

Norm Space

Linear Algebra

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P-norm



□ p−norm:

$$||x||_p = (|x_1|^p + |x_2|^p + ... + |x_n|^p)^{\frac{1}{p}}$$

subject to $p \ge 1$

- \square What is the shape of $||x||_p = 1$?
- ☐ Properties?

Norm



Definition (Norm)

- \square A function $f: \mathbb{R}^n \to \mathbb{R}$ is a norm if
 - 1. $f(x) \ge 0$, $f(x) = 0 \Leftrightarrow x = 0$ (positivity)
 - 2. $f(\alpha x) = |\alpha| f(x), \forall \alpha \in \mathbb{R}$ (homogeneity)
 - 3. $f(x + y) \le f(x) + f(y)$ (triangle inequality)

1-norm and 2-norm



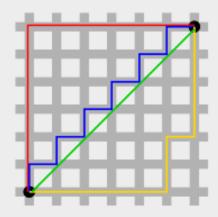
 \Box 1-norm(l_1):

$$||x||_1 = (|x_1| + |x_2| + ... + |x_n|)$$

- \square What is the shape of $||x||_1 = 1$?
- \Box The distance between two vectors under the l_1 norm is also referred to as the Manhattan Distance.
- □ Properties?

Example

 l_1 distance between (0,1) and (1,0)?



Norm Derivations



 \Box Square of l_2

$$x = \begin{bmatrix} x_1 \\ x_2 \\ \dots \\ x_n \end{bmatrix}$$

$$||x||_2^2 = x_1^2 + x_2^2 + \dots + x_n^2$$

$$\begin{cases} \frac{d\|x\|_2^2}{dx_1} = 2x \\ \frac{d\|x\|_2^2}{dx_2} = 2x \end{cases}$$

$$\implies \qquad \dots$$

Norm Derivations



$$x = \begin{bmatrix} x_1 \\ x_2 \\ \dots \\ x_n \end{bmatrix} \qquad ||x||_2 = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2} = (x_1^2 + x_2^2 + \dots + x_n^2)^{\frac{1}{2}}$$

$$\frac{d||x||_2}{dx_1} = \frac{1}{2} (x_1^2 + x_2^2 + \dots + x_n^2)^{\frac{1}{2} - 1} \cdot \frac{d}{dx_1} (x_1^2 + x_2^2 + \dots + x_n^2)$$

$$= \frac{1}{2} (x_1^2 + x_2^2 + \dots + x_n^2)^{-\frac{1}{2}} \cdot \frac{d}{dx_1} (x_1^2 + x_2^2 + \dots + x_n^2)$$

$$= \frac{1}{2} \cdot \frac{1}{(x_1^2 + x_2^2 + \dots + x_n^2)^{\frac{1}{2}}} \cdot \frac{d}{dx_1} (x_1^2 + x_2^2 + \dots + x_n^2)$$

$$= \frac{1}{2} \cdot \frac{1}{(x_1^2 + x_2^2 + \dots + x_n^2)^{\frac{1}{2}}} \cdot 2 \cdot x_1$$

$$= \frac{1}{(x_1^2 + x_2^2 + \dots + x_n^2)^{\frac{1}{2}}}$$

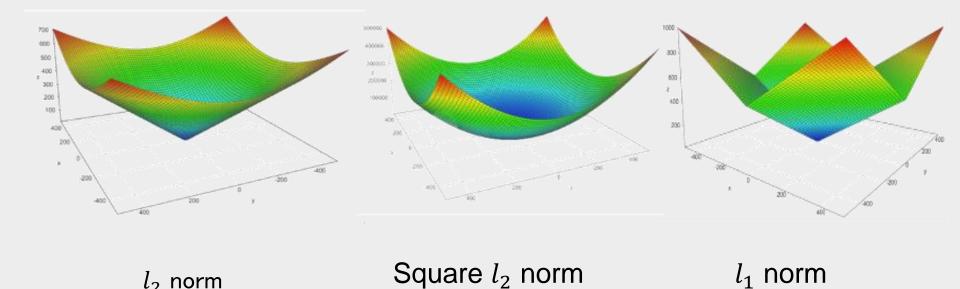
$$\frac{d||x||_2}{dx_1} = \frac{x_1}{(x_1^2 + x_2^2 + \dots + x_n^2)^{\frac{1}{2}}}$$

$$\frac{d||x||_2}{dx_2} = \frac{x_2}{(x_1^2 + x_2^2 + \dots + x_n^2)^{\frac{1}{2}}}$$

$$\frac{d\|x\|_2}{dx_n} = \frac{x_n}{(x_1^2 + x_2^2 + \dots + x_n^2)^{\frac{1}{2}}}$$

