



Euclidian Norm and Inequalities

CE282: Linear Algebra

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- Machine learning uses vectors, matrices, and tensors as the basic units of representation
- Two reasons to use norms:
 1. To estimate how **big** a vector/matrix/tensor is
 - How big is the difference between two tensors is
 2. To estimate how **close** one tensor is to another
 - How close is one image to another



Definition

Mean-square (MS) value of n-vector x is:

$$\frac{x_1^2 + x_2^2 + \dots + x_n^2}{n} = \frac{\|x\|^2}{n}$$

Root-mean-square value (RMS)

$$rms(x) = \sqrt{\frac{x_1^2 + x_2^2 + \dots + x_n^2}{n}} = \frac{\|x\|}{\sqrt{n}}$$

The RMS value of a vector x is useful when comparing norms of vectors with different dimensions

$rms(x)$ gives “typical” value of $|x_i|$



Example

$rms(1) = 1$ (independent of n)

if all the entries of a vector are the same, (a) then the RMS value of the vector is $|a|$



Theorem

Suppose that k of the numbers $|x_1|, |x_2|, \dots, |x_n|$ are $\geq a$ then k of the numbers $x_1^2, x_2^2, \dots, x_n^2$ are $\geq a^2$

So $\|x\|^2 = x_1^2 + x_2^2 + \dots + x_n^2 \geq ka^2$ so we have $k \leq \frac{\|x\|^2}{a^2}$

Number of x_i with $|x_i| \geq a$ is no more than $\frac{\|x\|^2}{a^2}$

Question

- What happens when $\frac{\|x\|^2}{a^2} \geq n$?
- No entry of a vector can be larger in magnitude than the norm of the vector. (why?)



Important

Chebyshev inequality is easier to interpret in terms of the RMS value of a vector.

$$\frac{k}{n} \leq \left(\frac{rms(x)}{a} \right)^2$$

Example

How many entries of x can have value more than $5rms(x)$?



Important

The Chebyshev inequality partially justifies the idea that the *RMS* value of a vector gives an idea of the size of a typical entry: It states that not too many of the entries of a vector can be much bigger (in absolute value) than its *RMS* value



Definition

- For n-vector x , $avg(x) = 1^T \left(\frac{x}{n} \right)$
- De-meanded vector is $\tilde{x} = x - avg(x)1$ (so, $avg(\tilde{x}) = 0$)
- Standard deviation of x is:

$$std(x) = rms(\tilde{x}) = \frac{\left\| x - \left(\frac{1^T x}{n} \right) 1 \right\|}{\sqrt{n}}$$

- $Std(x)$ gives “typical” amount x_i vary from $avg(x)$
- $Std(x) = 0$ only if $x = \alpha 1$ for some α
- Greek letters μ, σ commonly used for mean, standard deviation
- A basic formula

$$rms(x)^2 = avg(x)^2 + std(x)^2$$



Theorem

x is an n – *vector* with mean $avg(x)$, standard deviation $std(x)$

Rough idea: most entries of x are not too far from the mean

By Chebyshev inequality, fraction of entries of x with $|x_i - avg(x)| \geq \alpha std(x)$ is no more than

$$\frac{1}{\alpha^2} \text{ (for } \alpha > 1 \text{)}$$

❖ The fraction of entries of x within θ standard deviations of $avg(x)$ is at least $(1 - \frac{1}{\theta^2})$ for $\theta > 1$



Important

1. ***Adding a constant:*** For any vector x and any number a , we have $\text{std}(x + a\mathbf{1}) = \text{std}(x)$. Adding a constant to every entry of a vector doesn't change its standard deviation.
2. ***Multiplying by a scalar:*** For any vector x and any number a , we have $\text{std}(ax) = |a| \text{std}(x)$. Multiplying a vector by a scalar, multiplies the standard deviation by the absolute value of the scalar.



Definition

$$z = \frac{1}{std(x)} (x - avg(x)1).$$

- ❑ It has *mean* $(\mu) = 0$ and *std* $(\sigma) = 1$
- ❑ Its entries are sometimes called the z-scores associated with the original entries of x .
- ❑ The standardized values for a vector give a simple way to interpret the original values in the vectors.

