Flattening Irregular Nested Parallelism

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December 2024 DPP Lecture Slides

Parallel Basic Blocks Recap

Part I: Flattening Nested and Irregular Parallelism
What is "Flattening"? Recipe for Applying Flattening
Several Re-Write Rules (inefficient for replicate & iota)
Jagged (Irregular Multi-Dim) Array Representation
Revisiting the Rewrites for Replicate & Iota Nested Inside Map
Revisiting the Solution to Our Example

Part II: Flattening Nested and Irregular Parallelism Several Applications of Flattening More Flattening Rules Flattening by Function Lifting Flattening Quicksort Flattening Prime-Number (Sieve) Computation

Zip, Unzip, iota, replicate

- zip : $[n]\alpha_1 \rightarrow [n]\alpha_2 \rightarrow [n](\alpha_1, \alpha_2)$
- zip $[a_1,...,a_n]$ $[b_1,...,b_n] \equiv [(a_1,b_1),...,(a_n,b_n)],$
- unzip : $[n](\alpha_1,\alpha_2) \rightarrow ([n]\alpha_1,[n]\alpha_2)$
- unzip $[(a_1,b_1),...,(a_n,b_n)] \equiv ([a_1,...,a_n],[b_1,...,b_n]),$
- In some sense zip/unzip are syntactic sugar
- replicate : (n: int) $\rightarrow \alpha \rightarrow [n]\alpha$
- replicate n a \equiv [a, a,..., a],
- iota : $(n: int) \rightarrow [n]int$
- iota $n \equiv [0, 1, ..., n-1]$

Note: in Haskell zip does not expect same-length arrays; in Futhark it does!

Map, Reduce, and Scan Types and Semantics

- [n] α denotes the type of an array of n elements of type α .
- map : $(\alpha \to \beta) \to [n]\alpha \to [n]\beta$ map f $[x_1,...,x_n] = [f x_1,..., f x_n],$ i.e., $x_i : \alpha, \forall i$, and f : $\alpha \to \beta$.
- reduce : $(\alpha \to \alpha \to \alpha) \to \alpha \to [n]\alpha \to \alpha$ reduce \odot e $[x_1, x_2, ..., x_n]$ = e $\odot x_1 \odot x_2 \odot ... \odot x_n$, i.e., e: α , x_i : α , $\forall i$, and \odot : $\alpha \to \alpha \to \alpha$.
- $\operatorname{scan}^{exc}$: $(\alpha \to \alpha \to \alpha) \to \alpha \to [n]\alpha \to [n]\alpha$ $\operatorname{scan}^{exc} \odot \operatorname{e} [x_1, \dots, x_n] = [\operatorname{e}, \operatorname{e} \odot x_1, \dots, \operatorname{e} \odot x_1 \odot \dots x_{n-1}]$ i.e., $\operatorname{e} : \alpha, x_i : \alpha, \forall i, \text{ and } \odot : \alpha \to \alpha \to \alpha.$
- $\operatorname{scan}^{inc}$: $(\alpha \to \alpha \to \alpha) \to \alpha \to [n]\alpha \to [n]\alpha$ $\operatorname{scan}^{inc}$ ⊙ e $[x_1, \dots, x_n]$ = $[\operatorname{e} \odot x_1, \dots, \operatorname{e} \odot x_1 \odot \dots x_n]$ i.e., $\operatorname{e} : \alpha$, x_i : $\alpha, \forall i$, and \odot : $\alpha \to \alpha \to \alpha$.

Map2, Filter

- $\blacksquare map2: (\alpha_1 \to \alpha_2 \to \beta) \to [n]\alpha_1 \to [n]\alpha_2 \to [n]\beta$
- $\begin{array}{ll} \blacksquare \ \mathsf{map2} \ \odot \ [\mathsf{a}_1, \ldots, \mathsf{a}_n] \ [\mathsf{b}_1, \ldots, \mathsf{b}_n] \ \equiv \\ [\mathsf{a}_1 \odot \mathsf{b}_1, \ldots, \mathsf{a}_n \odot \mathsf{b}_n] \end{array}$
- map3 ...
- filter : $(\alpha \rightarrow \mathsf{Bool}) \rightarrow [\mathsf{n}] \alpha \rightarrow [\mathsf{m}] \alpha \ (\mathsf{m} \le \mathsf{n})$
- filter p $[a_1, \ldots, a_n] = [a_{k_1}, \ldots, a_{k_m}]$ such that $k_1 < k_2 < \ldots < k_m$, and denoting $\overline{k} = k_1, \ldots, k_m$, we have $(p \ a_j == true) \ \forall j \in \overline{k}$, and $(p \ a_j == false) \ \forall j \notin \overline{k}$.

Note: in Haskell map2, map3 do not expect same-length arrays; in Futhark they do!

Scatter: A Parallel Write Operator

Scatter updates in parallel a base array with a set of values at specified indices:

```
scatter : *[m]\alpha \rightarrow [n]int \rightarrow [n]\alpha \rightarrow *[m]\alpha

A (data vector) =[b0, b1, b2, b3]
I (index vector) =[2, 4, 1, -1]
X (input array) =[a0, a1, a2, a3, a4, a5]
scatter X I A =[a0, b2, b0, a3, b1, a5]
```

Scatter: A Parallel Write Operator

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A (data vector) =[b0, b1, b2, b3]
I (index vector) =[2, 4, 1, -1]
X (input array) =[a0, a1, a2, a3, a4, a5]
scatter X I A =[a0, b2, b0, a3, b1, a5]
```

- scatter has $D(n) = \Theta(1)$ and $W(n) = \Theta(n)$, i.e., requires n update operations (n is the size of I or A, not of X!).
 - 1 Array X is consumed by scatter; following uses of X are illegal!
 - 2 Similarly, X can alias neither I nor A!

In Futhark, scatter check and ignores the indices that are out of bounds (no update is performed on those). This is useful for padding the iteration space in order to obtain regular parallelism.

Partition2/Filter Implementation

partition2: $(\alpha \to Bool) \to [n]\alpha \to (i32,[n]\alpha)$ In result, the elements satisfying the predicate occur before the others. Can be implemented by means of map, scan, scatter.

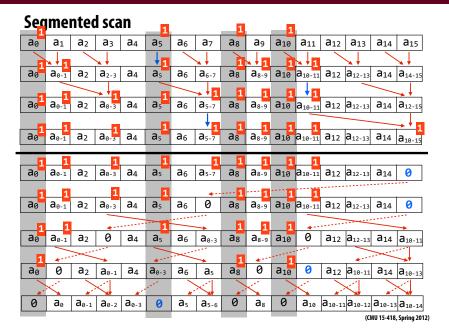
```
let partition 2 't [n] (dummy: t)
      (cond: t \rightarrow bool) (X: [n]t) :
                        (i64. [n]t) =
 let cs = map cond X
 let tfs = map (\ f \rightarrow ) if f then 1
                            else 0) cs
 let isT = scan (+) 0 tfs
 let i = isT[n-1]
 let ffs = map (f-> if f then 0
                           else 1) cs
 let isF = map (+i) < | scan (+) 0 ffs
 let inds=map (\(c,iT,iF) \rightarrow
                    if c then iT-1
                          else iF-1
               ) (zip3 cs isT isF)
 let tmp = replicate n dummy
 in (i, scatter tmp inds X)
```

Assume X = [5,4,2,3,7,8], and cond is T(rue) for even nums.

Partition2/Filter Implementation

```
partition2: (\alpha \to Bool) \to [n]\alpha \to (i32,[n]\alpha)
In result, the elements satisfying the predicate occur before the others. Can be implemented by means of map, scan, scatter.
```

```
let partition 2 't [n] (dummy: t)
                                             Assume X = [5,4,2,3,7,8], and
      (cond: t \rightarrow bool) (X: [n]t) :
                                             cond is T(rue) for even nums.
                       (i64. [n]t) =
                                             n = 6
 let cs = map cond X
                                             cs = \lceil F, T, T, F, F, T \rceil
 let tfs = map (\ f->if f then 1
                                             tfs = \lceil 0, 1, 1, 0, 0, 1 \rceil
                           else 0) cs
 let isT = scan (+) 0 tfs
                                             isT = [0, 1, 2, 2, 3]
 let i = isT[n-1]
                                             i = 3
 let ffs = map (f-> if f then 0
                                             ffs = [1, 0, 0, 1, 1, 0]
                          else 1) cs
                                             isF = [4, 4, 4, 5, 6, 6]
 let isF = map (+i) < | scan (+) 0 ffs
 let inds=map (\((c,iT,iF) \rightarrow
                                             inds= [3, 0, 1, 4, 5, 2]
                   if c then iT-1
                         else iF-1
               ) (zip3 cs isT isF)
                                             flags = [3, 0, 0, 3, 0, 0]
 let tmp = replicate n dummy
                                             Result = [4, 2, 8, 5, 3, 7]
 in (i, scatter tmp inds X)
```



Segmented Scan Is a Sort of Scan

