# **Matrix Properties**

CE40282-1: Linear Algebra Hamid R. Rabiee and Maryam Ramezani Sharif University of Technology



## **Basic Notation**

By  $A \in \mathbb{R}^{m \times n}$  we denote a matrix with m rows and n columns, where the entries of A are real numbers.

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} = \begin{bmatrix} | & | & | & | \\ a_1 & a_2 & \cdots & a_n \\ | & | & | & | \end{bmatrix} = \begin{bmatrix} - & a_1^T & - \\ - & a_2^T & - \\ \vdots & \vdots & | \\ - & a_m^T & - \end{bmatrix}$$

# **Matrices Equality**

Two matrices are equal if they have the same size (m × n) and entries corresponding to the same position are equal

For 
$$A=[a_{ij}]_{m\times n}$$
 and  $B=[b_{ij}]_{m\times n}$ , 
$$A=B \quad \text{if and only if} \quad a_{ij}=b_{ij} \ \text{for } 1\leq i\leq m, \qquad 1\leq j\leq n$$

## **Matrix Operations**

- Matrix-Matrix addition
- Scalar-Matrix multiplication
- Matrix-Vector multiplication
- Matrix-Matrix multiplication

## **Matrix-Matrix Addition**

 (just like vectors) we can add or subtract matrices of the same size:

$$(A + B)_{ij} = A_{ij} + B_{ij}, \quad i = 1, \dots, m, \quad j = 1, \dots, n$$

- Properties:
  - Commutative A + B = B + A
  - Associative A + (B + C) = (A + B) + C
  - Addition with zero A + 0 = A
  - Transpose  $(A + B)^T = A^T + B^T$

# Scalar-Matrix Multiplication

- Example  $2\begin{bmatrix} 1 & -1 & 2 \\ -3 & 0 & 4 \end{bmatrix} = \begin{bmatrix} 2 & -2 & 4 \\ -6 & 0 & 8 \end{bmatrix}$
- Properties:
  - Associative  $(\alpha\beta)A = \alpha(\beta A)$
  - Distributive property of scalar multiplication over real-number addition  $(\alpha + \beta)A = \alpha A + \beta A$
  - Distributive property of scalar multiplication over matrix addition  $\alpha(A + B) = \alpha A + \alpha B$

  - Transpose  $(\alpha A)^T = \alpha A^T$

#### Review: Vector-Vector Product

inner product or dot product

$$x^T y \in \mathbb{R} = \begin{bmatrix} x_1 & x_2 & \cdots & x_n \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} = \sum_{i=1}^n x_i y_i.$$

outer product

$$xy^{T} \in \mathbb{R}^{m \times n} = \begin{bmatrix} x_{1} \\ x_{2} \\ \vdots \\ x_{m} \end{bmatrix} \begin{bmatrix} y_{1} & y_{2} & \cdots & y_{n} \end{bmatrix} = \begin{bmatrix} x_{1}y_{1} & x_{1}y_{2} & \cdots & x_{1}y_{n} \\ x_{2}y_{1} & x_{2}y_{2} & \cdots & x_{2}y_{n} \\ \vdots & \vdots & \ddots & \vdots \\ x_{m}y_{1} & x_{m}y_{2} & \cdots & x_{m}y_{n} \end{bmatrix}.$$

- If we write A by rows, then we can express Ax as,

$$A \in \mathbb{R}^{m \times n}$$

$$y = Ax = \begin{bmatrix} - & a_1^T & - \\ - & a_2^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} x = \begin{bmatrix} a_1^T x \\ a_2^T x \\ \vdots \\ a_m^T x \end{bmatrix} \cdot a_i^T x = \sum_{j=1}^n a_{ij} x$$

If we write A by columns, then we have:

$$y = Ax = \begin{bmatrix} | & | & | & | \\ a_1 & a_2 & \cdots & a_n \\ | & | & | & | \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} a_1 \\ a_1 \end{bmatrix} x_1 + \begin{bmatrix} a_2 \\ a_2 \end{bmatrix} x_2 + \ldots + \begin{bmatrix} a_n \\ a_n \end{bmatrix} x_n .$$

y is a *linear combination* of the *columns* of A.

columns of A are linearly independent if Ax = 0 implies x = 0

 $A \in \mathbb{R}^{m \times n}$ 

It is also possible to multiply on the left by a row vector.