Cauchy-Schwartz Inequality



Theorem

For two n -vectors a and b , $|a^T b| \leq \|a\| \|b\|$

Written out:

$$|a_1 b_1 + \dots + a_n b_n| \leq (a_1^2 + \dots + a_n^2)^{\frac{1}{2}} (b_1^2 + \dots + b_n^2)^{\frac{1}{2}}$$

It is clearly true if either a or b is 0.

So, assume $\alpha = \|a\|$ and $\beta = \|b\|$ are non-zero

We have

$$\begin{aligned} 0 &\leq \|\beta a - \alpha b\|^2 \\ &= \|\beta a\|^2 - 2(\beta a)^T(\alpha b) + \|\alpha b\|^2 \\ &= \beta^2 \|a\|^2 - 2\beta\alpha(a^T b) + \alpha^2 \|b\|^2 \\ &= 2\|a\|^2 \|b\|^2 - 2\|a\| \|b\| (a^T b) \end{aligned}$$

Divide by $2\|a\|\|b\|$ to get $a^T b \leq \|a\| \|b\|$

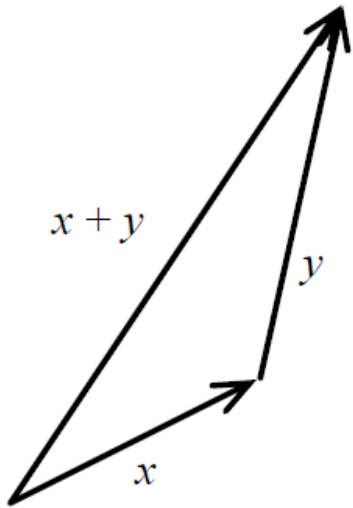
Apply to $-a, b$ to get other half of Cauchy-Schwartz inequality.

Cauchy-Schwarz inequality holds with equality when one of the vectors is a multiple of the other

Theorem

Consider a triangle in two or three dimensions:

$$||x + y|| \leq ||x|| + ||y||$$



Verification of triangle inequality:

$$\begin{aligned} ||x + y||^2 &= ||x||^2 + ||y||^2 + 2 \underline{x^T y} \\ &\leq ||x||^2 + ||y||^2 + 2 \underline{||x|| ||y||} \quad \text{Cauchy-Schwartz Inequality} \\ &= (||x|| + ||y||)^2 \\ &\Rightarrow ||x + y|| \leq ||x|| + ||y|| \end{aligned}$$



Definition

- Euclidean Norm (2-norm, l_2 norm, length)
 - A vector whose length is 1 is called a **unit vector**
 - **Normalizing**: divide a non-zero vector by its length which is a unit vector in the same direction of original vector

$$||x|| = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2} = \sqrt{x^T x}$$

- It is a nonnegative scalar
- In \mathbb{R}^2 follows from the Pythagorean Theorem.
- What about \mathbb{R}^3 ?
- What is the shape of $||x||_2 = 1$?



Important

Properties:

1. Absolute Homogeneity / Linearity:

$$||\alpha x|| = |\alpha| ||x||$$

2. Subadditivity / Triangle Inequality:

$$||x + y|| \leq ||x|| + ||y||$$

3. Positive definiteness / Point separating:

$$\text{if } ||x|| = 0 \text{ then } x = 0$$

(from 1 & 3): For every x , $||x|| = 0$ iff $x = 0$

4. Non-negativity:

$$||x|| \geq 0$$



Theorem

Take any inner product $\langle \cdot, \cdot \rangle$ and define $f(x) = \sqrt{\langle x, x \rangle}$. Then f is a norm.

Proof

Note

Every inner product gives rise to a norm, but not every norm comes from an inner product. (Think about norm 2 and norm max)



Theorem

If x and y are vectors:

$$||x + y|| = \sqrt{||x||^2 + 2 x^T y + ||y||^2}$$

Proof:

$$\begin{aligned} ||x + y||^2 &= (x + y)^T (x + y) \\ &= x^T x + x^T y + y^T x + y^T y \\ &= ||x||^2 + 2 x^T y + ||y||^2 \end{aligned}$$



Important

Suppose a, b, c are vectors:

$$|| (a, b, c) ||^2 = a^T a + b^T b + c^T c = ||a||^2 + ||b||^2 + ||c||^2$$

So, we have

$$|| (a, b, c) || = \sqrt{||a||^2 + ||b||^2 + ||c||^2} = || (||a||, ||b||, ||c||) ||$$

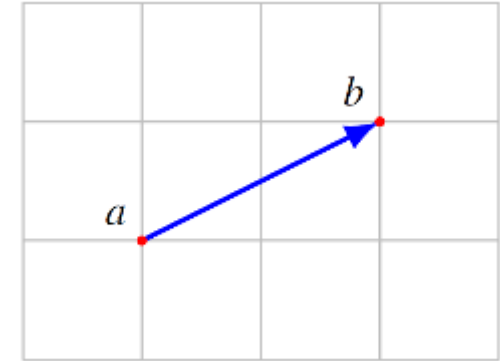
(Parse RHS very carefully!)

