#### CS5489

# Lecture 2.1: Naive Bayes and Linear Discriminant Analysis

#### Kede Ma

City University of Hong Kong (Dongguan)



Slide template by courtesy of Benjamin M. Marlin

#### The Classification Task

#### <u>Definition</u>: The Classification Task

Given a feature vector  $\mathbf{x} \in \mathbb{R}^N$  that describes an object that belongs to one of C classes from the set  $\mathcal{Y}$ , predict which class the object belongs to

#### **Definition: Classifier Learning**

Given a data set of example pairs  $\mathcal{D} = \{(\mathbf{x}^{(i)}, y^{(i)}), i = 1, \dots, M\}$  where  $\mathbf{x}^{(i)} \in \mathbb{R}^N$  is a feature vector and  $y^{(i)} \in \mathcal{Y} = \{1, \dots, C\}$  is a class label, learn a function  $f : \mathbb{R}^N \mapsto \mathcal{Y}$  that accurately predicts the class label y for any feature vector  $\mathbf{x}$ 

### Classification Error and Accuracy

#### <u>Definition</u>: Classification Error Rate

Given a data set of example pairs  $\mathcal{D} = \{(\mathbf{x}^{(i)}, y^{(i)}), i = 1, \dots, M\}$  and a function  $f : \mathbb{R}^N \mapsto \mathcal{Y}$ , the classification error rate of f on  $\mathcal{D}$  is:

$$\operatorname{Err}(f, \mathcal{D}) = \frac{1}{M} \sum_{i=1}^{M} \mathbb{I}[y^{(i)} \neq f(\mathbf{x}^{(i)})]$$

### The Bayes Optimal Classifier

■ The Bayes optimal classifier uses the classification function:

#### 这个B应该是Bayes

| 換定Bayes 
$$f_{\mathbf{B}}(\mathbf{x}) = \arg\max_{c \in \{1,...,C\}} p(y = c | \mathbf{x})$$
 因为去掉了分母的 $p(\mathbf{x})$ , argmax的结果不变,从第二行到第三行也是这个原因  $c \in \{1,...,C\}$  
$$= \arg\max_{c \in \{1,...,C\}} \log p(\mathbf{x}|y = c) + \log p(y = c)$$
  $c \in \{1,...,C\}$ 

The Bayes optimal classifier is the best classifier among all possible classifiers. However, it is not useful due to the difficulty

of estimating  $p(\mathbf{x}|y=c)$  in practice

已经知道是否篮球运动员 时,他们的身高体重双变量

#### Naive Bayes

- How to deal with multiple features? E.g.,  $\mathbf{x} = \begin{bmatrix} x_1 \\ x_1 \end{bmatrix} \in \mathbb{R}^2$
- Naive Bayes assumption

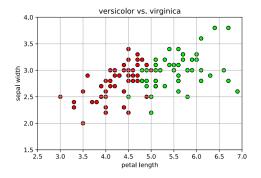
随即就讲了,他们假设变量相互独立,也就 是直接变单变量最后相乘

- The naive Bayes classifier approximates the Bayes optimal classifier using a simple form for the functions  $p(\mathbf{x}|\mathbf{y}=c)$
- This form assumes that all of the feature dimensions are statistically independent given the value of the class variable:
  - E.g., for 2 dimensions,  $p(x_1, x_2|y) = p(x_1|y)p(x_2|y)$
- Accumulates evidence from each feature dimension:
  - $\blacksquare \text{ E.g., } \log p(x_1, x_2|y) = \log p(x_1|y) + \log p(x_2|y)$
- Allows us to model each dimension of the observation with a simple univariate distribution 单变量的分布
- The general form for the classification function is:

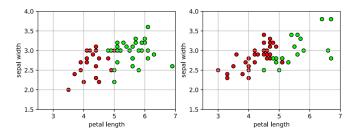
$$f_{\text{NB}}(\mathbf{x}) = \underset{c \in \{1, \dots, C\}}{\arg \max} p(y = c) \prod_{j=1}^{N} p(x_j | y = c)$$

■ We will consider the 2-dimensional iris data shown in the beginning of the lecture 

正是lec01的鸢尾花啦

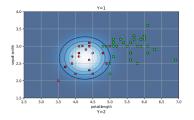


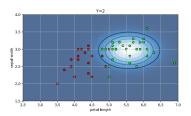
• We will select 50% of the data for training, and 50% for testing



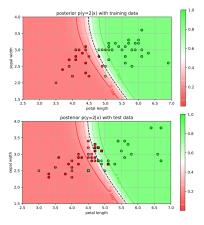
- Learn Gaussian Naive Bayes model
  - Treat each dimension as an independent Gaussian and fit the Gaussian parameters with MLE 最大似然估计
- View 2d class conditionals:

$$p(x_1, x_2|y = c) = p(x_1|y = c)p(x_2|y = c)$$





■ View the posterior  $p(y = c | \mathbf{x}) = p(y = c | x_1, x_2)$ 



#### Geometric Interpretation

■ What is the geometry of the decision boundary?

