

# **VE280 Final Review**

**August 4**

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# Outline

1. Subtype
2. Invariant
3. Dynamic allocation
4. Deepcopy

# Subtype

# Subtype

## Definition

S is a **subtype** of T, written "S<:T". T is a **supertype** of S.  
When a T object is expected, an S object can be supplied.

Example: `MyopicPlayer <: Player`

```
class MyopicPlayer: public Player {...};  
// All the methods of Player type is valid for mp.  
int main() {  
    MyopicPlayer mp;  
    Player *p_ptr = &mp;  
    p_ptr->selectPiece();  
    // Player is expected, MyopicPlayer is supplied  
    Player &p_ref = mp;  
    p_ref.selectPiece(); // Reference also works  
}
```

# Subtype

## Three ways to create a subtype

1. Add one or more operations
  - `MyopicPlayer` has `isBadPiece`, but `Player` does not.
2. Strengthen the postcondition of one or more operations
  - A same operation can do more things (More `EFFECTS`)
3. Weaken the precondition of one or more operations
  - A same operation has loose requirements (Less `REQUIRES`)
  - e.g. `| · |` supports real numbers  $|-2|=2$ ; it also supports complex numbers  $|3+4i|=5$

# Subtype

## Subclasses

|                          | <b>Public<br/>Members</b> | <b>Protected<br/>Members</b> | <b>Private<br/>Members</b> |
|--------------------------|---------------------------|------------------------------|----------------------------|
| Public<br>Inheritance    | public                    | protected                    | private                    |
| Protected<br>inheritance | protected                 | protected                    | private                    |
| Private<br>inheritance   | private                   | private                      | private                    |

- `protected` means can be accessed by its subclass but cannot be accessed by outside callers

# Subtype

## Subclasses

```
class A {  
public:  
    int x;  
protected:  
    int y;  
private:  
    int z;  
};  
class B : public A {  
    // x is public  
    // y is protected, accessible from B  
    // z is not accessible from B  
};  
  
// The other two types of inheritance  
// are not our focus in this course
```

# Subtype

## About `Dynamic_cast<Type*>()`

```
dynamic_cast<Type*>(pointer);  
// EFFECT: if pointer's actual type is either  
// pointer to Type or some pointer to derived  
// class of Type, returns a pointer to Type.  
// Otherwise, returns NULL;
```

This only works for classes which have one or more virtual methods. Otherwise, there's compile error.



# Subtype

## About `Dynamic_cast<Type *>()`

```
class A {  
public:  
    virtual void f() {  
        cout << "A::f()" << endl;  
    }  
};  
class B : public A {  
public:  
    void f() {  
        cout << "B::f()" << endl;  
    }  
};
```

```
A a, *pa;  
B b, *pb;
```

```
pa = &b; pa->f(); // B::f()
```

```
pa = &b;  
pb = dynamic_cast<B*>(pa); 括号里面必须是B type / subtype of B type  
// It succeeds because pa's actual type is B (B<:A)  
// which has at least one virtual method  
pb->f(); // As expected, B::f()
```

```
pa = &a;  
pb = dynamic_cast<B*>(pa);  
// It fails because pa points to A type,  
// which is not a B type or a subtype of B type  
// It returns nullptr  
pb->f(); // segmentation fault
```

```
pb = &b; pa = dynamic_cast<A*>(pb); // always valid
```

# Interfaces & Invariants

# Interfaces

Only provide the usage of this type. Do not expose the implementation details.

In order to protect hp

# Interfaces

Singleton: when only one instance is needed

```
// player.h
extern Player *getHumanPlayer(Board *b, Pool *p);

// player.cpp
Player *getHumanPlayer(Board *b, Pool *p) {
    static HumanPlayer hp(b, p);
    // static variables will only be initialized once
    return &hp;
}
```

The user can only access the `HumanPlayer` instance by

```
// game.cpp
Player *hp = getHumanPlayer(&board, &pool);
```

# Invariants

## Definition

- It describes the conditions that must hold on those members for the representation to correctly implement the abstraction.
- It must hold immediately before exiting each method of that implementation  $\tilde{A} \not\models \neg \phi$  including the constructor.

## Question:

What's the invariant of `IntSet` regarding `size` ?

- `size` represents the number of elements in this `IntSet` , which is always less than or equal to `MAXELTS`

# Dynamic allocation

Example: Dynamic length array

```
int num = 100;  
int *array = new int[num](0);  
delete [] array;
```

Do not create an array with variable length.

```
int num = 100;  
int array[num]; // no! deduction warning!
```

## Find the problems in p5:

```
Customer *c = new Customer();  
c = gold.removeFront(); // new memory above is lost
```

```
Customer *c = new Customer(*gold.removeFront());  
// the returned Customer from gold.removeFront is lost  
// Violate Conservation rule
```

```
Customer *c = new Customer();  
// ... take input and store into c ... two containers are managing 1 c invariant  
  
all.insertBack(c); // queue 'all' has all the customers  
  
if (c->type == "platinum") platinum.insertBack(c);  
else if (c->type == "gold") gold.insertBack(c);  
else if (c->type == "silver") silver.insertBack(c);  
else if (c->type == "regular") regular.insertBack(c);  
// violate At-most-once Invariant
```



# Deepcopy

# Deepcopy

## Why we need deepcopy?

- Sometimes a type needs to manage members in dynamic memory.

