

Machine Learning Intern Summer 2019

· I built and open-sourced a cross-domain text-to-SQL parser in PyTorch.

Retune DSP Kongens Lyngby, Denmark Feb 2019 - Dec 2019 Student Assistant

· I helped a team of engineers build and maintain deep learning pipelines for embedded voice control.

Nordic Transition Gentofte, Denmark

Student Software Developer

July 2016 - Dec 2019

· I developed and maintained a data management and analysis platform for the HR industry.

Awards and Scholarships

2023	NVIDIA Graduate Fellowship 2024-25	Fellowship
2021	· An award of \$60,000 to cover stipend and tuition for 1 year (10 recipients worldwide). Robotics Summer School Scholarship	Scholarship
2021	· A scholarship to participate in a two-week summer program in Denmark.	Scholarship
2020	Spar Nord Fond Scholarship	Scholarship
	· A scholarship to study a semester at UC Berkeley (5 recipients nation-wide).	
2020	UC Berkeley's SCET Collider Cup Finalist	Award
2020	· Biannual startup competition. Best student project from each class is nominated. Innovation Center Denmark's SPARK Winner	A
2020	Best project in a 6-month entrepreneurial program in the Bay Area.	Award
2017	Otto Mønsted Fonds Legat	Scholarship
	· A grant for students with a GPA >= 8.0 who wish to study a semester abroad.	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,
Volun	iteering	
2023 2022	UC San Diego GradAMP Mentor (PhD Applications) · Supported prospective students through weekly mentor-mentee meetings in Fall.	Mentorship
Misc.	Open-Source Projects	
· Publ	PC2 Official Implementation (★265) ic code release for "TD-MPC2: Scalable, Robust World Models for Continuous Control". /github.com/nicklashansen/tdmpc2	2023
· Publ	m Official Implementation (★82) ic code release for "MoDem: Accelerating Visual Model-Based Manipulation with Demonstrations/github.com/facebookresearch/modem	2022
· Publ	PC Official Implementation (★301) ic code release for "Temporal Difference Learning for Model Predictive Control". /github.com/nicklashansen/tdmpc	2022
· Bend	chtrol Generalization Benchmark (*159) chmark for generalization in continuous control from pixels. /github.com/nicklashansen/dmcontrol-generalization-benchmark	2020
· Publ	Official Implementation (110) ic code release for "Policy Adaptation During Deployment". /github.com/nicklashansen/policy-adaptation-during-deployment	2020
· Code	Activity Detection in Noisy Environments (★184) e for training and running a neural Voice Activity Detector (VAD) in PyTorch. /github.com/nicklashansen/voice-activity-detection	2019
· Educ	o build RNNs and LSTMs from scratch with NumPy (*240) cational material on recurrent neural networks. /github.com/nicklashansen/rnn_lstm_from_scratch	2019