

Scalar and vector potentials, Helmholtz decomposition, and de Rham cohomology

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Outline

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- 4 Helmholtz decomposition
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The objects

Beyond a doubt, among the “stars” of vector calculus we have the operators

- **grad**
- **div**
- **curl**

Aim of this talk is to understand better their properties and their connections with some topological concepts.

First results

First well-known results are (just compute...):

- $\mathbf{curl} \mathbf{grad} \psi = \mathbf{0}$ for each scalar function ψ
- $\operatorname{div} \mathbf{curl} \mathbf{H} = 0$ for each vector field \mathbf{H} .

We can thus write

Theorem (1)

If $\mathbf{H} = \mathbf{grad} \psi$, then $\mathbf{curl} \mathbf{H} = \mathbf{0}$ (namely, \mathbf{H} is curl-free).

Theorem (2)

If $\mathbf{B} = \mathbf{curl} \mathbf{A}$, then $\operatorname{div} \mathbf{B} = 0$ (namely, \mathbf{B} is divergence-free).

First results (cont'd)

The natural question is:

- are these conditions sufficient?

We will see that the answer depends on the **geometry** of the region Ω where we are working.

In the whole space...

Let us start from $\Omega = \mathbb{R}^3$. We need some tools. First of all we know [just compute...] that the function

$$K(\mathbf{x}, \mathbf{y}) = \frac{1}{4\pi} \frac{1}{|\mathbf{x} - \mathbf{y}|} \quad (1)$$

satisfies

$$-\Delta_{\mathbf{x}} K(\mathbf{x}, \mathbf{y}) = 0 \quad \text{for } \mathbf{x} \neq \mathbf{y}$$

$$\int_{\partial B} \mathbf{grad}_{\mathbf{x}} K(\mathbf{x}, \mathbf{0}) \cdot \mathbf{n}(\mathbf{x}) dS_{\mathbf{x}} = -1,$$

where B is the ball of center $\mathbf{0}$ and radius 1, and \mathbf{n} the unit outward normal on ∂B .

Dirac δ_0 distribution

[Indeed, in a more advanced mathematical language, the function $K(\mathbf{x}, \mathbf{y})$ is the *fundamental solution* of the $-\Delta$ operator, namely, it satisfies $-\Delta_x K(\mathbf{x}, \mathbf{y}) = \delta_0(\mathbf{x} - \mathbf{y})$ in the distributional sense, δ_0 being the *Dirac delta distribution* centered at $\mathbf{0}$.

Roughly speaking, for each (suitable...) function f the Dirac delta distribution satisfies

$$\int_{\mathbb{R}^3} \delta_0(\mathbf{x} - \mathbf{y}) f(\mathbf{y}) d\mathbf{y} = f(\mathbf{x}).$$

We also know that the function

$$u(\mathbf{x}) = \int_{\mathbb{R}^3} K(\mathbf{x}, \mathbf{y}) f(\mathbf{y}) d\mathbf{y}$$

satisfies $-\Delta u = f$ in \mathbb{R}^3 . In fact (formally...)

$$\begin{aligned} -\Delta u(\mathbf{x}) &= -\Delta_x \left[\int_{\mathbb{R}^3} K(\mathbf{x}, \mathbf{y}) f(\mathbf{y}) d\mathbf{y} \right] = \int_{\mathbb{R}^3} [-\Delta_x K(\mathbf{x}, \mathbf{y})] f(\mathbf{y}) d\mathbf{y} \\ &= \int_{\mathbb{R}^3} \delta_0(\mathbf{x} - \mathbf{y}) f(\mathbf{y}) d\mathbf{y} = f(\mathbf{x}). \end{aligned}$$

Scalar and vector potentials

Let us come to the determination of a **scalar potential** for a curl-free vector field \mathbf{H} (namely, a scalar function ψ such that $\mathbf{grad} \psi = \mathbf{H}$) and of a **vector potential** \mathbf{A} for a divergence-free vector field \mathbf{B} (namely, a vector field \mathbf{A} such that $\mathbf{curl} \mathbf{A} = \mathbf{B}$).

Consider a vector field \mathbf{H} and define in \mathbb{R}^3 the function

$$\psi(\mathbf{x}) = - \int_{\mathbb{R}^3} K(\mathbf{x}, \mathbf{y}) \operatorname{div} \mathbf{H}(\mathbf{y}) d\mathbf{y}. \quad (2)$$

Consider a vector field \mathbf{B} and define in \mathbb{R}^3 the vector field

$$\mathbf{A}(\mathbf{x}) = \int_{\mathbb{R}^3} K(\mathbf{x}, \mathbf{y}) \mathbf{curl} \mathbf{B}(\mathbf{y}) d\mathbf{y}. \quad (3)$$

Theorems

Theorem (3)

Assume that \mathbf{H} decays sufficiently fast at infinity and satisfies $\operatorname{curl} \mathbf{H} = \mathbf{0}$ in \mathbb{R}^3 . The function ψ satisfies $\operatorname{grad} \psi = \mathbf{H}$ in \mathbb{R}^3 .

Proof. It is easily shown that

$$D_{x_i} K(\mathbf{x}, \mathbf{y}) = -\frac{1}{4\pi} \frac{x_i - y_i}{|\mathbf{x} - \mathbf{y}|^3} = -D_{y_i} K(\mathbf{x}, \mathbf{y}),$$

hence (formally, and using that $D_i H_j = D_j H_i \dots$)

$$\begin{aligned} D_i \psi(\mathbf{x}) &= - \int_{\mathbb{R}^3} D_{x_i} K(\mathbf{x}, \mathbf{y}) \operatorname{div} \mathbf{H}(\mathbf{y}) d\mathbf{y} = \int_{\mathbb{R}^3} D_{y_i} K(\mathbf{x}, \mathbf{y}) \operatorname{div} \mathbf{H}(\mathbf{y}) d\mathbf{y} \\ &= - \sum_j \int_{\mathbb{R}^3} D_{y_j} D_{y_i} K(\mathbf{x}, \mathbf{y}) H_j(\mathbf{y}) d\mathbf{y} = \sum_j \int_{\mathbb{R}^3} D_{y_j} K(\mathbf{x}, \mathbf{y}) D_i H_j(\mathbf{y}) d\mathbf{y} \\ &= \sum_j \int_{\mathbb{R}^3} D_{y_j} K(\mathbf{x}, \mathbf{y}) D_j H_i(\mathbf{y}) d\mathbf{y} = - \int_{\mathbb{R}^3} \Delta_y K(\mathbf{x}, \mathbf{y}) H_i(\mathbf{y}) d\mathbf{y} \\ &= \int_{\mathbb{R}^3} \delta_0(\mathbf{x} - \mathbf{y}) H_i(\mathbf{y}) d\mathbf{y} = H_i(\mathbf{x}). \end{aligned}$$

