

# 嵌入式作業系統實作

## Embedded OS Implementation

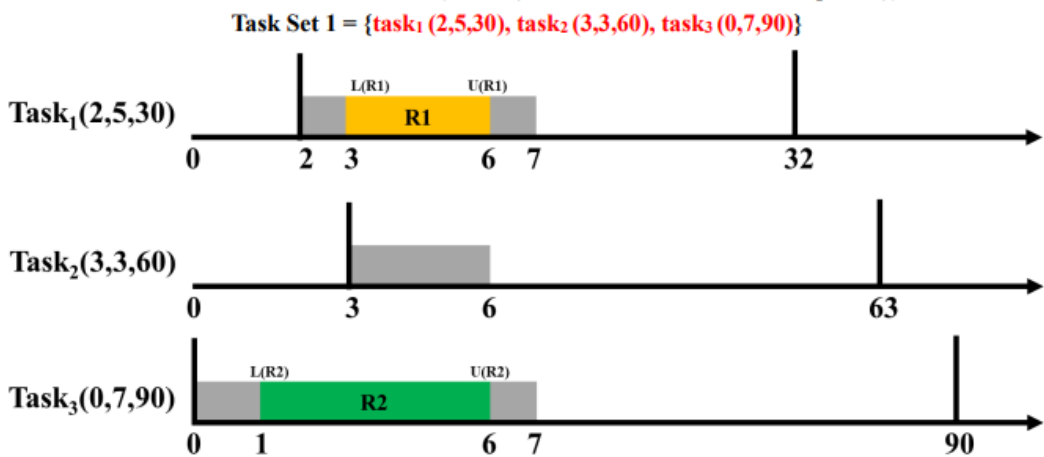
### PA\_3

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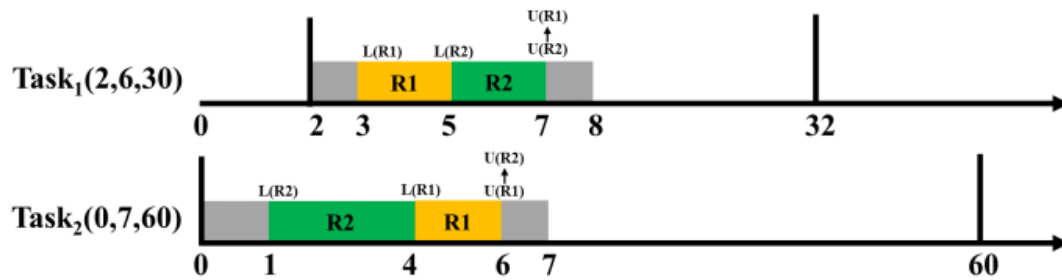
# [ PART I] NPCS Implementation [50%]

- The screenshot result (with the given format) of the two task sets. (Time tick 0-100) (10%)



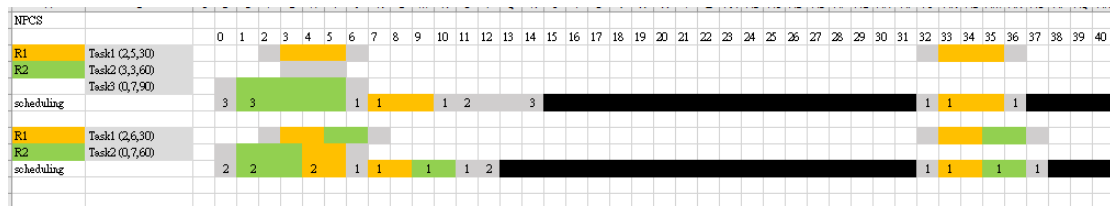
Tick	Event
0	Task 3
1	Task 3 get R2
6	Task 3 release R2
6	Task 1
7	Task 1 get R1
10	Task 1 release R1
11	Task 2
14	Task 3
15	Task 63
32	Task 1
33	Task 1 get R1
36	Task 1 release R1
37	Task 63
62	Task 1
63	Task 1 get R1
66	Task 1 release R1
67	Task 2
70	Task 63
90	Task 3
91	Task 3 get R2
96	Task 3 release R2
96	Task 1
97	Task 1 get R1
100	Task 1 release R1
101	Task 3
102	Task 63

