Amortized Analysis

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For Algorithm Course



Outline

- Amortized Analysis
 - Definition
 - Types
- 2 Three Methods
 - Aggregate Analysis
 - Accounting Method
 - Potential Function Method
- 3 Dynamic Tables
 - Description
 - Supporting TABLEINSERT Only
 - Supporting TABLEINSERT and TABLEDELETE



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Amortized Analysis: A strategy to give a **tighter bound evenly** for a sequence of operations under **worst case** scenario.

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Example: serving coffee in a bar



Amortized Analysis versus Average-Case Analysis

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Average-case analysis: average over all input, e.g., INSERTIONSORT algorithm performs well on "average" over all possible input even if it performs very badly on certain input.

Amortized analysis: average over operations, e.g.,

TABLEINSERTION algorithm performs well on "average" over all operations even if some operations use a lot of time.

- Probability is not involved;
- Guarantees the average performance of each operation in the worst case.



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Aggregate Analysis: determine an upper bound T(n) on the total cost of a sequence of n operations, and the average cost per operation is then T(n)/n (referred as *amortized cost*).

Accounting Method: determine an amortized cost of each operation, different cost for different operations. Store "prepaid credit" for overcharge at early stage and pay for operations later in the sequence.

Potential Method: determine costs for operations, and maintain credit as the "potential energy" as a whole instead of associating the credit within individual objects.



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Stack Operations: Push and pop elements from an empty stack;

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Dynamic Table: A continuous storage array that could change size dynamically.

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First Method: Aggregate Analysis

Compute the worst time T(n) in total for a sequence of n operations. The *amortized cost* (average cost) per operation is T(n)/n in the worst case.

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Compute the worst time T(n) in total for a sequence of n operations. The *amortized cost* (average cost) per operation is T(n)/n in the worst case.

- Cost T(n)/n applies to each operation (There may be several types of operations)
- The other two methods may assign different amortized costs to different types of operation.

Example: Stack with Multipop Operations

There are two fundamental stack operations, each takes O(1) time:

PUSH(S, x): push object x onto stack S.

POP(S): pop the top of stack S and returns the popped object.

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Assign cost for each operation as **1**.

Time Complexity: The total cost of a sequence of n PUSH and POP operations is n, and the actual running time for n operations is $\Theta(n)$.

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ALGORITHM 1: MULTIPOP(S, k)

- while S is not empty and k > 0 do
- POP (S); $k \leftarrow k 1$;

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MULTIPOP(S, k): pop k top objects of stack S (or pop entire stack if it contains fewer than k objects).

ALGORITHM 1: MULTIPOP(S, k)

- 1 while S is not empty and k > 0 do
- $\mathbf{2} \quad \mathsf{POP}(S);$
- $3 \quad k \leftarrow k-1$

The total cost of MULTIPOP is $\min\{|S|, k\}$.



A Sequence of Operations

Consider a sequence of n POP, PUSH, and MULTIPOP operations on an initially empty stack.

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ALGORITHM 2: Stack with MULTIPOP

```
Input: An array A[1..n] of n elements and an integer k.

Output: Stack S.

1 for i = 1 to n do

2 | if A[i] \ge A[i-1] then

3 | PUSH(S, A[i]);

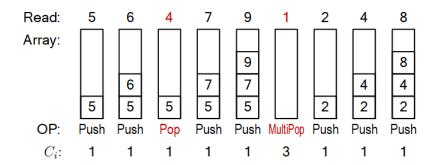
4 else if A[i] \le A[i-1] - k then

5 | MULTIPOP(S, k);

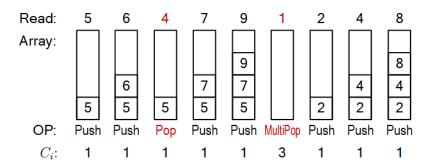
6 else

7 | POP(S);
```

An Example Scenario



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Cursory analysis: MULTIPOP(S, k) may take O(n) time; thus,

$$T(n) = \sum_{i=1}^{n} C_i \le n^2.$$

Cursory Analysis versus Tighter Analysis

In a sequence of operations, some operations may be cheap, but some operations may be expensive, say MULTIPOP(S, k).



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Objective: For each operation we hope to assign an amortized cost \widehat{C}_i to bound the actual total cost.



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Objective: For each operation we hope to assign an amortized cost \hat{C}_i to bound the actual total cost.

For any sequence of n operations, we have

$$T(n) = \sum_{i=1}^{n} C_i \le \sum_{i=1}^{n} \widehat{C}_i.$$

Here, C_i denotes the actual cost of step i.



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$$= \#Push + \#Pop$$

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$$= \#Push + \#Pop$$

$$\leq 2 \times \#Push$$

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Conclusion: on average, the MULTIPOP(S, k) step takes only O(1) time rather than O(k) time.



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Initially, x = 0, A[i] = 0 for $i = 0, \dots, k - 1$.



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Counter Value	A[7]	A[6]	A[5]	A[4]	A[3]	A[2]	A[1]	A[0]	Cost	Total Cost
0	0	0	0	0	0	0	0	0	0	0

Counter Value	<i>A</i> [7]	A[6]	A[5]	A[4]	A[3]	A[2]	A[1]	A[0]	Cost	Total Cost
0	0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	0	0	1	1	1

•	Counter Value	A[7]	A[6]	A[5]	A[4]	A[3]	A[2]	A[1]	A[0]	Cost	Total Cost
•	0	0	0	0	0	0	0	0	0	0	0
	1	0	0	0	0	0	0	0	1	1	1
	2	0	0	0	0	0	0	1	0	2	3

Counter Value	<i>A</i> [7]	A[6]	A[5]	A[4]	A[3]	A[2]	A[1]	A[0]	Cost	Total Cost
0	0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	0	0	1	1	1
2	0	0	0	0	0	0	1	0	2	3
3	0	0	0	0	0	0	1	1	1	4