❖ The norm of a stacked vector is the norm of the vector formed from the norms of sub-vectors.



Distance:

$$\text{dist}(a, b) = ||a - b||$$



RMS deviation between the two vectors:

$$\text{rms}(a - b) = \frac{||a - b||}{\sqrt{n}}$$



Distance between two n-vectors shows the vectors are “close” or “nearby” or “far”.

Example

$$u = \begin{bmatrix} 1.8 \\ 2 \\ -3.7 \\ 4.7 \end{bmatrix}, v = \begin{bmatrix} 0.6 \\ 2.1 \\ 1.9 \\ -1.4 \end{bmatrix}, w = \begin{bmatrix} 2.0 \\ 1.9 \\ -4.0 \\ 4.6 \end{bmatrix}$$

The distance between pairs of them are:

$$||u - v|| = 8.368, \quad ||u - w|| = 0.387, \quad ||v - w|| = 8.533$$



Norm
(Normed Linear Space)

1. $\|x - y\| \geq 0$
2. $\|x - y\| = 0 \Rightarrow x = y$
3. $\|\lambda(x - y)\| = |\lambda| \|x - y\|$

Distance Function
(Metric Space)

1. $\text{dist}(x, y) \geq 0$
2. $\text{dist}(x, y) = 0 \Rightarrow x = y$
3. $\text{dist}(x, y) = \text{dist}(y, x)$



Definition

Angle between two non-zero vectors a, b is defined as:

$$\angle(a, b) = \arccos\left(\frac{a^T b}{\|a\| \|b\|}\right)$$

$\angle(a, b)$ is the number in $[0, \pi]$ that satisfies:

$$a^T b = \|a\| \|b\| \cos(\angle(a, b))$$

Coincides with ordinary angle between vectors in 2D and 3D



❑ **Norm:** $2n$ flops

❑ $O(n)$

❑ **RMS:** $2n$ flops

❑ $O(n)$

❑ **Distance:** $3n$ flops

❑ $O(n)$

❑ **Angle:** $6n$ flops

❑ $O(n)$

❑ **Standardizing:** $5n$ flops

❑ $O(n)$

❑ **Correlation Coefficient:** $10n$ flops

❑ $O(n)$

❑ **Standard Deviation:** $4n$ flops

❑ $O(n)$

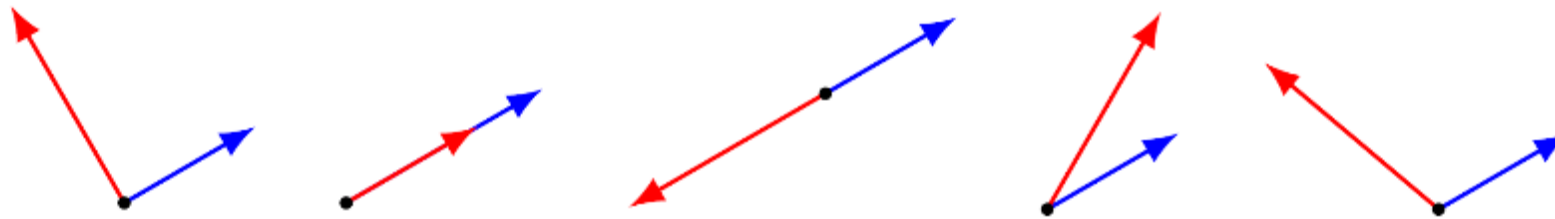
❑ Can reduce to $3n$ flops.