Task Set 2 = {task<sub>1</sub> (2,6,30), task<sub>2</sub> (0,7,60)}



Tick	Event
0	Task 2
1	Task 2 get R2
4	Task 2 get R1
6	Task 2 release R1
6	Task 2 release R2
6	Task 1
7	Task 1 get R1
9	Task 1 get R2
11	Task 1 release R2
11	Task 1 release R1
12	Task 2
13	Task 63
32	Task 1
33	Task 1 get R1
35	Task 1 get R2
37	Task 1 release R2
37	Task 1 release R1
38	Task 63
60	Task 2
61	Task 2 get R2
64	Task 2 get R1
66	Task 2 release R1
66	Task 2 release R2
66	Task 1
67	Task 1 get R1
69	Task 1 get R2
71	Task 1 release R2
71	Task 1 release R1
72	Task 2
73	Task 63
92	Task 1
93	Task 1 get R1
95	Task 1 get R2
97	Task 1 release R2
97	Task 1 release R1
98	Task 63
120	Task 2
121	Task 2 get R2

- A report that describes your implementation, including scheduling results of two task sets, modified functions, data structure, etc. (please **ATTACH** the screenshot of the code and **MARK** the modified part). (40%)



上次 RMS 的實現條列說明：

#### 1. 在OS\_TCB中新增變數

INT32U begin\_ready\_time; //紀錄task變ready的時間點

INT32U response; //反應時間

INT32U arrival; //到達時間

INT32U execution; //執行時間

INT32U period; //週期

INT32U job\_id; //工作次數

2. 在OSTimeTick中去察看目前的ReadyTable有哪些Task正在Ready狀態，把所有正在Ready且不是目前正在執行的task的所有task的response都加一，因為task正在Ready卻沒有被執行表示被延後了一個tick，response一開始初始值是週期內的執行時間，所以task工作執行只要沒有執行滿response的時間就會一直卡在while迴圈內。
3. Task執行完會執行OS\_Sched()去切換給下個Task，所以在OS\_Sched()中顯示完成的字串。
4. 當TimeTick中斷產生之後會進OSIntExit()把低優先權的task中斷給高優先權的task，所以在這裡顯示中斷狀態的字串。
5. 當有task已經快要完成時有可能會被其他優先權高的task給搶占，所以會在OSIntExit()增加判斷程式迴避掉那次的context switch，讓快要做完的task先完成它的工作。
6. 當有一個task完成了一個周期內的工作後要做下個週期的工作時因為不會進入OS\_Sched()做context switch，所以在OSTimeDly(0)時表示task的反應時間等於週期，在OSTimeDly內去print完成的字串。
7. 判斷是否有task已經miss deadline，只要在OSTimeTick中去判斷reponse是否大於period，表示說反應時間已經大於週期就是miss deadline。

NPCS 的實現條列說明：

1. 在OS\_TCB中新增變數

```
INT32U deadline; //EDF的最後期限
```

```
INT32U runtime; //執行了多久
```

2. 在ucos\_ii.h中新增OS\_EXT OS\_EVENT \*Jack\_event\_Tbl[OS\_LOWEST\_PRIO + 1u]，記錄所有 mutex event。