#### Geometric Interpretation

The decision boundary consists of the set of points 
$$(x_1, x_2)$$
 where  $\log p(y=1) + \sum_{j=1}^{2} \log p(x_j|y=1) \equiv \log p(y=2) + \sum_{j=1}^{2} \log p(x_j|y=2)$ :

$$\log p(y=1) + \sum_{j=1}^{2} \left( -\frac{1}{2} \log(2\pi\sigma_{j|1}^{2}) - \frac{1}{2\sigma_{j|1}^{2}} (x_{j} - \mu_{j|1})^{2} \right)$$
$$-\log p(y=2) - \sum_{j=1}^{2} \left( -\frac{1}{2} \log(2\pi\sigma_{j|2}^{2}) - \frac{1}{2\sigma_{j|2}^{2}} (x_{j} - \mu_{j|2})^{2} \right) = 0$$

It's not hard to see that the decision boundary is a quadratic function of  $(x_1, x_2)$  with the form:  $\sum_{j=1}^{2} \left( a_j x_j^2 + b_j x_j \right) + c = 0$ 

#### Naive Bayes Model For Boolean Vectors

- Model each feature independently
  - Absence/presence of a feature  $x_i$  in an input example
  - Bernoulli distribution

Present: 
$$p(x_p = 1|y = c) = \varphi_{fic}$$

Absent:  $p(x_j = 0|y = c) = 1 - \varphi_{j|c}$ 
 $y=0$   $y=0$ 

- MLE paramters:  $\varphi_{i|c} = M_{i|c}/M_c$ 
  - $M_{i|c}$  is the number of training examples in Class c that contain feature  $x_i$
  - $\blacksquare$   $M_c$  is the number of training examples in Class c
- Class-conditional distribution

$$p(x_1,...,x_N|y=c) = \prod_{i=1}^N p(x_i|y=c)$$

$$\log p(x_1, \dots, x_N | y = c) = \sum_{j=1}^N \log p(x_j | y = c)$$

For an input example x, the log-probabilities of features present given y = c adds

### Smoothing

平常处理是要做什么事情?处理局斯NB中的另一个问题(前一个是上贝 的特征值非连续值而是布尔值),这一次的问题是特征值为某个值时概 率竟然是0,此时独立概率联乘不就整体变0?How to deal with—

- Some features may not be present in any training examples for a given class
  - $M_{j|c} = 0$  and thus  $\varphi_{j|c} = 0$ 
    - I.e., examples in the class **definitely** will not contain the feature
    - Can be a problem since we simply may not have seen an example with that feature due to the limited size of the training set
- Smoothed MLE
  - Add a smoothing parameter  $\alpha$ , i.e., adding a "virtual" count
  - Parameter:  $\varphi_{j|c} = (M_{j|c} + \square)/(M_c + N\alpha)$
  - If  $\alpha = 1$ , this is called **Laplace smoothing** (or additive smoothing)
- In general, regularizing or smoothing of the estimate helps to prevent overfitting of the parameters

# Multinomial Naive Bayes

#### 多项式,我一开始以为是多特征值的,误解了

- What if  $x_j$  has a finite set of categories, i.e.,  $x_j \in \mathcal{X}_j = \{1, \dots, |\mathcal{X}_j|\}$ , instead of only two states of absence and presence with  $x_j \in \{1, 2\}$ 
  - Use a multinomial (or called categorical) distribution as class conditional

$$p(x_j = x | y = c) = \varphi_{x,j|c}$$

$$\sum_{x \in \mathcal{X}_c} \varphi_{x,j|c} = 1$$

$$\sum_{x \in \mathcal{X}_j} \varphi_{x,j|c} = 1$$

- MLE paramters:  $\varphi_{x,j|c} = M_{x,j|c}/M_c$ 
  - $M_{x,j|c}$  is the number of training examples in Class c with feature  $x_j = x$
  - $M_c$  is the number of training examples in Class c

#### Linear Discriminant Analysis

due to Fisher that dates back to the 1930's

■ Linear Discriminant Analysis (LDA) is a classification technique

- ■ Instead of a product of independent Gaussians in Naive Bayes.
- LDA assumes  $p(\mathbf{x}|y=c) = \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_c, \boldsymbol{\Sigma})$ , i.e., multivariate Gaussian with a shared covariance matrix

$$p(\mathbf{x}|y=c) = \frac{1}{|(2\pi)^N \mathbf{\Sigma}|^{1/2}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu}_c)^T \mathbf{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu}_c)\right)$$
The classification function is   
这个||要求是矩阵特征值det。  
这是个对角矩阵??