- If we write A by columns, then we can express  $x^{T}A$  as,

$$y^T = x^T A = x^T \begin{bmatrix} | & | & | \\ a_1 & a_2 & \cdots & a_n \\ | & | & | \end{bmatrix} = \begin{bmatrix} x^T a_1 & x^T a_2 & \cdots & x^T a_n \end{bmatrix}$$

- expressing A in terms of rows we have:

$$y^{T} = x^{T}A = \begin{bmatrix} x_{1} & x_{2} & \cdots & x_{m} \end{bmatrix} \begin{bmatrix} - & a_{1}^{T} & - \\ - & a_{2}^{T} & - \\ & \vdots & \\ - & a_{m}^{T} & - \end{bmatrix}$$
$$= x_{1} \begin{bmatrix} - & a_{1}^{T} & - \end{bmatrix} + x_{2} \begin{bmatrix} - & a_{2}^{T} & - \end{bmatrix} + \dots + x_{m} \begin{bmatrix} - & a_{m}^{T} & - \end{bmatrix}$$

 $y^T$  is a linear combination of the *rows* of A.

Example for different representations of matrix-vector multiplication

#### Properties

$$A(u + v) = Au + Av$$

$$(A+B)u = Au + Bu$$

$$(\alpha A)u = \alpha(Au) = A(\alpha u) = \alpha Au$$

$$0u = 0$$

$$A0 = 0$$

$$Iu = u$$

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} = \begin{bmatrix} | & | & | & | \\ a_1 & a_2 & \cdots & a_n \\ | & | & | & | \end{bmatrix} = \begin{bmatrix} - & a_1^T & - \\ - & a_2^T & - \\ \vdots & \vdots & | \\ - & a_m^T & - \end{bmatrix}$$

- Column j:  $a_j =$
- Row i:  $a_i^T =$
- Vector sum of rows of A=
- Vector sum of columns of A=

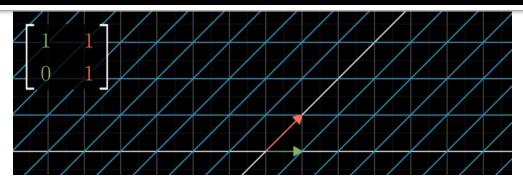
$$\begin{bmatrix} -1 & 2 & 1 \\ 2 & 0 & -2 \end{bmatrix}$$

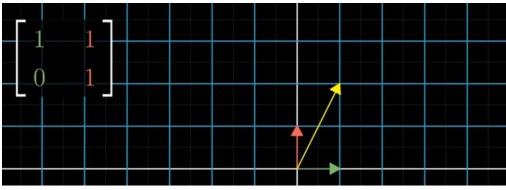
## **Linear Transformation**

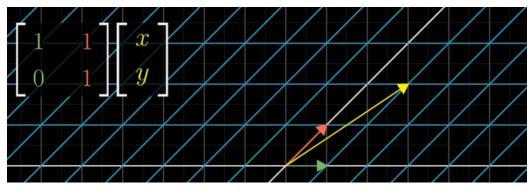
$$\begin{split} L(\vec{\mathbf{v}} + \vec{\mathbf{w}}) &= L(\vec{\mathbf{v}}) + L(\vec{\mathbf{w}}) \\ L(c\vec{\mathbf{v}}) &= cL(\vec{\mathbf{v}}) \end{split}$$
 "Additivity"   
 "Scaling"