Counter Value	A[7]	A[6]	A[5]	A[4]	A[3]	A[2]	A[1]	A[0]	Cost	Total Cost
0	0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	0	0	1	1	1
2	0	0	0	0	0	0	1	0	2	3
3	0	0	0	0	0	0	1	1	1	4
4	0	0	0	0	0	1	0	0	3	7

Counter Value	A[7]	A[6]	A[5]	A[4]	A[3]	A[2]	A[1]	A[0]	Cost	Total Cost
0	0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	0	0	1	1	1
2	0	0	0	0	0	0	1	0	2	3
3	0	0	0	0	0	0	1	1	1	4
4	0	0	0	0	0	1	0	0	3	7
5	0	0	0	0	0	1	0	1	1	8

Counter Value	A[7]	A[6]	A[5]	A[4]	A[3]	A[2]	A[1]	A[0]	Cost	Total Cost
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2	0	0	0	0	0	0	1	0	2	3
3	0	0	0	0	0	0	1	1	1	4
4	0	0	0	0	0	1	0	0	3	7
5	0	0	0	0	0	1	0	1	1	8
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Counter Value	A[7]	A[6]	A[5]	A[4]	A[3]	A[2]	A[1]	A[0]	Cost	Total Cost
0	0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	0	0	1	1	1
2	0	0	0	0	0	0	1	0	2	3
3	0	0	0	0	0	0	1	1	1	4
4	0	0	0	0	0	1	0	0	3	7
5	0	0	0	0	0	1	0	1	1	8
6	0	0	0	0	0	1	1	0	2	10
7	0	0	0	0	0	1	1	1	1	11

Counter Value	A[7]	A[6]	A[5]	A[4]	A[3]	A[2]	A[1]	A[0]	Cost	Total Cost
0	0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	0	0	1	1	1
2	0	0	0	0	0	0	1	0	2	3
3	0	0	0	0	0	0	1	1	1	4
4	0	0	0	0	0	1	0	0	3	7
5	0	0	0	0	0	1	0	1	1	8
6	0	0	0	0	0	1	1	0	2	10
7	0	0	0	0	0	1	1	1	1	11
8	0	0	0	0	1	0	0	0	4	15

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1	0	0	0	0	0	0	0	1	1	1
2	0	0	0	0	0	0	1	0	2	3
3	0	0	0	0	0	0	1	1	1	4
4	0	0	0	0	0	1	0	0	3	7
5	0	0	0	0	0	1	0	1	1	8
6	0	0	0	0	0	1	1	0	2	10
7	0	0	0	0	0	1	1	1	1	11
8	0	0	0	0	1	0	0	0	4	15
9	0	0	0	0	1	0	0	1	1	16

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2	0	0	0	0	0	0	1	0	2	3
3	0	0	0	0	0	0	1	1	1	4
4	0	0	0	0	0	1	0	0	3	7
5	0	0	0	0	0	1	0	1	1	8
6	0	0	0	0	0	1	1	0	2	10
7	0	0	0	0	0	1	1	1	1	11
8	0	0	0	0	1	0	0	0	4	15
9	0	0	0	0	1	0	0	1	1	16
10	0	0	0	0	1	0	1	0	2	18

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2	0	0	0	0	0	0	1	0	2	3
3	0	0	0	0	0	0	1	1	1	4
4	0	0	0	0	0	1	0	0	3	7
5	0	0	0	0	0	1	0	1	1	8
6	0	0	0	0	0	1	1	0	2	10
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9	0	0	0	0	1	0	0	1	1	16
10	0	0	0	0	1	0	1	0	2	18
11	0	0	0	0	1	0	1	1	1	19

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6	0	0	0	0	0	1	1	0	2	10
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8	0	0	0	0	1	0	0	0	4	15
9	0	0	0	0	1	0	0	1	1	16
10	0	0	0	0	1	0	1	0	2	18
11	0	0	0	0	1	0	1	1	1	19
12	0	0	0	0	1	1	0	0	3 .	22

Pseudo Code for Binary Counter

INCREMENT is used to add 1 (modulo 2^k) to the value in the counter.

ALGORITHM 3: INCREMENT(*A*)

- 1 $i \leftarrow 0$:
- **2 while** $i \le k 1$ **and** A[i] = 1 **do**
- $A[i] \leftarrow 0;$ $i \leftarrow i + 1;$
- **5** if i < k 1 then
- 6 $A[i] \leftarrow 1$;

Consider a sequence of *n* operations that counts upward from 0:

ALGORITHM 4: BINARYCOUNTER

- 1 **for** i = 1 *to* n **do**
- INCREMENT(A);



Question: $T(n) \le ?$



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Cursory analysis: $T(n) \le kn$ since an increment step might change all k bits.

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During a sequence of n INCREMENT operations:

A[0] flips each time INCREMENT is called $\leftarrow n$ times;

A[1] flips every other time $\leftarrow \lfloor n/2 \rfloor$ times;

.

A[i] flips $\lfloor n/2^i \rfloor$ times.



Thus,

$$T(n) = \sum_{i=1}^{n} C_i$$

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$$= \# flip(A[0]) + \# flip(A[1]) + \cdots + \# flip(A[k]) \text{ (add by column)}$$

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Thus,

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$$= \# flip(A[0]) + \# flip(A[1]) + \cdots + \# flip(A[k]) \text{ (add by column)}$$

$$= n + \frac{n}{2} + \frac{n}{4} + \cdots$$

$$\leq 2n$$

Amortized Analysis

Tighter Analysis: Aggregate Technique (Cont.)

Thus,

$$T(n) = \sum_{i=1}^{n} C_{i}$$

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Amortized cost of each operation: O(n)/n = O(1).



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Accounting Method

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Intuition: If $\widehat{C_{op}} > C_{op}$, the overcharge will be stored as prepaid credit; the credit will be used later for the operations with $\widehat{C_{op}} < C_{op}$.

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The requirement that $\sum_{i=1}^{n} C_i \leq \sum_{i=1}^{n} \widehat{C}_i$ is essentially credit never goes negative.



