

zkInterface, a tool for zero-knowledge interoperability

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[Add abstract —Eran]

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1 Overview

1.1 Background

[Rewrite: —Eran] Implementing zero-knowledge proof constructions is not a trivial task and comes with diverse matters, as is extensively explained in the Implementation Track proceeding of the first ZKProof workshop. One of the requirements is to create a compiler of programs into constraint systems that are consumed by the proving system.

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There are several trade-offs one can consider when designing general-purpose (front-end) compilers, leading to distinct frameworks, APIs, generality, etc. Today, existing compilers are implemented to work best with their corresponding (back-end) proving system (sometimes more than one). For a comprehensive list of front-ends and back-ends, you can go to zkp.science.

These libraries are usually built end-to-end: they take in some program that defines the statement and generate or verify a proof, in many cases without explicitly exposing the constraint system compilation. Moreover, if the compilers can output intermediary files and configurations, they are usually native to the specific back-end. In practice this means that

- there is no portability between different proving systems and compilers, and
- it is not possible to compile a program using code from different frameworks

1.2 Goals

[Rewrite: —Eran]

[Copy relevant text from the Implementation Track, especially Advanced Interoperability —Eran]

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We aim to solve this issue, as seen in Figure 1, by creating a community standard proposal for the ZKProof effort around constraint system formatting, building upon the work done at the first ZKProof workshop.

We design and implement a standard rank-1 constraint system (R1CS) interface between front-ends and back-ends. Our design encompasses programmable instance and witness reductions, while capturing the parameters of the different components of the statement to be proven. Given that these statements can be large and difficult to build, developers usually build smaller components that are re-usable with different statements; these components are sometimes called “gadgets”. With our zkInterface one can piece together programmatically the different components to form a complete statement.

Desiderata

- Interoperability across frontend frameworks and programming languages.

- Ability to write components that can be consumed by different frontends and backends.
- Minimize copying and duplication of data.
- The overhead of the R1CS construction and witness reduction should be low (and in particular, linear) compared to a native implementation of the same gadgets in existing frameworks.
- Expose details of the backend's interface that are necessary for performance (e.g., constraint system representation and algebraic fields).
- Approach can be extended to support constraint systems beyond R1CS.

Scope and limitations. [Rewrite: —Eran]

We aim for the standard interface to be as generic as possible, including non-R1CS-based proving systems. However, the current proposal is more limited, mainly due to time constraints.

The standard that we propose can be seen in three different levels:

1. The first level defines
 - standard messages and their serialization that the caller and callee exchange,
 - a data format for R1CS constraints,
 - a data format for R1CS variables assignments.
2. The second level defines a simple C API that allows for the exchange of messages.
3. The third level defines the self-contained packaging of a component for its portable execution on different platforms.

This proposal is not aiming to standardize a language or framework for generating constraint systems, nor the way that components of the proving statement should be written. However, it is important to point that any such framework could use the proposed interface.

2 Design

2.1 Approach

zkInterface is a procedural, purely functional interface for zero-knowledge systems that enables cross-language interoperability. The current version, even if limiting, creates an interface based on R1CS formatting and offers the ability to abstractly craft a constraint system building from different components, possibly written in different frameworks, by defining how data should be written and read. It is independent of any particular proving systems.

The same interface can be used in two use-cases:

- To connect the construction and execution of a zero-knowledge program to a proving system. See Figure 2.
- To decompose a zero-knowledge program into multiple components that can be engineered separately. See Figure 3.

Interface. The interaction between caller and components is based on exchanging messages. Messages are purely read-only data, which grants a great flexibility to implementations of components and applications.