- Linear Transformation
  - Lines remain lines
  - Origin remains fixed

## **Linear Transformation**







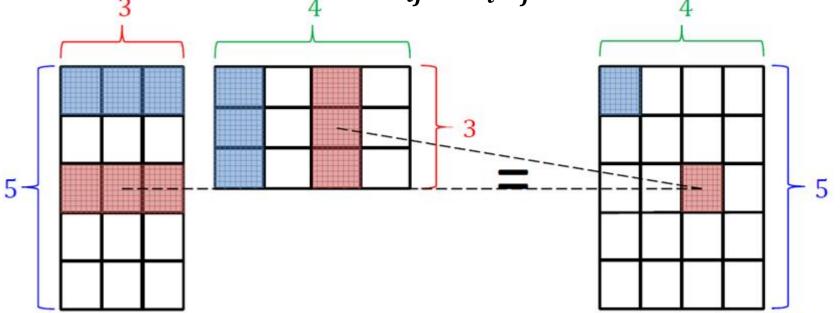
#### Source:

https://www.youtube.com/watch?v =kYB8IZa5AuE&list=PLZHQObO WTQDPD3MizzM2xVFitgF8hE\_ab &index=3

# Matrix-Matrix Multiplication

• Matrix-matrix:  $A \in \mathbb{R}^{m \times k}$ ,  $B \in \mathbb{R}^{k \times n} \to \mathbb{R}^{m \times n}$ -  $a_i$  rows of A,  $b_i$  cols of B

C = AB for  $1 \le i \le m$ ,  $1 \le j \le n$  inner product  $C_{ij} = \alpha_i^T b_j$ 



#### Matrix-Matrix Multiplication (different views)

1. As a set of vector-vector products

$$C = AB = \begin{bmatrix} - & a_1^T & - \\ - & a_2^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \begin{bmatrix} | & | & | & | \\ b_1 & b_2 & \cdots & b_p \\ | ^1 & | ^2 & \cdots & | \end{bmatrix} = \begin{bmatrix} a_1^T b_1 & a_1^T b_2 & \cdots & a_1^T b_p \\ a_2^T b_1 & a_2^T b_2 & \cdots & a_2^T b_p \\ \vdots & \vdots & \ddots & \vdots \\ a_m^T b_1 & a_m^T b_2 & \cdots & a_m^T b_p \end{bmatrix}$$

2. As a sum of outer products

#### Matrix-Matrix Multiplication (different views)

3. As a set of matrix-vector products.

$$C = AB = A \begin{bmatrix} | & | & & | \\ b_1 & b_2 & \cdots & b_p \\ | & | & & | \end{bmatrix} = \begin{bmatrix} | & | & | & | \\ Ab_1 & Ab_2 & \cdots & Ab_p \\ | & | & & | \end{bmatrix}.$$

Here the *i*th column of C is given by the matrix-vector product with the vector on the right,  $c_i = Ab_i$ . These matrix-vector products can in turn be interpreted using both viewpoints given in the previous subsection.

4. As a set of vector-matrix products.

$$C = AB = \begin{bmatrix} - & a_1^T & - \\ - & a_2^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} B = \begin{bmatrix} - & a_1^T B & - \\ - & a_2^T B & - \\ & \vdots & \\ - & a_m^T B & - \end{bmatrix}$$

#### **Matrix-Matrix Multiplication**

- Properties:
  - Associative

$$(AB)C = A(BC)$$

Distributive

$$A(B+C) = AB + BC$$

NOT commutative

$$AB \neq BA$$

- Dimensions may not even be conformable

## **Matrix Power**

 $\blacksquare$   $A^k$ : repeated multiplication of a square matrix

$$A^1 = A, A^2 = AA, ..., A^k = \underbrace{AA \cdots A}_{k \text{ matrices}}$$

- Properties:
  - $A^{j}A^{k} = A^{j+k}$

where j and k are nonegative integers and A<sup>0</sup> is assumed to be I

- $(A^j)^k = A^{jk}$
- For diagonal matrices:

$$D = \begin{bmatrix} d_1 & 0 & \cdots & 0 \\ 0 & d_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & d_n \end{bmatrix} \Rightarrow D^k = \begin{bmatrix} d_1^k & 0 & \cdots & 0 \\ 0 & d_2^k & \cdots & 0 \\ \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & d_n^k \end{bmatrix}$$

#### Note

- Two properties which is held for real numbers, but not for matrices:
  - (1) commutative property of matrix multiplication

$$ab = ba$$
  $AB \neq BA$ 

Example

$$A = \begin{bmatrix} 1 & 3 \\ 2 & -1 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 2 & -1 \\ 0 & 2 \end{bmatrix}$$
$$AB = \begin{bmatrix} 1 & 3 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} 2 & 5 \\ 4 & -4 \end{bmatrix}$$
$$BA = \begin{bmatrix} 2 & -1 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 2 & -1 \end{bmatrix} = \begin{bmatrix} 0 & 7 \\ 4 & -2 \end{bmatrix}$$

