



# Affine Function

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## Linear Algebra

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## Definition

A function  $f: R^n \rightarrow R$  is **affine** if and only if it can be expressed as  $f(x) = a^T x + b$  (linear function plus a constant (**offset**))

- ❑ **Superposition property** for affine function which is called restricted superposition

$$f(\alpha x + \beta y) = \alpha f(x) + \beta f(y), \quad \alpha + \beta = 1$$



## Theorem

Any scalar-valued function that satisfies the **restricted superposition property** is **affine**.

## Conclusion

**Every** affine function can be written as  $f(x) = a^T x + b$  with:

$$a^T = [f(e_1) - f(0), f(e_2) - f(0), \dots, f(e_n) - f(0)]$$

$$b = f(0)$$



## Conclusion

We can write linear and affine functions in two methods:

### ❑ Method 1:

#### ❑ Linear:

$$f(\alpha_1 x_1 + \cdots + \alpha_n x_n) = \alpha_1 f(x_1) + \cdots + \alpha_n f(x_n), \forall \alpha_1, \dots, \alpha_n$$

#### ❑ Affine:

$$f(\alpha_1 x_1 + \cdots + \alpha_n x_n) = \alpha_1 f(x_1) + \cdots + \alpha_n f(x_n), \alpha_1 + \cdots + \alpha_n = 1$$

### ❑ Method 2:

#### ❑ Linear:

$$f(x) = a^T x$$

#### ❑ Affine:

$$f(x) = a^T x + b$$



## Definition

In many applications, scalar-valued functions of  $n$  variables, or relations between  $n$  variables and a scalar one, can be approximated as linear or affine functions, which is called “**Model**”.



□ **Derivative** of function  $f: R \rightarrow R$  at the point  $(z, f(z))$ :

$$\lim_{t \rightarrow 0} \frac{f(z + t) - f(z)}{t}$$

□ It gives the slope of the graph of  $f$  at the point  $(z, f(z))$ .

□  $f'(z)$  is a scalar-valued function of a scalar variable



- The **partial derivative** of function  $f: R^n \rightarrow R$  at the point  $z$ , with respect to its  $i$ th argument

$$\frac{\partial f}{\partial x_i}(z) = \lim_{t \rightarrow 0} \frac{f(z_1, \dots, z_{i-1}, z_i + t, z_{i+1}, \dots, z_n) - f(z)}{t} = \lim_{t \rightarrow 0} \frac{f(z + te_i) - f(z)}{t}$$

- The partial derivative is the derivative with respect to the  $i$  –th argument, with all other arguments fixed.



- **Gradient:** The partial derivatives of  $f(x)$  with respect to its  $n$  arguments can be collected into an  $n$  vector called the gradient of  $f(x)$  (at point  $z$ ):

$$\nabla f(z) = \begin{bmatrix} \frac{\partial f}{\partial x_1}(z) \\ \vdots \\ \frac{\partial f}{\partial x_n}(z) \end{bmatrix}$$

## Theorem

Gradient of a combination of functions:

$$f(z) = ag(z) + bh(z)$$

$$\nabla f(z) = a\nabla g(z) + b\nabla h(z)$$





□  $f: R^n \rightarrow R$  is differentiable: its partial derivatives exist

## Definition

The (first-order) Taylor approximation of  $f$  near (or at) the point  $z$ :

$$\hat{f}(x) = f(z) + \frac{\partial f}{\partial x_1}(z)(x_1 - z_1) + \cdots + \frac{\partial f}{\partial x_n}(z)(x_n - z_n)$$



## Example

□  $\hat{f}(x)$  is a linear function or a affine function?

$$\hat{f}(x) = \underbrace{f(z)}_{\text{Constant}} + \underbrace{\nabla f(z)^T (x - z)}_{\text{Deviation or Perturbation of } x \text{ from } z}$$

Constant- value of function at  $z$

Deviation or Perturbation of  $x$  from  $z$

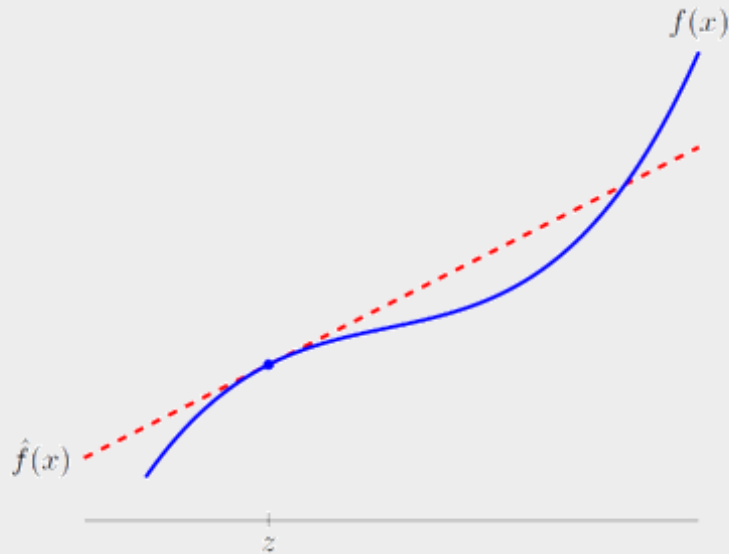
$$\hat{f}(x) = \underbrace{\nabla f(z)^T x}_{\text{Linear function}} + \underbrace{(f(z) - \nabla f(z)^T z)}_{\text{Constant}}$$

Linear function

Constant



- The Taylor approximation is sometimes called the linear approximation or linearized approximation of  $f$  (at  $z$ )



A function  $f$  of one variable, and the first order Taylor approximation  $\hat{f}(x) = f(z) + f'(z)(x - z)$  at  $z$