```
def sqmscan 't \lceil n \rceil (op: t->t->t) (ne: t)
               (flq : [n]bool) (arr : [n]t) : [n]t =
  let flqs vals =
    zip flq arr |>
    scan (\ (f1, \times1) (f2, \times2) ->
              let f = f1 || f2
              in if f2 then (f, x2)
                   else (f, op x1 x2)
          ) (false, ne)
  let ( , vals) = unzip flgs vals
  in vals
                                  map (\ row -> scan (+) 0 row)
sqmscan (+) 0 [1,0,0,1,0, 0, 0]
                                     [[1,2,3], [4,5, 6, 7]]
            [1,2,3,4,5, 6, 7]
            Γ1.3.6.4.9.15.227
                                     [[1,3,6], [4,9,15,22]]
```

Correctness Argument:

Segmented Scan Is a Sort of Scan

```
def sqmscan 't \lceil n \rceil (op: t->t->t) (ne: t)
               (flg : [n]bool) (arr : [n]t) : [n]t =
  let flqs vals =
    zip flq arr |>
    scan (\ (f1, \times1) (f2, \times2) ->
              let f = f1 || f2
              in if f2 then (f, x2)
                   else (f, op x1 x2)
          ) (false, ne)
  let ( , vals) = unzip flgs vals
  in vals
sqmscan (+) 0 [1,0,0,1,0, 0, 0]
                                  map (\ row -> scan (+) 0 row)
            [1,2,3,4,5, 6, 7]
                                     [[1,2,3], [4,5, 6, 7]]
            Γ1.3.6.4.9.15.227
                                     [[1,3,6], [4,9,15,22]]
```

Correctness Argument:

verify sequential semantics + associative operator ⇒ parallel semantics also holds

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Several Applications of Flattening
More Flattening Rules
Flattening by Function Lifting
Flattening Quicksort
Flattening Prime-Number (Sieve) Computation

What is "Flattening"?

A code transformation, attributed to Blelloch in the context of the NESL languages, that takes as input a nested parallel program—possibly involving recursion and irregular/jagged arrays—and produces a semantically-equivalent, flat-parallel programs that runs optimally on a PRAM machine.

Meaning: it is guaranteed to preserve the work and depth of the original nested-parallel program.**

** As long as scan has O(1) depth and concat has O(1) work and . . .

Flattening Pros and Cons

Pros:

- + clever code transformation
- important as a programming technique as well (promotes parallel thinking)
- perhaps the only way of mapping a set of challenging problems to capricious architectures such as GPUs (e.g., that do not supports dynamic scheduling of parallelism)

Flattening Pros and Cons

Pros:

- + clever code transformation
- important as a programming technique as well (promotes parallel thinking)
- perhaps the only way of mapping a set of challenging problems to capricious architectures such as GPUs (e.g., that do not supports dynamic scheduling of parallelism)

Cons:

- does not consider communication/locality and hardware gets more and more heterogeneous
- worse, it tends to destroy the available locality and may explode memory footprint
- useful to cover datasets that fall outside the "common case"
 Demonstration at the end of the second Flattening lecture

Flattening: A Bird's Eye View

Incomplete recipe for flattening a nested-parallel program consisting of maps and scan/reduce/scatters at innermost level:

- Normalize the program (think 3-address form).
 The easy way is to replicate free variables appearing in the current map if they are variant in an outer, enclosing map.
- II. Distribute the parallel context (perfect nest of maps) across the enclosed let-binding statements and handle recurrences by function lifting or map-loop interchange. Systematic application results in a smallish number of code patterns.
- III. Apply a set of rewrite rules to flatten each pattern, e.g., treating the cases of a reduce, scan, replicate, iota, scatter, array index which is perfectly nested inside the context.

Flattening: A Bird's Eye View

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Differences w.r.t. the PMPH material:

- 1 **also optimize the number of accesses to global memory** flattening results in memory-bound performance behavior.
- 2 **cover more rewrite rules and more challenging problems** (e.g., divide-and-conquer recursion)

Contrived Example:

```
let arr = [1, 2, 3, 4] in
map (\i -> map (+(i+1)) (iota i)) arr
-- Result: [[2],[3,4],[4,5,6],[5,6,7,8]]
```

Contrived Example:

```
let arr = [1, 2, 3, 4] in
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I. Normalize the code:

Contrived Example:

```
let arr = [1, 2, 3, 4] in
map (\i -> map (+(i+1)) (iota i)) arr
-- Result: [[2],[3,4],[4,5,6],[5,6,7,8]]
```

I. Normalize the code:

II. Distribute the map across every statement in the body and adjust the inputs accordingly (\mathcal{F} denotes the transformation)

```
  \mathcal{F}(\text{map } (\text{i} \rightarrow \text{map } (+(\text{i}+1)) \text{ (iota i)) arr}) \equiv \\ 1. \text{ let ip1s = map } (\text{i} \rightarrow \text{i}+1) \text{ arr in } -- [2, 3, 4, 5] \\ 2. \text{ let iots = } \mathcal{F}(\text{map } (\text{i} \rightarrow \text{(iota i)) arr}) \text{ in} \\ 3. \text{ let ip1rs= } \mathcal{F}(\text{map2 } (\text{i ip1} \rightarrow \text{(replicate i ip1)) arr ip1s}) \\ 4. \text{ in } \mathcal{F}(\text{map2 } (\text{ip1r iot} \rightarrow \text{map2 } (+) \text{ip1r iot}) \text{ ip1rs iots})
```

For simplicity we assume arr contains strictly-positive integers.

According to inefficient rule "iota nested inside a map"

(assuming arr = [1,2,3,4]):

2. let iots = \(\frac{1}{2} \) (\(\) iota i \) arr)

\[
\begin{align*}
\text{inds} = \(\) scan^{exc} (+) \(\) arr \quad \text{---} \(\)

iots = $sqmScan^{exc}$ (+) 0 flag tmp -- [0, 0, 1, 0, 1, 2, 0, 1, 2, 3]

According to inefficient rule "replicate nested inside a map" (assuming arr = [1,2,3,4]):

```
3. let ip1rs= \mathcal{F}(\text{map2 }(\ i \ ip1 \ -> \ replicate \ i \ ip1) \ arr \ ip1s) \equiv vals = scatter (replicate size 0) inds ip1s -- [2,3,0,4,0,0,5,0,0,0] ip1rs= sgmScan^{inc} (+) 0 flag vals -- [2,3,3,4,4,4,5,5,5,5]
```

According to rule "map nested inside a map"

At each step we also reason about the shape of the resulting array. The shape of the 2D jagged arrays iots, ip1rs, result is arr.

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Nested vs Flattened Parallelism: Scan inside a Map

(1) Scan nested inside a map:

```
res = map (\row->scan<sup>inc</sup> (+) 0 row) [[1,3], [2,4,6]] \equiv res = [ scan<sup>inc</sup> (+) 0 [1,3], scan<sup>inc</sup> (+) 0 [2,4,6] ] \equiv res = [ [ 1, 4], [2, 6, 12] ]
```

Nested vs Flattened Parallelism: Scan inside a Map

(1) Scan nested inside a map:

```
res = map (\row->scan<sup>inc</sup> (+) 0 row) [[1,3], [2,4,6]] \equiv res = [ scan<sup>inc</sup> (+) 0 [1,3], scan<sup>inc</sup> (+) 0 [2,4,6] ] \equiv res = [ [ 1, 4], [2, 6, 12] ]
```

becomes a segmented scan, which requires a flag array as arg:

```
sgmScan^{inc} (+) 0 [1, 0, 1, 0, 0] [1, 3, 2, 4, 6] \equiv [ 1, 4, 2, 6, 12 ]
```

Flattening a scan directly nested inside a map:

- S_{arr}^1 , F_{arr} , D_{arr} denote the shape, flag & flat data of input arr.
- The flat-data result is obtained by a segmented scan.
- The shape of the result array is the same as the input array.

```
\mathcal{F}(\text{res} = \text{map (\row -> scan }(\odot) \ \theta_{\odot} \text{ row) arr}) \Rightarrow S_{res}^{1} = S_{arr}^{1}
D_{res} = \text{sgmScan }(\odot) \ \theta_{\odot} \text{ F}_{arr} D_{arr}
```

Nested vs Flattened Parallelism: Map inside a Map

(2) Map nested inside a map:

```
res = map (\row->map f row) [[1,3], [2,4,6]] \equiv res = [ map f [1, 3], map f [2, 4, 6] ] \equiv res = [ [f(1),f(3)], [f(2),f(4),f(6)] ]
```

Nested vs Flattened Parallelism: Map inside a Map

(2) Map nested inside a map:

```
res = map (\row->map f row) [[1,3], [2,4,6]] 

= res = [ map f [1, 3], map f [2, 4, 6] ] 

= res = [ [f(1),f(3)], [f(2),f(4),f(6)] ]
```

Flattening a map directly nested inside a map:

- the flat-data array is obtained by a map on the flat input;
- the shape of the result array is the same as the input array.

```
\mathcal{F}(\text{res} = \text{map (\row -> map f row) arr}) \Rightarrow S_{res}^1 = S_{arr}^1
D_{res} = \text{map f } D_{arr}
```