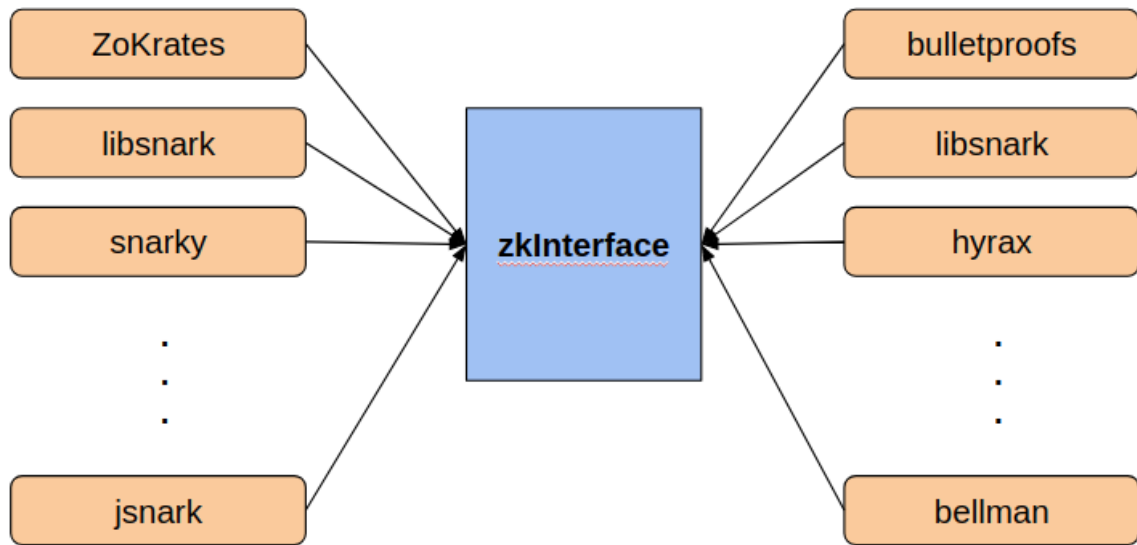


Figure 1: `zkInterface` [Replace by diagram on slack —Eran]

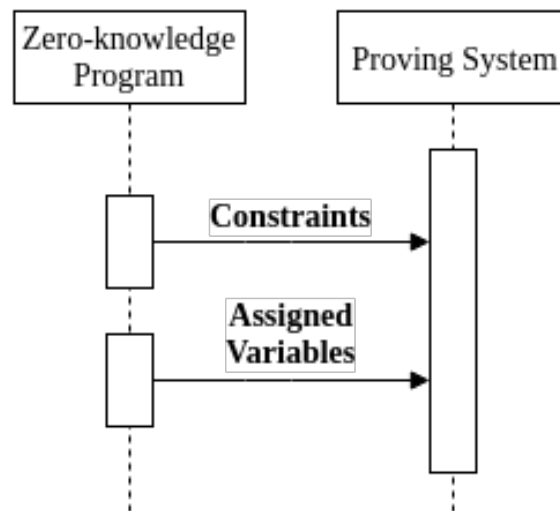


Figure 2: The interaction between a zero-knowledge program and a proving system.

Different parts of an application may be written in different programming languages, and interoperate through messages. These parts may be linked and executed in a single process, calling functions, and exchanging messages through buffers of shared memory. They may also run as separate processes, writing and reading messages in files or through pipes.

The set of messages is defined in Listing 1, using the FlatBuffers interface definition language. All messages and fields are defined in this schema.

Note The FlatBuffers system includes an interface definition language which implies a precise data layout at the byte level.

Code to write and read messages can be generated for all common programming languages. Code examples for C++ and for Rust are provided.

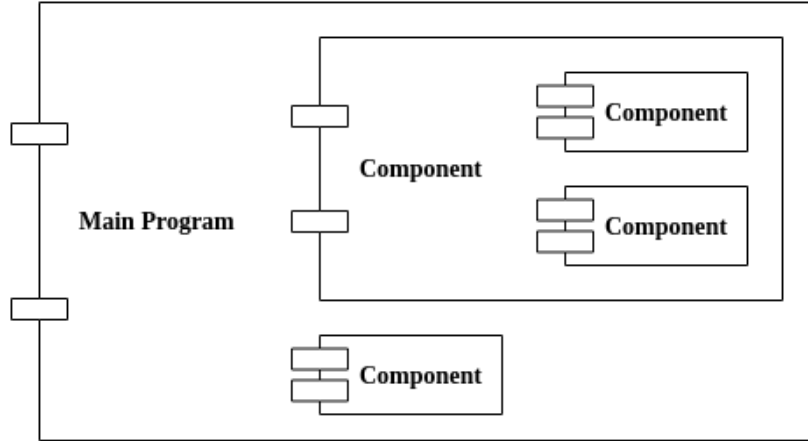


Figure 3: A zero-knowledge program built from multiple components.