□

Theorems (cont'd)

Theorem (4)

Assume that \mathbf{B} decays sufficiently fast at infinity and satisfies $\operatorname{div} \mathbf{B} = \mathbf{0}$ in \mathbb{R}^3 . The vector field \mathbf{A} satisfies $\operatorname{curl} \mathbf{A} = \mathbf{B}$ (and $\operatorname{div} \mathbf{A} = 0$) in \mathbb{R}^3 .

Proof. We have

$$\begin{aligned} D_1 A_2(\mathbf{x}) &= \int_{\mathbb{R}^3} D_{x_1} K(\mathbf{x}, \mathbf{y})(D_3 B_1 - D_1 B_3)(\mathbf{y}) d\mathbf{y} \\ &= - \int_{\mathbb{R}^3} D_{y_1} K(\mathbf{x}, \mathbf{y})(D_3 B_1 - D_1 B_3)(\mathbf{y}) d\mathbf{y} \\ &= \int_{\mathbb{R}^3} [-D_{y_1} D_{y_1} K(\mathbf{x}, \mathbf{y}) B_3(\mathbf{y}) + D_{y_3} D_{y_1} K(\mathbf{x}, \mathbf{y}) B_1(\mathbf{y})] d\mathbf{y} \\ &= \int_{\mathbb{R}^3} [-D_{y_1} D_{y_1} K(\mathbf{x}, \mathbf{y}) B_3(\mathbf{y}) - D_{y_3} K(\mathbf{x}, \mathbf{y}) D_1 B_1(\mathbf{y})] d\mathbf{y}. \end{aligned}$$

Similarly,

$$D_2 A_1(\mathbf{x}) = \int_{\mathbb{R}^3} [D_{y_2} D_{y_2} K(\mathbf{x}, \mathbf{y}) B_3(\mathbf{y}) + D_{y_3} K(\mathbf{x}, \mathbf{y}) D_2 B_2(\mathbf{y})] d\mathbf{y}.$$

Theorems (cont'd)

Since $D_1 B_1 + D_2 B_2 = -D_3 B_3$, we find

$$\begin{aligned} & - \int_{\mathbb{R}^3} D_{y_3} K(\mathbf{x}, \mathbf{y}) [D_1 B_1(\mathbf{y}) + D_2 B_2(\mathbf{y})] d\mathbf{y} \\ &= \int_{\mathbb{R}^3} D_{y_3} K(\mathbf{x}, \mathbf{y}) D_3 B_3(\mathbf{y}) d\mathbf{y} = - \int_{\mathbb{R}^3} D_{y_3} D_{y_3} K(\mathbf{x}, \mathbf{y}) B_3(\mathbf{y}) d\mathbf{y}, \end{aligned}$$

hence

$$\begin{aligned} D_1 A_2(\mathbf{x}) - D_2 A_1(\mathbf{x}) &= - \int_{\mathbb{R}^3} \Delta_y K(\mathbf{x}, \mathbf{y}) B_3(\mathbf{y}) d\mathbf{y} \\ &= \int_{\mathbb{R}^3} \delta_0(\mathbf{x} - \mathbf{y}) B_3(\mathbf{y}) d\mathbf{y} = B_3(\mathbf{x}). \end{aligned}$$

Repeating the same computations for the other components, the first part of the thesis follows.

On the other hand

$$\begin{aligned} D_1 A_1(\mathbf{x}) &= - \int_{\mathbb{R}^3} D_{y_1} K(\mathbf{x}, \mathbf{y}) (D_2 B_3 - D_3 B_2)(\mathbf{y}) d\mathbf{y} \\ &= - \int_{\mathbb{R}^3} [D_{y_1} K(\mathbf{x}, \mathbf{y}) D_2 B_3(\mathbf{y}) - D_{y_3} K(\mathbf{x}, \mathbf{y}) D_1 B_2(\mathbf{y})] d\mathbf{y}, \end{aligned}$$

and, proceeding similarly for $D_2 A_2$ and $D_3 A_3$, the second part of the thesis is easily verified.

Leading idea

What has been the **idea**?

- If ψ satisfies $\mathbf{grad} \psi = \mathbf{H}$, then

$$-\operatorname{div} \mathbf{H} = -\operatorname{div} \mathbf{grad} \psi = -\Delta \psi,$$

hence we can use the (scalar) integral representation formula in terms of the fundamental solution K ;

- if \mathbf{A} satisfies $\mathbf{curl} \mathbf{A} = \mathbf{B}$ (and $\operatorname{div} \mathbf{A} = 0$), then

$$\mathbf{curl} \mathbf{B} = \mathbf{curl} \mathbf{curl} \mathbf{A} = \mathbf{curl} \mathbf{curl} \mathbf{A} - \mathbf{grad} \operatorname{div} \mathbf{A} = -\Delta \mathbf{A},$$

hence we can use the (vector) integral representation formula in terms of the fundamental solution K .

Biot–Savart formulas

An alternative (and essentially equivalent) point of view is the one leading to the **Biot–Savart formulas**:

- Scalar potential: look for $\psi = \operatorname{div} \mathbf{grad} \varphi$.