Norm Comparisons





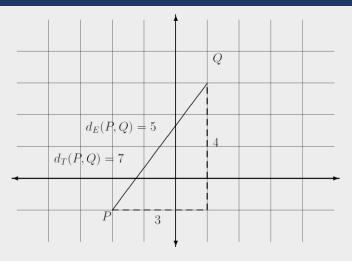
CE282: Linear Algebra

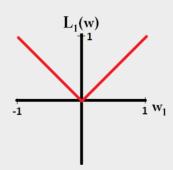
 l_2 norm

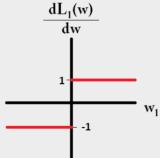
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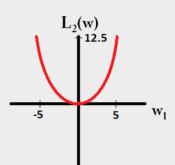
L1 and L2 norm comparisons

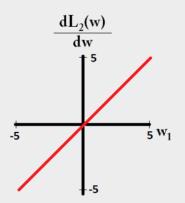












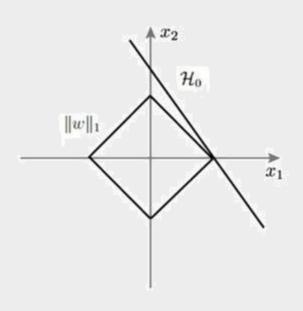
L1 and L2 norm comparisons



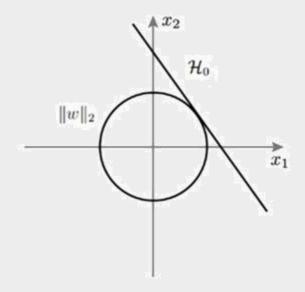
- Robustness is defined as resistance to outliers in a dataset. The more able a model is to ignore extreme values in the data, the more robust it is.
- □ Stability is defined as resistance to horizontal adjustments. This is the perpendicular opposite of robustness.
- Solution numeracy
- Computational difficulty
- Sparsity

Why is l_1 supposed to lead to sparsity than l_2 ?





 $\min_{x} ||x||_{1 \text{ or } 2},$ subject to Ax = b



 l_1 regularization

 l_2 regularization

∞-norm



 \square ∞ -norm(l_{∞})(max norm):

$$l_{\infty} = \max(|x_1|, |x_2|, ..., |x_n|)$$

- \square What is the shape of $|x|_{\infty} = 1$?
- □Properties?

$$\frac{1}{2}$$
 –norm



$$\square$$
 What is the shape of $|x|_{\frac{1}{2}} = 1$?



 \Box 0-norm(l_0):

$$||x||_0 = \lim_{\alpha \to 0^+} ||x||_\alpha = \left(\sum_{k=1}^n |x|^\alpha\right)^{\frac{1}{\alpha}} = \sum_{k=1}^n 1_{(0,\infty)}(|x|)$$

□ 0-norm, defined as the number of non-zero elements in a vector, is an ideal quantity for feature selection. However, minimization of 0-norm is generally regarded as a combinatorially difficult optimization

$$\square \|x\|_0 = \sum_{x_i \neq 0} 1$$



☐ Is 0-norm a valid norm?

 \square What is the shape of $||x||_0 = 1$?

Examples

- l_0 distance between (0,0) and (0,5)?
- l_0 distance between (1,1) and (2,2)?
- (username, password)



Class Activity

- l_0 distance between (0,0) and (0,5)?
- l_0 distance between (1,1) and (2,2)?
- (username, password)



Or go to the below link https://forms.gle/xFHSDKJDq1KoL4Kx6

Timer: (2:30 minutes)



Examples

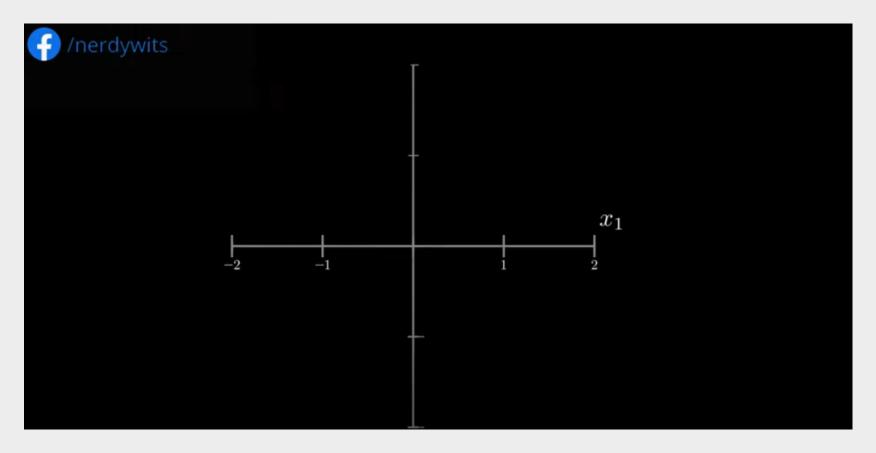
- l_0 distance between (0,0) and (0,5)?
- l_0 distance between (1,1) and (2,2)?
- (username, password)