Multiple paths for evolution and extensions of the standard are possible, thanks to the flexibility and backward-compatibility features of the encoding.

The encoding is designed to require little to no data transformation, making it possible to implement the standard with minimal overhead in very large applications.

The specification of FlatBuffers can be found at <https://google.github.io/flatbuffers/>.

Instance and Witness Reductions. Instance reduction is the process of constructing a constraint system. Witness reduction is the process of assigning values to all variables in the system before generating a proof about concrete input values.

When using a proving system with pre-processing, instance reduction is performed once ahead of time and used in a trusted setup. In proving systems without pre-processing, instance reduction is used in proof verification. The standard supports both execution flows with similar messages.

2.2 Architecture

Messages Flow. The flow of messages is illustrated in Figure 4.

The caller calls the component code with a single `ComponentCall` message. The component exits with a single `ComponentReturn` message. This is a control flow analogous to a function call in common programming languages.

The caller also provides a way for the component to send `R1CSConstraints` and `AssignedVariables` messages. This is an output channel distinct from the return messages.

The caller can request an instance reduction, or a witness reduction, or both at once. This is controlled by the fields `generate_r1cs` and `generate_assignment` of `ComponentCall` messages.

During instance reduction, a component may add any number of constraints to the constraint system by sending one or more `R1CSConstraints` messages. The caller and other components may do so as well.

During witness reduction, a component may assign values to variables by sending one or more `AssignedVariables` messages.

Note The design of constraints and assignments channels allows a component to call subcomponents itself. Messages from all (sub-)components can simply be sent separately without the need to aggregate them into a single message.

Moreover, an implementation can decouple the proving system from the logic of building constraints and assignments, by arranging for the constraints and assignments messages to be