$$\text{std}(x)^2 = \text{rms}^2 - \text{avg}(x)^2$$



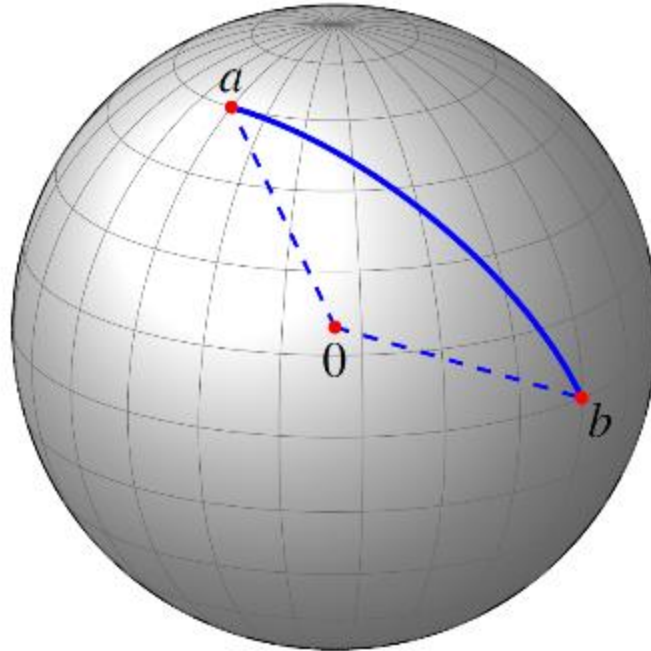
$$\theta = \angle(a, b)$$

- $\theta = \frac{\pi}{2} = 90^\circ$: a and b are orthogonal, written $a \perp b$ ($a^T b = 0$)
- $\theta = 0$: a and b are aligned ($a^T b = \|a\| \|b\|$)
- $\theta = \pi = 180^\circ$: a and b are anti-aligned ($a^T b = -\|a\| \|b\|$)
- $\theta \leq \frac{\pi}{2} = 90^\circ$: a and b make an acute angle ($a^T b \geq 0$)
- $\theta \geq \frac{\pi}{2} = 90^\circ$: a and b make an obtuse angle ($a^T b \leq 0$)



Spherical distance:

if a, b are on sphere with radius R , distance along the sphere is $R \angle(a, b)$





Correlation Coefficient:

We have vectors a, b and de-meaned vectors $\tilde{a} = a - \text{avg}(a)1$, $\tilde{b} = b - \text{avg}(b)1$

correlation coefficient (between a, b with $\tilde{a} \neq 0, \tilde{b} \neq 0$) is $\rho = \frac{\tilde{a}^T \tilde{b}}{\|\tilde{a}\| \|\tilde{b}\|}$

$$\rho = \cos \angle(\tilde{a}, \tilde{b})$$

- $\rho = 0 \Rightarrow a, b$ are uncorrelated
- $\rho > 0.8$ (or so) $\Rightarrow a, b$ are highly correlated
- $\rho < -0.8$ (or so) $\Rightarrow a, b$ are highly anti-correlated

Very roughly: highly correlated means a_i and b_i are typically both above (below) their means together.