Nested vs Flattened Parallelism: Replicate inside Map

(3) Replicate nested inside a map:

```
res = map2 (\ n m -> replicate n m) [1,0,3,2] [7,3,8,9] \equiv res = [ replicate 1 7, replicate 0 3, replicate 3 8, replicate 2 9 ] \equiv res = [ [7], [], [8,8,8], [9,9] ]
```

Nested vs Flattened Parallelism: Replicate inside Map

(3) Replicate nested inside a map:

```
res = map2 (\ n m -> replicate n m) \lceil 1,0,3,2 \rceil \lceil 7,3,8,9 \rceil \equiv
res = [ replicate 1 7, replicate 0 3, replicate 3 8, replicate 2 9 ] ≡
res = [7], [7], [8,8,8], [9,9]
res = map2(\n m-> replicate n m) ns ms
```

becomes a scan-scatter composition:

Nested vs Flattened Parallelism: Replicate inside Map

(3) Replicate nested inside a map:

```
res = map2 (\ n m -> replicate n m) [1,0,3,2] [7,3,8,9] =
res = [ replicate 1 7, replicate 0 3, replicate 3 8, replicate 2 9 ] =
res = [ [7], [], [8,8,8], [9,9] ]
```

```
res = map2(\n m-> replicate n m) ns ms
becomes a scan-scatter composition:
```

- 1. the shape of the result array is ns
- 2-3. builds the indices at which segment start (-1 for null shape)
 - 4. get the size of the flat array (summing ns)
- 5-6. write the ms and ns values at the start of their segments
 - $\ensuremath{\mathsf{7}}.$ propagate the ms values throughout their segments.

Nested vs Flattened Parallelism: Iota inside Map

```
(4) lota nested inside a map ((iota n)\equiv[0,...,n-1]): res = map (\i -> iota i) [1,3,2] \equiv res = [ iota 1, iota 3, iota 2 ] \equiv [ [0], [0,1,2], [0,1] ]
```

Nested vs Flattened Parallelism: Iota inside Map

(4) lota nested inside a map ((iota n) \equiv [0,...,n-1]):

```
res = map (\i -> iota i) [1,3,2] \equiv
res = [ iota 1, iota 3, iota 2 ] \equiv [ [0], [0,1,2], [0,1] ]
```

boils down to a segmented scan applied to an array of ones:

- 1. by definition of iota, ns contains the size of each subarray, hence the shape of the result is ns;
- 2-3. the flag-array of the result, F_{res} , is constructed from ns; (we will introduce function mkFlagArray a bit later).
 - 4. the result is obtained by an exclusive segmented scan operation applied to an array of ones.

```
\mathcal{F}(\text{res} = \text{map } (\n -> \text{iota } n) \text{ ns}) \Rightarrow
1. S_{res}^1 = \text{ns} -- ns = [1, 3, 2]
```

Note 1: iota n \equiv scan^{exc} (+) 0 (replicate n 1).

- 2. trues = replicate (length ns) true
- 3. (_, F_{res}) = mkFlagArray ns **false** trues -- F_{res} = [1, 1, 0, 0, 1, 0]
- 4. $D_{res} = sgmScan^{exc}$ (+) 0 F_{res} (replicate flen_{res} 1) -- [0, 0, 1, 2, 0, 1]
- Note 2: 1 and 0 denote true and false; flen_{res} is the sum of ns.

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Shape-Based Representation

Two dimensional arrays:

```
arr = [ [1,2,3], [4], [], [5,6] ]

\Rightarrow

S_{arr}^{0} = [4]

S_{arr}^{1} = [3, 1, 0, 2]

D_{arr} = [1, 2, 3, 4, 5, 6]
```

Shape-Based Representation

Two dimensional arrays:

```
arr = [ [1,2,3], [4], [], [5,6] ]

\Rightarrow

S_{arr}^{0} = [4]

S_{arr}^{1} = [3, 1, 0, 2]

D_{arr} = [1, 2, 3, 4, 5, 6]
```

Three dimensional arrays:

```
arr = [ [], [ [1,2,3], [4], [], [5,6] ], [ [7], [], [8,9,10] ] ] 
⇒
```

Shape-Based Representation

Two dimensional arrays:

```
arr = [ [1,2,3], [4], [], [5,6] ] 

\Rightarrow
S_{arr}^{0} = [4]
S_{arr}^{1} = [3, 1, 0, 2]
D_{arr} = [1, 2, 3, 4, 5, 6]
```

Three dimensional arrays:

```
arr = [ [], [ [1,2,3], [4], [], [5,6] ], [ [7], [], [8,9,10] ] ] \Rightarrow
S_{arr}^{0} = [3]
S_{arr}^{1} = [0, 4, 3]
S_{arr}^{2} = [3, 1, 0, 2, 1, 0, 3]
flen_{arr} = 10
D_{arr} = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10]
```

Assume a n-dimensional array; The following invariant holds:

```
length S_{arr}^i = reduce (+) 0 S_{arr}^{i-1}, \forall 1 \le i < n length D_{arr} = reduce (+) 0 S_{arr}^{n-1}
```

Flat Representation: Auxiliary Structures

```
arr = [ [], [ [1,2,3], [4], [], [5,6] ], [ [7], [], [8,9,10] ] \Rightarrow
S_{arr}^{0} = [3]
S_{arr}^{1} = [0, 4, 3]
S_{arr}^{2} = [3, 1, 0, 2, 1, 0, 3]
D_{arr} = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10]
```

Offset Indices (B): segment-start offset in the flat data:

```
B_{arr}^1 = [0, 0, 6]

B_{arr}^2 = [0, 3, 4, 4, 6, 7, 7]
```

 Flag Array (F): start of a segment indicated by a true value (could also use !=0 integrals), e.g., used for segmented scans:

```
F_{arr}^1 = [1, 0, 0, 0, 0, 0, 1, 0, 0, 0]

F_{arr}^2 = [1, 0, 0, 1, 1, 0, 1, 1, 0, 0]
```

Segment and Inner indices (II):

Auxiliary structures are useful to optimize the replication of values.

Nested-Execution Example:

```
let xss = [ [1,2,3], [], [5,7] ]
let ys = [ 4, 2, 1 ]
let rss = map2 (\ xs y → map (+y) xs ) xss ys

⇒
rss = [ map (+4) [1,2,3], map (+2) [], map (+1) [5,7] ]
rss = [ [5,6,7], [], [6,8] ]
```

Traditional flattening would replicate the values of y:

```
let (S_{yss}^1, D_{yss}) = \mathcal{F}(\text{map2 } (\xs y -> \text{replicate } (\text{length } xs) y) \text{ xss } ys) let D_{rss} = \text{map2 } (\xs y -> x + y) D_{xss} D_{yss} \Rightarrow D_{xss} = [1, 2, 3, 5, 7] + + + + + + + D_{yss} = [4, 4, 4, 1, 1] = = = = = = D_{rss} = [5, 6, 7, 6, 8]
```

Auxiliary structures are useful to optimize the replication of values.

Nested-Execution Example:

```
let xss = [ [1,2,3], [], [5,7] ]
let ys = [ 4, 2, 1 ]
let rss = map2 (\ xs y -> map (+y) xs ) xss ys

⇒
rss = [ map (+4) [1,2,3], map (+2) [], map (+1) [5,7] ]
rss = [ [5,6,7], [], [6,8] ]
```

Using the auxiliary structures we indirectly access other arrays:

```
let D_{rss} = map2 (\ x sgmind -> x + ys[sgmind]) D_{xss} II_{rss}^1 \Rightarrow S_{rss}^1 = [3, 0, 2] II_{rss}^1 = [0, 0, 0, 2, 2] D_{xss} = [1, 2, 3, 5, 7] D_{rss} = [1+4, 2+4, 3+4, 5+1, 7+1] = [5, 6, 7, 6, 8]
```

But what have we gained? Creating II_{rss}^1 is as expensive as xss (or better said the expanded yss from the other slide) ...

Auxiliary structures are useful to optimize replication:

- they depend only on the shape of the result (created once)
- can indirectly access several lower-dimensional arrays, sharing parallel dimensions!

Nested-Execution Example:

```
let xss = [ [1,2,3], [], [5,7] ]
let ys = [ 4, 2, 1 ]
let zs = [ 1, 2, 3 ]
let rss = map3 (\ xs y z → map (\x → x*y + z ) xs ) xss ys zs
⇒
rss = [ [5,9,13], [], [8,10] ]
```

Using the auxiliary structures we indirectly access other arrays:

```
let D_{rss} = map2 (\ y sgmind -> x*ys[sgmind] + zs[sgmind]) D_{xss} | II_{rss}^{1} \Rightarrow | II_{rss}^{1} = [0, 0, 0, 2, 2] | D_{xss} = [1, 2, 3, 5, 7] | D_{rss} = [1*4+1, 2*4+1, 3*4+1, 5*1+3, 7*1+3] = [5, 9, 13, 8, 10]
```

We build II_{rss}^1 once and reuse it twice. Also improves locality: ys and zs are much smaller than xss, hence reused from L1/2\$.