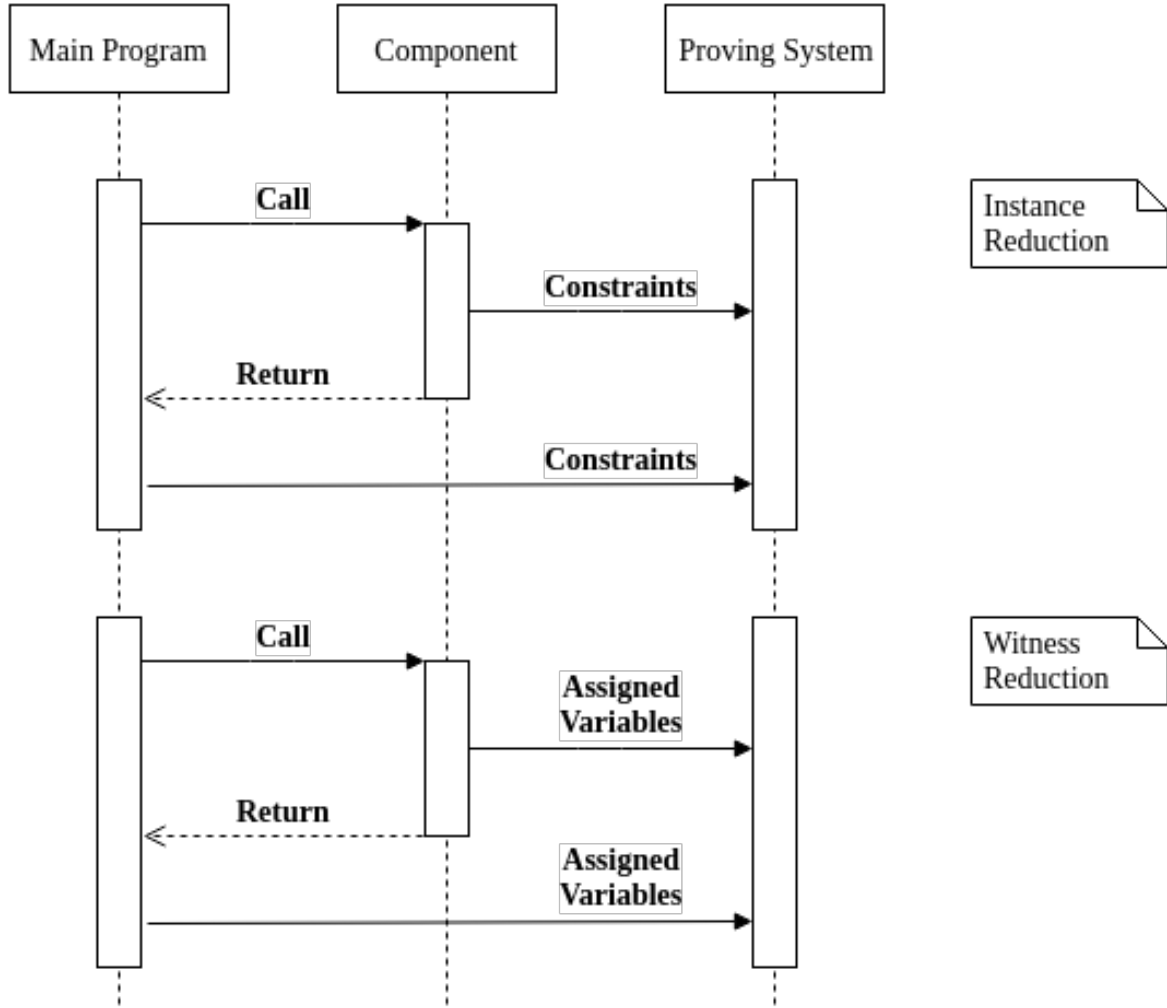


Figure 4: The flow of messages between libraries using the interface.

processed by the proving system, independently from the control logic.

Variables. The constraint system reasons about variables, which are assigned a numerical identifier that are unique within a constraint system. The variable numbers are incrementally allocated in a global namespace. Messages that contain constraints or assignments refer to variables by this numeric ID. It is up to gadgets that create the constrain system to keep track of the semantics (and if desired, helpful symbolic names) of the variables that they deal with, and to allocate new variables for their internal use. The messages defined by the framework include a simple protocol for conveying the state of of the variable allocator (i.e., the first free variable number), and the identity of variables that tie a gadget to other gadgets.

Note This design allows implementations to aggregate and handle messages in a generic way, without any reference to the components or mechanisms that generated them.

[Must be consecutive or are gaps allowed? —Aurell]

Local Variables Allocation. A component may allocate a number of local variables to use in the internal implementation of the function that it computes. They are analogous to stack variables in common programming languages.

The following protocol is used to allocate variable IDs that are unique within a whole

constraint system.

- The caller must provide a numerical ID greater than all IDs that have already been allocated, called the Free-Before ID.
- The component may use the Free-Before ID and consecutive IDs as its local variables IDs.
- The component must return the next consecutive ID that it did not use, called the Free-After ID.
- The caller must treat IDs lesser than the Free-After ID as allocated by the component, and must not use them.

During instance reduction, the component can refer to its local variables in the R1CSConstraints messages that it generates. The caller and other parts of the program must not refer to these local variables.

During witness reduction, the component must assign values to its local variables by sending AssignedVariables messages.

Incoming/Outgoing Variables. The concept of incoming, outgoing variables arises when a program is decomposed into components. These variables serve as the functional interface between a component and its caller. They are analogous to arguments and return values of functions in common programming languages. A variable is not inherently incoming, outgoing, nor local; rather, this is a convention in the context of a component call.