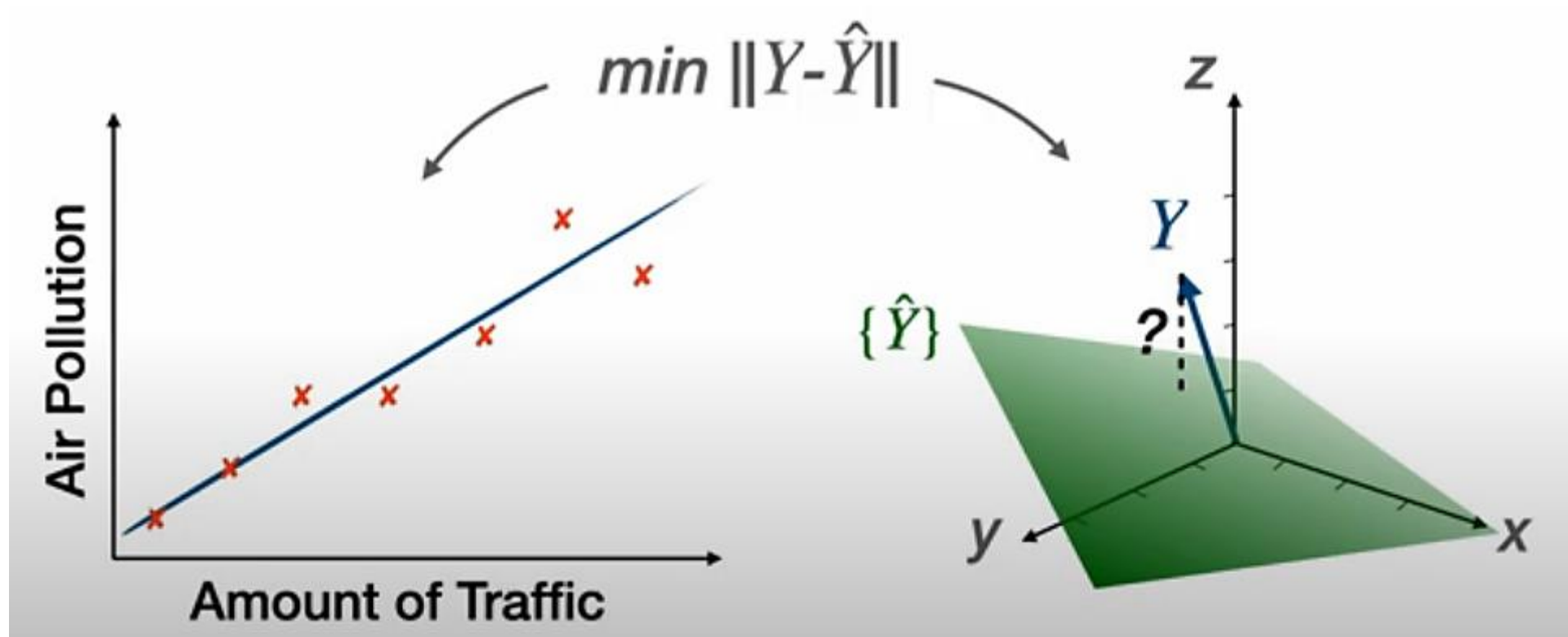


Document dissimilarity by angles

- ▶ measure dissimilarity by angle of word count histogram vectors
- ▶ pairwise angles (in degrees) for 5 Wikipedia pages shown below

	Veterans Day	Memorial Day	Academy Awards	Golden Globe Awards	Super Bowl
Veterans Day	0	60.6	85.7	87.0	87.7
Memorial Day	60.6	0	85.6	87.5	87.5
Academy A.	85.7	85.6	0	58.7	85.7
Golden Globe A.	87.0	87.5	58.7	0	86.0
Super Bowl	87.7	87.5	86.1	86.0	0

The best linear regression model comes from choosing the closest \hat{Y} to Y based on



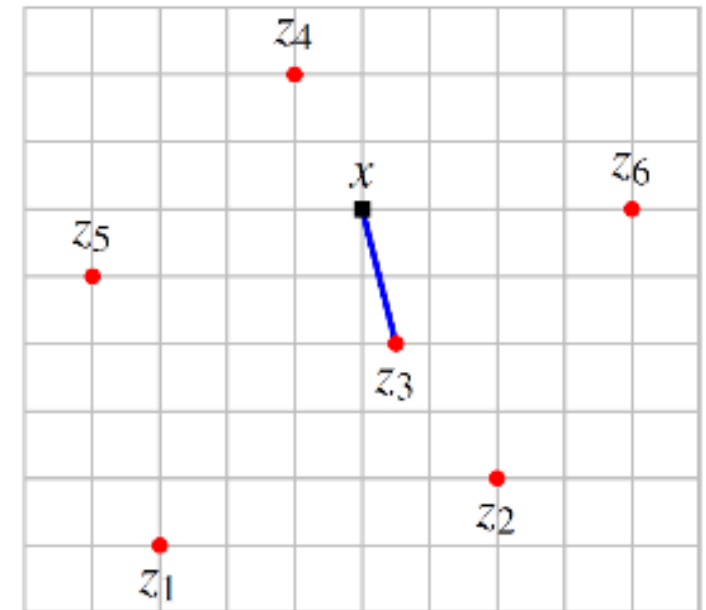
Feature Distance and Nearest Neighbors:

if x, y are feature vectors for two entities, $\|x - y\|$ is the feature distance

if z_1, z_2, \dots, z_m is a list of vectors, z_j is the nearest neighbor of x if:

$$\|x - z_j\| \leq \|x - z_i\|, \quad i = 1, 2, \dots, m$$

❖ Number of flops and order?





- Linear Algebra and Its Applications David C. Lay
- Introduction to Applied Linear Algebra Vectors, Matrices, and Least Squares
- <https://www.youtube.com/watch?v=76B5cMEZA4Y>