#### Note

#### (2) cancellation law

$$ac = bc$$
,  $c \neq 0 \Rightarrow a = b$ 

AC = BC and  $C \neq 0$  (C is not a zero matrix)

- (1) If C is invertible, then A = B
- (2) If C is not invertible, then  $A \neq B$
- Example

$$A = \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix}, \qquad B = \begin{bmatrix} 2 & 4 \\ 2 & 3 \end{bmatrix}, \qquad C = \begin{bmatrix} 1 & -2 \\ -1 & 2 \end{bmatrix}$$

$$AC = \begin{bmatrix} 1 & 3 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & -2 \\ -1 & 2 \end{bmatrix} = \begin{bmatrix} -2 & 4 \\ -1 & 2 \end{bmatrix} \qquad BC = \begin{bmatrix} 2 & 4 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 1 & -2 \\ -1 & 2 \end{bmatrix} = \begin{bmatrix} -2 & 4 \\ -1 & 2 \end{bmatrix}$$

So, although 
$$AC = BC$$
 ,  $A \neq B$ 

# Matrix Exponential Application

Solve systems of linear ordinary differential equations.

$$rac{d}{dt}y(t)=Ay(t),\quad y(0)=y_0$$

where A is a constant matrix, is given by

$$y(t)=e^{At}y_0$$
 .

## **Matrix Exponential**

Is a matrix function on square matrices (A) using Taylor series:

$$e^{A} = 1 + A + \frac{1}{2!}A^{2} + \frac{1}{3!}A^{3} + \frac{1}{4!}A^{4} + \cdots$$

Special Case: When A is Diagonal:

$$A = \begin{bmatrix} & & & \\ & & & \\ & & & \\ & & & \\ \end{bmatrix} \Rightarrow \underline{e}^{A} = \begin{bmatrix} & & & \\ & & & \\ & & & \\ & & & \\ \end{bmatrix}$$

# **Matrix Operations Complexity**

- $m \times n$  matrix stored A as  $m \times n$  array of numbers (for sparse A, store only  $\mathbf{nnz}(A)$  nonzero values)
- matrix addition, scalar-matrix multiplication cost mn flops
- ► matrix-vector multiplication costs  $m(2n 1) \approx 2mn$  flops (for sparse A, around  $2\mathbf{nnz}(A)$  flops)

## Transpose

The *transpose* of a matrix results from "flipping" the rows and columns. Given a matrix  $A \in \mathbb{R}^{m \times n}$ , its transpose, written  $A^T \in \mathbb{R}^{n \times m}$ , is the  $n \times m$  matrix whose entries are given by

$$(A^T)_{ij} = A_{ji}$$
.

- Properties:
  - $(A^T)^T = A$
  - $(A+B)^T = A^T + B^T$
  - $(cA)^T = c(A^T)$
  - $(AB)^T = B^T A^T \longrightarrow (A_1 A_2 A_3 \cdots A_n)^T = A_n^T \cdots A_3^T A_2^T A_1^T$

## Conjugate Transpose

$$oldsymbol{A}^* = oldsymbol{A}^{\mathrm{H}} = \left(\overline{oldsymbol{A}}
ight)^{\mathsf{T}} = \overline{oldsymbol{A}^{\mathsf{T}}}$$

$$oldsymbol{A} = egin{bmatrix} 1 & -2-i & 5 \ 1+i & i & 4-2i \end{bmatrix} \qquad oldsymbol{A}^{\mathrm{H}} = egin{bmatrix} 1 & 1-i \ -2+i & -i \ 5 & 4+2i \end{bmatrix}$$