Solution

- **1**
- **2**
- When l_0 is 0, then we can infer that username and password is a match and we can authenticate the user.

Vector Norms Shapes

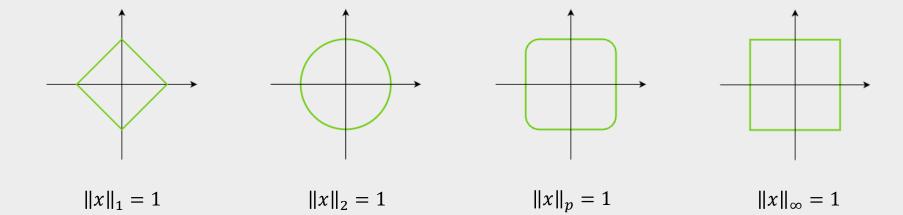




Norms and Convexity



 \Box For $p \geq 1$, l_p norm is convex



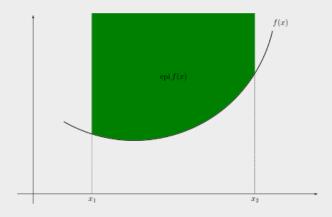
Convex function



- A function is convex iff its epigraph is a convex set.
- Epigraph or supergraph

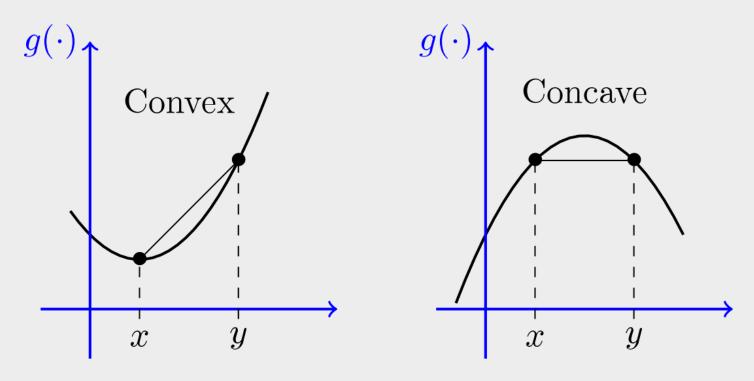
$$\mathrm{epi} f = \{(x,\mu) \,:\, x \in \mathbb{R}^n,\, \mu \in \mathbb{R},\, \mu \geq f(x)\} \subseteq \mathbb{R}^{n+1}$$

$$f((1-\theta)x^{(0)} + \theta x^{(1)}) \le (1-\theta)f(x^{(0)}) + \theta f(x^{(1)}), \quad \forall \theta \in [0,1]$$



Convex and Concave Function

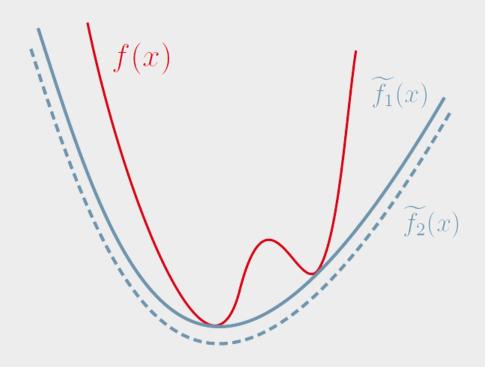




second derivative is nonnegative on its entire domain

Convex Relaxation





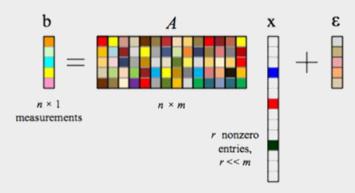
Sparse Applications



□ Alternative viewpoint: We try to find the sparsest solution which explains our noisy measurements

$$\min_{x} \|x\|_{0}, \quad subject \ to \ \|Ax - b\|_{2} < \epsilon$$

 \square Here, the l_0 -norm is a shorthand notation for counting the number of non-zero elements in x.



