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## This lecture

#### 00

- Object-oriented design
  - Assignment Operator
    - Copy control
    - Copy control with hierarchies
  - Exceptions Ch. 18.1
  - Static attributes and methods, Ch. 7.6
  - Inline functions, Ch. 6.5.2
  - Friend operator, Ch. 7.2.1



# Review: Copy Constructor vs. Assignment Operator

Copy constructor creates a new object

```
Point2D pt1( 3.0, 4.0 );
Point2D pt(pt1);
```

- Creates a new object pt by calling the copy constructor.
   pt1 is a Point2D (same type than pt) which existed before the call.
- Assignment operator makes two existing objects the same

```
Point2D pt, pt1(3.0, 4.0);
pt = pt1;
```

- Copies the content of an existing object pt1 to another existing object pt
- Both are synthesized by the compiler!



# **Review: Deep Copy**

Consider the following class with a pointer member

```
class Stack {
  int d capacity, d size;
  string* d stack;
public:
  Stack( int capacity = 10 ) :
       d capacity { capacity }, d size {0},
       d stack{new string[ capacity]}
  { }
  ~Stack() { delete [] d stack; }
  Stack& push (const string& s);
  string pop();
  string top() const;
  void print() const;
```

# **Review Deep Copy**

### Stack example without defining a deep copy is in error

Define a deep copy

## Rule of 3/5

If a class needs a non-default copy constructor, it also needs a non-default destructor and assignment operator

- Assignment operator prototype
  - operator and not a constructor as we are assigning to an existing object
  - return type is a reference to the assigned to object as we want to chain assignment

```
Stack& Stack::operator=( const Stack& oS )
```

 Rule of 3 has become rule of 5 in some cases with C++11 for move ctor and move assignment (to be discussed later)



# **Deep Assignment**

Must check for self assignment!

```
Stack& Stack::operator=( const Stack& oS ) {
    if (this != &oS) {
     delete [] d stack;
     d size = oS.d size;
     d capacity = oS.d capacity;
     d stack = new string[d capacity];
      for ( int i=0; i<d size; ++i ) {
        d stack[i] = oS.d stack[i];
    return *this;
```

# Review: Copy Constructor and Class Hierarchies

- Default Copy Constructor
  - Calls copy constructor of base class first
- Defined copy constructor
  - Must explicitly call copy constructor of base class

```
class House : protected Building {
    ...
public:
    House( const House& _oHouse )
    : Building{_oHouse}, d_noOccu{_oHouse.d_noOccu} {}
};
```

# **Assignment Operator and Class Hierarchies**

- Default assignment operator
  - Calls assignment operator of base class first
- Defined assignment operator
  - Must explicitly call assignment operator of base class

```
class House : protected Building {
public:
   const House& operator=( const House& _oHouse ) {
     // Should always check against self-assignment
     if ( this != &_oHouse ) {
        Building::operator=( _oHouse );
        d_noOccu = _oHouse.d_noOccu;
     } return *this; }
};
```

# **Exceptions**

- Key concept in object-oriented programming
- Supports Robustness

### Advantages

- Code where the error occurs and code to deal with the error can be separated
- Exceptions can be used with constructors and other functions/operators which can not return an error code
- Properly implemented exceptions lead to better code



# **Basic Exception Concepts**

### try

- Try executing some block of code
- See if an error occurs

#### throw

- An error condition occurred
- Throw an exception

#### catch

Handle an exception thrown in a try block



# C++ Exception Syntax

- Syntax is again very similar to Java
- Except for empty throw (rethrows the currently handled exception) and catch(...) (catch all)

```
try-block:
   try compound-statement handler-list
handler-list:
   handler handler-listont
handler:
   catch ( exception-declaration ) compound-statement
exception-declaration:
   type-specifier-list declarator
   type-specifier-list abstract-declarator
   type-specifier-list
throw-expression:
   throw assignment-expression ont
```

# **An Example**

```
size t szA; int* iA;
try { // try block
  cin >> szA;
  if ( cin.fail() ) {
    string line; getline(cin, line); throw line;
  iA = new int[szA];
  cout << "Array of size " << szA
       << " successfully allocated." << endl;</pre>
 delete[] iA;
} catch ( string inLine ) {
  cerr << "Error: Not an integer:" << inLine <<endl;</pre>
  throw; // re-throw exception
 catch (...) { // Catch anything else
```

 Note: In C++, the argument for throw can be of any type. No requirement for it to be a subclass of an exception.