If ψ satisfies $\mathbf{grad} \psi = \mathbf{H}$, then

$$\mathbf{H} = \mathbf{grad} \operatorname{div} \mathbf{grad} \varphi = \Delta \mathbf{grad} \varphi,$$

hence

$$\mathbf{grad} \varphi = - \int_{\mathbb{R}^3} K(\mathbf{x}, \mathbf{y}) \mathbf{H}(\mathbf{y}) d\mathbf{y}$$

and

$$\psi(\mathbf{x}) = \frac{1}{4\pi} \int_{\mathbb{R}^3} \frac{\mathbf{x} - \mathbf{y}}{|\mathbf{x} - \mathbf{y}|^3} \cdot \mathbf{H}(\mathbf{y}) d\mathbf{y}. \quad (4)$$

Biot–Savart formulas (cont'd)

- Vector potential: look for $\mathbf{A} = \operatorname{curl} \mathbf{Q}$ (with $\operatorname{div} \mathbf{Q} = 0$).

If \mathbf{A} satisfies $\operatorname{curl} \mathbf{A} = \mathbf{B}$, then

$$\mathbf{B} = \operatorname{curl} \operatorname{curl} \mathbf{Q} = -\Delta \mathbf{Q},$$

hence

$$\mathbf{Q}(\mathbf{x}) = \int_{\mathbb{R}^3} K(\mathbf{x}, \mathbf{y}) \mathbf{B}(\mathbf{y}) d\mathbf{y}$$

and

$$\mathbf{A}(\mathbf{x}) = \frac{1}{4\pi} \int_{\mathbb{R}^3} \frac{\mathbf{y} - \mathbf{x}}{|\mathbf{x} - \mathbf{y}|^3} \times \mathbf{B}(\mathbf{y}) d\mathbf{y}. \quad (5)$$

In a bounded domain...

The problem is more complicated in a bounded domain Ω . However, some well-known results are usually presented in any calculus course.

Theorem (5)

Assume that \mathbf{H} satisfies $\operatorname{curl} \mathbf{H} = \mathbf{0}$ in Ω and that any closed curve in Ω is the boundary of a suitable surface $S \subset \Omega$. Then there exists a scalar function ψ satisfying $\operatorname{grad} \psi = \mathbf{H}$ in Ω .

Proof. Since the flux of $\operatorname{curl} \mathbf{H}$ is vanishing on each surface S , from the Stokes theorem the line integral of \mathbf{H} on each closed curve in Ω is vanishing. \square

In a bounded domain... (cont'd)

- A domain Ω for which any closed curve $c \subset \Omega$ is the boundary of a surface $S \subset \Omega$ is called **homologically trivial**.

Many of you could have in mind the following definition: a domain Ω is said to be **simply-connected** if any closed curve $c \subset \Omega$ can be retracted in Ω to a point $\mathbf{p} \in \Omega$. [Using a different language, it is called **homotopically trivial**.]

The preceding theorem has clarified this fact: for establishing if a curl-free vector field is a gradient, the relevant geometrical property is related to homology, not to homotopy.

Question (left apart... but we will come back to it):

- A simply-connected domain is clearly homologically trivial. Do we have examples of homologically trivial domains that are **not** simply-connected?

In a bounded domain... (cont'd)

Concerning the vector potential, we have the (less known...) result:

Theorem (6)

Assume that \mathbf{B} satisfies $\operatorname{div} \mathbf{B} = 0$ in Ω and that any closed surface in Ω is the boundary of a suitable subdomain $D \subset \Omega$. Then there exists a **scalar function** \mathbf{A} satisfying $\operatorname{curl} \mathbf{A} = \mathbf{B}$ in Ω .

Proof. Since the integral of $\operatorname{div} \mathbf{B}$ is vanishing in each subdomain D , from the divergence theorem the flux of \mathbf{B} on each closed surface in Ω is vanishing. This is enough to guarantee the existence of a vector potential \mathbf{A} (more details later on...). \square

In a bounded domain... (cont'd)

Other simple results are the following:

Theorem (7)

Assume that \mathbf{H} satisfies $\operatorname{curl} \mathbf{H} = \mathbf{0}$ in Ω and $\mathbf{H} \times \mathbf{n} = \mathbf{0}$ on $\partial\Omega$.

Then there exists a scalar function ψ satisfying $\operatorname{grad} \psi = \mathbf{H}$ in Ω .

Proof. Extend \mathbf{H} by $\mathbf{0}$ outside Ω ; since $\mathbf{H} \times \mathbf{n} = \mathbf{0}$ on $\partial\Omega$, the extension is still curl-free, therefore it is the gradient of a scalar potential in \mathbb{R}^3 . □

In a bounded domain... (cont'd)

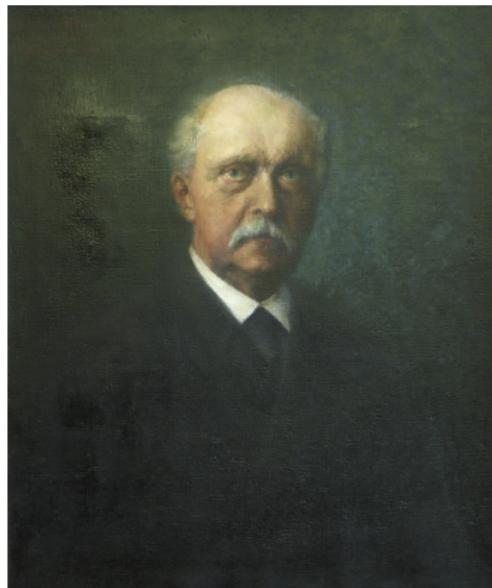
Theorem (8)

Assume that \mathbf{B} satisfies $\operatorname{div} \mathbf{B} = 0$ in Ω and $\mathbf{B} \cdot \mathbf{n} = 0$ on $\partial\Omega$. Then there exists a vector field \mathbf{A} satisfying $\operatorname{curl} \mathbf{A} = \mathbf{B}$ in Ω .

Proof. Extend \mathbf{B} by $\mathbf{0}$ outside Ω ; since $\mathbf{B} \cdot \mathbf{n} = 0$ on $\partial\Omega$, the extension is still divergence-free, therefore it is the curl of a vector potential in \mathbb{R}^3 . □

- But: can we find **necessary and sufficient** conditions?

