### homework5

December 7, 2021

# 1 Exercise 1 (6 points)

A bacterial population P grows according to the geometric progression

$$P_t = rP_{t-1}$$

Where r is the growth rate. The following population counts  $P_1, \ldots, P_8$  (in billions) are observed:

```
[2]: import numpy as np
data = np.array( [0.19, 0.36, 0.69, 1.3, 2.5, 4.7, 8.5, 14] )
```

# 2 (a)

Read chapter 6.6 on Nonlinear Least squares. Use the Gauss-Newton Method to fit the model function  $f(t, x_1, x_2) = x_1 \cdot x_2^t$  to the data. Find estimates for the initial population  $P_0 = x_1$  and the growth rate  $r = x_2$ . Implement the Gauss-Newton method yourself (you may use linear algebra functions from scipy and numpy).

```
[3]: import numpy.linalg as la
    import matplotlib.pyplot as plt

def f(t, x):
        x1, x2 = x
        return x1 * x2 ** t

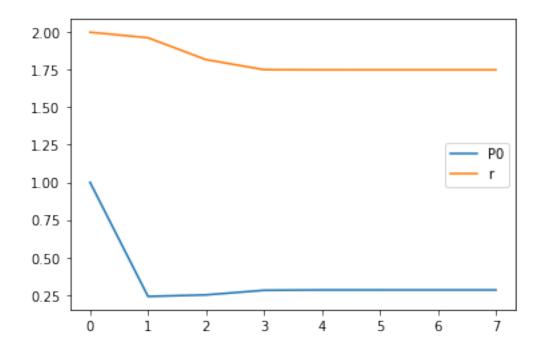
def residual(t, x, y):
        fit = f(t, x)
        return y - fit

def J(t, x):
        x1, x2 = x
        return np.array([-x2 ** t, -x1 * (t * x2 **(t - 1))])

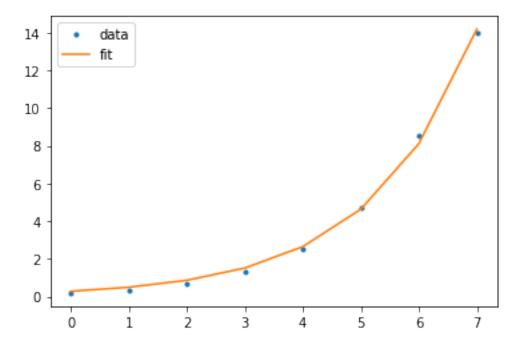
def Gaus_Newton(t, x, y, iterations):
        x_ks = [x]
        for i in range(iterations):
```

```
s_k = la.lstsq(J(t, x_ks[-1]).T,-residual(t, x_ks[-1], y),_{\sqcup}
 →rcond=None) [0]
        x_ks.append(x_ks[-1] + s_k)
        if la.norm(residual(t, x_ks[-1], y)) < 0.000001:
            print("Size of function is below tolerance.")
            break
        if la.norm(x_ks[-1] - x_ks[-2]) < 0.000001:
            print("The difference in two subsequent iterations is below.
 →tolerance.")
            break
    if len(x_ks) == iterations + 1:
        print("The number of iterations was reached.")
    return x_ks
x0 = np.array([1.,2.])
t = np.arange(len(data))
x_fit = Gaus_Newton(t,x0,data,10)
y_{fit} = f(t, x_{fit}[-1])
print("Estimations Each Iteration")
plt.plot([a[0] for a in x_fit], label="P0")
plt.plot([a[1] for a in x_fit], label="r")
plt.legend(loc=5)
plt.show()
print("Data and Fit")
plt.plot(t, data, '.', label="data")
plt.plot(t, y_fit, label="fit")
plt.legend()
plt.show()
```

The difference in two subsequent iterations is below tolerance. Estimations Each Iteration



# Data and Fit



## 3 (b)

Let f be a vector valued function  $f = [f_1, \dots, f_m]^T$ . In weighted least squares one aims to minimize the objective function

$$\phi(x) = \frac{1}{2} \sum_{i=1}^{m} W_{ii} (y_i - f_i(x))^2, \qquad W_{ii} = \frac{1}{\sigma_i^2},$$

where  $\sigma_i$  is an estimate of the standard deviation in the data point  $y_i$ . This is equivalent to the standard least squares problem

$$\min_{x} \frac{1}{2} ||Y - F(x)||_{2}^{2}$$

with  $F_i(x) = \frac{1}{\sigma_i} f(x)$ ,  $Y_i = \frac{1}{\sigma_i} y_i$ . Assume that for each data point  $y_i$  in the list above, the estimate for the standard deviation is given by

$$\sigma_i = 0.05y_i$$
.