Nested-Execution Example:

```
let xss = [1,3], [2]
let yss = [2], [4,5]
let rss = map2 (\xspace x ys -> map (\xspace x x -> map (+x) ys ) xs ) xss yss
rss = [[3],[5]], [[6,7]]
Using the auxiliary structures we indirectly access other arrays:
let D_{rss} = map3(\ s1 \ s2 \ s3 \rightarrow \ let \ ind_x = B^1_{xss}[s1] + s2
                                    let ind_y = B_{vss}^{1}[s1] + s3
                                   in X[ind_x] + Y[ind_y]
                  | | |_{rss}^{1} |_{rss}^{2} |_{rss}^{3} |_{rss}^{3}
B_{vcc}^1 = [0, 2]
B_{vec}^1 = [0, 1]
```

```
\begin{aligned} & D_{yss} = \{0, 1\} \\ & | I_{rSS} = \{0, 0, 1, 1\} \\ & | I_{rSS} = \{0, 1, 0, 0\} \\ & | I_{rSS} = \{0, 0, 0, 1\} \\ & D_{rSS} = \{0, 0
```

Constructing the Offset Indices (B)

```
arr = [ [], [ [1,2,3], [4], [], [5,6] ], [ [7], [], [8,9,10] ] \Rightarrow
S_{arr}^{0} = [3]
S_{arr}^{1} = [0, 4, 3]
S_{arr}^{2} = [3, 1, 0, 2, 1, 0, 3]
D_{arr} = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10]
```

Offset Indices (B): segment-start offset in the flat data:

```
B_{arr}^1 = [0, 0, 6]

B_{arr}^2 = [0, 3, 4, 4, 6, 7, 7]
```

How to construct Offset Indices (B)?

Constructing the Offset Indices (B)

```
arr = [ [], [ [1,2,3], [4], [], [5,6] ], [ [7], [], [8,9,10] ] \Rightarrow
S_{arr}^{0} = [3]
S_{arr}^{1} = [0, 4, 3]
S_{arr}^{2} = [3, 1, 0, 2, 1, 0, 3]
D_{arr} = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10]
```

Offset Indices (B): segment-start offset in the flat data:

```
B_{arr}^1 = [0, 0, 6]

B_{arr}^2 = [0, 3, 4, 4, 6, 7, 7]
```

How to construct Offset Indices (B)?

By exclusive scanning the corresponding shape and reindexing!

$$B_{arr}^{2} = scan^{exc}$$
 (+) $0 S_{arr}^{2}$ -- [0, 3, 4, 4, 6, 7, 7]
 $B_{arr}^{1} = scan^{exc}$ (+) $0 S_{arr}^{1}$ -- [0, 0, 4]
|> map (\int i -> B_{arr}^{2} [i]) -- [0, 0, 6]

Constructing the Flag Array

From now on, we discuss only TWO-dimensional irregular arrays!

```
def mkFlagArray 't [m]
          (aoa_shp: [m]u32) (zero: t) --aoa_shp = [0,3,1,0,4,2,0]
          (aoa\_val: [m]t) : ([m]u32, []t) = -- aoa\_val = [1,1,1,1,1,1,1]
  let shp_rot = map (\i i -> if i == 0 then 0 -- shp_rot = [0,0,3,1,0,4,2]
                        else aoa_shp[i-1]
                   ) (iota m)
  let shp_scn = scan (+) 0 shp_rot
                                          -- shp_scn = [0,0,3,4,4,8,10
  let aoa_len = if m == 0 then 0i64
                                           -- and len = 10
               else i64.u32 <
                    shp\_scn[m-1]+aoa\_shp[m-1]
  let shp_ind = map2 (\shp ind ->
                                    -- shp_ind=
                      if shp==0 then -1i64 -- [-1,0,3,-1,4,8,-1]
                      else i64.u32 ind -- scatter
                    ) aoa_shp shp_scn -- [0,0,0,0,0,0,0,0,0]
  let r = scatter (replicate aoa_len zero) -- [-1,0,3,-1,4,8,-1]
```

-- [1,1,1, 1,1,1, 1] -- r = [1,0,0,1,1,0,0,0,1,0]

Versatile: computes B¹ and F¹ of a 2D jagged array of shape aoa_shp, with the start-segment values taken from aoa_val.

Unless you have a good reason, F should be a bool array (to reduce memory traffic).

shp_ind aoa_val

in (shp_scn, r)

From now on, we discuss only TWO-dimensional irregular arrays!

```
arr = [ [1,2,3], [4], [], [5,6], [7], [], [8,9,10] ] 

\Rightarrow
S_{arr}^{0} = [7]
S_{arr}^{1} = [3, 1, 0, 2, 1, 0, 3]
S_{arr}^{1} = reduce (+) 0 S_{arr}^{1} = 10
D_{arr} = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10]
```

Segment and Inner indices (II):

```
|1|_{arr}^{1} = [0, 0, 0, 1, 3, 3, 4, 6, 6, 6]
|1|_{arr}^{2} = [0, 1, 2, 0, 0, 1, 0, 0, 1, 2]
```

Constructing Segment and Inner indices (II):

```
(B_{arr}^1, F_{arr}) = mkFlagArray S_{arr}^1 0 (iota (length <math>S_{arr}^1))
-- ([0, 3, 4, 4, 6, 7, 7], [0, 0, 0, 1, 3, 0, 4, 6, 0, 0])
II_{arr}^1 = ???
```

```
||_{arr}^{2} = ???
```

I need to get this:

```
II_{arr}^{1} = [0, 0, 0, 1, 3, 3, 4, 6, 6, 6]
```

from this:

```
(_, F<sub>arr</sub>) = mkFlagArray S_{arr}^1 0 (iota (length S_{arr}^1))
-- [0, 0, 0, 1, 3, 0, 4, 6, 0, 0]
```

How?

I need to get this:

$$|| ||_{arr}^2 = [0, 1, 2, 0, 0, 1, 0, 0, 1, 2]$$

from these:

$$B_{arr}$$
 = [0, 3, 4, 4, 6, 7, 7]
 II_{arr}^1 = [0, 0, 0, 1, 3, 3, 4, 6, 6, 6]
iota 10 = [0, 1, 2, 3, 4, 5, 6, 7, 8, 9]

 II_{arr}^1 and II_{arr}^2 have the same length as flat arr, in our case 10.

How?

We can also construct it by binary searching $B_{\it arr}$ or by means of a segmented scan.

From now on, we discuss only TWO-dimensional irregular arrays!

```
arr = [ [1,2,3], [4], [], [5,6], [7], [], [8,9,10] ]
S_{arr}^0 = [7]
S_{arr}^1 = [3, 1, 0, 2, 1, 0, 3]
flen<sub>arr</sub> = reduce (+) 0 S_{arr}^1 = 10
D_{arr} = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10]
Segment and Inner indices (II):
\prod_{arr}^{1} = [0, 0, 0, 1, 3, 3, 4, 6, 6, 6]
\prod_{arr}^{2} = [0, 1, 2, 0, 0, 1, 0, 0, 1, 2]
Constructing Segment and Inner indices (II):
(B_{arr}^1, F'_{arr}) = mkFlagArray S_{arr}^1 O (iota (length <math>S_{arr}^1))
         -- ([0, 3, 4, 4, 6, 7, 7], [0, 0, 0, 1, 3, 0, 4, 6, 0, 0])
F_{arr} = map bool.u32 F'_{arr}
II_{arr}^{1} = sgmScan^{inc} (+) 0 F_{arr} F'_{arr}
II_{arr}^2 = map2 \ (\ i \ sgm \rightarrow i - B_{arr}^1[sgm] \ ) \ (iota \ flen_{arr}) \ II_{arr}^1
-- ^ this fuses better & performs less memory traffic than the below:
\Pi_{arr}^2 = \text{sgmScan}^{inc} (+) 0 \Gamma_{arr} (replicate flen 1) |> map (-1)
```

B^{inc} and **II**¹ Are the Important Ones

Because you can deduce the other arrays by means of simple maps, that fuse better and generate less traffic.

```
arr = [ [1,2,3], [4], [], [5,6], [7], [], [8,9,10] ] \Rightarrow S_{arr}^{0} = [7] S_{arr}^{1} = [3, 1, 0, 2, 1, 0, 3] flen_{arr} = reduce (+) 0 S_{arr}^{1} = 10 D_{arr} = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10]
```

If we know the Segment Offsets (B_{arr}^{inc}) and Indices (II_{arr}^{1}):

```
B_{arr}^{inc} = [3, 4, 4, 6, 7, 7, 10] -- inclusive scan of S_{arr}^1 and II_{arr}^1 = [0, 0, 0, 1, 3, 3, 4, 6, 6, 6]
```

We can efficiently compute the S_{arr}^1 and F_{arr} arrays (also II_{arr}^2) by:

```
S_{arr}^1 = iota (length B_{arr}^{inc})

|> map (\i -> if i == 0 then B_{arr}^{inc}[i] else B_{arr}^{inc}[i] - B_{arr}^{inc}[i-1])

F_{arr} = iota flen<sub>arr</sub> -- flen<sub>arr</sub> is the length of |I|_{arr}^1

|> map (\i i -> if i == 0 then true else |I|_{arr}^1[i] != |I|_{arr}^1[i-1])
```

Note: B_{arr}^{inc} different than B_{arr}^1 : inclusive vs exclusive scan of shape!