Helmholtz



Hermann von Helmholtz (1821–1894),
in a painting by Hans Schadow (1891).

Harmonic fields

A way for finding the answer is the resort to the so-called **Helmholtz decomposition**: any vector field can be written as the sum of a gradient and a curl.

For stating the precise results we need the definitions of the spaces of **harmonic fields**:

$$\mathcal{H}(m; \Omega) = \{\mathbf{w} \in (L^2(\Omega))^3 \mid \mathbf{curl} \, \mathbf{w} = \mathbf{0}, \operatorname{div} \mathbf{w} = 0, \mathbf{w} \cdot \mathbf{n} = 0 \text{ on } \partial\Omega\}$$

$$\mathcal{H}(e; \Omega) = \{\mathbf{w} \in (L^2(\Omega))^3 \mid \mathbf{curl} \, \mathbf{w} = \mathbf{0}, \operatorname{div} \mathbf{w} = 0, \mathbf{w} \times \mathbf{n} = \mathbf{0} \text{ on } \partial\Omega\}.$$

Note that an element of $\mathcal{H}(m; \Omega)$ can be written as the **curl** of a vector potential, an element of $\mathcal{H}(e; \Omega)$ can be written as the **gradient** of a scalar potential.

Harmonic fields (cont'd)

A preliminary remark about the structure of these spaces: they are “reading” some topological properties of the domain Ω . In fact:

Theorem (9)

Let Ω be topologically equivalent to a ball. Then $\mathcal{H}(m; \Omega) = \{\mathbf{0}\}$ and $\mathcal{H}(e; \Omega) = \{\mathbf{0}\}$.

Proof. Let $\mathbf{w} \in \mathcal{H}(m; \Omega)$ or $\mathbf{w} \in \mathcal{H}(e; \Omega)$. Since a ball is homologically trivial, we have $\mathbf{w} = \mathbf{grad} \psi$, where ψ satisfies $\Delta \psi = 0$ in Ω . When $\mathbf{w} \in \mathcal{H}(m; \Omega)$ we also have $\mathbf{grad} \psi \cdot \mathbf{n} = 0$ on $\partial\Omega$. Well-known results on the Neumann problem furnish $\mathbf{grad} \psi = \mathbf{0}$ in Ω . When $\mathbf{w} \in \mathcal{H}(e; \Omega)$, we also have $\mathbf{grad} \psi \times \mathbf{n} = 0$ on $\partial\Omega$. Since $\partial\Omega$ is connected, we obtain $\psi = \text{const}$ on $\partial\Omega$. Well-known results on the Dirichlet boundary value problem for the Laplace operator give $\psi = \text{const}$ and $\mathbf{grad} \psi = \mathbf{0}$ in Ω . □



Harmonic fields (cont'd)

A doubt:

- Have we examples of **non-trivial** harmonic fields?

The answer is "**yes**".

- Take the magnetic field generated in the vacuum by a current of constant intensity I^0 passing along the x_3 -axis: as it is well-known, for $x_1^2 + x_2^2 > 0$ it is given by

$$\mathbf{H}(x_1, x_2, x_3) = \frac{I^0}{2\pi} \left(-\frac{x_2}{x_1^2 + x_2^2}, \frac{x_1}{x_1^2 + x_2^2}, 0 \right).$$

As Maxwell equations require, one sees that $\mathbf{curl} \, \mathbf{H} = \mathbf{0}$ and $\operatorname{div} \mathbf{H} = 0$. Consider the torus T obtained by rotating a disk (contained in the plane $\{x_2 = 0\}$) around the x_3 -axis: it is easily checked that $\mathbf{H} \cdot \mathbf{n} = 0$ on ∂T . Hence we have found a non-trivial harmonic field $\mathbf{H} \in \mathcal{H}(m; T)$.

Harmonic fields (cont'd)

- Consider the electric field generated in the vacuum by a pointwise charge ρ_0 placed at the origin. For $\mathbf{x} \neq \mathbf{0}$ it is given by

$$\mathbf{E}(x_1, x_2, x_3) = \frac{\rho_0}{4\pi\varepsilon_0} \frac{\mathbf{x}}{|\mathbf{x}|^3},$$

where ε_0 is the electric permittivity of the vacuum. It satisfies $\operatorname{div} \mathbf{E} = 0$ and $\operatorname{curl} \mathbf{E} = \mathbf{0}$, and moreover $\mathbf{E} \times \mathbf{n} = \mathbf{0}$ on the boundary of $C = B_{R_2} \setminus \overline{B_{R_1}}$ (here $0 < R_1 < R_2$, and B_R is the ball of centre $\mathbf{0}$ and radius R). We have thus found a non-trivial harmonic field $\mathbf{E} \in \mathcal{H}(e; C)$.

Helmholtz decomposition

Theorem (10)

Any vector function $\mathbf{v} \in (L^2(\Omega))^3$ can be decomposed into the following sum

$$\mathbf{v} = \mathbf{curl} \mathbf{Q} + \mathbf{grad} \psi + \boldsymbol{\rho}, \quad (6)$$

where $\boldsymbol{\rho} \in \mathcal{H}(m; \Omega)$ (hence it can be written as the curl of a vector potential), and each term of the decomposition is orthogonal to the others.

Moreover, if $\mathbf{curl} \mathbf{v} = \mathbf{0}$ in Ω it follows $\mathbf{Q} = \mathbf{0}$, if $\operatorname{div} \mathbf{v} = 0$ in Ω and $\mathbf{v} \cdot \mathbf{n} = 0$ on $\partial\Omega$ one has $\mathbf{grad} \psi = \mathbf{0}$, and if $\mathbf{v} \perp \mathcal{H}(m; \Omega)$ one finds $\boldsymbol{\rho} = \mathbf{0}$.