Example 1: Stack with MULTIPOP Operation

Example: For stack with MULTIPOP, assign amortized cost as:

Operation	Real Cost C_{op}	Amortized Cost $\widehat{C_{op}}$
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Credit: the number of items in the stack.

Starting from an empty stack, any sequence of n_1 PUSH, n_2 POP, and n_3 MULTIPOP operations takes at most $T(n) = \sum_{i=1}^n C_i \le \sum_{i=1}^n \widehat{C}_i = 2n_1$. Here $n = n_1 + n_2 + n_3$.

Note: when there are more than one type of operations, each type of operation might be assigned with different amortized cost.

Algorithm@SJTU Xiaofeng Gao Amortized Analysis 24/94

Suppose you are renting a "coin-operation" machine, and are charged according to the number of operations.



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Two payment strategies:

- Pay actual cost for each operation:
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If "average" cost > actual cost: the extra will be deposited as *credit*.

If "average" cost < actual cost: credit will be used to pay actual cost.

Constraint: $\sum_{i=1}^{n} C_i \le \sum_{i=1}^{n} \widehat{C}_i$ for arbitrary *n* operations, i.e. you have enough credit in your account.

Xiaofeng Gao

Amortized Analysis

25/94

Read: 5

Array:

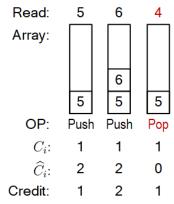
Push OP:

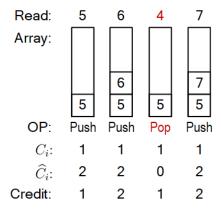
5

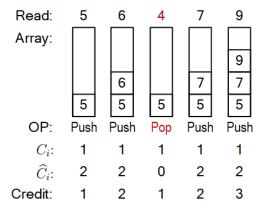
 C_i : 1 \widehat{C}_i : 2

Credit:

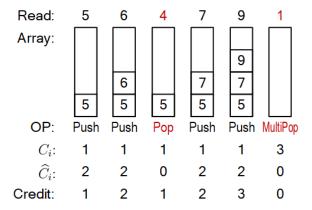
Read: 5 6 Array: 6 5 5 Push OP: Push C_i : 1 1 \widehat{C}_i : 2 2 Credit:

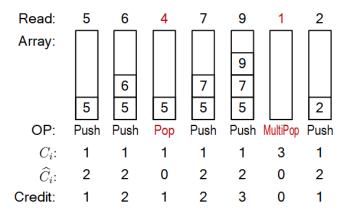


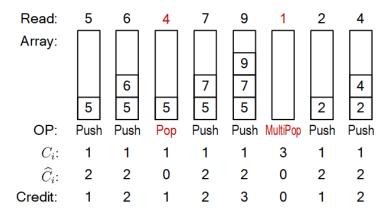


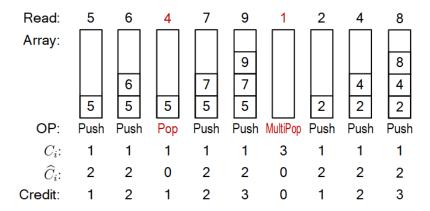


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Algorithm@SJTU Xiaofeng Gao Amortized Analysis 34/94

Example 2: Incrementing Binary Counter

Set amortized cost as follows:

OP	Real Cost C_{OP}	Amortized Cost $\widehat{C_{OP}}$
$flip(0\rightarrow 1)$	1	2
flip $(1\rightarrow 0)$	1	0

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Key observation: $\#flip(0 \rightarrow 1) \ge \#flip(1 \rightarrow 0)$

$$T(n) = \sum_{i=1}^{n} C_{i}$$

$$= \# flip(0 \to 1) + \# flip(1 \to 0)$$

$$\leq 2 \# flip(0 \to 1)$$

$$\leq 2n$$

Outline

- Amortized Analysis
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Basic idea: sometimes it is not easy to set \widehat{C}_{op} for each operation OP directly.

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Define a potential function as a bridge, i.e. we can assign a value to state rather than operation, and amortized costs are then calculated based on potential function.



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Potential Function: $\Phi(S): S \to R$, where *S* is state collection.

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Algorithm@SJTU Xiaofeng Gao Amortized Analysis

Basic idea: sometimes it is not easy to set $\widehat{C_{op}}$ for each operation OP directly.

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Potential Function: $\Phi(S): S \to R$, where *S* is state collection.

Amortized Cost Setting: $\widehat{C}_i = C_i + \Phi(S_i) - \Phi(S_{i-1})$.



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Then we have

$$\sum_{i=1}^{n} \widehat{C}_{i} = \sum_{i=1}^{n} (C_{i} + \Phi(S_{i}) - \Phi(S_{i-1}))$$
$$= \sum_{i=1}^{n} C_{i} + \Phi(S_{n}) - \Phi(S_{0})$$

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Requirement: To guarantee $\sum_{i=1}^{n} C_i \leq \sum_{i=1}^{n} \widehat{C}_i$, it suffices to assure

$$\Phi(S_n) \geq \Phi(S_0).$$



Potential Function: Let $\Phi(S)$ denote the number of items in stack.



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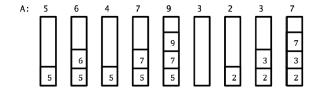
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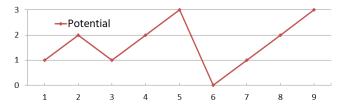
Correctness: $\Phi(S_i) \ge 0 = \Phi(S_0)$ for any i;



States of Stack S:



Polyline of Potential Function $\Phi(S_i)$:



Potential Function Technique: Amortized Cost Setting

Definition: $\Phi(S)$ denotes the number of items in stack;



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Push:
$$\begin{aligned} \Phi(S_i) - \Phi(S_{i-1}) &= 1 \\ \widehat{C}_i &= C_i + \Phi(S_i) - \Phi(S_{i-1}) = 2 \end{aligned}$$



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Potential Function Technique: Amortized Cost Setting

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 $\widehat{C}_i = C_i + \Phi(S_i) - \Phi(S_{i-1}) = 2$

Pop:
$$\Phi(S_i) - \Phi(S_{i-1}) = -1$$

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$$\Phi(S_i) - \Phi(S_{i-1}) = -1$$

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MULTIPOP:
$$\Phi(S_i) - \Phi(S_{i-1}) = -\#Pop$$

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Multipop:
$$\Phi(S_i) - \Phi(S_{i-1}) = -\#Pop$$

 $\widehat{C}_i = C_i + \Phi(S_i) - \Phi(S_{i-1}) = 0$

Thus, starting from an empty stack, any sequence of n_1 PUSH, n_2 POP, and n_3 MULTIPOP operations takes at most

$$T(n) = \sum_{i=1}^{n} C_i \le \sum_{i=1}^{n} \widehat{C}_i = 2n_1$$
. Here $n = n_1 + n_2 + n_3$.