The caller provides the IDs of variables to be used as incoming and outgoing variables by the component. There may be no outgoing variables if the component implements a pure assertion.

During instance reduction, both the caller and the component can refer to these variables in the R1CSConstraints messages that they generate. Other parts of the program may also refer to these same variables in their own contexts.

During witness reduction, the caller must pass incoming values to the component in the ComponentCall message. The component must return outgoing values to the caller in the ComponentReturn message.

The caller is responsible for the assignment of values to both incoming and outgoing variables. How this is achieved depends on the caller and proving system, and on whether some variables are treated as public inputs of the zero-knowledge program.

In-memory execution - C API. The application may execute the code of a component in its own process.

The component exposes its functionality as a function callable using the C calling convention of the platform. The component code may be linked statically or be loaded from a shared library.

The application must prepare a ComponentCall message in memory, and implement one callback functions to receive the messages of the component, and call the component function with pointers to the message and the callbacks.

The component function reads the call message and performs its specific computation. It prepares the resulting messages (R1CSConstraints, AssignedVariables, or ComponentReturn) in memory, and calls the callbacks with pointers to these messages.

The function definition that implements this flow is defined in Listing 2 as a C header. Refer to the inline documentation for more details.

Multi-process execution - Stream and File Format. [Explain what's already induced by Flat-Buffers: explain that the framework, plus our .fbs file, specify how the aforementioned high-level messages are actually represented at the byte level, including message framing, message naming, etc.. —Eran] All messages are framed, meaning that they can be concatenated and distinguished in streams of bytes or in files. Messages must be prefixed by the size of the message not including the prefix,



as a 4-bytes little-endian unsigned integer. [Say something about streams - stdio/stdout, files, TCP connections, etc.? —Eran]



2.3 Interface Definition

Listing 1: gadget.fbs - Interface definition

```
// This is a FlatBuffers schema.
// See https://google.github.io/flatbuffers/

namespace Gadget;

/// The messages that the caller and component can exchange.
union Message {
    ComponentCall,
    ComponentReturn,

    R1CSConstraints,
    AssignedVariables,
}

/// Caller calls a component.
table ComponentCall {
    /// All details necessary to construct the instance.
    /// The same instance must be provided for R1CS and assignment generation.
    instance :GadgetInstance;

    /// Whether constraints should be generated.
    generate_r1cs :bool;

    /// Whether an assignment should be generated.
    /// Provide witness values to the component.
    generate_assignment :bool;
    witness :Witness;
}

/// Description of a particular instance of a gadget.
table GadgetInstance {
    /// Which gadget to instantiate.
    /// Allows a library to provide multiple gadgets.
    gadget_name :string;

    /// Incoming Variables to use as connections to the gadget.
    /// Allocated by the caller.
    /// Assigned by the caller in `Witness.incoming_elements`.
    incoming_variable_ids :[uint64];

    /// Outgoing Variables to use as connections to the gadget.
    /// There may be no Outgoing Variables if the gadget is a pure assertion.
    /// Allocated by the caller.
    /// Assigned by the called gadget in `ComponentReturn.outgoing_elements`.
    outgoing_variable_ids :[uint64];

    /// First free Variable ID before the call.
    /// The gadget can allocate new Variable IDs starting with this one.
    free_variable_id_before :uint64;

    /// The order of the field used by the current system.
    /// A BigInt.
    field_order :[ubyte];
}
```

```

    /// Optional: Any static parameter that may influence the instance
    /// construction. Parameters can be standard, conventional, or custom.
    /// Example: the depth of a Merkle tree.
    /// Counter-example: a Merkle path is not configuration (rather witness).
    configuration      :[KeyValue];
}

/// Details necessary to compute an assignment.
table Witness {
    /// The values that the caller assigned to Incoming Variables.
    /// Contiguous BigInts in the same order as `instance.incoming_variable_ids`.
    incoming_elements  :[ubyte];

    /// Optional: Any info that may be useful to the gadget to compute assignments.
    /// Example: Merkle authentication path.
    info               :[KeyValue];
}

/// Generic key-value for custom attributes.
table KeyValue {
    key   :string;
    value :[ubyte];
}

/// Component returns to the caller. This is the final message
/// after all R1CSConstraints or AssignedVariables have been sent.
table ComponentReturn {
    /// First variable ID free after the gadget call.
    /// A variable ID greater than all IDs allocated by the gadget.
    free_variable_id_after :uint64;

    /// Optional: Any info that may be useful to the caller.
    info :[KeyValue];

    /// Optional: An error message. Null if no error.
    error :string;

    /// The values that the gadget assigned to outgoing variables, if any.
    /// Contiguous BigInts in the same order as `instance.outgoing_variable_ids`.
    outgoing_elements :[ubyte];
}

/// Report constraints to be added to the constraints system.
/// To send to the stream of constraints.
table R1CSConstraints {
    constraints :[BilinearConstraint];
}

/// An R1CS constraint between variables.
table BilinearConstraint {
    // (A) * (B) = (C)
    linear_combination_a :VariableValues;
    linear_combination_b :VariableValues;
    linear_combination_c :VariableValues;
}

/// Report local assignments computed by the gadget.
/// To send to the stream of assigned variables.
/// Does not include input and output variables.
table AssignedVariables {
    values :VariableValues;
}

