ID1000500C CONVOLUTION IP-CORE USER MANUAL

1. DESCRIPTION

The convolution task between two vectors u and v is a mathematical operation that represents the area of superposition under the points when v spans the same length as u.

1.1. CONFIGURABLE FEATURES

Software configurations	Description
Shape	Convolution type FULL or SAME
sizeX	Memory size X
sizeY	Memory size Y

1.2. TYPICAL APPLICATION

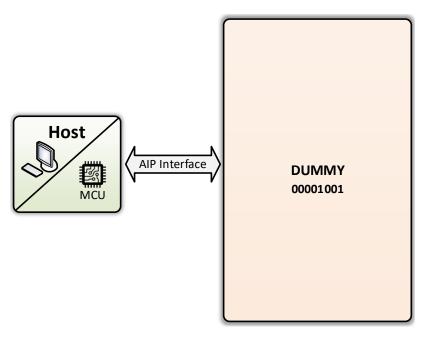


Figure 1.1 IP Dummy connected to a host

2. CONTENTS

1	. DES	SCRIPTION	1
	1.1.	CONFIGURABLE FEATURES	1
	1.2.	TYPICAL APPLICATION	1
2	. CON	NTENTS	2
	2.1.	List of figuresiError! Marcador	no definido.
	2.2.	List of tables	2
3	. INP	UT/OUTPUT SIGNAL DESCRIPTION	3
4	. THE	ORY OF OPERATION	5
5	. AIP	interface registers and memories description	5
	5.1.	Status register	5
	5.1.	Configuration register	6
	5.2.	Input data memory X	6
	5.1.	Input data memory Y	6
	5.2.	Output data memory Z	6
6	. PYT	HON DRIVER	7
7	. CDI	RIVER	7
	2.1. Li	ist of tables	
T	able 1 II	P Dummy input/output signal description	3

3. INPUT/OUTPUT SIGNAL DESCRIPTION

Table 1 IP Dummy input/output signal description

Signal	Bitwidth	Direction	Description											
			General signals											
clk	1	Input	System clock											
rst_a	1	Input	Asynchronous system reset, low active											
en_s	1	Input	Enables the IP Core functionality											
	AIP Interface													
data_in 32 Input Input data for configuration and processing														
data_out	32	Output	Output data for processing results and status											
conf_dbus	5	Input	Selects the bus configuration to determine the information flow from/to the IP Core											
write	1	Input	Write indication, data from the data_in bus will be written into the AIP Interface according to the conf_dbus value											
read	1	Input	Read indication, data from the AIP Interface will be read according to the conf_dbus value. The data_out bus shows the new data read.											
start	1	Input	Initializes the IP Core process											
int_req	1	Output	Interruption request. It notifies certain events according to the configurated interruption bits.											
		<u> </u>	Core signals											
memX_addr	5	output	Data memory address X											
dataX	8	Input	Data X											
sizeX	5	Input	Size of X											
memY_addr	5	output	Data memory address Y											
dataY	8	Input	Data Y											
sizeX	5	Input	Size of Y											
memZ_addr	6	output	Data memory address z											
dataZ	16	Input	Data Z											
Start	1	Input	Convolution start signal											

Shape	1	Input	Convolution type FULL=0 , SAME =1
Busy	1	output	Status of co-processor 1=bussy, 0= available
Done	1	output	Co-processor task status 1= completed, 0= in process

4. THEORY OF OPERATION

The convolution core receives as input the data from two inputs memories X and Y with configurable size and the type of convolution FULL or SAME, after of receiving the start command, according to the data obtained from test performed, it has an area of 88 register, and works at maximum frequency of 106.25 MHz. The operation of two memories X of size 10 and Z of size 5, the convolution takes 230 clock cycles.

5. AIP interface registers and memories description

5.1. Status register

Config: STATUS Size: 32 bits

Mode: Read/Write.

This register is divided in 3 sections, see Figure 5.1:

• Status Bits: These bits indicate the current state of the core.

- Interruption Flags: These bits are used to generate an interruption request in the *int_req* signal of the AIP interface.
- Mask Bits: Each one of these bits can enable of disable the interruption flags.

Status Register

		30	29	_28	27	26	.25	_24	_23	22	21	_20	_19	_18	17	16	.15	14	_13	. 12	_11	10	9	8	7	6	5	4	3	2	.1	0
												Mask		:			Status Bits								Interrupt/Clear Flags							
Reserved								Reserved						MSK			Reserved					BSY			Re	carv	۵d			DN		
	Reserved							Reserved rw						Reserved						r	Reserved r							rw				

Figure 5.1 IP Dummy status register

Bits 31:24 – Reserved, must be kept cleared.

Bits 23:17 – Reserved Mask Bits for future use and must be kept cleared.

Bit 16 – **MSK**: mask bit for the DN (Done) interruption flag. If it is required to enable the DN interruption flag, this bit must be written to 1.

Bits 15:9 – Reserved Status Bits for future use and are read as 0.

Bit 8 – **BSY**: status bit "**Busy**".

Reading this bit indicates the current IP Dummy state:

0: The IP Dummy is not busy and ready to start a new process.

1: The IP Dummy is busy, and it is not available for a new process.

Bits 7:1 – Reserved Interrupt/clear flags for future use and must be kept cleared.

Bit 0 – **DN**: interrupt/clear flag "**Done**"

Reading this bit indicates if the IP Dummy has generated an interruption:

0: interruption not generated.

1: the IP Dummy has successfully finished its processing.

Writing this bit to 1 will clear the interruption flag DN.

5.1. Configuration register

31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	- Y/Sizes[10:6] - X/Sizes[5:1]-Shape[0]																														
w	w	W	w	w	W	w	w	w	w	w	W	W	w	W	W	W	W	w	w	w	w	W	W	W	w	w	W	w	W	W	w
																					ZY	ZY	ZY	ZY	ZY	ZY	ZX	ZX	ZX	ZX	Shape

Tabla 1 Convolution configuration register..

Bit 0- It is reserved for FULL or SAME convolution operation type.

1: SAME

0: FULL

Bits 5:1- Reserved for the size of memory X.

Bits 10:6- Reserved for the size of memory Y.

5.2. Input data memory X

Config: memX

Size: Nx32 bits

Mode: Write

This is the X memory used for the convolution operation between the X and Y memory.

5.1. Input data memory Y

Config: memY

Size: Nx32 bits

Mode: Write

This is the Y memory used for the convolution operation between the X and Y memory.

5.2. Output data memory **Z**

Config: memZ

Size: Nx32 bits

Mode: Read

This is the Z memory used to store the result of the convolution operation between X and Y memory.

6. PYTHON DRIVER

7. C DRIVER