Perform a weighted least squares fit to obtain estimates for  $P_0$  and r.

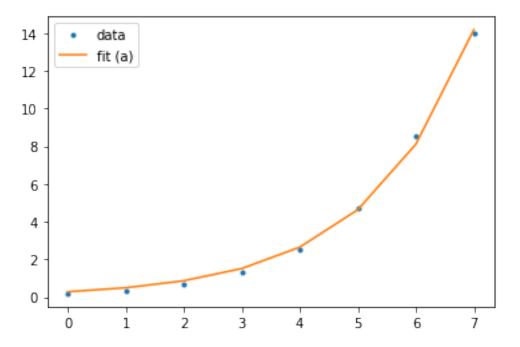
Plot the results of (a) and (b), showing the data points and the fitted curve. Compare the residuals (the values of  $y_i - f_i(x)$ ) obtained in (a) and (b) and discuss the differences between the results of the weighted and the unweighted optimization.

```
[4]: from scipy.optimize import minimize
     def F(t, x, sigma):
         return f(t,x)/sigma
     def std(y):
         return 0.05 * y
     def weighted_lstsq(x, *args):
         t, Y, sigmas = args[0], args[1], args[2]
         norm = la.norm(Y - F(t, x, sigmas))
         return 0.5 * norm ** 2
     sigmas = std(data)
     Y = data/sigmas
     x0 = np.array([1,2])
     x_weighted = minimize(weighted_lstsq, x0, args=(t, Y, sigmas)).x
     y_weighted = f(t,x_weighted)
     print("(a) Fitted using unweighted least squares")
     plt.plot(t, data, '.', label="data")
     plt.plot(t, y fit, label="fit (a)")
     plt.legend()
     plt.show()
     print("(b) Fitted using weighted least squares")
     plt.plot(t, data, '.', label="data")
     plt.plot(t, y_weighted, label="fit (b)")
     plt.legend()
```

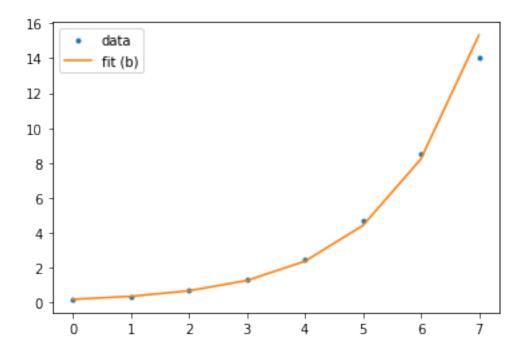
```
plt.show()

print("Residuals of both methods")
residual_lstsq = np.abs(residual(t, x_fit[-1], data))
residual_weighted = np.abs(residual(t, x_weighted, data))
plt.plot(residual_lstsq, label="Residual (a)")
plt.plot(residual_weighted, label="Residual (b)")
plt.yscale("log")
plt.legend()
plt.show()
```

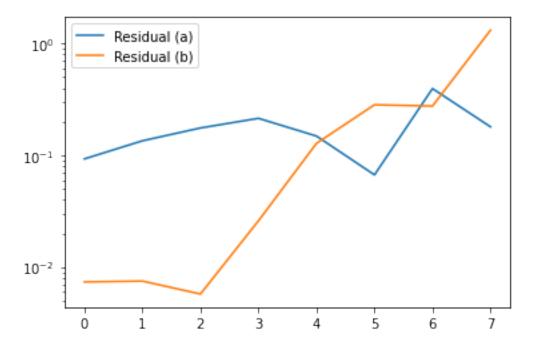
### (a) Fitted using unweighted least squares



(b) Fitted using weighted least squares



#### Residuals of both methods



The unweighted fit performs worse than the weighted fit for smaller numbers of t and y, but better for the bigger numbers of t and y. The residual of (a) keeps more constant, i.e. the residual does not increase or decrease when t gets bigger. The residual of (b) increases when t gets bigger. Therefore,

for bigger t the unweighted least squares is performs better and for smaller t the weighted least squares performs better.