Helmholtz decomposition (cont'd)

Proof. Take: the vector field \mathbf{Q} solution to

$$\begin{cases} \operatorname{\mathbf{curl}} \operatorname{\mathbf{curl}} \mathbf{Q} = \operatorname{\mathbf{curl}} \mathbf{v} & \text{in } \Omega \\ \operatorname{div} \mathbf{Q} = 0 & \text{in } \Omega \\ \mathbf{Q} \times \mathbf{n} = \mathbf{0} & \text{on } \partial\Omega \\ \mathbf{Q} \perp \mathcal{H}(e; \Omega); \end{cases}$$

the scalar function ψ solution to

$$\begin{cases} \Delta \psi = \operatorname{div} \mathbf{v} & \text{in } \Omega \\ \operatorname{\mathbf{grad}} \psi \cdot \mathbf{n} = \mathbf{v} \cdot \mathbf{n} & \text{on } \partial\Omega; \end{cases}$$

the vector field ρ , orthogonal projection of \mathbf{v} on $\mathcal{H}(m; \Omega)$.

Helmholtz decomposition (cont'd)

The orthogonality is easily checked:

$$\int_{\Omega} \mathbf{curl} \mathbf{Q} \cdot \mathbf{grad} \psi = \int_{\Omega} \mathbf{Q} \cdot \mathbf{curl grad} \psi + \int_{\partial\Omega} \mathbf{n} \times \mathbf{Q} \cdot \mathbf{grad} \psi = 0$$

$$\int_{\Omega} \mathbf{curl} \mathbf{Q} \cdot \boldsymbol{\rho} = \int_{\Omega} \mathbf{Q} \cdot \mathbf{curl} \boldsymbol{\rho} + \int_{\partial\Omega} \mathbf{n} \times \mathbf{Q} \cdot \boldsymbol{\rho} = 0,$$

$$\int_{\Omega} \mathbf{grad} \psi \cdot \boldsymbol{\rho} = - \int_{\Omega} \psi \operatorname{div} \boldsymbol{\rho} + \int_{\partial\Omega} \psi \mathbf{n} \cdot \boldsymbol{\rho} = 0.$$

Moreover we have

$$\begin{cases} \mathbf{curl} (\mathbf{v} - \mathbf{curl} \mathbf{Q} - \mathbf{grad} \psi - \boldsymbol{\rho}) = \mathbf{0} & \text{in } \Omega \\ \operatorname{div} (\mathbf{v} - \mathbf{curl} \mathbf{Q} - \mathbf{grad} \psi - \boldsymbol{\rho}) = 0 & \text{in } \Omega \\ (\mathbf{v} - \mathbf{curl} \mathbf{Q} - \mathbf{grad} \psi - \boldsymbol{\rho}) \cdot \mathbf{n} = 0 & \text{on } \partial\Omega \end{cases}$$

(recall that $\mathbf{Q} \times \mathbf{n} = \mathbf{0}$ gives $\mathbf{curl} \mathbf{Q} \cdot \mathbf{n} = 0$ on $\partial\Omega$),

Helmholtz decomposition (cont'd)

Hence we have found

$$(\mathbf{v} - \operatorname{\mathbf{curl}} \mathbf{Q} - \operatorname{\mathbf{grad}} \psi - \rho) \in \mathcal{H}(m; \Omega),$$

but we also have

$$(\mathbf{v} - \operatorname{\mathbf{curl}} \mathbf{Q} - \operatorname{\mathbf{grad}} \psi - \rho) \perp \mathcal{H}(m; \Omega),$$

therefore $\mathbf{v} = \operatorname{\mathbf{curl}} \mathbf{Q} + \operatorname{\mathbf{grad}} \psi + \rho.$

□

The characterization theorem for scalar potentials

We can conclude with

Theorem (11)

The following statements are equivalent:

- there exists a scalar function φ such that $\mathbf{v} = \mathbf{grad} \varphi$ in Ω
- $\mathbf{curl} \mathbf{v} = \mathbf{0}$ in Ω and $\mathbf{v} \perp \mathcal{H}(m; \Omega)$.

Proof. We have only to check that $\mathbf{grad} \varphi \perp \mathcal{H}(m; \Omega)$. Taking $\rho \in \mathcal{H}(m; \Omega)$ we have

$$\int_{\Omega} \mathbf{grad} \varphi \cdot \rho = - \int_{\Omega} \varphi \operatorname{div} \rho + \int_{\partial\Omega} \varphi \mathbf{n} \cdot \rho = 0.$$

□

Helmholtz decomposition

Theorem (12)

Any vector function $\mathbf{v} \in (L^2(\Omega))^3$ can be decomposed into the following sum

$$\mathbf{v} = \mathbf{curl} \mathbf{A} + \mathbf{grad} \chi + \boldsymbol{\eta}, \quad (7)$$

where $\boldsymbol{\eta} \in \mathcal{H}(e; \Omega)$ (hence it can be written as the gradient of a scalar potential), and each term of the decomposition is orthogonal to the others.

Moreover, if $\mathbf{curl} \mathbf{v} = \mathbf{0}$ in Ω and $\mathbf{v} \times \mathbf{n} = \mathbf{0}$ on $\partial\Omega$ it follows

$\mathbf{A} = \mathbf{0}$, if $\operatorname{div} \mathbf{v} = 0$ in Ω one has $\mathbf{grad} \chi = \mathbf{0}$, and if $\mathbf{v} \perp \mathcal{H}(e; \Omega)$ one finds $\boldsymbol{\eta} = \mathbf{0}$.

Helmholtz decomposition (cont'd)

Proof. Take: the vector field \mathbf{A} solution to

$$\left\{ \begin{array}{ll} \operatorname{\mathbf{curl}} \operatorname{\mathbf{curl}} \mathbf{A} = \operatorname{\mathbf{curl}} \mathbf{v} & \text{in } \Omega \\ \operatorname{div} \mathbf{A} = 0 & \text{in } \Omega \\ \mathbf{A} \cdot \mathbf{n} = 0 & \text{on } \partial\Omega \\ \operatorname{\mathbf{curl}} \mathbf{A} \times \mathbf{n} = \mathbf{v} \times \mathbf{n} & \text{on } \partial\Omega \\ \mathbf{Q} \perp \mathcal{H}(m; \Omega); \end{array} \right.$$

the scalar function χ solution to

$$\left\{ \begin{array}{ll} \Delta \chi = \operatorname{div} \mathbf{v} & \text{in } \Omega \\ \chi = 0 & \text{on } \partial\Omega; \end{array} \right.$$

the vector field $\boldsymbol{\eta}$, orthogonal projection of \mathbf{v} on $\mathcal{H}(e; \Omega)$.