Algorithm@SJTU Xiaofeng Gao Amortized Analysis 41/94

Binary Counter

Definition: Set potential function as $\Phi(S) = \#1$ in counter

Counter Value	A[7]	A[6]	A[5]	A[4]	A[3]	A[2]	A[1]	A[0]	Cost	Total Cost
0	0	0	0	0	0	0	0	0	0	0
1	0	0	0	0	0	0	0	1	1	1
2	0	0	0	0	0	0	1	0	2	3
3	0	0	0	0	0	0	1	1	1	4
4	0	0	0	0	0	1	0	0	3	7
5	0	0	0	0	0	1	0	1	1	8
6	0	0	0	0	0	1	1	0	2	10
7	0	0	0	0	0	1	1	1	1	11
8	0	0	0	0	1	0	0	0	4	15

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3	0	0	0	0	0	0	1	1	1	4
4	0	0	0	0	0	1	0	0	3	7
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Polyline of Potential Function $\Phi(S)$:



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Thus we have

$$T(n) = \sum_{i=1}^{n} C_i \le \sum_{i=1}^{n} \widehat{C}_i = 2n$$

In other words, starting from 00....0, a sequence of n INCREMENT operations takes at most 2n time.

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- 1 Amortized Analysis
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A Practical Problem

Suppose you are asked to develop a C++ compiler.



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vector is one of a C++ class templates to hold a set of objects. It supports the following operations:

- push_back: to add a new object onto the tail;
- pop_back: to pop out the last object;

Recall that vector uses a contiguous memory area to store objects.

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- push_back: to add a new object onto the tail;
- pop_back: to pop out the last object;

Recall that vector uses a contiguous memory area to store objects.

Question: How to design an efficient **memory-allocation strategy** for vector?

Description
Supporting TABLEINSERT Only
Supporting TABLEINSERT and TABLEDELET

DYNAMICTABLE Problem



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Thus we have to allocate space for a table, only to find out later that it is not enough.

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DYNAMIC CONTRACTION: Similarly, if many objects have been removed from a table, it is worthwhile to reallocate the table with a smaller size.

We will show a **memory allocation strategy** such that the amortized cost of insertion and deletion is O(1), even if the actual cost of an operation is large when it triggers an expansion or contraction.

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Table Expansion Operation

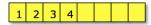
ALGORITHM 5: TABLE_INSERT(T, i)

- 1 if size[T] = 0 then
- allocate a table with 1 slot;
- size[T] = 1;
- 4 if num[T] = size[T] then
- allocate a new table with $2 \times size[T]$ slots; //double size
- 6 $size[T] = 2 \times size[T];$
- 7 copy all items into the new table;
- 8 | free the original table;
- 9 insert the new item i into T;
- 10 $num[T] \leftarrow num[T] + 1$;



Example: TABLEINSERT

An Example Dynamic Table *T*:

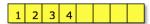


num[T]: #used slots

size[T]: total number of slots

Example: TABLEINSERT

An Example Dynamic Table *T*:



num[T]: #used slots

size[T]: total number of slots

Consider a sequence of operations starting with an empty table:

ALGORITHM 6: TABLE_INSERT

- 1 Table *T*;
- **2 for** i = 1 *to* n **do**
- 3 | TABLE_INSERT(T, i);



INSERT(1) 1
INSERT(2) overflow

 $C_1 = 1$

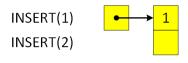
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INSERT(1)
INSERT(2)

1



 $C_1 = 1$



 $C_1 = 1$

INSERT(1) INSERT(2)



C₁=1 C₂=2

INSERT(1)

INSERT(2)

INSERT(3)

1

overflow

INSERT(1)

INSERT(2)

INSERT(3)

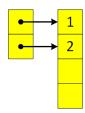
1

C₁=1 C₁=2

INSERT(1)

INSERT(2)

INSERT(3)



 $C_1=1$ $C_2=2$

INSERT(1)

INSERT(2)

INSERT(3)

1

3

 $C_1 = 1$

 $C_2 = 2$ $C_3 = 3$

INSERT(1)

INSERT(2)

INSERT(3)

INSERT(4)

1

2

3

3

C₁=1

 $C_2 = 2$

 $C_3 = 3$

C₄=1

INSERT(1)

INSERT(2)

INSERT(3)

INSERT(4)

INSERT(5)

1

2

3 4 C₁=1

 $C_2 = 2$ $C_3 = 3$

C₄=1

overflow

INSERT(1)

INSERT(2)

INSERT(3)

INSERT(4)

INSERT(5)

1

2

3 4

C₁=1

 $C_2 = 2$

 $C_3 = 3$

C₄=1

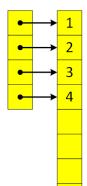
INSERT(1)

INSERT(2)

INSERT(3)

INSERT(4)

INSERT(5)



$$C_1 = 1$$

 $C_2 = 2$

 $C_3 = 3$

C₄=1

TABLEINSERT(5)

INSERT(1)

INSERT(2)

INSERT(3)

INSERT(4)

INSERT(5)

1

2

 $C_1=1$ $C_2=2$

 $C_3 = 3$

3 4 5

 $C_4 = 1$

C₅=5

TABLEINSERT(6)