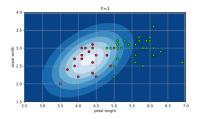
$$f_{\text{LDA}}(\mathbf{x}) = \underset{c \in \{1, \dots, C\}}{\operatorname{arg \, max}} p(y=c) p(\mathbf{x}|y=c)$$
 这个公式依然是基于P4的第二行

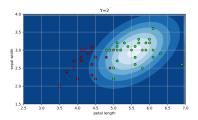
#### Learning for LDA

- As with naive Bayes, LDA parameters are learned using MLE, which reduces to using sample estimates
- Class probabilities:  $p(y = c) = \frac{1}{M} \sum_{i=1}^{M} \mathbb{I}[y^{(i)} = c] = \frac{M_c}{M}$
- Class means:  $\underline{\mu_c} = \frac{\sum_{i=1}^M \mathbb{I}[y^{(i)} = c]\mathbf{x}^{(i)}}{\sum_{i=1}^M \mathbb{I}[y^{(i)} = c]} = \frac{\sum_{i=1}^{M_c} \mathbf{x}^{(i)}}{M_c}$ , where  $\mathbf{x}^{(i)}$  belongs to Class c Uc是均值向量,就是是各种运动员时的平均身高平均体重等的向量

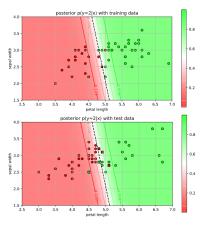
  Shared covariance:  $\Sigma = \frac{1}{M} \sum_{i=1}^M (\mathbf{x}^{(i)} \boldsymbol{\mu}_{y^{(i)}}) (\mathbf{x}^{(i)} \boldsymbol{\mu}_{y^{(i)}})^T$

- View 2d class conditionals:
  - $p(x_1, x_2|y=c) = \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}_c, \boldsymbol{\Sigma})$





■ View the posterior



#### Geometric Interpretation

- What is the geometry of the decision boundary for LDA?
- $\blacksquare$  The decision boundary consists of the set of points **x** where:

$$\log p(y = 1) - \frac{1}{2} \log |(2\pi)^2 \mathbf{\Sigma}| - \frac{1}{2} (\mathbf{x} - \boldsymbol{\mu}_1)^T \mathbf{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}_1)$$
$$-\log p(y = 2) + \frac{1}{2} \log |(2\pi)^2 \mathbf{\Sigma}| + \frac{1}{2} (\mathbf{x} - \boldsymbol{\mu}_2)^T \mathbf{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}_2) = 0$$

We can cancel a large number of terms because of the common covariance matrix and obtain the following result:

$$\log \frac{p(y=1)}{p(y=2)} - \frac{1}{2} \boldsymbol{\mu}_1^T \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu}_1 + \frac{1}{2} \boldsymbol{\mu}_2^T \boldsymbol{\Sigma}^{-1} \boldsymbol{\mu}_2 + (\boldsymbol{\mu}_1 - \boldsymbol{\mu}_2)^T \boldsymbol{\Sigma}^{-1} \mathbf{x} = 0$$

 $\blacksquare$  This shows that the decision boundary is actually linear in  $\mathbf{x}$ 

#### NB Versus LDA

- Storage: NB requires  $\mathcal{O}(N)$  parameters, whereas LDA requires  $\mathcal{O}(N^2)$  parameters
- Speed: The quadratic dependence on N makes LDA slower than NB during learning and classification
- Interpretability: Both models have good interpretability since the parameters of  $p(\mathbf{x}|y=c)$  correspond to class conditional averages
- Data: LDA will generally need more data than NB since it needs to estimate the  $O(N^2)$  parameters in the shared covariance matrix

#### Summary

- Generative classification model
  - Estimate probability distributions of features from each class
  - Given feature, predict class with the largest posterior probability
- Advantages:
  - Works with small amount of data
  - Works with multiple classes
- Disadvantages:
  - Accuracy depends on selecting an appropriate probability distribution
    - If the probability distribution doesn't model the data well, then accuracy might be bad