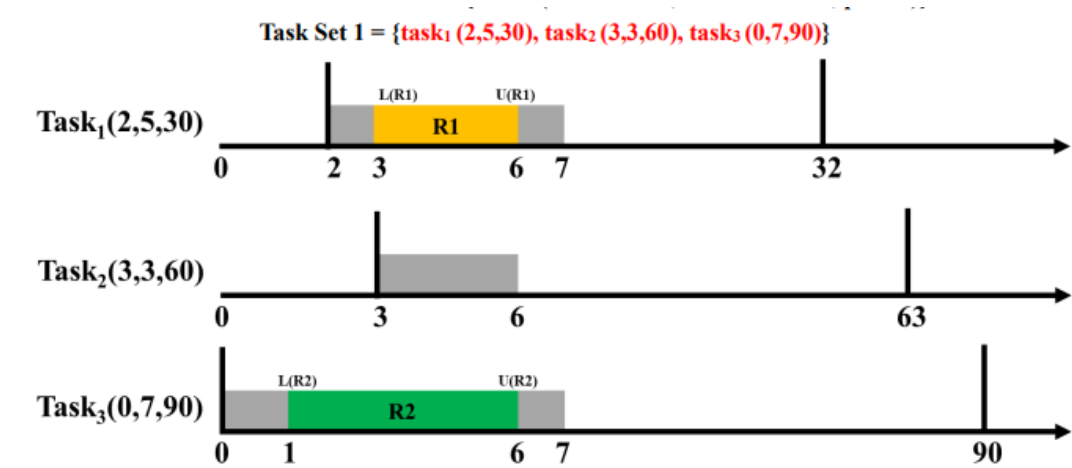
3. 在OSTimeTick()中當前工作的 task 的 runtime 就加 1。

4. 在OSIntExit()和OS\_Sched()中會做 context switch，在做之前先做判斷，判斷 Jack\_event\_Tbl 中當前 task 是否有占用任何資源，若有占用到資源就迴避不做 context switch。

➤ 程式截圖部分跟 CPP 的程式截圖整合在一起

[ PART II] CPP Implementation [40%]

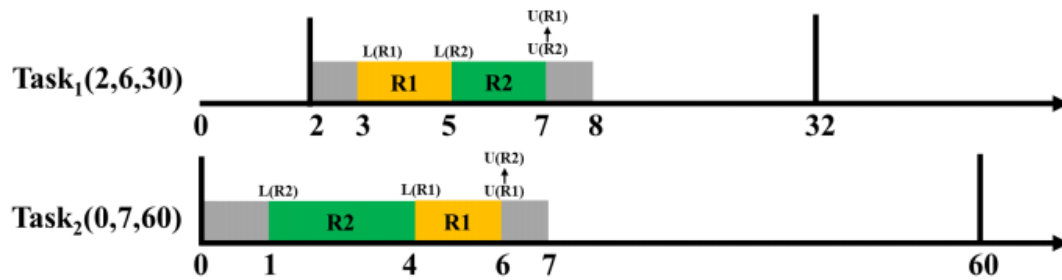
- The screenshot result (with the given format) of the two task sets. (Time tick 0-100) (10%)



選取 C:\Users\You-Quan\Desktop\嵌入式系統實習\PA3\Micrium\_Win32

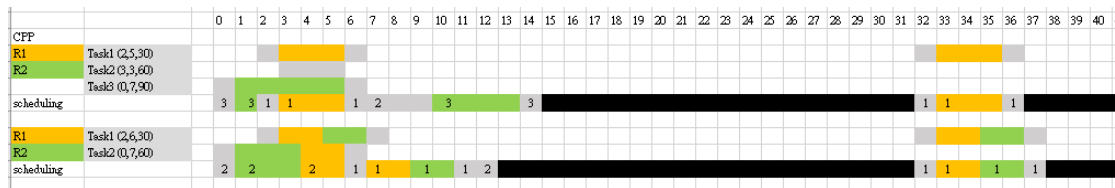
Tick	Event	Prio_Inheritance
0	Task 3	
1	Task 3 get R2	5>>4
2	Task 1	
3	Task 1 get R1	2>>1
6	Task 1 release R1	1>>2
7	Task 2	
10	Task 3	
14	Task 3 release R2	4>>5
15	Task 63	
32	Task 1	
33	Task 1 get R1	2>>1
36	Task 1 release R1	1>>2
37	Task 63	
62	Task 1	
63	Task 1 get R1	2>>1
66	Task 1 release R1	1>>2
67	Task 2	
70	Task 63	
90	Task 3	
91	Task 3 get R2	5>>4
92	Task 1	
93	Task 1 get R1	2>>1
96	Task 1 release R1	1>>2
97	Task 3	
101	Task 3 release R2	4>>5
102	Task 63	