INSERT(1)

INSERT(2)

INSERT(3)

INSERT(4)

INSERT(5)

INSERT(6)

1

C₁=1

2

 $C_2 = 2$ $C_3 = 3$

3

C₄=1

5

C₅=5

6

C₆=1

TableInsert(7)

INSERT(1)

INSERT(2)

INSERT(3)

INSERT(4)

INSERT(5)

INSERT(6)

INSERT(7)

1

C₁=1

2

 $C_2 = 2$

3

 $C_3 = 3$

4

 $C_4 = 1$

5

 $C_5 = 5$

6

 $C_6 = 1$

7

 $C_7 = 1$

TABLEINSERT(8)

		COS
INSERT(1)	1	C ₁ =1
INSERT(2)	2	C ₂ =2
INSERT(3)	3	C ₃ =3
INSERT(4)	4	C ₄ =1
INSERT(5)	5	C ₅ =5
INSERT(6)	6	C ₆ =1
INSERT(7)	7	C ₇ =1
INSERT(8)	8	C ₈ =1

Cursory analysis: $O(n^2)$

Consider a sequence of operations starting with an empty table. Define C_i as the cost of the *i*th operation (elementary insertions or deletions),



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Cursory analysis: $O(n^2)$

Consider a sequence of operations starting with an empty table. Define C_i as the cost of the *i*th operation (elementary insertions or deletions),

$$C_i = \begin{cases} i & \text{if } i - 1 \text{ is an exact power of 2} \\ 1 & \text{otherwise} \end{cases}$$

Here $C_i = i$ when the table is full, since we need to perform 1 insertion, and copy i - 1 items into the new table.

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Here $C_i = i$ when the table is full, since we need to perform 1 insertion, and copy i - 1 items into the new table.

If *n* operations are performed, the worst-case cost of an operation will be O(n). Thus, the total running time is $O(n^2)$. Not tight!



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Tighter Analysis 1: Aggregate Method

Key Observation: Table expansions are rare.

The $O(n^2)$ bound is not tight since **table expansion** doesn't occur often in the course of n operations.



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Specifically, **table expansion** occurs at the *i*th operation, where i-1 is an exact power of 2.

i	1	2	3	4	5	6	7	8	9	10	11	12
Sizei	1	2	4	4	8	8	8	8	16	16	16	16
C_i	1	2	3	1	5	1	1	1	9	1	1	1

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Sizei	1	2	4	4	8	8	8	8	16	16	16	16
C_i	1	2	3	1	5	1	1	1	9	1	1	1

We can decompose C_i as follows:

i	1	2	3	4	5	6	7	8	9	10	11	12
Sizei	1	2	4	4	8	8	8	8	16	16	16	16
$C_{i \text{ (insert)}}$	1	1	1	1	1	1	1	1	1	1	1	1
C_{i} (copy)		1	2		4				8			

The total cost of n operations is:

$$\sum_{i=1}^{n} C_i = 1 + 2 + 3 + 1 + 5 + 1 + 1 + 1 + 9 + 1 + \dots$$

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$$= 3n$$

Thus the amortized cost of an operation is 3.

In other words, the average cost of each TABLEINSERT operation is O(n)/n = O(1).

Xiaofeng Gao



Amortized Analysis

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For the *i*-th operation, an **amortized cost** $\widehat{C}_i = \$3$ is charged.

- \$1 pays for the insertion **itself**;
- \$2 is stored for **later table doubling**, \$1 for copying one of the recent $\frac{i}{2}$ items, \$1 for copying one of the old $\frac{i}{2}$ items.

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Original:



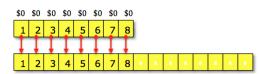
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Original:

\$0 \$0 \$0 \$0 \$2 \$2 \$2 \$2 1 2 3 4 5 6 7 8

Expansion:



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Key observation: the credit never goes negative. In other words, the sum of amortized cost provides an upper bound of the sum of actual costs.



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$$T(n) = \sum_{i=1}^{n} C_i \le \sum_{i=1}^{n} \widehat{C}_i = 3n.$$

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Key observation: the credit never goes negative. In other words, the sum of amortized cost provides an upper bound of the sum of actual costs.

$$T(n) = \sum_{i=1}^{n} C_i \le \sum_{i=1}^{n} \widehat{C}_i = 3n.$$

i	1	2	3	4	5	6	7	8	9	10	11	12
Size _i	1	2	4	4	8	8	8	8	16	16	16	16
$C_{i \text{ (insert)}}$	1	1	1	1	1	1	1	1	1	1	1	1
C_{i} (copy)		1	2		4				8			
\widehat{C}_{ι}	3	3	3	3	3	3	3	3	3	3	3	3
Credit	2	3	3	5	3	5	7	9	3	5	7	9

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Tighter Analysis 3: Potential Function Technique

Basic idea: the **bank account** can be viewed as potential function of the dynamic set. More specifically, we prefer a potential function $\Phi: \{T\} \to R$ with the following properties:

- $\Phi(T) = 0$ immediately **after** an expansion;
- $\Phi(T) = size[T]$ immediately **before** an expansion; thus, the next expansion can be paid for by the potential.

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Tighter Analysis 3: Potential Function Technique

Basic idea: the **bank account** can be viewed as potential function of the dynamic set. More specifically, we prefer a potential function $\Phi: \{T\} \to R$ with the following properties:

- $\Phi(T) = 0$ immediately **after** an expansion;
- $\Phi(T) = size[T]$ immediately **before** an expansion; thus, the next expansion can be paid for by the potential.

A possibility:
$$\Phi(T) = 2 \times num[T] - size[T]$$

$$\emptyset = 2num[T] - size[T] = 4$$

$\Phi(T) = 2 \times num[T] - size[T]$: An Example

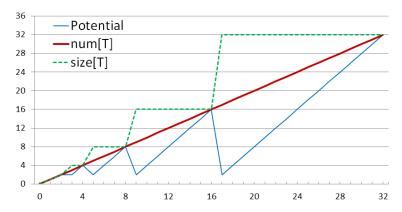


Figure: The effect of a sequence of n TABLEINSERT on $size_i$ (green), num_i (red), and Φ_i (blue).