Helmholtz decomposition (cont'd)

The orthogonality is easily checked:

$$\int_{\Omega} \mathbf{curl} \mathbf{A} \cdot \mathbf{grad} \chi = \int_{\Omega} \mathbf{A} \cdot \mathbf{curl grad} \chi - \int_{\partial\Omega} \mathbf{n} \times \mathbf{grad} \chi \cdot \mathbf{A} = 0$$

$$\int_{\Omega} \mathbf{curl} \mathbf{A} \cdot \boldsymbol{\eta} = \int_{\Omega} \mathbf{A} \cdot \mathbf{curl} \boldsymbol{\eta} - \int_{\partial\Omega} \mathbf{n} \times \boldsymbol{\eta} \cdot \mathbf{A} = 0,$$

$$\int_{\Omega} \mathbf{grad} \chi \cdot \boldsymbol{\eta} = - \int_{\Omega} \chi \operatorname{div} \boldsymbol{\eta} + \int_{\partial\Omega} \chi \mathbf{n} \cdot \boldsymbol{\eta} = 0.$$

Moreover we have

$$\begin{cases} \mathbf{curl} (\mathbf{v} - \mathbf{curl} \mathbf{A} - \mathbf{grad} \chi - \boldsymbol{\eta}) = \mathbf{0} & \text{in } \Omega \\ \operatorname{div} (\mathbf{v} - \mathbf{curl} \mathbf{A} - \mathbf{grad} \chi - \boldsymbol{\eta}) = 0 & \text{in } \Omega \\ (\mathbf{v} - \mathbf{curl} \mathbf{A} - \mathbf{grad} \chi - \boldsymbol{\eta}) \times \mathbf{n} = \mathbf{0} & \text{on } \partial\Omega. \end{cases}$$

Helmholtz decomposition (cont'd)

Hence we have found

$$(\mathbf{v} - \operatorname{\mathbf{curl}} \mathbf{A} - \operatorname{\mathbf{grad}} \chi - \boldsymbol{\eta}) \in \mathcal{H}(e; \Omega),$$

but we also have

$$(\mathbf{v} - \operatorname{\mathbf{curl}} \mathbf{A} - \operatorname{\mathbf{grad}} \chi - \boldsymbol{\eta}) \perp \mathcal{H}(e; \Omega),$$

therefore $\mathbf{v} = \operatorname{\mathbf{curl}} \mathbf{A} + \operatorname{\mathbf{grad}} \chi + \boldsymbol{\eta}$.

□

The characterization theorem for vector potentials

We can conclude with

Theorem (13)

The following statements are equivalent:

- there exists a vector field \mathbf{w} such that $\mathbf{v} = \mathbf{curl} \mathbf{w}$ in Ω
- $\operatorname{div} \mathbf{v} = \mathbf{0}$ in Ω and $\mathbf{v} \perp \mathcal{H}(e; \Omega)$.

Proof. We have only to check that $\mathbf{curl} \mathbf{w} \perp \mathcal{H}(e; \Omega)$. Taking $\eta \in \mathcal{H}(e; \Omega)$ we have

$$\int_{\Omega} \mathbf{curl} \mathbf{w} \cdot \eta = \int_{\Omega} \mathbf{w} \cdot \mathbf{curl} \eta - \int_{\partial\Omega} \mathbf{n} \times \eta \cdot \mathbf{w} = 0.$$

□

Back to the harmonic fields

It is now useful trying to characterize the spaces of harmonic fields $\mathcal{H}(m; \Omega)$ and $\mathcal{H}(e; \Omega)$.

Let us start from the latter. Denote by $(\partial\Omega)_j$, $j = 0, 1, \dots, p$, the connected components of $\partial\Omega$ ($(\partial\Omega)_0$ being the external one).

Theorem (14)

*The space $\mathcal{H}(e; \Omega)$ is finite dimensional. Its dimension is p (one less than the number of the connected components of $\partial\Omega$). A basis is given by **grad** w_j , $j = 1, \dots, p$, where w_j is the solution of*

$$\begin{cases} \Delta w_j = 0 & \text{in } \Omega \\ w_j = 0 & \text{on } \partial\Omega \setminus (\partial\Omega)_j \\ w_j = 1 & \text{on } (\partial\Omega)_j \end{cases}$$

Back to the harmonic fields (cont'd)

Proof. Clearly, $\mathbf{grad} w_j \in \mathcal{H}(e; \Omega)$. It is enough to show that they give a basis. From $\sum_{j=1}^p \alpha_j \mathbf{grad} w_j = \mathbf{0}$ we find

$\sum_{j=1}^p \alpha_j w_j = \text{const.}$ Since all the w_j are 0 on $(\partial\Omega)_0$, it follows

$\sum_{j=1}^p \alpha_j w_j = 0$ in $\bar{\Omega}$. But $\sum_{j=1}^p \alpha_j w_j = \alpha_k$ on $(\partial\Omega)_k$, hence $\alpha_k = 0$ for each $k = 1, \dots, p$, and $\mathbf{grad} w_j$ are linearly independent.

Take now $\eta \in \mathcal{H}(e; \Omega)$. We already know that there exists q such that $\mathbf{grad} q = \eta$. Due to the boundary condition $\mathbf{grad} q \times \mathbf{n} = \mathbf{0}$ we know that q is constant on each connected component $(\partial\Omega)_j$, $j = 0, 1, \dots, p$ (and on $(\partial\Omega)_0$ we can suppose that it is vanishing).

Define $\beta_j = q|_{(\partial\Omega)_j}$, $j = 1, \dots, p$, and consider $z = q - \sum_{j=1}^p \beta_j w_j$.