```



```

    /// Concrete variable values.
    /// Used for linear combinations and assignments.
    table VariableValues {
        /// The IDs of the variables being assigned to.
        variable_ids :[uint64];

        /// Field Elements assigned to variables.
        /// Contiguous BigInts in the same order as variable_ids.
        ///
        /// The field in use is defined in `instance.field_order`.
        ///
        /// The size of an element representation is determined by:
        ///     element size = elements.length / variable_ids.length
        ///
        /// The element representation may be truncated and therefore shorter
        /// than the canonical representation. Truncated bytes are treated as zeros.
        elements :[ubyte];
    }

    // type Variable ID = uint64
    //
    // IDs must be unique within a constraint system.
    // Zero is a reserved special value.

    // type BigInt
    //
    // Big integers are represented as canonical little-endian byte arrays.
    // Multiple big integers can be concatenated in a single array.
    //
    // Evolution plan:
    // If a different representation of elements is to be supported in the future,
    // it should use new fields, and omit the current canonical fields.
    // This will allow past implementations to detect whether they are compatible.

    table Root {
        message :Message;
    }

    root_type Root;
    file_identifier "zkp2";
    file_extension "zkp2";

```

Listing 2: gadget.h - C Interface

```

#ifndef GADGET_H
#define GADGET_H
#ifdef __cplusplus
extern "C" {
#endif

/* Callback functions.

The caller implements these functions and passes function pointers to the component.
The caller may also pass pointers to arbitrary opaque `context` objects of its choice.
The component calls the callbacks with its response messages, and repeating the context pointers.

*/
typedef bool (*gadget_callback_t)(
    void *context,
    unsigned char *response
);

```

```

/* A function that implements a component.

It receives a `ComponentCall` message, callbacks, and callback contexts.
It calls `constraints_callback` one or more times with `constraints_context` and a `R1CSConst...
It calls `assigned_variables_callback` one or more times with `assigned_variables_context` and...
Finally, it calls `return_callback` with `return_context` and a `ComponentReturn` message.
The callbacks and the contexts pointers may be identical and may be NULL.

The following memory management convention is used both for `call_gadget` and for the callback...
All pointers passed as arguments to a function are only valid for the duration of this function...
The code calling a function is responsible for managing the pointed objects after the function...
*/
bool call_gadget(
    unsigned char *call_msg,

    gadget_callback_t constraints_callback,
    void *constraints_context,

    gadget_callback_t assigned_variables_callback,
    void *assigned_variables_context,

    gadget_callback_t return_callback,
    void *return_context
);

#ifdef __cplusplus
} // extern "C"
#endif
#endif //GADGET_H

```