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Correctness of
$$\Phi(T) = 2 \times num[T] - size[T]$$

Correctness: Initially $\Phi_0 = 0$, and it is easy to verify that $\Phi_i \ge \Phi_0$ since the table is always at least half full.



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Correctness: Initially $\Phi_0 = 0$, and it is easy to verify that $\Phi_i \ge \Phi_0$ since the table is always at least half full.

The **amortized cost** \widehat{C}_i with respect to Φ is defined as:

$$\widehat{C}_i = C_i + \Phi(T_i) - \Phi(T_{i-1}).$$



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The **amortized cost** \widehat{C}_i with respect to Φ is defined as:

$$\widehat{C}_i = C_i + \Phi(T_i) - \Phi(T_{i-1}).$$

Thus
$$\sum_{i=1}^n \widehat{C}_i = \sum_{i=1}^n C_i + \Phi_n - \Phi_0$$
 is really an upper bound of the actual $\cot \sum_{i=1}^n C_i$.

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Case 1: the *i*-th insertion does not trigger an expansion

```
size_i = size_{i-1} (size_i: the table size after the i-th operation.) num_i = num_{i-1} + 1 (num_i: no. of items after the i-th operations)
```



Case 1: the *i*-th insertion does not trigger an expansion

 $size_i = size_{i-1}$ ($size_i$: the table size after the *i*-th operation.) $num_i = num_{i-1} + 1$ (num_i : no. of items after the *i*-th operations)

$$\widehat{C}_{i} = C_{i} + \Phi_{i} - \Phi_{i-1}
= 1 + (2num_{i} - size_{i}) - (2num_{i-1} - size_{i-1})
= 1 + 2
= 3$$

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= 1 + 2
= 3$$

- Insert(1)
- 2. Insert(2)
- 3. Insert(3)
- 4. Insert(4)

- 2
- 3

- C1: 1
- C2: 2
- C3: 3
- C4: 1

Case 2: the *i*-th insertion triggers an expansion

$$size_i = 2 \times size_{i-1}.$$

 $size_{i-1} = num_{i-1} = num_i - 1.$



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Case 2: the *i*-th insertion triggers an expansion

$$size_{i} = 2 \times size_{i-1}.$$

 $size_{i-1} = num_{i-1} = num_{i} - 1.$
 $\widehat{C}_{i} = C_{i} + \Phi_{i} - \Phi_{i-1}$
 $= num_{i} + (2num_{i} - size_{i}) - (2num_{i-1} - size_{i-1})$
 $= num_{i} + 2 - (num_{i} - 1)$
 $= 3$

Case 2: the *i*-th insertion triggers an expansion

$$size_i = 2 \times size_{i-1}.$$

$$size_{i-1} = num_{i-1} = num_i - 1.$$

$$\widehat{C}_{i} = C_{i} + \Phi_{i} - \Phi_{i-1}
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= num_{i} + 2 - (num_{i} - 1)
= 3$$

- 1. Insert(1)
- 2. Insert(2)
- 3. Insert(3)



- C1: 1
 - C2: 2
 - C3: 3

Outline

- Amortized Analysis
 - Definition
 - Types
- Three Methods
 - Aggregate Analysis
 - Accounting Method
 - Potential Function Method
- 3 Dynamic Tables
 - Description
 - Supporting TABLEINSERT Only
 - Supporting TABLEINSERT and TABLEDELETE



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TABLEDELETE Operation

To implement TABLEDELETE operation, it is simple to remove the specified item from the table, followed by a CONTRACTION operation when the **load factor** (denoted as $\alpha(T) = \frac{num[T]}{size[T]}$) is small, so that the wasted space is not exorbitant.

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Specifically, when the number of the items in the table drops too low, we allocate a new, smaller space, copy the items from the old table to the new one, and finally free the original table.

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Specifically, when the number of the items in the table drops too low, we allocate a new, smaller space, copy the items from the old table to the new one, and finally free the original table.

We would like the following two properties:

- The load factor is bounded below by a constant;
- The amortized cost of a table operation is bounded above by a constant.

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Trial 1: load factor $\alpha(T)$ never drops below 1/2



Trial 1: load factor $\alpha(T)$ never drops below 1/2

A natural strategy is:

- To double the table size when inserting an item into a full table;
- To halve the table size when deletion causes $\alpha(T) < \frac{1}{2}$.



Trial 1: load factor $\alpha(T)$ never drops below 1/2

A natural strategy is:

- To double the table size when inserting an item into a full table;
- To halve the table size when deletion causes $\alpha(T) < \frac{1}{2}$.

The strategy guarantees that load factor $\alpha(T)$ never drops below 1/2.

However, the amortized cost of an operation might be quite large.

Consider a sequence of n = 16 operations:

- The first 8 operations: I, I, I,
- The second 8 operations: I, D, D, I, I, D, D, I
- Repeat the I, D, D, I opertions · · · · ·

Algorithm@SJTU Xiaofeng Gao Amortized Analysis 80/94

Consider a sequence of n = 16 operations:

- The first 8 operations: I, I, I,
- The second 8 operations: I, D, D, I, I, D, D, I
- Repeat the I, D, D, I opertions · · · · ·

Note:

- After the 8-th I, we have $num_8 = size_8 = 8$.
- The 9-th I leads to a table expansion;
- The following two D lead to a table contraction;
- The following two I lead to a table expansion, and so on.

4□▶
4□▶
4□▶
4□▶
4□▶
4□▶
4□▶
4□▶
4□▶
4□▶
4□▶

After 8 Insertions

1 2 3 4 5 6 7 8

Insert(9) causes an expansion

1 2 3 4 5 6 7 8 9

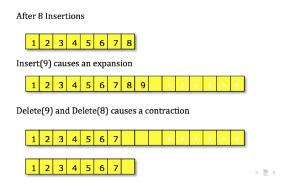
Delete(9) and Delete(8) causes a contraction

1 2 3 4 5 6 7

1 2 3 4 5 6 7



4 2 3



The expansion/contraction takes O(n) time, and there are n of them.