- ullet  $(m{A}+m{B})^{
  m H}=m{A}^{
  m H}+m{B}^{
  m H}$  for any two matrices  $m{A}$  and  $m{B}$  of the same dimensions.
- ullet  $(zoldsymbol{A})^{
  m H}=ar{z}oldsymbol{A}^{
  m H}$  for any complex number z and any m-by-n matrix  $oldsymbol{A}$ .
- ullet  $(m{A}m{B})^{ ext{H}}=m{B}^{ ext{H}}m{A}^{ ext{H}}$  for any m-by-n matrix  $m{A}$  and any n-by-p matrix  $m{B}$ . Note that the order of the factors is reversed.
- $ullet \left(oldsymbol{A}^{\mathrm{H}}
  ight)^{\mathrm{H}} = oldsymbol{A}$  for any *m*-by-*n* matrix  $oldsymbol{A}$  ,

For real matrices, the conjugate transpose is just the transpose,  $m{A}^{
m H} = m{A}^{
m T}$  .

#### Trace

The **trace** of a square matrix  $A \in \mathbb{R}^{n \times n}$ , denoted  $\operatorname{tr} A$ , is the sum of diagonal elements in the matrix:

$$\operatorname{tr} A = \sum_{i=1}^{n} A_{ii}. \qquad \operatorname{Tr} \begin{pmatrix} \frac{a_{11}}{a_{21}} & \frac{a_{12}}{a_{22}} & \cdots & a_{1,n-1} & a_{1n} \\ a_{21} & \frac{a_{22}}{a_{22}} & \cdots & a_{2,n-1} & a_{2n} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{n-1,1} & a_{n-1,2} & \cdots & a_{n-1,n-1} & a_{n-1,n} \\ a_{n1} & a_{n2} & \cdots & a_{n,n-1} & a_{nn} \end{pmatrix} = a_{11} + a_{22} + \cdots + a_{nn}.$$

The trace has the following properties:

- For  $A \in \mathbb{R}^{n \times n}$ ,  $\operatorname{tr} A = \operatorname{tr} A^T$ .
- For  $A, B \in \mathbb{R}^{n \times n}$ ,  $\operatorname{tr}(A + B) = \operatorname{tr}A + \operatorname{tr}B$ .
- For  $A \in \mathbb{R}^{n \times n}$ ,  $t \in \mathbb{R}$ ,  $\operatorname{tr}(tA) = t \operatorname{tr} A$ .
- For A, B such that AB is square, trAB = trBA.
- For A, B, C such that ABC is square, trABC = trBCA = trCAB, and so on for the product of more matrices.
- Trace is a linear function on the matrix space. Why?
- Example:

Show that there do not exist matrices  $A, B \in \mathcal{M}_n$  such that AB - BA = I.

## Kronecker sum

A and B are square matrices, the Kronecker sum is:

$$A \oplus B = A \otimes I_b + I_a \otimes B$$

**Matrix exponential** 

Properties:

$$\exp(A) \otimes \exp(B) = \exp(A \oplus B)$$

Example

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \oplus \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix} = \begin{bmatrix} a_{11} + b_{11} & b_{12} & a_{12} & 0 \\ b_{21} & a_{11} + b_{22} & 0 & a_{12} \\ a_{21} & 0 & a_{22} + b_{11} & b_{12} \\ 0 & a_{21} & b_{21} & a_{22} + b_{22} \end{bmatrix}$$

# **Elementary Matrices**

 An elementary matrix is one that is obtained by performing a single elementary row operation on an identity matrix.

If an elementary row operation is performed on an  $m \times n$  matrix A, the resulting matrix can be written as EA, where the  $m \times m$  matrix E is created by performing the same row operation on  $I_m$ .

Example

$$E_{1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -4 & 0 & 1 \end{bmatrix}, \quad E_{2} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad E_{3} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 5 \end{bmatrix},$$
$$A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$$

- An  $m \times n$  matrix is
  - $\blacksquare$  Tall m > n
  - Wide n > m
  - Square m = n
- Main diagonal of matrix

$$A_{n\times n} = \boxed{ \qquad \qquad a_{11}, a_{22}, \dots a_{nn}}$$

$$a_{11}, a_{22}, \dots a_{nn}$$

Anti diagonal of matrix

$$A_{n\times n} = \boxed{\hspace{1cm}} a_{1,n}, a_{2,n-1}, \dots a_{n,1}$$

$$a_{1,n}, a_{2,n-1}, \dots a_{n,1}$$

#### Identity matrix

$$\begin{bmatrix}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{bmatrix}$$

$$I_n = [e_1, e_2, e_3]$$

 $I \in \mathbb{R}^{n \times n}$ , is a square matrix with ones on the diagonal and zeros everywhere else. That is,

$$I_{ij} = \left\{ \begin{array}{ll} 1 & i = j \\ 0 & i \neq j \end{array} \right.$$

It has the property that for all  $A \in \mathbb{R}^{m \times n}$ ,

$$AI = A = IA$$
.