Parallel Basic Blocks Recap

Part I: Flattening Nested and Irregular Parallelism

What is "Flattening"? Recipe for Applying Flattening Several Re-Write Rules (inefficient for replicate & iota) Jagged (Irregular Multi-Dim) Array Representation Revisiting the Rewrites for Replicate & Iota Nested Inside Map Revisiting the Solution to Our Example

Part II: Flattening Nested and Irregular Parallelism

Several Applications of Flattening More Flattening Rules Flattening by Function Lifting Flattening Quicksort Flattening Prime-Number (Sieve) Computation

Revisiting Replicate inside Map

(3) Replicate nested inside a map:

```
res = map2 (\ n m -> replicate n m) [1,0,3,2] [7,3,8,9] = res = [ replicate 1 7, replicate 0 3, replicate 3 8, replicate 2 9 ] = res = [ [7], [], [8,8,8], [9,9] ]
```

```
res = map2(\n m-> replicate n m) ns ms
```

becomes a very simple gather operation:

- 1. the shape of the result array is ns
- 2. build II^1 of a jagged array of shape ns

Revisiting Replicate inside Map

(3) Replicate nested inside a map:

```
res = map2 (\ n m -> replicate n m) [1,0,3,2] [7,3,8,9] =
res = [ replicate 1 7, replicate 0 3, replicate 3 8, replicate 2 9 ] =
res = [ [7], [], [8,8,8], [9,9] ]
```

```
res = map2(\n m-> replicate n m) ns ms
```

becomes a very simple gather operation:

- 1. the shape of the result array is ns
- 2. build II^1 of a jagged array of shape ns
- gather the corresponding values from ms by indexing through II¹

Nested vs Flattened Parallelism: Iota inside Map

(4) lota nested inside a map ((iota n) \equiv [0,...,n-1]): res = map (\i -> iota i) [1,3,2] \equiv res = [iota 1, iota 3, iota 2] \equiv [[0], [0,1,2], [0,1]] res = map (\n-> iota n) ns

The result is exactly the II^2 array of a jagged array of shape ns

```
\mathcal{F}(\text{res} = \text{map } (\backslash n \rightarrow \text{iota } n) \text{ ns}) \Rightarrow
1. S_{res}^1 = \text{ns}
2. II_{res}^2 = \dots -- \text{construct } II^2 \text{ of a jagged array of shape ns}
4. D_{res} = II_{res}^2
```

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Revisiting Our Demonstration of How to Flatten

Contrived Example:

```
let arr = [1, 2, 3, 4] in
map (\i -> map (+(i+1)) (iota i)) arr
-- Result: [[2],[3,4],[4,5,6],[5,6,7,8]]
```

I. Normalize the code:

II. Distribute the map across every statement in the body and adjust the inputs accordingly (\mathcal{F} denotes the transformation)

```
  \mathcal{F}(\mathsf{map} \ (\ i \ -> \ \mathsf{map} \ (+(i+1)) \ (iota\ i)) \ \mathsf{arr}) \equiv \\ 1. \ \mathsf{let} \ \mathsf{ip1s} = \ \mathsf{map} \ (\ i \ -> \ i+1) \ \mathsf{arr} \ \mathsf{in} \ -- \ [2,\ 3,\ 4,\ 5] \\ 2. \ \mathsf{let} \ \mathsf{iots} = \ \mathcal{F}(\mathsf{map} \ (\ i \ -> \ (iota\ i)) \ \mathsf{arr}) \ \mathsf{in} \\ 3. \ \mathsf{let} \ \mathsf{ip1rs} = \ \mathcal{F}(\mathsf{map2} \ (\ i \ \mathsf{ip1} \ -> \ (\mathsf{replicate}\ i \ \mathsf{ip1})) \ \mathsf{arr} \ \mathsf{ip1s}) \\ 4. \ \mathsf{in} \ \mathcal{F}(\mathsf{map2} \ (\ \mathsf{ip1r} \ \mathsf{iot} \ -> \ \mathsf{map2} \ (+) \ \mathsf{ip1r} \ \mathsf{iot}) \ \mathsf{ip1rs} \ \mathsf{iots})
```

We do **not** assume that arr contains strictly-positive integers.

Revisiting Our Example: Think Like a Compiler

1. let ip1s = map ($i \rightarrow i+1$) arr in -- [2, 3, 4, 5]

 $\mathcal{F}(\text{map }(i \rightarrow \text{map }(+(i+1)) \text{ (iota i)) arr}) \equiv$

```
2. let iots = \mathcal{F}(\text{map}(\{i \rightarrow \{i \text{ ota } i\}))) arr) in
3. let ip1rs= \mathcal{F}(\text{map2} (\ i \ \text{ip1} \rightarrow (\text{replicate i ip1})) \ \text{arr ip1s})
4. in \mathcal{F}(\text{map2} (\setminus \text{ip1r iot} \rightarrow \text{map2} (+) \text{ip1r iot}) \text{ ip1rs iots})
Applying the new rules results in:
1. S_{res}^{1} = arr
                                                            -- arr = [1, 2, 3, 4]
2. (B_{res}^1, F_{res}^1) = mkFlagArray arr 0 (iota (length arr))
                                                             --B_{roc}^{1} = [0, 1, 3, 6]
3. F_{res} = map bool.u32 F'_{res}
4. II_{res}^1 = sgmScan^{inc} (+) 0 F<sub>res</sub> F'<sub>res</sub> -- [0, 1,1, 2,2,2, 3,3,3]
5. ip1s = map (\ i -> i+1 ) arr -- [2, 3, 4, 5]
6. iots = map2 (\ ind sqm -> ind - B_{res}^1[sqm] ) (iota flen<sub>res</sub>) II_{res}^1
                                            -- = 11_{arr}^{2} = [0, 0, 1, 0, 1, 2, 0, 1, 2, 3]
7. ip1rs = map (\ sgm -> ip1s[sgm] ) \Pi_{res}^1 -- [2, 3,3, 4,4,4, 5,5,5,5]
8. in map2 (+) ip1rs iots
                                                        -- 12. 3.4. 4.5.6. 5.6.7.81
```

Lines 6-8 are trivially fusable \Rightarrow the iots and ip1rs arrays are not manifested in memory.

Revisiting Our Example: Think Like a Human

I. Normalize the code:

Using the new intuition results in:

Have done a tiny bit better job than the compiler, as array ip1s is not manifested either.

Fusion in Futhark

Map fusion:

```
(\mathsf{map}\ g)\ \circ\ (\mathsf{map}\ f)\ \equiv\ \mathsf{map}\ (g\circ f)
x = \qquad \qquad \mathsf{map}\ f\ [\quad a_1, \qquad a_2, \qquad ..., \qquad a_n \qquad ]
\downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow
x \equiv \qquad \qquad [\quad f\ a_1, \qquad f\ a_2, \qquad ..., \qquad f\ a_n \qquad ]
\downarrow \qquad \qquad \downarrow \qquad \qquad \downarrow
\mathsf{map}\ g\ x = \qquad \qquad [\quad g(f\ a_1), \quad g(f\ a_2), \quad ..., \quad g(f\ a_n) \quad ]
\equiv \qquad \qquad \qquad = \qquad \qquad =
\mathsf{map}\ (g\circ f)\ x = \qquad [\quad g(f\ a_1), \quad g(f\ a_2), \quad ..., \quad g(f\ a_n) \quad ]
```

All other SOACs (reduce, scan, reduce-by-index, scatter) fuse with a map producer, if the mapped array is not used elsewhere.

