Design and Analysis of Algorithms

L28: Heapsort
Transform and Conquer Approach

Dr. Ram P Rustagi
Sem IV (2019-H1)
Dept of CSE, KSIT/KSSEM
rprustagi@ksit.edu.in

Resources

- Text book 1: Sec 9.1-5.4 Levitin
- RI: Introduction to Algorithms
 - Cormen et al.

Transform and Conquer

- Secret to life: Replace one worry with another.
 - American cartoonist Charles M Shultz (1922-2000)
- Transform and conquer approach
 - A two stage process
 - Transformation stage: change the problem instance to another form, more amenable to solution
 - Conquering stage: Solve the problem
- Transformation can be done in 3 ways
 - Instance simplification: to a simpler or more convenient instance of the problem: presorted lists
 - Different representation: Heaps, Horner's rule
 - Problem reduction: transform to a different problem for which solution is available.

Priority Queue

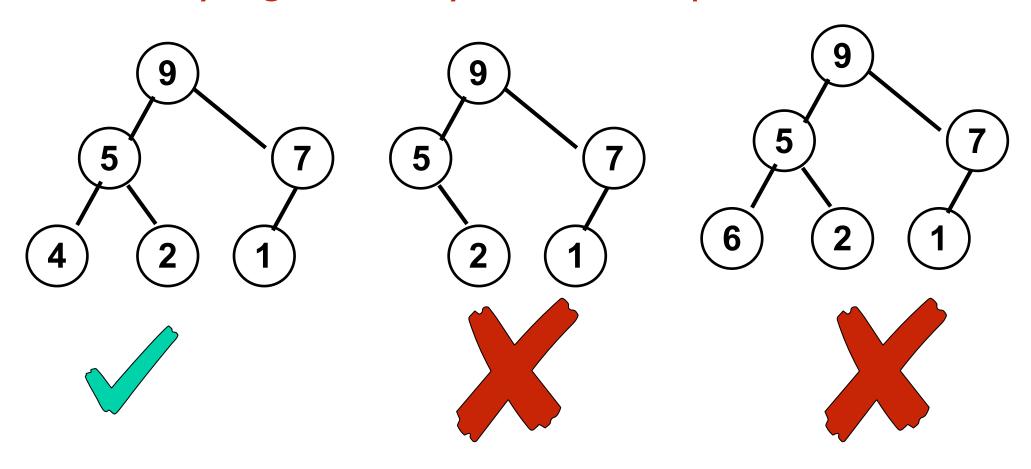
- Priority Queue:
 - A data structure with an orderable (called priority)
 characteristic on set of elements maintained by it
 - Allows 3 operations in an efficient way
 - FindMin (or even FindMax):
 - -Find an item with highest priority (e.g. max, min)
 - -DeleteMin:
 - -Delete an item with highest priority
 - Insert:
 - -Add a new item to the data structure
- Heaps makes these 3 operations interesting and useful
- Heapsort: a cornerstone of theoretical sorting problem

Heap

- Definition:
 - Heap is defined as binary tree with keys assigned to nodes (one key per node) with following conditions
 - Binary tree is a a complete tree except possibly at the last level
 - -Few rightmost leaves may be missing
 - The key of a parent is greater than or equal to keys of its children and hence descendants
 - -Also, known as parental dominance.

Examples

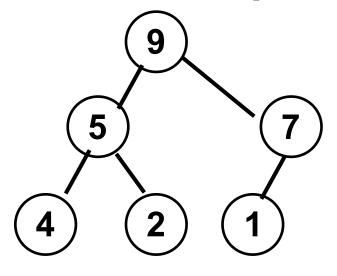
Q: Identify if given binary tree is a heap?