Example: Dlist

```
template <class T>
void Dlist<T>::copyAll(const Dlist<T> &l) {
    node *tmp = l.first;
    while (tmp) {
        T *op = new T(*tmp->op);
        // tmp->op is managed by "l"
        // need to create new dynamic object
        insertBack(op);
        tmp = tmp->next;
    }
}
```

# Deepcopy

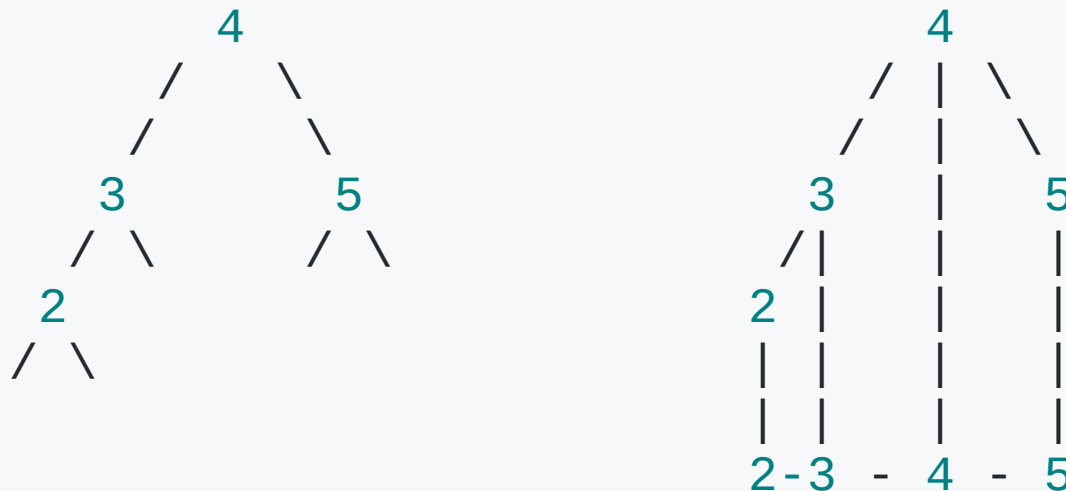
## Question:

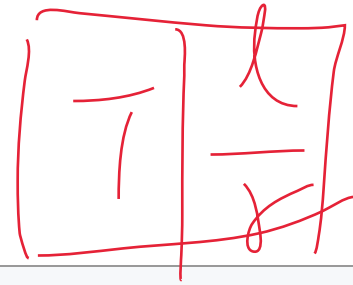
Recall `binary tree` and **in-order traversal** that we met in p2.

We define that

a **good tree** is a binary tree with ascending in-order traversal.

For example, the binary tree below is good (2-3-4-5).





How to deep copy a template good tree?

Provided interface:

```
template <class T>
class GoodTree {
    T *op;
    GoodTree *left;
    GoodTree *right;
public:
    void removeAll();
    // EFFECTS: remove all things of "this"
    void insert(T *op);
    // REQUIRES: T type has a linear order "<"
    // EFFECTS: insert op into "this". Assume no
    //           duplicate op.
};
```

For each `op`, there's only one valid insertion position.

You may use `removeAll` and `insert` in your `copyAll` method.

# Deepcopy

## Sample Answer:

```
template <class T>
void GoodTree<T>::copy_helper(const GoodTree<T> *t) {
    if (t == nullptr) return;
    T *tmp = new(t->op); insert(tmp);
    copy_helper(t->left);
    copy_helper(t->right);
}

template <class T>
void GoodTree<T>::copyAll(const GoodTree<T> &t) {
    removeAll(); // you can also call removeAll outside
    copy_helper(&t);
}
```

- If use friend helper function?
- How to implement removeAll ? How about insert ?

## The rule of the Big Three: **Dlist**

A destructor

```
template <class T>
Dlist<T>::~~Dlist() { removeAll(); }
```

A copy constructor

```
template <class T>
Dlist<T>::Dlist(const Dlist &l): first(0), last(0) {
    if (this != &l) copyAll(l);
}
```

An assignment operator

both variables and const things are accepted

```
template <class T>
Dlist<T> &Dlist<T>::operator=(const Dlist<T> &l) {
    if (this != &l) { removeAll(); copyAll(l); }
    return *this;
}
```

**Thanks. Good luck!** 

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