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SUMMARY

- Over 3 years experience in embedded systems, robotics and control systems, and automation as demonstrated in extesa robotic arm, accelerando robot, and a number of other award wining projects.
- Able to learn quickly and apply to daily problem solving as shown in side projects.
- Project Manager and Designer for a variety of teams and projects.

SKILLS

Hardware:

SolidWorks, Vectorworks, AutoCAD, Arduino, mySTEM and Quick Prototyping

Software:

Most experience with Java, C++, Javascript, HTML5, CSS, jQuery, RobotC, Data Structures & Algorithms, OPP (Tools): Git, Eclipse, NetBeans, Xcode, Atom Some experience with LabView, PLC, and C

ACTIVITIES

UW Mars Rover 2017

Mechanical & Electrical Member | 2016 - present

 Implementing a creative mechanical design solution for soil extraction and cleaning mechanisms.

PackAnts

Front-End Web Developer \mid 2017 - present

Improved the website and the integration of back-ends

FRC Team 3161

Mechanical Designer | Sept. 2015 - July. 2016

 Designed the robot using SolidWorks for in First Robotic Competition.

Photography

Personal Hobby

 A way of touching, feeling, creating, and loving.

EDUCATION

University of Waterloo |

Mechatronics Engineering B.A.Sc 2016-2021 | 1A-GPA: 3.9

PROJECTS

– JXinBOX.com 裔

Personal Web Portfolio | July 2016 - present

- Devised a website using Javascript, HTML5, CSS, and jQuery.
- Created an interactive simulation of dot creatures with a tree-like linked data structure, restricted by simple rules and possibilities.
- Currently working on the implementation of machine learning to bring dots more vivid and lovely, which eventually accelerates new evolution.

Extensa Robotic Arm

Project Designer | November 2016

- Designed and built a robotic arm with 4.5 Degrees of Freedom from scratch using LEGO NXT, Tetrix Kit, C++ and RobotC.
- Developed 2 extended libraries and 4 demo programs for other developers with focus on industrial performance (Safety + Auto calibration + PID control + 3D cartesian coordinate system) and recreational use (Bluetooth Joystick control + Fun Interactive Games).

– Acclerando Robot

Project Manager | October 2016

- Organized a team of 5 to devise a line follower with a grayscale to music converter from mechanical, electrical, and software design (C).
- Laser cutted the robot created in AutoCAD and SolidWorks.
- Designed, tested, and soldered entire circuits layout with DAC converter, buffering and filterring system, and home made color sensors (with self-designed 3D printed sensor hoods), which save 50% of budgets.

EXPERIENCE

- Project Lead and LabView Programmer

Robotic and control system Design Competition | Dec. 2015

- Won 1st Place for Robotic and Control System Design at Halton Skill Competition in Halton Region
- Designed, prototyped, and programmed a variety of embedded systems to resolves challenges involving Mechanical Systems, Controls, Automation, Mobile Robotics, and Software Design,
- Devised innovative safety protocols in both Hardware (mySTEM Engineering Kits) and Software (LabView) design such as physical stops, circuit breaker, limit switches, and visual and sound feedback.
- Related Projects :
 - 3 Floor Elevator
- Vehicle Lift
- Microwave Prototype
- · Green House Simulator

Architecture Designer

5th Annual Architecture Design Competiton [JWA] | Dec. 2015

- Earned a 2nd Place in a light house design competition for Oakville.
- Illustrated the concept using AutoCAD, Vectorworks,
 Adobe Illustrator, and Photoshop.
- Incorporated engineering aspect onto artistic design of the light house to ensure the reliability of the lighthouse by analyzing wind pressure using Autodesk Flow Design.