Thus the total cost of n operations are $O(n^2)$, and the amortized cost of an operation is O(n).

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Trial 2: load factor $\alpha(T)$ never drops below 1/4



Trial 2: load factor $\alpha(T)$ never drops below 1/4

Another strategy is:

- To double the table size when inserting an item into a full table;
- To halve the table size when deletion causes $\alpha(T) < \frac{1}{4}$.

Trial 2: load factor $\alpha(T)$ never drops below 1/4

Another strategy is:

- To double the table size when inserting an item into a full table;
- To halve the table size when deletion causes $\alpha(T) < \frac{1}{4}$.

The strategy guarantees that load factor $\alpha(T)$ never drops below 1/4.

Amortized Analysis

We start by defining a potential function $\Phi(T)$ that is 0 immediately after an expansion or contraction, and builds as $\alpha(T)$ increases to 1 or decreases to $\frac{1}{4}$.

Amortized Analysis

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$$\Phi(T) = \begin{cases} 2 \times num[T] - size[T] & \text{if } \alpha(T) \ge \frac{1}{2} \\ \frac{1}{2} size[T] - num[T] & \text{if } \alpha(T) < \frac{1}{2} \end{cases}$$

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Amortized Analysis

We start by defining a potential function $\Phi(T)$ that is 0 immediately after an expansion or contraction, and builds as $\alpha(T)$ increases to 1 or decreases to $\frac{1}{4}$.

$$\Phi(T) = \begin{cases} 2 \times num[T] - size[T] & \text{if } \alpha(T) \ge \frac{1}{2} \\ \frac{1}{2} size[T] - num[T] & \text{if } \alpha(T) < \frac{1}{2} \end{cases}$$

Correctness: the potential is 0 for an empty table, and $\Phi(T)$ never goes negative. Thus, the total amortized cost of a sequence of n operations with respect to Φ is an upper bound of the actual cost.

Algorithm@SJTU Xiaofeng Gao Amortized Analysis 83/94

Case 1: $\alpha_{i-1} \geq \frac{1}{2}$ and no expansion



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Case 1: $\alpha_{i-1} \geq \frac{1}{2}$ and no expansion

The amortized cost is:

$$\widehat{C}_{i} = C_{i} + \Phi_{i} - \Phi_{i-1}
= 1 + (2num_{i} - size_{i}) - (2num_{i-1} - size_{i-1})
= 1 + (2(num_{i-1} + 1) - size_{i-1}) - (2num_{i-1} - size_{i-1})
= 3$$

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= 1 + (2(num_{i-1} + 1) - size_{i-1}) - (2num_{i-1} - size_{i-1})
= 3$$

Case 2: $\alpha_{i-1} \geq \frac{1}{2}$ and an expansion was triggered



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Case 2: $\alpha_{i-1} \geq \frac{1}{2}$ and an expansion was triggered

The amortized cost is:

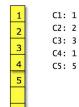
$$\widehat{C}_{i} = C_{i} + \Phi_{i} - \Phi_{i-1}
= num_{i} + (2num_{i} - size_{i}) - (2num_{i-1} - size_{i-1})
= num_{i-1} + 1 + (2(num_{i-1} + 1) - 2size_{i-1}) - (2num_{i-1} - size_{i-1})
= 3 + num_{i-1} - size_{i-1} \leftarrow num_{i-1} = size_{i-1}
= 3$$

Case 2: $\alpha_{i-1} \geq \frac{1}{2}$ and an expansion was triggered

The amortized cost is:

$$\begin{array}{lll} \widehat{C}_{i} & = & C_{i} + \Phi_{i} - \Phi_{i-1} \\ & = & num_{i} + (2num_{i} - size_{i}) - (2num_{i-1} - size_{i-1}) \\ & = & num_{i-1} + 1 + (2(num_{i-1} + 1) - 2size_{i-1}) - (2num_{i-1} - size_{i-1}) \\ & = & 3 + num_{i-1} - size_{i-1} & \leftarrow num_{i-1} = size_{i-1} \\ & = & 3 \\ & & & 1. \text{ Insert(1)} \\ & = & 3 \\ & & & 1. \text{ Insert(2)} \end{array}$$





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Case 3: $\alpha_{i-1} < \frac{1}{2}$ and $\alpha_i < \frac{1}{2}$



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Case 3:
$$\alpha_{i-1} < \frac{1}{2}$$
 and $\alpha_i < \frac{1}{2}$

The amortized cost is:

$$\widehat{C}_{i} = C_{i} + \Phi_{i} - \Phi_{i-1}
= 1 + (\frac{1}{2}size_{i} - num_{i}) - (\frac{1}{2}size_{i-1} - num_{i-1})
= 1 + (\frac{1}{2}size_{i} - num_{i}) - (\frac{1}{2}size_{i} - (num_{i} - 1))
= 0$$

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Case 3:
$$\alpha_{i-1} < \frac{1}{2}$$
 and $\alpha_i < \frac{1}{2}$

The amortized cost is:

$$\begin{split} \widehat{C}_i &= C_i + \Phi_i - \Phi_{i-1} \\ &= 1 + (\frac{1}{2} size_i - num_i) - (\frac{1}{2} size_{i-1} - num_{i-1}) \\ &= 1 + (\frac{1}{2} size_i - num_i) - (\frac{1}{2} size_i - (num_i - 1)) \\ &= 0 \\ &= 0 \end{split}$$

$$num = 7, size=16, phi = 1$$

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Case 4:
$$\alpha_{i-1} < \frac{1}{2}$$
 but $\alpha_i \ge \frac{1}{2}$



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Case 4:
$$\alpha_{i-1} < \frac{1}{2}$$
 but $\alpha_i \ge \frac{1}{2}$

The amortized cost is:

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Case 4:
$$\alpha_{i-1} < \frac{1}{2}$$
 but $\alpha_i \ge \frac{1}{2}$