Direct indexing in the map-produced array prevents fusion.E.g., assuming array as of length n the following will **not fuse:**

Demonstrating Performance of New vs Old Rules

PERFORMANCE DEMONSTRATION

Demo on Prime Numbers: Haskell Implementation

```
If we have all primes from 2 to \sqrt{n} we could generate all
 multiples of these primes (up to n) at once: {[2*p:n:p]:
  in sqr_primes} in NESL. Also call algorithm recursively on \sqrt{n}
 \Rightarrow Depth: O(lg lg n) (solution of n^{(1/2)^{depth}} = 2). Work: O(n lg lg n)
primesOpt :: Int -> [Int]
primesOpt n =
  if n \le 2 then \lceil 2 \rceil
  else
   let sqrtN = floor (sqrt (fromIntegral n))
       sqrt primes = primesOpt sqrtN
       nested = map (p->let m = (n 'div' p)
                          in map (i->i*p)
                                   Γ2..m7
                     ) sqrt_primes
       not primes = reduce (++) [] nested
       mm = length not_primes
       zeros = replicate mm False
       prime flags=scatter(replicate (n+1) True)
                             not primes zeros
       (primes, )= unzip filter((i,f)->f)
                     $ (zip [0..n] prime flags)
   in drop 2 primes
```

Demo on Prime Numbers: Haskell Implementation

```
If we have all primes from 2 to \sqrt{n} we could generate all
 multiples of these primes (up to n) at once: {[2*p:n:p]:
 in sqr_primes} in NESL. Also call algorithm recursively on \sqrt{n}
 \Rightarrow Depth: O(lg lg n) (solution of n^{(1/2)^{depth}} = 2). Work: O(n lg lg n)
primesOpt :: Int -> [Int]
                                       Assume n = 9, sqrtN = 3
primesOpt n =
 if n \le 2 then \lceil 2 \rceil
                                       call primesOpt 3
                                       n = 3, sqrtN = 1, sqrt_primes = [2]
 else
  let sqrtN = floor (sqrt (fromIntegral nn))sted = [[]]; not_primes = []
      nested = map (p->let m = (n 'div' p)jime_flags = [T,T,T,T]
                       in map (j \rightarrow j*p)rimes = [0,1,2,3]; returns [2]
                              [2..m]
                  ) sqrt_primes
                                       in primesOpt 9, afer
      not primes = reduce (++) [] nestedreturn from primesOpt3,
      mm = length not_primes sqrt_primes = [2,3]
      zeros = replicate mm False nested = [[4,6,8],[6,9]]
      prime flags=scatter(replicate (n+1)norum)imes = [4,6,8,6,9]
                          not_primes zermons=5;zeros= [F,F,F,F,F]
      (zip [0..n] prime flagsines = [0,1,2,3,5,7]
  in drop 2 primes
                                       returns [2,3,5,7]
```

Demonstrating Performance of New vs Old Rules

PERFORMANCE DEMONSTRATION

Parallel Basic Blocks Recap

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Eratosthenes Alg. for Computing Prime Numbers up To n

See also "Scan as Primitive Parallel Operation" [Bleelloch].

Start with an array of size n filled initially with 1, i.e., all are primes, and iteratively zero out all multiples of numbers up to \sqrt{n} .

```
int res[n] = {0, 0, 1, 1, 1, ..., 1}
for(i = 2; i <= sqrt(n); i++) { //sequential
   if ( res[i] != 0 ) {
      forall m ∈ multiples of i ≤ n do {
        res[m] = 0;
      }
   }
}</pre>
```

Work: $O(n \lg \lg n)$ but Depth: $O(\sqrt{n})$ (Not Good Enough!)

Eratosthenes Algorithm Improved for Parallel Execution

```
If we have all primes from 2 to \sqrt{n} we could generate all
multiples of these primes (up to n) at once: {[2*p:n:p]:
in sqr_primes} in NESL. Also call algorithm recursively on \sqrt{n}
\Rightarrow Depth: O(lg lg n) (solution of n^{(1/2)^{depth}} = 2). Work: O(n lg lg n)
      primesOpt :: Int -> [Int]
      primesOpt n =
         if n \le 2 then \lceil 2 \rceil
         else
          let sqrtN = floor (sqrt (fromIntegral n))
              sqrt primes = primesOpt sqrtN
              nested = map (p->let m = (n 'div' p)
                                 in map (\j-> j*p)
                                          Γ2..m7
                            ) sqrt_primes
              not primes = reduce (++) [] nested
              mm = length not_primes
              zeros = replicate mm False
              prime flags=scatter(replicate (n+1) True)
                                    not_primes zeros
              (primes, )= unzip filter((i,f)->f)
                            $ (zip [0..n] prime flags)
          in drop 2 primes
```

Batch of Rank-Search K Problems

Rank-Search k: finds the k^{th} smallest element of a vector.

Typically used for median computation.

```
let rankSearch (k: i64) (A: []f32) : f32 =
  let p = random_element A
  let A_lth_p = filter (< p) A</pre>
  let A_{eqt_p} = filter (==p) A
  let A_qth_p = filter (> p) A
  if (k <= A_lth_p.length)</pre>
  then rankSearch k A_lth_p
  else if (k <= A_lth_p.length + A_eqt_p.length)</pre>
       then p
       else rankSearch (k - A_lth_p.length - A_eqt_p.length) A_gth_p
let main [m] (ks: [m]i64) (As: [m][]f32) : [m]f32 =
  map2 rankSearch ks As
```

Quicksort with Nested Parallelism

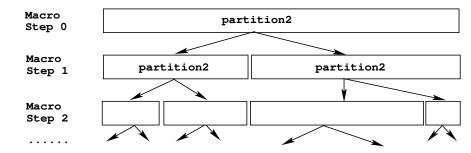
Using n for the input's length: Average Work is $O(n \log N)$.

If filter would have depth 1, then Average Depth: O(lg n).

In practice we have depth: $O(lg^2 n)$.

In principle, the implementation can be re-structured to use one partition2 instead of three filters.

Quicksort: Illustrating Flat-Parallel Execution



QuickHull with Nested Parallelism

Algorithm 1 QuickHull

```
Require: S: a set of n \ge 2 two-dimensional points
Ensure: CH: the convex-hull set of S
    (A, B) = the leftmost
               and rightmost
               points of S
    S_{1,2} = points of S above
          and below line AB
    CH = \{A, B\} \cup
      findHull(S_1, A, B) \cup
      findHull(S_2, A, B)
```

QuickHull with Nested Parallelism

Algorithm 2 Divide-And-Conquer Helper

```
1: procedure findHull(S, P, Q)
        HuII = \emptyset
 2:
 3:
        if S \neq \emptyset then
 4:
             C = furthest point of S from line PQ
             (S_l, S_r) = the points of S on the left-
 5:
                              and right-hand side of lines
 6:
                              CP and CO, respectively
 7:
                              (and not inside \triangle PCQ)
 8:
            Hull = \{C\} \cup
 9:
                        findHull(S_i, P, C) \cup
10:
                        findHull(S_r, C, Q)
11:
        return Hull
12:
```

Parallel Basic Blocks Recap

Part I: Flattening Nested and Irregular Parallelism

What is "Flattening"? Recipe for Applying Flattening Several Re-Write Rules (inefficient for replicate & iota) Jagged (Irregular Multi-Dim) Array Representation Revisiting the Rewrites for Replicate & Iota Nested Inside Map Revisiting the Solution to Our Example

Part II: Flattening Nested and Irregular Parallelism

Several Applications of Flattening

More Flattening Rules

Flattening by Function Lifting Flattening Quicksort Flattening Prime-Number (Sieve) Computation

(5) Reduce Inside a Map or Segmented Reduce:

```
let arr = [[1, 3, 4], [6, 7]] in
let res = map (\x -> reduce (+) 0 x) arr
-- should result in [8, 13]
```

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```
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-- should result in [8, 13]
```

translates to a scan-pack composition:

- 1. the length of res equals the number of subarrays of arr;
- the shape of arr is scanned: the result records the position of the last element in a segment plus one;
- 3. segmented scan is applied on the input array: the last elem in a segment holds the reduced value of the segment;
- 4. segment's last element is extracted by a map operation.

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```
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We can also "cheat" and use a histogram-like computation

```
\mathcal{F}(\text{res} = \text{map } (\text{row} - \text{reduce } \odot 0_{\odot} \text{ row}) \text{ arr}) \Rightarrow
--S_{arr}^{0} = [2], S_{arr}^{1} = [3,2], F_{arr} = [1,0,0,1,0], D_{arr} = [1,3,4,6,7]
1. S_{res}^{0} = S_{arr}^{0} \qquad \qquad --S_{res}^{0} = [2]
2. D_{res} = \text{hist } (\odot) O_{\odot} (S_{arr}^{0}[0]) II_{arr}^{1} D_{arr}
```

How else can I try to optimize this code by hand?

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1. S_{res}^{0} = S_{arr}^{0} \qquad \qquad --S_{res}^{0} = [2]
2. D_{res} = \text{hist } (\odot) O_{\odot} (S_{arr}^{0}[0]) II_{arr}^{1} D_{arr}
```

How else can I try to optimize this code by hand?

- practical performance refers to how many global-memory accesses you perform
- accessing II¹_{arr} from memory has significant cost
- in some practical cases, it might be more efficient to not manifest II_{arr}^1 , but instead to compute its elements by binary searching the B_{arr}^1 array.

Flattening Scatter and Histogram

How does one flattens a scatter perfectly nested inside a map?

How does one flattens a histogram perfectly nested inside a map?

Flattening Scatter and Histogram

How does one flattens a scatter perfectly nested inside a map?

How does one flattens a histogram perfectly nested inside a map?