We have $\Delta z = 0$ in Ω and $z = 0$ on $(\partial\Omega)_k$, $k = 0, 1, \dots, p$.

Therefore we obtain $z = 0$, hence $q = \sum_{j=1}^p \beta_j w_j$ in Ω , and $\mathbf{grad} w_j$ are generators. □

Back to the characterization theorem for vector potentials

This characterization of $\mathcal{H}(e; \Omega)$ permits to rephrase the main theorem on vector potentials.

Theorem (15)

The following statements are equivalent:

- there exists a vector field \mathbf{w} such that $\mathbf{v} = \mathbf{curl} \mathbf{w}$ in Ω
- $\operatorname{div} \mathbf{v} = \mathbf{0}$ in Ω and $\int_{(\partial\Omega)_j} \mathbf{v} \cdot \mathbf{n} = 0$ for each $j = 1, \dots, p$.

Proof. We have only to check the meaning of the condition $\mathbf{v} \perp \mathcal{H}(e; \Omega)$. We find, by integration by parts

$$\begin{aligned} 0 &= \int_{\Omega} \mathbf{v} \cdot \mathbf{grad} w_j = - \int_{\Omega} \operatorname{div} \mathbf{v} w_j + \int_{\partial\Omega} \mathbf{v} \cdot \mathbf{n} w_j \\ &= \int_{(\partial\Omega)_j} \mathbf{v} \cdot \mathbf{n}. \end{aligned}$$



Another theorem for vector potentials (rephrased)

We are now in a condition to prove a result we stated before.

Theorem (16)

Assume that a divergence-free vector field \mathbf{B} has vanishing flux on each closed surface in Ω . Then there exists of a vector field \mathbf{A} such that $\operatorname{curl} \mathbf{A} = \mathbf{B}$.

Proof. Nothing has to be proved if the boundary of Ω is connected. If it is not connected, slightly “inflating” a connected component $(\partial\Omega)_j$ we find a closed surface S_j in Ω . From the divergence theorem, the flux of \mathbf{B} on S_j is equal to the flux of \mathbf{B} on $(\partial\Omega)_j$, hence the latter is vanishing. \square

Homology and de Rham cohomology

The characterization of $\mathcal{H}(m; \Omega)$ is less straightforward, and needs a (very) brief dive in the theory of algebraic topology. First of all, two definitions:

- the **first homology group** is given, roughly speaking, by the quotient between the cycles and the bounding cycles in $\overline{\Omega}$.
- the **first de Rham cohomology group** is given by the quotient between the curl-free vector fields and the gradients defined in Ω .

de Rham



Georges de Rham (1903–1990).

[Thanks to Oscar Burlet, Souvenirs de Georges de Rham, 2004, for this picture and the following ones.]

de Rham (cont'd)

A parenthesis, on a different topic:

**Claire-Eliane
Engel
Storia
dell'alpinismo**

Fra la folta degli alpinisti svizzeri figurano arrampicatori di gran classe: André Roch, Georges de Rham, E.-R. Blanchet, morto qualche anno addietro, René Dittert e altri ancora.

La tecnica dei chiodi ha reso accessibile la cresta più difficile, quella di Furggen, con l'immenso strapiombo. Nel 1941 Alfred Perina, Luigi Carrel e Jacques Chiara risalgono completamente il Grand Ressaut in scalata artificiale. Evidentemente è il modo di risolvere quella scalata asperrima. Da allora la via è stata rifatta dal professor G. de Rham e Alfred Tissière di Losanna, poi da Lionel Terray e Louis Lachenal nel luglio 1947.

de Rham (cont'd)



Furggen ridge: second climbing



Homology and de Rham cohomology (cont'd)

Theorem (de Rham)

*The first homology group and the first de Rham cohomology group are finitely generated, and have the same rank, that is given by g , the **first Betti number** of $\overline{\Omega}$.*

In other words, the first homology group is generated by g independent (classes of equivalence of) **non-bounding cycles** in $\overline{\Omega}$, and the first de Rham cohomology group is generated by g independent (classes of equivalence of) **loop fields** in Ω (namely, curl-free vector fields that cannot be represented as gradients in Ω).

Let us denote by $\{\sigma_k\}_{k=1,\dots,g}$, a set of cycles such that their classes of equivalence $\{[\sigma_k]\}_{k=1,\dots,g}$ are generators of the first homology group.

Homology and de Rham cohomology (cont'd)

Theorem (17)

A set of generators of the first de Rham cohomology group is given by the classes of equivalence of g loop fields $\hat{\rho}_k$ such that

$$\oint_{\sigma_k} \hat{\rho}_k \cdot d\mathbf{s} = 1 \quad , \quad \oint_{\sigma_l} \hat{\rho}_k \cdot d\mathbf{s} = 0 \quad \text{for } l \neq k .$$

Proof. It is enough to show that $[\hat{\rho}_k]$ are linearly independent. If $\sum_k \alpha_k [\hat{\rho}_k] = \mathbf{0}$ (namely, if $\sum_k \alpha_k \hat{\rho}_k = \mathbf{grad} \chi$), integrating on σ_l we have

$$0 = \oint_{\sigma_l} \sum_k \alpha_k \hat{\rho}_k \cdot d\mathbf{s} = \alpha_l .$$

□

Back to the harmonic fields

Denote by ω_k the solution of the Neumann problem

$$\begin{cases} \Delta \omega_k = \operatorname{div} \hat{\rho}_k & \text{in } \Omega \\ \mathbf{grad} \omega_k \cdot \mathbf{n} = \hat{\rho}_k \cdot \mathbf{n} & \text{on } \partial\Omega. \end{cases}$$

We have

Theorem (18)

The space $\mathcal{H}(m; \Omega)$ is finite dimensional. Its dimension is g , the first Betti number of $\overline{\Omega}$. A basis is given by $\rho_k = \hat{\rho}_k - \mathbf{grad} \omega_k$, $k = 1, \dots, g$.