Sparse Solution



- \Box l_0 optimization is np-hard.
- Convex relaxation for solving the problem.

$$\min_{1} ||x||_{1}$$

subject to
$$||Ax - b||_2 < \epsilon$$

$$\min_{1} ||x||_{0}$$

subject to
$$||Ax - b||_2 < \epsilon$$

L1-L2 norm inequality



Theorem

For all $x \in \mathbb{R}^d$:

$$\left| |x| \right|_2 \le \left| |x| \right|_1 \le \sqrt{d} \left| |x| \right|_2$$

Proof

Max norm inequality



Theorem

For all $x \in \mathbb{R}^d$:

$$\begin{aligned} \big| |x| \big|_{\infty} &\leq \big| |x| \big|_{1} \leq d \big| |x| \big|_{\infty} \\ \big| |x| \big|_{\infty} &\leq \big| |x| \big|_{2} \leq \sqrt{d} \big| |x| \big|_{\infty} \end{aligned}$$

Proof

Conclusion



By a normed linear space (briefly normed space) is meant a real or complex vector space E in which every vector x is associated with a real number |x|, called its absolute value or norm, in such a manner **that the properties** (a') - (c') holds. That is, for any vectors $x, y \subset E$ and scalar α we have:

$$|x| \ge 0$$

ii.
$$|x| = 0$$
 iif $x = \vec{0}$

iii.
$$|\alpha x| = |\alpha||x|$$

$$iv. \quad |x+y| \le |x| + |y|$$

Inner product and norm



Theorem

Take any inner product $\langle \cdot, \cdot \rangle$ and define $f(x) = \sqrt{\langle x, x \rangle}$. Then f is a norm.

Proof

Note

Every inner product gives rise to a norm, but not every norm comes from an inner product. (Think about norm 2 and norm max)

Entry-wise matrix norms



Definition

$$||A||_{p,p} = ||vec(A)||_p = \left(\sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^p\right)^{\frac{1}{p}}$$

Special Cases

☐ Frobenius (Eucilian, Hilbert Schmidt) norm:(p = 2)

$$||A||_F = \left(\sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^2\right)^{\frac{1}{2}} = \sqrt{trace(A^*A)}$$

 \square Max norm $(p = \infty)$

$$||A||_{max} = \max_{ij} |a_{ij}|$$

■ Sum-absolute-value norm

$$||A||_{sav} = \sum_{i,j} |A_{i,j}|$$

Frobenius (Euclidian, Hilbert Schmidt) norm



Special Cases

□Invariant under rotations (unitary operations)

$$||A||_F = ||AU||_F = ||UA||_F$$

$$||A + B||_F^2 = ||A||_F^2 + ||B||_F^2 + 2\langle A, B \rangle$$

$$||A^*A||_F = ||AA^*||_F \le ||A||_F^2$$

$$||A||_F = \left(\sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^2\right)^{\frac{1}{2}} = \sqrt{trace(A^*A)}$$

Frobenius (Euclidean norm)



Theorem

Let b_1, b_2, \dots, b_n denote the columns of B. Then

$$||AB||_{HS}^2 = \sum_{i=1}^n ||Ab_i||^2 \le \sum_{i=1}^n ||A||^2 ||b_i||^2 = ||A||^2 ||B||_{HS}^2$$

Using Cauchy-Schawrtz Inequality

Matrix norms induced by vector norms



Definition

$$||A||_p = \max_{\vec{x} \neq \vec{0}} \frac{||A\vec{x}||_p}{||\vec{x}||_p} = \max_{||\vec{x}||_p = 1} ||A\vec{x}||_p$$

Theorem

1. $||Ax|| \le ||A|| ||x||$ for all vectors ||x||

2. For all matrices $A, B: ||AB|| \le ||A|| ||B||$

Matrix norms induced by vector norms



Definition

- ☐ The norm of a matrix is a real number which is a measure of the magnitude of the matrix.
- **□** Norm 1:

$$||A||_1 = \max_{1 \le j \le n} \left(\sum_{i=1}^n |a_{ij}| \right)$$

□ Norm max:

$$||A||_{\infty} = \max_{1 \le i \le n} \left(\sum_{j=1}^{n} |a_{ij}| \right)$$

Example

$$B = \begin{bmatrix} 5 & -4 & 2 \\ -1 & 2 & 3 \\ -2 & 1 & 0 \end{bmatrix}$$

References



- □ Linear Algebra and Its Applications, David C. Lay
- Introduction to Applied Linear Algebra Vectors, Matrices, and Least Squares
- https://www.youtube.com/watch?v=76B5cMEZA4Y