## **Static Members**

#### Static class attributes

- Sharing a variable between all instances of a class
- Same concept than a static variable in a function

#### Static class methods

- Global functions; static member functions exist without object
  - no object to access, no this, no non-static attributes, no non-static methods (similar to Java)
- Access modifiers can be applied

#### Note:

 Static variables are not initialized in a constructor but default initialized the same way as global variables



## **Initialization of Static Class Variables**

- Static class variables must be defined and initialized outside the class
  - Might be used without an object of the class!
- Useful convention
- Declare in header file (as usual):

```
class MountainBike {
   static const float WHEELSIZE; ...
```

## Define in cpp file OUTSIDE any method!

```
static const float MountainBike::WHEELSIZE = 26.0f;
```



# In-class Initialization of Static Class Variables

- const Types initialized from constant expression can be initialized in the class
  - Before C++11 only const integral and enumeration types could be initialized in class with a constant expression
  - use constexpr to clarify
  - can only use literal types (e.g., no strings)

```
class MountainBike {
  static constexpr float WHEELSIZE = 26.0f;
...
}
```

## **Inline Functions**

- Inline functions (methods) avoid overhead for function call at run-time
  - Inline functions (methods) are "copied" and "pasted" into code
  - Access methods should (typically) be inlined to avoid overhead of function calls
- Example

```
class Matrix3D {
  double d_elements[9];
public:
  inline double& element( int _row, int _col );
}
```

# **Restrictions on Inlining**

- Inline method must be available when used
  - Define in header file together with declaration
  - 2 possible variations, use the second (separation of class functionality and method implementation.)

```
// header file
class Matrix3D {
  double d_elements[9];
  inline void element( int _row, int _col, double _val ) {
    d_elements[ _row * 3 + _col ] = _val;
  }
  inline double element( int _row, int _col );
}
double Matrix3D::element( int _row, int _col ) {
  return d_elements[ _row * 3 + _col ]; }
```

# **More Restrictions on Inlining**

### Inline is a compiler directive

- Inlining can save substantial overhead, function calls are expensive
- Compiler may choose to ignore inline
- Compiler switches are important, e.g., in Visual C++ debug mode methods are usually not inlined
  - Often makes debug mode useless for matrix and image classes which use a lot of inlined accessor methods

## **Friends**

- Friend keyword changes access rights
  - Friend can be applied to classes, global or member functions and global or member operators
- Application
  - A set of classes which deal with a common issue
    - Similar to java package accessibility
- Example

```
class Matrix3D;
class Vector3D {
    friend class Matrix3D;
...
}
```

# **Example: Friendly Matrix Vector Multiply**

```
class Vector3D {
  friend class Matrix3D;
  double d components[3]; ... }
class Matrix3D {
 double d elements[9]; ... }
Vector3D Matrix3D::Multiply( Vector3D& vec ) {
 Vector3D res:
  for ( int row=0; row<3; row++ ) {
    res.d components[row] = 0.0;
    for ( int col=0; col<3; col++ ) {
      res.d components[row] += d elements[row*3+col] *
        vec.d components[col];
  } }
  return res;
```

# **Less Friendly**

- Friend keyword can be applied to a specific function or operator
  - limits access to protected and private members to specific operator or function
- Example

```
class Matrix3D;
class Vector3D {
    friend Vector3D Matrix3D::Multiply( Vector3D& );
}
```

Note: Previous implementation example works with the above declaration as well



# **Limitation of Friendship**

### Friend is not inherited, e.g.:

- B has friend access to A
- childA is derived class from A
- childB is derived class from B
- childB cannot access A
- childA cannot be accessed by B

## Friend is not transitive, e.g.:

- C has friend access to B
- B has friend access to A
- C does not have access to A

```
class B;
class A {
  friend class B;
}
class childA : A;
class childB : B;
```

```
class C;
class B {
  friend class C;
}
class A {
  friend class B;
}
```



## Next

#### 00

- Object-oriented design
  - Polymorphism
    - Virtual Functions, Ch. 15.3, 15.7
    - Abstract classes, Ch. 15.4
    - Dynamic cast, Ch. 19.2.1