#### Diagonal matrix

a matrix where all non-diagonal elements are 0.  $D = \operatorname{diag}(d_1, d_2, \ldots, d_n)$ , with

Clearly, 
$$I = \operatorname{diag}(1, 1, \dots, 1)$$
. 
$$D_{ij} = \left\{ \begin{array}{ll} d_i & i = j \\ 0 & i \neq j \end{array} \right. \quad A = \operatorname{diag}(a_1, \dots, a_m) = \left[ \begin{array}{ll} a_1 & \cdots & 0 \\ \vdots & a_i & \vdots \\ 0 & \cdots & a_m \end{array} \right]$$

• Scalar matrix A special kind of diagonal matrix in which all diagonal elements are the same  $\begin{bmatrix} 3 & 0 & 0 \end{bmatrix}$ 

$$\begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

- A matrix A over R is called:
  - symmetric if  $A^T = A$
  - skew-symmetric if  $A^T = -A$
  - $A^TA$  must be symmetric (<u>A with any size, it is not necessary</u> for A to be a square matrix)

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & -1 \\ 3 & -1 & 4 \end{bmatrix} \text{ and } B = \begin{bmatrix} 0 & 1 & 2 \\ -1 & 0 & -3 \\ -2 & 3 & 0 \end{bmatrix}$$

• A is orthogonal if  $AA^T = A^TA = I$ 

$$A = \begin{bmatrix} \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{6}} & -\frac{2}{\sqrt{6}} \end{bmatrix}$$

- Let  $A = [a_{ij}]$  be an  $n \times n$  matrix with  $a_{ij} = \begin{cases} 1 & if \ i = j + 1 \\ 0 & other \end{cases}$ . Then  $A^n = 0$  and  $A^k \neq 0$  for  $1 \leq k \leq n-1$ 
  - Nilpotent: A for which a positive integer p exists such that  $A^{p} = 0.$
  - Order of nilpotency (degree, index): Least positive integer pfor which  $A^p = 0$  is called the.

$$A = egin{bmatrix} 0 & 1 \ 0 & 0 \end{bmatrix} \quad C = egin{bmatrix} 5 & -3 & 2 \ 15 & -9 & 6 \ 10 & -6 & 4 \end{bmatrix}$$

## **Hermitian Matrix**

 Hermitian matrix (or self-adjoint matrix) is a complex square matrix that is equal to its own conjugate transpose

$$A ext{ Hermitian} \quad \Longleftrightarrow \quad A = A^{\mathsf{H}}$$

conjugate transpose

$$A^H = A^* = (\overline{A})^T$$

# **Unitary matrix**

$$U^*U = UU^* = UU^{-1} = I$$

If *U* is a square, complex matrix, then the following conditions are equivalent:<sup>[2]</sup>

- 1. U is unitary.
- 2.  $U^*$  is unitary.
- 3. U is invertible with  $U^{-1}=U^*$ .
- 4. The columns of U form an orthonormal basis of  $\mathbb{C}^n$  with respect to the usual inner product. In other words,  $U^*U=I$ .
- 5. The rows of U form an orthonormal basis of  $\mathbb{C}^n$  with respect to the usual inner product. In other words,  $UU^*=I$ .