Heap Properties

- There exists only 1 complete binary tree with n nodes.
- The root of the heap is always the largest element
- A node of heap taken together with all its descendants is also a heap
- Heap implementation
 - Can be an array H[] with top-down and left to right
 - Store heap elements in positions thru 1 to n.
 - Element H [0] can either be unused or a sentinel
 - Its value can be greater than every element of heap
 - Parental nodes are in first $\lfloor n/2 \rfloor$ positions of the array
 - Leaf nodes will be last $\lceil n/2 \rceil$ positions of the array

Example: Heap Implementation

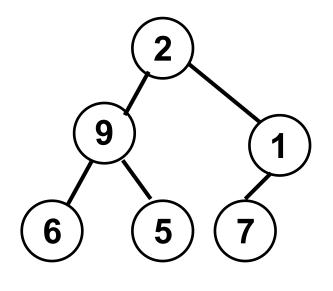


- Left child of node at j is at 2 j
- Right child (if exists) of node at j is at 2 j +1
- Parent of node at j is at [j/2]
- Parental nodes are in first $\lfloor n/2 \rfloor$ positions of the array
- Leaf nodes are in last $\lceil n/2 \rceil$ positions of the array

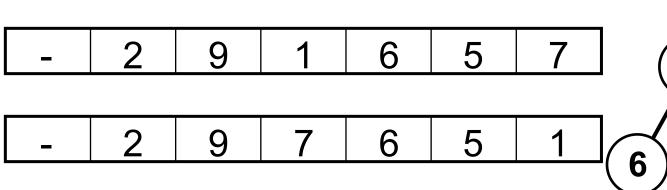
0	1	2	3	4	5	6
	9	5	7	4	2	1

- S0: Initiaize heap structure with keys in order
- S1: Start with the last (right most) parental node
 - Fix the heap rooted at it.
 - If it fails the heap condition, then exchange with larger child
 - Repeat the process till heap condition satisfies
- S2: Repeat the previous step (s1) for preceding parental nodes.

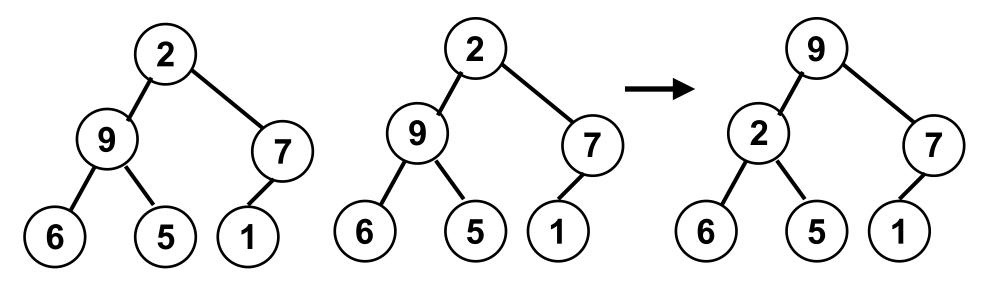
- Consider the data: 2, 9, 1, 6, 5, 7
- Construct the heap in order.



- Let us heapify
- Last parental node (at $\lfloor 6/2 \rfloor = 3$ is 1
 - Smaller than child node 7 at pos 6
 - Exchange it
 - Heap property satisfies

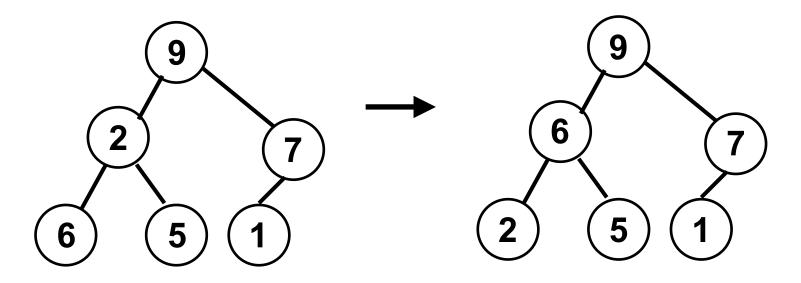


- Consider preceding parental node 9 (at pos 3-1=2)
- It is in order. No exchange required
- Next parental node 2 (at pos 1). Needs heapification.
- Exchange it with 9, and repeat the process



keys: 2, 9, 7, 6, 5, 1

- Since exchanged node 2 is not in heap order
- This needs to be exchanged with 6.