### 4 Exercise 2 (3 points)

A triangle has been measured. The measurements, a vector  $x \in \mathbb{R}^6$ , are as follows:

Here  $\alpha, \beta, \gamma$  are the angles opposite the sides with length a, b, c, respectively. The measurements x have errors. We would like to correct them so that the new values  $\tilde{x} = x + h$  are consistent quantities of a triangle. The have to satisfy:

Sum of angles: 
$$\tilde{x}_1 + \tilde{x}_2 + \tilde{x}_3 = 180^{\circ}$$
  
Sine theorem:  $\tilde{x}_4 \sin(\tilde{x}_2) - \tilde{x}_5 \sin(\tilde{x}_1) = 0$  (\*)  
 $\tilde{x}_5 \sin(\tilde{x}_3) - \tilde{x}_6 \sin(\tilde{x}_2) = 0$ .

#### 4.1 (a)

Solve the constrained least squares problem  $\min_x ||h||_2^2$  subject to the constraints given by (\*).

Use scipy.optimize.minimize.

Hint: Don't forget to work in radians!

Check that for the new values also e.g. the cosine theorem  $c^2 = a^2 + b^2 - 2ab\cos(\gamma)$  holds.

```
[5]: from scipy.optimize import minimize
    import numpy as np
    import numpy.linalg as la
    import matplotlib.pyplot as plt

x_deg = np.array([67.5,52,60,172,146,165])
    x_rad = np.array([1.178,0.907,1.047,172,146,165])
    x_guess = np.array([1,1,1,1,1])

def con1(x):
    return(x[0] + x[2] + x[3] - np.pi)

def con2(x):
    return x[3] * np.sin(x[1]) - x[4] * np.sin(x[0])

def con3(x):
    return x[4] * np.sin(x[2]) - x[5] * np.sin(x[1])
```

```
h = args[0] - x
    norm = la.norm(h)
    return 0.5 * norm **2
cons = [ {
    'type':'eq',
    'fun': con1
    },
    'type':'ineq',
    'fun': con2
    },
    {
    'type':'ineq',
    'fun': con3
    }
]
results = minimize(lst, x_rad, args=(x_guess,),constraints = cons).x
print(results)
print(results[0]+results[1]+results[2])
print(results[3]*np.sin(results[1])-results[4]*np.sin(results[0]))
test_0 = (results[3]**2 + results[4]**2) - (2*results[3]*results[4]*np.
\rightarrowcos(results[2])) - results[5]**2
print(test_0)
```

```
[1.04720163 0.99999772 1.0472033 1.04718773 0.99998822 0.99998666] 3.094402641434005 0.015159556252400508 0.04944029273353567
```

#### 4.2 (b)

You will notice that the corrections will be made mainly to the angles and much less to the lengths of the sides of the triangle. This is because the measurements have not the same absolute errors. While the error in last digit of the sides is about 1, the errors in radians of the angles are about 0.01. Repeat your computation by taking in account with appropriate weighting the difference in

measurement errors. Minimize not simply  $||h||_2^2$  but

```
[6]: def lst_w(x,*args):
    h = args[0] - x
    for i in range(2):
        h[i] *= 100
    norm = la.norm(h)
    return 0.5 * norm **2

print(minimize(lst_w, x_guess, args=(x_rad,),constraints = cons))
results = minimize(lst_w, x_guess, args=(x_rad,),constraints = cons).x

test_w = (results[3]**2 + results[4]**2) - (2*results[3]*results[4]*np.
        →cos(results[2])) - results[5]**2
print(test_w)

fun: 38468.06589619741
    jac: array([-466.77294922, 176.21240234, -0.86962891, -170.16503906,
```