• Idempotent: satisfy the condition that  $A^2 = A$ 

Examples of  $2 \times 2$  idempotent matrices are:

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad \begin{bmatrix} 3 & -6 \\ 1 & -2 \end{bmatrix}$$

Examples of  $3 \times 3$  idempotent matrices are:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \qquad \begin{bmatrix} 2 & -2 & -4 \\ -1 & 3 & 4 \\ 1 & -2 & -3 \end{bmatrix}$$

If a matrix  $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$  is idempotent, then

- $\bullet \ a=a^2+bc,$
- ullet b=ab+bd, implying b(1-a-d)=0 so b=0 or d=1-a,
- ullet c=ca+cd, implying c(1-a-d)=0 so c=0 or d=1-a,
- $d = bc + d^2$ .

- Toeplitz: diagonal-constant matrix: values on diagonals are equal
- A Toeplitz matrix is not necessarily square.

$$A = \begin{bmatrix} a_0 & a_{-1} & a_{-2} & \cdots & \cdots & a_{-(n-1)} \\ a_1 & a_0 & a_{-1} & \ddots & & \vdots \\ a_2 & a_1 & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & a_{-1} & a_{-2} \\ \vdots & & \ddots & a_1 & a_0 & a_{-1} \\ a_{n-1} & \cdots & \cdots & a_2 & a_1 & a_0 \end{bmatrix}$$

$$T(b) = \begin{bmatrix} b_1 & 0 & 0 & 0 \\ b_2 & b_1 & 0 & 0 \\ b_3 & b_2 & b_1 & 0 \\ 0 & b_3 & b_2 & b_1 \\ 0 & 0 & b_3 & b_2 \\ 0 & 0 & 0 & b_3 \end{bmatrix}$$

Submatrix of matrix: A matrix obtained by deleting some of the rows and/or columns of a matrix is said to be a submatrix of the given matrix.

$$A = \begin{bmatrix} 1 & 4 & 5 \\ 0 & 1 & 2 \end{bmatrix}$$

$$[1], [2], \begin{bmatrix} 1 \\ 0 \end{bmatrix}, [1\ 5], \begin{bmatrix} 1 & 5 \\ 0 & 2 \end{bmatrix}, A. \begin{bmatrix} 1 & 4 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 4 \\ 0 & 2 \end{bmatrix}$$

#### Zero or null Matrix

If  $A \in M_{m \times n}$ , and c is a scalar,

then (1) 
$$A + 0_{m \times n} = A$$

 $X \otimes S_0$ ,  $\mathbf{0}_{m \times n}$  is also called the additive identity for the set of all  $m \times n$  matrices

(2) 
$$A + (-A) = 0_{m \times n}$$

X Thus, -A is called the additive inverse of A

(3) 
$$cA = 0_{m \times n} \Rightarrow c = 0 \text{ or } A = 0_{m \times n}$$

All above properties are very similar to the counterpart properties for the real number 0

Block Matrix whose entries are matrices, such as

$$A = \begin{bmatrix} B & C \\ D & E \end{bmatrix}$$
 Submatrix or block of A 
$$B = \begin{bmatrix} 0 & 2 & 3 \end{bmatrix}, \quad C = \begin{bmatrix} -1 \end{bmatrix}, \quad D = \begin{bmatrix} 2 & 2 & 1 \\ 1 & 3 & 5 \end{bmatrix}, \quad E = \begin{bmatrix} 4 \\ 4 \end{bmatrix}$$
 then

 $\left[\begin{array}{ccc} B & C \\ D & E \end{array}\right] = \left[\begin{array}{cccc} 0 & 2 & 3 & -1 \\ 2 & 2 & 1 & 4 \\ 1 & 3 & 5 & 4 \end{array}\right]$ 

- Matrices in each block row must have same height (row dimension)
- Matrices in each block column must have same width (column dimension)
- Note: A is not a square matrix but it is a block square matrix.