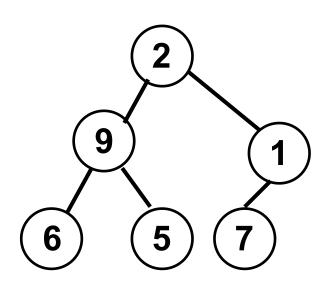


Now heap is in order.

Heap Algorithm

```
    Algo HeapBottomUp (H[1:n])

// i/p: an array H[1:n] of items to be ordered
// o/p: Heap H[1:n] of ordered items
for i \leftarrow \lfloor n/2 \rfloor to 1 do
   k←i; v←H[k]; heap←False
   while not heap and 2*k≤n do
       j ←2*k
       if ¬i <n // there are two children
          if H[\dot{j}] < H[\dot{j}+1]
             j ←j+1
       if ∨≥H [ ¬ ]
          heap←True
       else
          H[k] \leftarrow H[j]; k \leftarrow j
   H[k] \leftarrow V
```



Complexity Analysis

- Consider the tree height
 - height of a node: length of the path from it to leaf
 - n-element heap has height [lg2 n]
 - Number of nodes at height h is $\lceil n/2^{h+1} \rceil$
 - e.g. n=15, h=3,
 - nodes at h=0 is 8, at h=1 is 4, at h=2 is 2
- Generalized analysis
 - Moving $\lfloor n/2 \rfloor$ nodes i.e. considering parent nodes
 - Each node may move h= llg2 nj times.
 - Thus complexity for heapifying array is Θ (nlg₂ n)

Complexity Analysis: Improved

- Node at height 1 moves at most 1 times
- Node at height 2 moves at most 2 times
- i.e. Node at height h moves at most h times.
- Total number of moves are

$$\sum_{i=0}^{h} \left\lceil \frac{n}{2^{i+1}} \right\rceil * i = O\left(n \sum_{i=0}^{\lg_2 n} \left\lceil \frac{i}{2^i} \right\rceil\right) \tag{1}$$

Some basic mathematics

$$\sum_{k=0}^{\infty} x^k = \frac{1}{1-x} \quad \text{for } x < 1$$

Differentiating both sides

$$\sum_{k=1}^{\infty} kx^{k-1} = \frac{1}{(1-x)^2} \Rightarrow \sum_{k=0}^{\infty} kx^k = \frac{x}{(1-x)^2}$$
 (2)

DAA/Greedy Algorithms

Complexity Analysis: Improved

Taking x=1/2 in eqn (2) gives

$$\sum_{k=0}^{\infty} k(\frac{1}{2})^k = \frac{\frac{1}{2}}{(1-\frac{1}{2})^2}$$

$$\Rightarrow \sum_{k=0}^{\infty} \frac{k}{2^k} = \frac{\frac{1}{2}}{\frac{1}{4}}$$

$$\Rightarrow \sum_{i=0}^{\infty} \frac{i}{2^i} = 2$$

Thus eqn (1) becomes $O(n\sum_{i=0}^{lg_2n} \lceil \frac{i}{2^i} \rceil) \le O(n.2) = O(n)$

That is heap from the array can be built in O(n) time

Exercises:

Consider the array

$$-3, 5, 6, 7, 20, 8, 2, 9, 12, 15, 30, 17$$

- Draw the Complete Binary Tree
- Heapify the tree.
 - Workout the upates in array when heapifying.
- In the above heap, insert the following items, one at a time.

```
-16, 21, 45
```

- Perform 3 DeleteMax operations
 - Show the heap structure after each delete

Summary

- Priority queue
- 3 Operations
 - FindMin
 - DeleteMin
 - Add
- Heap
- Heapification (building an heap)
- Time complexity analysis