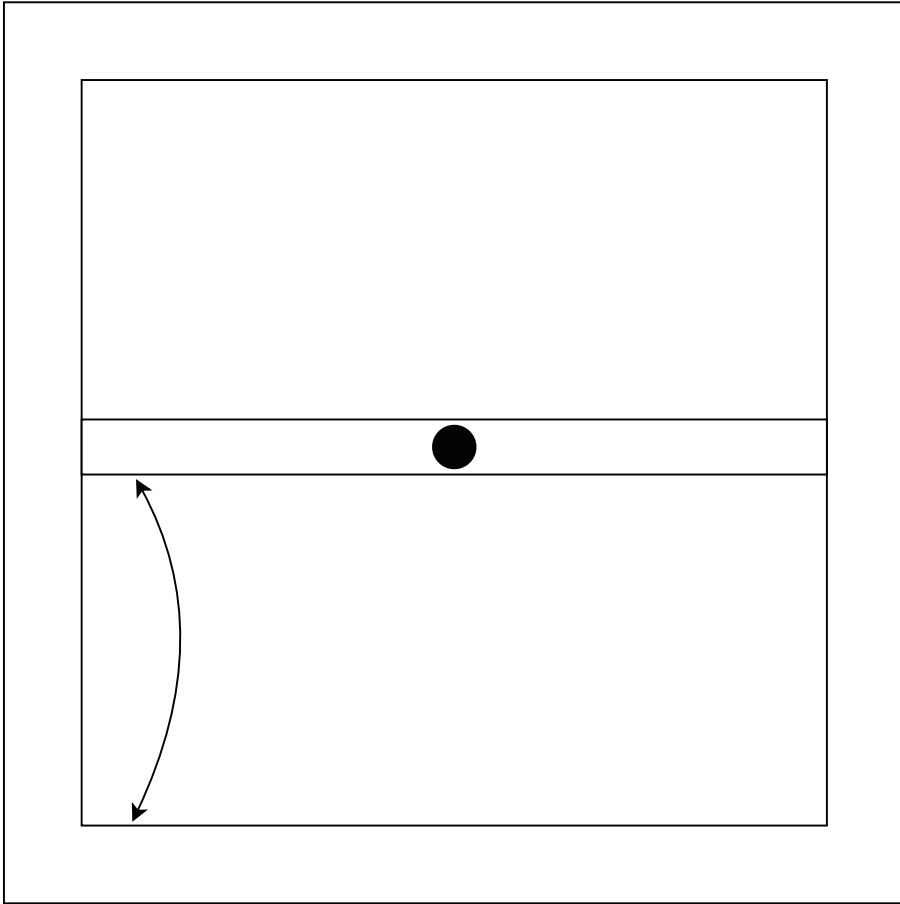
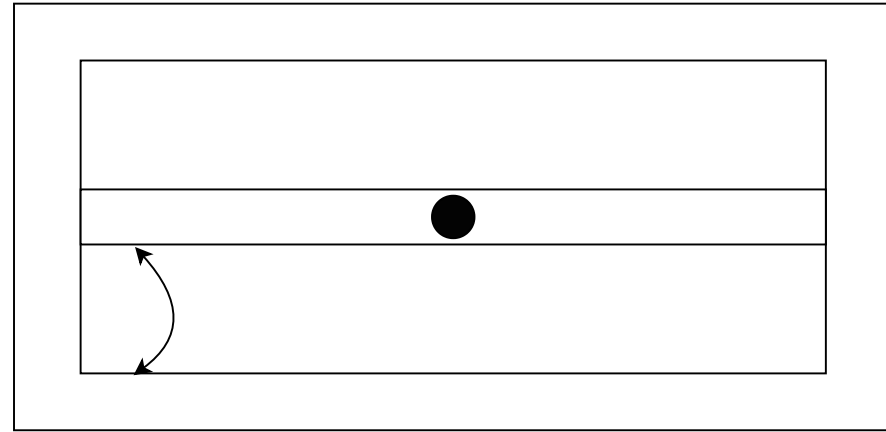


D_1  $D_2 \cdot \sin(\theta_{tilt})$ D_1  $D_2 \cdot \sin(\Delta\theta_{tilt})$