#### Block Matrix

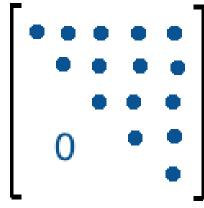
- Transpose of block matrix  $\begin{bmatrix} A & B \\ C & D \end{bmatrix}^T = \begin{bmatrix} A^T & C^T \\ B^T & D^T \end{bmatrix}$
- Multiplication

$$A = \begin{bmatrix} 2 & -3 & 1 & 0 & -4 \\ 1 & 5 & -2 & 3 & -1 \\ 0 & -4 & -2 & 7 & -1 \end{bmatrix} = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix}, \quad B = \begin{bmatrix} 0 & 4 \\ -2 & 1 \\ -3 & 7 \\ -1 & 3 \\ 5 & 2 \end{bmatrix} = \begin{bmatrix} B_1 \\ B_2 \end{bmatrix}$$

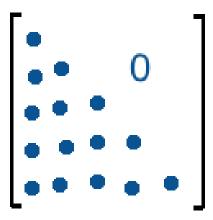
$$AB = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \end{bmatrix} = \begin{bmatrix} A_{11}B_1 + A_{12}B_2 \\ A_{21}B_1 + A_{22}B_2 \end{bmatrix} = \begin{bmatrix} -5 & 4 \\ -6 & 2 \\ 2 & 1 \end{bmatrix}$$

#### Triangular matrix

- Upper triangular  $a_{ij}=0, \quad i>j$
- Lower triangular  $a_{ij} = 0$ , i < j



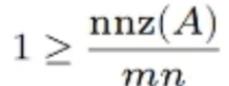
Upper Triangular Matrix



Lower Triangular Matrix

#### Sparse matrix

- Density of matrix  $A_{m \times n}$
- Density of identity matrix?
- Sparse matrix has low density



## **Permutation Matrix**

- A square  $n \times n$  matrix (P) obtained by rearranging the rows of  $I_n$
- Permutation matrix is orthogonal  $(PP^T = I)$ 
  - How many possible permutation matrix?  $P = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$
  - A product of permutation matrices is again a permutation matrix
  - Some power of a permutation matrix is identity. Why?  $(e. g: p^3 = I)$
  - The inverse of a permutation matrix is again a permutation matrix is again a permutation matrix, Pamid R. Rabiee & Maryam Ramezani, SUT CE40282-1: Linear Algebra

# Permutation Matrix Application

$$B = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 3 & 4 \\ 5 & 6 & 7 \end{pmatrix} \qquad P = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

Interchange the columns of matrix B:  $P_{ii}=1$  column i is moved to column j (1 2 0)(0 0 1) (0 2 1)

$$BP = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 3 & 4 \\ 5 & 6 & 7 \end{pmatrix} \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 2 & 1 \\ 4 & 3 & 0 \\ 7 & 6 & 5 \end{pmatrix}$$

Interchange the rows of matrix B:  $P_{ij}=1$  row j is moved to row i

$$PB = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 2 & 0 \\ 0 & 3 & 4 \\ 5 & 6 & 7 \end{pmatrix} = \begin{pmatrix} 5 & 6 & 7 \\ 0 & 3 & 4 \\ 1 & 2 & 0 \end{pmatrix}$$

## **Vec Operator**

 The vec-operator applied on a matrix A stacks the columns into a vector

$$\mathbf{A} = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \qquad \text{vec}(\mathbf{A}) = \begin{bmatrix} A_{11} \\ A_{21} \\ A_{12} \\ A_{22} \end{bmatrix}$$

Properties:

$$vec(\mathbf{A}\mathbf{X}\mathbf{B}) = (\mathbf{B}^T \otimes \mathbf{A})vec(\mathbf{X})$$

$$Tr(\mathbf{A}^T\mathbf{B}) = vec(\mathbf{A})^T vec(\mathbf{B})$$

$$vec(\mathbf{A} + \mathbf{B}) = vec(\mathbf{A}) + vec(\mathbf{B})$$

$$vec(\alpha \mathbf{A}) = \alpha \cdot vec(\mathbf{A})$$

$$\mathbf{a}^T \mathbf{X} \mathbf{B} \mathbf{X}^T \mathbf{c} = vec(\mathbf{X})^T (\mathbf{B} \otimes \mathbf{c} \mathbf{a}^T) vec(\mathbf{X})$$

# Conclusion

Real Case	Complex Case
$u \cdot v = u^T v = v^T u$	$u \cdot v = v^*u$
Transpose $()^T$	Conjugate transpose ()*
Orthogonal matrix $AA^T = I$	Unitary matrix $UU^* = I$
Symmetric matrix $A = A^T$	Hermitian matrix $H = H^*$