Back to the harmonic fields (cont'd)

Proof. The ρ_k are linearly independent, as, from $\sum_k \alpha_k \rho_k = \mathbf{0}$, integrating on σ_I we find

$$\begin{aligned} 0 &= \oint_{\sigma_I} \sum_k \alpha_k \rho_k \cdot d\mathbf{s} = \oint_{\sigma_I} \sum_k \alpha_k [\hat{\rho}_k - \mathbf{grad} \omega_k] \cdot d\mathbf{s} \\ &= \oint_{\sigma_I} \sum_k \alpha_k \hat{\rho}_k \cdot d\mathbf{s} = \alpha_I. \end{aligned}$$

Let $\rho \in \mathcal{H}(m; \Omega)$. Its class of equivalence $[\rho]$ is an element of the first de Rham cohomology group, hence we can write

$$[\rho] = \sum_k \beta_k [\hat{\rho}_k], \quad \rho = \sum_k \beta_k \hat{\rho}_k + \mathbf{grad} \chi,$$

and clearly χ satisfies

$$\begin{cases} \Delta \chi = - \sum_k \beta_k \operatorname{div} \hat{\rho}_k = - \sum_k \beta_k \Delta \omega_k & \text{in } \Omega \\ \mathbf{grad} \chi \cdot \mathbf{n} = - \sum_k \beta_k \hat{\rho}_k \cdot \mathbf{n} = - \sum_k \beta_k \mathbf{grad} \omega_k \cdot \mathbf{n} & \text{on } \partial\Omega. \end{cases}$$

Hence $\mathbf{grad} \chi = - \sum_k \beta_k \mathbf{grad} \omega_k$ and $\rho = \sum_k \beta_k \rho_k$.

Back to the characterization theorem for scalar potentials

This characterization of $\mathcal{H}(m; \Omega)$ permits to rephrase the main theorem on scalar potentials.

Theorem (19)

The following statements are equivalent:

- there exists a scalar function φ such that $\mathbf{v} = \mathbf{grad} \varphi$ in Ω
- $\mathbf{curl} \mathbf{v} = \mathbf{0}$ in Ω and $\oint_{\sigma_k} \mathbf{v} \cdot d\mathbf{s} = 0$ for each $k = 1, \dots, g$.

Proof. It is enough to show that a curl-free vector field \mathbf{v} with $\oint_{\sigma_k} \mathbf{v} \cdot d\mathbf{s} = 0$ for each $k = 1, \dots, g$ can be written as a gradient. First of all, since it is curl-free, from (6) we know that

$\mathbf{v} = \mathbf{grad} \psi + \boldsymbol{\rho}$, and $\boldsymbol{\rho} = \sum_k \beta_k \boldsymbol{\rho}_k$. Integrating on σ_I it follows $0 = \oint_{\sigma_I} \mathbf{v} \cdot d\mathbf{s} = \oint_{\sigma_I} \sum_k \beta_k \boldsymbol{\rho}_k \cdot d\mathbf{s} = \beta_I$, hence $\mathbf{v} = \mathbf{grad} \psi$. \square

Homotopy or homology?

A question was left apart: do we have examples of homologically trivial domains that are **not** simply-connected?

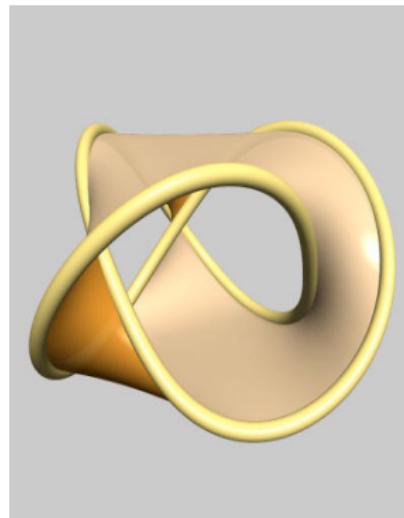
Let us recall the definitions:

- a domain Ω is said **simply-connected** (or homotopically trivial) if any cycle c can be retracted in Ω to a point $\mathbf{p} \in \Omega$
- a domain Ω is said **homologically trivial** if any cycle c is the boundary of a surface $S \subset \Omega$.

Clearly, if a cycle can be retracted to a point, it is also the boundary of a surface. Hence, a **simply-connected domain is homologically trivial**.

However, there are cycles that **are the boundary of a surface**, but that **cannot be retracted** (consider the complement in a box of the trefoil knot, and take a cycle... as explained in the picture).

The trefoil knot



The trefoil knot and its Seifert surface.

[Image produced with SeifertView, Jarke J. van Wijk, Technische Universiteit Eindhoven.]

Homotopy or homology? (cont'd)

This seems to suggest that **there exist** homologically trivial domains that are not simply-connected. However, what we have seen **is not an example of this fact**, as, if we look at the previous picture, in the complement of the trefoil knot there is **another** cycle that is **not** bounding a surface.

So, try to refine the analysis: it is worth noting that, in the engineering literature, this example is indeed the basis for the statement that “homologically trivial” is a less restrictive than “simply-connected”. The reason is that, considering the complement in a box of the trefoil knot **together** with its Seifert surface, we have cut the latter cycle (the one that is non-bounding), without cutting the former (the one that is bounding but cannot be retracted).

Homotopy or homology? (cont'd)

Let us jump to the conclusion:

Theorem (Borsuk, Benedetti–Frigerio–Ghiloni)

Let $\Omega \subset \mathbb{R}^3$ be a bounded domain with Lipschitz boundary. Then it is simply-connected if and only if it is homologically trivial.

And what we have told just above? There is a subtle mistake in the argument: we have not cut the former cycle, but we have cut **the surface** of which it was the boundary!

It can be easily checked that now it is not a bounding cycle (in the electrical engineering language, it links the current running along the Seifert surface).

Homotopy or homology? (cont'd)

Conclusion: you are lucky.

It is true that, speaking about the operators **grad**, **div**, **curl**,
homology (and not homotopy) is the right concept. But we can
still use the words “a simply-connected domain”, as it has the
same meaning of “a homologically trivial domain”.