The amortized cost is:

$$num = 7, \quad size = 16, \quad phi = 1$$

$$num = 8$$
, $size = 16$, $phi = 0$

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Case 1: $\alpha_{i-1} < \frac{1}{2}$ and no contraction



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Case 1: $\alpha_{i-1} < \frac{1}{2}$ and no contraction

The amortized cost is:

$$\begin{split} \widehat{C}_{i} &= C_{i} + \Phi_{i} - \Phi_{i-1} \\ &= 1 + (\frac{1}{2}size_{i} - num_{i}) - (\frac{1}{2}size_{i-1} - num_{i-1}) \\ &= 1 + (\frac{1}{2}size_{i-1} - (num_{i-1} - 1)) - (\frac{1}{2}size_{i-1} - num_{i-1}) \\ &= 2 \end{split}$$

Case 1: $\alpha_{i-1} < \frac{1}{2}$ and no contraction

The amortized cost is:

$$\widehat{C}_{i} = C_{i} + \Phi_{i} - \Phi_{i-1} \\
= 1 + (\frac{1}{2}size_{i} - num_{i}) - (\frac{1}{2}size_{i-1} - num_{i-1}) \\
= 1 + (\frac{1}{2}size_{i-1} - (num_{i-1} - 1)) - (\frac{1}{2}size_{i-1} - num_{i-1}) \\
= 2 \\
num = 7, size = 16, phi = 1 \\
\boxed{1 | 2 | 3 | 4 | 5 | 6 | 7}$$

$$num = 6, size = 16, phi = 2$$

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Case 2: $\alpha_{i-1} < \frac{1}{2}$ and a contraction was triggered



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Case 2: $\alpha_{i-1} < \frac{1}{2}$ and a contraction was triggered

The amortized cost is:

$$\begin{array}{lll} \widehat{C}_{i} & = & C_{i} + \Phi_{i} - \Phi_{i-1} \\ & = & num_{i} + 1 + \left(\frac{1}{2}size_{i} - num_{i}\right) - \left(\frac{1}{2}size_{i-1} - num_{i-1}\right) \\ & = & num_{i-1} + \left(\frac{1}{4}size_{i-1} - (num_{i-1} - 1)\right) - \left(\frac{1}{2}size_{i-1} - num_{i-1}\right) \\ & = & 1 + num_{i-1} - \frac{1}{4}size_{i-1} \quad \leftarrow num_{i-1} = \frac{1}{4}size_{i-1} \\ & = & 1 \end{array}$$

Case 2: $\alpha_{i-1} < \frac{1}{2}$ and a contraction was triggered

The amortized cost is:

$$\begin{array}{lll} \widehat{C}_{i} & = & C_{i} + \Phi_{i} - \Phi_{i-1} \\ & = & num_{i} + 1 + \left(\frac{1}{2}size_{i} - num_{i}\right) - \left(\frac{1}{2}size_{i-1} - num_{i-1}\right) \\ & = & num_{i-1} + \left(\frac{1}{4}size_{i-1} - (num_{i-1} - 1)\right) - \left(\frac{1}{2}size_{i-1} - num_{i-1}\right) \\ & = & 1 + num_{i-1} - \frac{1}{4}size_{i-1} \quad \leftarrow num_{i-1} = \frac{1}{4}size_{i-1} \\ & = & 1 \end{array}$$



Case 3: $\alpha_{i-1} \geq \frac{1}{2}$ and $\alpha_i \geq \frac{1}{2}$



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Case 3:
$$\alpha_{i-1} \geq \frac{1}{2}$$
 and $\alpha_i \geq \frac{1}{2}$

The amortized cost is:

$$\widehat{C}_{i} = C_{i} + \Phi_{i} - \Phi_{i-1}
= 1 + (2num_{i} - size_{i}) - (2num_{i-1} - size_{i-1})
= 1 + (2(num_{i-1} - 1) - size_{i-1}) - (2num_{i-1} - size_{i-1})
= -1$$

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Case 3:
$$\alpha_{i-1} \geq \frac{1}{2}$$
 and $\alpha_i \geq \frac{1}{2}$

The amortized cost is:

$$\begin{array}{lcl} \widehat{C}_{i} & = & C_{i} + \Phi_{i} - \Phi_{i-1} \\ & = & 1 + (2num_{i} - size_{i}) - (2num_{i-1} - size_{i-1}) \\ & = & 1 + (2(num_{i-1} - 1) - size_{i-1}) - (2num_{i-1} - size_{i-1}) \\ & = & -1 \end{array}$$

$$num = 9, \quad size = 16, \quad phi = 2$$

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Case 4: $\alpha_{i-1} \geq \frac{1}{2}$ and $\alpha_i < \frac{1}{2}$



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Case 4:
$$\alpha_{i-1} \geq \frac{1}{2}$$
 and $\alpha_i < \frac{1}{2}$

The amortized cost is:

Amortized Analysis

91/94

Case 4:
$$\alpha_{i-1} \geq \frac{1}{2}$$
 and $\alpha_i < \frac{1}{2}$

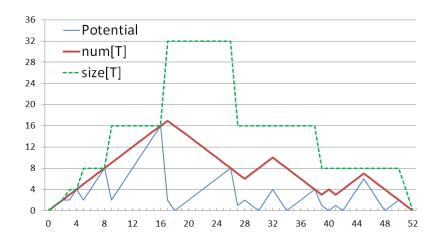
The amortized cost is:

$$num = 7$$
, $size = 16$, $phi = 1$



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An Example Polyline of Φ_i



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Conclusion

Since the amortized cost of each operation is bounded above by a constant, Starting with an empty table:

- a sequence of n TABLEINSERT operations cost O(n) time in the worst case.
- the actual cost of any sequence of n TABLEINSERT and TABLEDELETE operations is still O(n) in the worst case.

Summary

Amortized costs can provide a clean abstraction of data-structure performance.



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Different schemes may work for assigning amortized costs in the accounting method, or potentials in the potential method, sometimes yielding radically different bounds.