You will have to answer it yourselves as part of the third weekly assignment:)

Treating a Scalar Variant to the Outer Map

(6) The inner construct uses a scalar variant to the outer map:

```
let res = map2 (\x ys -> map (+x) ys) [1,3] [[4,5,6], [9,7]] \equiv let res = [map (+1) [4,5,6], map (+3) [9,7]] let res = [ [5,6,7], [12,10] ]
```

Treating a Scalar Variant to the Outer Map

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```

Traditionally, this is handled by expanding (replicating) each \boldsymbol{x} across the whole segment

Instead, we use II_{arr}^1 to indirectly access in the xs array:

Treating Indexing Variant to the Outer Map

(7) Indexing Operations Variant to the Outer Map:

```
let res = map2 (\i xs -> xs[i]) [2,0] [[4,5,6], [9,7]] \equiv let res = [6, 9]
```

Treating Indexing Variant to the Outer Map

(7) Indexing Operations Variant to the Outer Map:

```
let res = map2 (\i xs -> xs[i]) [2,0] [[4,5,6], [9,7]] \equiv let res = [ 6, 9 ]
```

To corresponding flat index in D_{yss} is obtained by summing up

- the start offset of every segment, which we get from B_{vss}^1 , and
- the index inside the segment, which we get from is

```
\mathcal{F}(\text{res} = \text{map2} (\ \text{i} \ \text{xs} \rightarrow \text{xs[i]}) \ \text{is} \ \text{xss}) \Rightarrow
-- \ is = [2,0], \ S_{xss}^1 = [3,2], \ B_{xss}^1 = [0,3], \ D_{xss} = [4,5,6,9,7]
1. S_{res}^0 = S_{is}^0 -- = S_{is}^0 = [2]
2. D_{res} = \text{map2} (\ \text{off} \ \text{i} \rightarrow D_{xss}[\text{off} + \text{i}]) \ B_{xss}^1 \ \text{is} \ -- \ D_{res} = [6,9]
```

Nested vs Flattened Parallelism: If Inside a Map 2D Case

(8) If-Then-Else with inner parallelism nested inside a map:

```
bs = [F,T,F,T]

xss = [[1,2,3],[4,5,6,7],[8,9],[10]]

res = map(\b xs -> if b then map (+1) xs else map (*2) xs) bs xss

res = [ map(*2)[1,2,3], map(+1)[4,5,6,7], map(*2)[8,9], map(+1)[10] ]

res = [ [2,4,6], [5,6,7,8], [16,18], [11] ]
```

Nested vs Flattened Parallelism: If Inside a Map 2D Case

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xss = [[1,2,3],[4,5,6,7],[8,9],[10]]
res = map(\b xs -> if b then map (+1) xs else map (*2) xs) bs xss
res = [ map(*2)[1,2,3], map(+1)[4,5,6,7], map(*2)[8,9], map(+1)[10] ]
res = [ [2,4,6], [5,6,7,8], [16,18], [11] ]
```

translates to a scatter-map-gather composition. Intuition:

- compute iinds, the permutation of segments w.r.t. bs;
- 2-3. partition the xss array based on bs;
- 4-5. flatten outer map and/on top of the parallel code of the then and else branches;
- 6. inverse permute the resulted segments according to iinds.
 1. iinds = partition2 (λi -> bs[i]) (iota (length b)) -- [1,3,0,2]

```
2. xss<sub>then</sub> = gatherThen iinds xss -- ([4,1], [4,5,6,7, 10])
3. xss<sub>else</sub> = gatherElse iinds xss -- ([3,2], [1,2,3, 8,9])
-- Recursively Flatten the Then and Else Branches!
```

- 4. $res_{then} = \mathcal{F}(map (map (+1)) \times ss_{then}) -- ([4,1], [5,6,7,8, 11])$ 5. $res_{else} = \mathcal{F}(map (map (*2)) \times ss_{else}) -- ([3,2], [2,4,6,16,18])$
- 6. res = inversePermute iinds (res_{then}++res_{else}) -- ($\lceil 3,4,2,1 \rceil$, $\lceil 2,4,6,5,6,7,8,16,18,11 \rceil$)

Nested vs Flattened Parallelism: If Inside a Map 2D Case

(8) If-Then-Else with inner parallelism nested inside a map: bs = [F,T,F,T], xss = [[1,2,3],[4,5,6,7],[8,9],[10]], S¹_{txc}=[3,4,2,1], f=map (+1), g=map (*2)

```
\mathcal{F}(\text{res} = \text{map2} (\b xs -> \text{if b then } f xs \text{ else } q xs) \text{ bs } xss) \Rightarrow
(spl, iinds) = partition2 bs (iota (length bs)) -- (2, [1,3,0,2])
(S_{XSS_{then}}^1, S_{XSS_{else}}^1) = \text{split spl} (\text{map} (\langle ii - \rangle S_{XSS}^1[ii]) iinds) - ([4,1],[3,2])
mask_{xss} = map (\setminus sgmind \rightarrow bs[sgmind]) \prod_{xss}^{1} -- [F,F,F,T,T,T,T,F,F,T]
(brk, D_{rss}^{\rho}) = partition2 mask<sub>rss</sub> D_{rss}
(D_{xss_{then}}, D_{xss_{else}}) = split brk D_{xss}^{p} -- ([4,5,6,7,10],[1,2,3,8,9])
(S_{res_{then}}^1, D_{res_{then}}) = \mathcal{F}(map f) (S_{xss_{then}}^1, D_{xss_{then}}) -- ([4,1], [5,6,7,8,11])
(S_{res_{else}}^1, D_{res_{else}}) = \mathcal{F}(map g) (S_{xss_{else}}^1, D_{xss_{else}}) -- ([3,2], [2,4,6,16,18])
S_{res}^{1P} = S_{res_{then}}^{1} + + S_{res_{oleg}}^{1} - - [4, 1, 3, 2]
S_{res}^1 = scatter (replicate (length bs) 0) iinds S_{res}^{1P} -- [3,4,2,1]
B_{res}^1 = scan^{exc} (+) 0 S_{res}^1 - [0,3,7,9]
F_{res}^{p} = mkFlagArray S_{res}^{1p} 0  (map (+1) iinds) -- [2,0,0,0,4,1,0,0,3,0]
|| f_{res}^{1p}| = sgmscan (+) 0 F_{res}^{p} F_{res}^{p} | > map(\langle x - \rangle x - 1) - [1, 1, 1, 1, 3, 0, 0, 0, 2, 2]
||_{res}^{2P} = ||_{res_{then}}^{2} + + ||_{res_{olige}}^{2} - [0,1,2,3,0,0,1,2,0,1]
sinds_{res} = map2 (\sqm iin -> B_{res}^{1}[sqm] + iin) H_{res}^{1p} H_{res}^{2p}
--[3+0.3+1.3+2.3+3.9+0.0+0.0+1.0+2.7+0.7+1] = [3.4.5.6.9.0.1.2.7.8]
D_{res} = scatter (replicate flen_{res} 0) sinds_{res} (D_{res_{then}} + + D_{res_{olso}})
   -- [2,4,6,5,6,7,8,16,18,11]
(S_{res}^1, D_{res})
```

Nested vs Flattened Parallelism: Do Loop Inside a Map

(9) Flattening a Do Loop Nested Inside a Map:

- compute the maximal loop count n_{max}
- interchange the loop and the map:
 - ► loop count becomes n_{max}
 - ▶ the loop body is wrapped inside a if i<n condition, and
 - the new loop body is flattened!

```
      \mathcal{F}(\text{res = map2} \ (\n xs \rightarrow \text{loop}(xs) \ \text{for} \ i < n \ \text{do} \ f \ xs) \ ns \ xss) \Rightarrow \\       1. \ n_{max} = \text{reduce} \ max \ 0i32 \ ns \\       2. \ g \ i \ m \ arr = if \ i < m \ then \ f \ arr \ else \ arr \\       3. \ loop(S_{xss}^1, D_{xss}) \ \text{for} \ i < n_{max} \ \text{do} \\       4. \qquad \mathcal{F}(\text{map2} \ (g \ i)) \ ns \ (S_{xss}^1, D_{xss}) \\       5. \qquad -- \ (g \ i)^L \ ns \ (S_{xss}^1, D_{xss}) \\
```

But this treatment does not necessarily preserve the work asymptotic ... what to do?

Nested vs Flattened Parallelism: Do Loop Inside a Map

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- compute the maximal loop count n_{max}
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```
      \mathcal{F}(\text{res} = \frac{\text{map2}}{\text{map2}} \ (\n \text{ xs } -> \frac{\text{loop}}{\text{ks}} \ \text{for } i < n \ \text{do} \ \text{f xs}) \ \text{ns xss}) \Rightarrow \\       1. \ n_{max} = \frac{\text{reduce}}{\text{max}} \ \text{max} \ \text{0i32 ns} \\       2. \ g \ i \ m \ \text{arr} = \frac{\text{if}}{\text{i}} \ i < m \ \text{then} \ \text{f arr} \ \text{else} \ \text{arr} \\       3. \ loop(S_{xss}^1, D_{xss}) \ \text{for} \ i < n_{max} \ \text{do} \\       4. \qquad \mathcal{F}(\text{map2} \ (g \ i)) \ \text{ns} \ (S_{xss}^1, D_{xss}) \\       5. \qquad -- \ (g \ i)^L \ \text{ns} \ (S_{xss}^1, D_{xss}) \\
```

But this treatment does not necessarily preserve the work asymptotic ... what to do?

If the size of the result can be deduced/inferred:

- allocate the flat-result array before the loop
- filter out the empty segments, and make the loop iterate until the shape is empty
- each time a segment finish execution (i) it is scattered into the result, and (2) it is filtered out from the running set of segments.

Parallel Basic Blocks Recap

Part I: Flattening Nested and Irregular Parallelism

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Part II: Flattening Nested and Irregular Parallelism

Several Applications of Flattening More Flattening Rules

Flattening by Function Lifting

Flattening Quicksort Flattening Prime-Number (Sieve) Computation

Flattening by Function Lifting: Basic Idea

Assume a simple function f:

```
let f(x: i32) : i32 = x + 1
```

f lifted, denoted \mathbf{f}^L semantically corresponds to map \mathbf{f} , where the arguments have been expanded to an extra array dimension, and the inner operators/functions have also been lifted:

```
let +<sup>L</sup> [n] (as: [n]i32) (bs: [n]i32) : [n]i32 =
    map2 (+) as bs
```

```
let f^{L} [n] (xs: [n]i32) : [n]i32 = xs +<sup>L</sup> (replicate n 1)
```

Flattening by Function Lifting: Basic Idea

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    map2 (+) as bs
```

```
let f^{L} [n] (xs: [n]i32) : [n]i32 = xs +<sup>L</sup> (replicate n 1)
```

- Locals such as $x \Rightarrow$ left alone
- Global such as $+ \Rightarrow$ lifted $(+^{L})$
- Constants such as $k \Rightarrow$ replicate (length xs) k
 - good for vectorization, bad for locality, asymptotics
 - for GPU better to indirectly index into a smaller array, rather than replicate.

Flattening by Function Lifting: Key Insight!

```
let f (xs: []i32) : []i32 = map g xs -- = g^L xs
let f<sup>L</sup> (xss: [][]i32) : [][]i32 = (g^L)^L -- ???
How do we stop lifting? g and g^L are enough: no need for (g^L)^L!
```

Flattening by Function Lifting: Key Insight!

```
let f (xs: []i32) : []i32 = map g xs -- = g^L xs
let f^L (xss: \lceil \rceil \lceil \rceil i32) : \lceil \rceil \lceil \rceil i32 = (q^L)^L -- ???
How do we stop lifting? q and q^L are enough: no need for (q^L)^L!
let f (xs: \lceil \rceil i32) : \lceil \rceil i32 = map q xs -- = q^L xs
-- in nested parallel form
let f^L (xss: \lceil \rceil \lceil \rceil i32) : \lceil \rceil \lceil \rceil i32 =
      segment xss (q<sup>L</sup> (concat xss))
-- in flatten form
let f^L (S_{vec}^1: []i32, D_{xss}: []i32) : ([]i32, []i32) =
      (S_{vss}^1, q^L D_{xss})
In Haskell Notation:
concat :: [[a]] -> [a]
```

shape flat data nested data

segment :: [[a]] -> [b] -> [[b]]

Parallel Basic Blocks Recap

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More Flattening Rules
Flattening by Function Lifting
Flattening Quicksort
Flattening Prime-Number (Sieve) Computation

Recounting Quicksort

Recount the classic nested-parallel definition:

```
let quicksort [n] (arr : [n]f32) : [n]f32 =
    if n < 2 then arr else
    let i = getRand (0, (length arr) - 1)
    let a = arr[i]
    let s1 = filter (< a ) arr
    let s2 = filter (== a) arr
    let s3 = filter (> a) arr
    in (quicksort s1) ++ s2 ++ (quicksort s3)
    -- can be re-written as:
    -- rs = map nestedQuicksort [s1, s3]
    -- in (rs[0]) ++ s2 ++ (rs[1])
```

Note: Futhark does not support recursive calls, hence not valid code!

Nested-Parallel Quicksort Simplified

For simplicity we will rewrite it in terms of partition2:

```
let isSorted [n] (as: [n]f32) : bool =
    map (\i i -> if i ==0 then true else as[i-1] < as[i]) (iota n)
    |> reduce (&&) true

let quicksort [n] (arr: [n]f32) : [n]f32 =
    if isSorted arr then arr else
    let i = getRand (0, (length arr) - 1)
    let a = arr[i]
    let bs = map (< a) arr
    let (q, arr') = partition2 bs 0.0f32 arr
    let (arr<, arr≥) = split q arr'
    in concat <| map quicksort [arr<, arr≥]</pre>
```

Note: Futhark does not support recursive calls, irregular map operation, or concat!

Partition2

Reorders the elements of an array such that those that correspond to a true mask come before those corresponding to false.

```
let partition2 [n] 't (conds: [n]bool) (dummy: t) (arr: [n]t)
        : (i32, [n]t) =
  let tflgs = map (\ c \rightarrow if \ c \ then \ 1 \ else \ 0) conds
  let fflgs = map (\setminus b -> 1 - b) tflgs
  let indsT = scan (+) 0 tflqs
  let tmp = scan (+) 0 fflqs
  let lst = if n > 0 then indsT[n-1] else -1
  let indsF = map (+lst) tmp
  let inds = map3 (\ c indT indF -> if c then indT-1 else indF-1)
                    conds indsT indsE
  let fltarr = scatter (replicate n dummy) inds arr
  in (lst, fltarr)
```

For example:

```
conds = [F,T,F,T,F,F,T]

xss = [1,2,3,4,5,6,7]

partition2 conds 0 xss => (3, [2,4,7,1,3,5,6])
```

Lifting Quicksort

Key Idea: write a function with the semantics of map nestedQuicksort, i.e., it operates on array of arrays.

Important observations:

- map quicksort = quicksort^L
- map(map quicksort) = quicksort = segment o quicksort o concat
- the flat data of $[xs_<, xs_>] \equiv xs^p$, the result of partition 2

Lifting Quicksort

Let us treat the last three lines from the previous implem:.

```
let quicksort<sup>L</sup> (S_{xss}^1:[]i32, D_{xss}:[]f32): ([]i32,[]f32) = --(xss: [][]f32)
   if is Sorted D_{xss} then (S_{xss}^1:[]i32, D_{xss}:[]f32) else -- big cheat!
  let (S_{bss}^1, D_{bss}) = \mathcal{F} (
        map (\setminus xs \rightarrow
                 let i = getRand(0, (length xs) - 1)
                 let a = xs[i]
                 let bs = map (< a) xs
                 in bs
              ) xss
  let (ps, (S_{xssp}^1, D_{xssp}^1)) = partition 2^L D_{bss} 0.0 f 32 (S_{xss}^1, D_{xss})
  -- Invariant: S_{xssp}^{1} == S_{hss}^{1} == S_{xss}^{1}
  let S^1_{[xss],xss} =  filter (!=0) <| flatten <|
           map2 (\lambda p s -> if s==0 then [0,0] else [p,s-p]) ps S_{vcc}^1
  in quicksort<sup>L</sup> (S_{[xss_{<},xss_{>}]}^{1},D_{xss^{p}})
   ■ S^1_{[xss < a, xss > a]} is the shape of [xs < xs > a]
```

(concat <| quicksort^L)^L xsss ≡ concat <| segment xsss <| quicksort^L (concat xsss) ≡ quicksort^L (concat xsss)
 The function looks tail recursive now: let's replace it with a loop!

Lifting Quicksort: Final Implementation

```
let quicksort<sup>L</sup> [m][n] (S_{xss}^1:[m]i32, D_{xss}:[n]f32): [n]f32 =
  let (stop, count) = (isSorted D_{xss}, 0i32)
  let (_,res,_,_) =
     loop(S_{xss}^1, D_{xss}, stop, count) while (!stop) do
          -- compute helper-representation structures
          let B_{xss}^1 = scan^{exc} (+) 0 S_{xss}^1
          let F_{xss}^1 = mkFlagArray S_{xss}^1 0i32 <| map (+1) <| iota m
          let \prod_{res}^{1} = sgmscan (+) 0 F_{res}^{1} < |
                    map (\f -> if f==0 then 0 else f-1) F_{vec}^1
          -- flattening quicksort:
          let rL = map (\u -> randomInd (0,u-1) count) S_{xss}^1
          let aL = map3(\r l i-> if l \le 0 then 0.0 else D_{xss}[B_{xss}^1[i]+r]
                           ) rL S_{vec}^1 (iota m)
          let D_{bss} = map2 \ (\x sgmind -> aL[sgmind] > x ) D_{xss} \ ||_{xss}^1
          let (ps, (S_{xss}^1, D_{xss}^{per})) = partition<sup>2L</sup> D_{bss} 0.0 f32 (S_{xss}^1, D_{xss})
          let S^1_{[xss_-,xss_-]} = filter (!=0) <| flatten <|
                  map2 (\ p s -> if s==0 then [0,0] else [p,s-p]) ps S_{xcc}^1
          in (S^1_{[xss],xss}], D^{per}_{xss}, is Sorted D^{per}_{xss}, count +1)
  in
       res
```

PFP Weekly 2 Exercise: Implement partition2^L

Parallel Basic Blocks Recap

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How Does One Flattens Prime Numbers?

The important bit with nested parallelism:

How Does One Flattens Prime Numbers?

The important bit with nested parallelism:

Normalize the nested map:

Flattening PrimeOpt was part of PMPH's Weekly Assignment 2!