Task Set 2 = {task<sub>1</sub> (2,6,30), task<sub>2</sub> (0,7,60)}



Tick	Event	Prio_Inheritance
0	Task 2	
1	Task 2 get R2	4>>2
4	Task 2 get R1	2>>1
6	Task 2 release R1	1>>2
6	Task 2 release R2	2>>4
6	Task 1	
7	Task 1 get R1	3>>1
9	Task 1 get R2	1>>1
11	Task 1 release R2	1>>1
11	Task 1 release R1	1>>3
12	Task 2	
13	Task 63	
32	Task 1	
33	Task 1 get R1	3>>1
35	Task 1 get R2	1>>1
37	Task 1 release R2	1>>1
37	Task 1 release R1	1>>3
38	Task 63	
60	Task 2	
61	Task 2 get R2	4>>2
64	Task 2 get R1	2>>1
66	Task 2 release R1	1>>2
66	Task 2 release R2	2>>4
66	Task 1	
67	Task 1 get R1	3>>1
69	Task 1 get R2	1>>1
71	Task 1 release R2	1>>1
71	Task 1 release R1	1>>3
72	Task 2	
73	Task 63	
92	Task 1	
93	Task 1 get R1	3>>1
95	Task 1 get R2	1>>1
97	Task 1 release R2	1>>1
97	Task 1 release R1	1>>3
98	Task 63	
120	Task 2	
121	Task 2 get R2	4>>2

- A report that describes your implementation, including scheduling results of two task sets, modified functions, data structure, etc. (please **ATTACH** the screenshot of the code and **MARK** the modified part). (30%)



CPP 實現方式條列說明：

1. 根據 NPCS 再進行後續的追加實現 CPP。
2. 在 OSIntExit()和 OS\_Sched()中會做 context switch，在做之前先做判斷，判斷 Jack\_event\_Tbl 中當前 task 占用的資源中，若有占用的資源的優先權高於下個要切換的 task 的話，就迴避不做這次的 context switch。

## Main.c

```

61 static OS_STK StartupTaskStk[APP_CFG_STARTUP_TASK_STK_SIZE];
62
63 #define TASK_STACKSIZE 2048
64
65 static OS_STK Task1_STK[TASK_STACKSIZE];
66 static OS_STK Task2_STK[TASK_STACKSIZE];
67 static OS_STK Task3_STK[TASK_STACKSIZE];
68
69 #define TASK1_ID 1 //定義task1的id、priority、arrival、execution、period
70 #define TASK1_PRIORITY 3
71 #define TASK1_ARRIVAL 2
72 #define TASK1_EXECUTION 6
73 #define TASK1_PERIOD 30
74
75 #define TASK2_ID 2 //定義task2的id、priority、arrival、execution、period
76 #define TASK2_PRIORITY 4
77 #define TASK2_ARRIVAL 0
78 #define TASK2_EXECUTION 7
79 #define TASK2_PERIOD 60
80
81 /*#define TASK3_ID 3 //定義task3的id、priority、arrival、execution、period
82 #define TASK3_PRIORITY 5
83 #define TASK3_ARRIVAL 0
84 #define TASK3_EXECUTION 7
85 #define TASK3_PERIOD 90*/
86
87 //R1的ID為1 R2的ID為2
88 #define R1_ID 1
89 #define R1_PRIO 1
90 #define R2_ID 2
91 #define R2_PRIO 2
92
93 OS_EVENT* R1;
94 OS_EVENT* R2;

```



```

151  □ #ifndef TASK1_ID //假如task1有被定義的話 就創建task1工作
152      OSTaskCreateExt(task1,
153          0,
154          &Task1_STK[TASK_STACKSIZE - 1u],
155          TASK1_PRIORITY,
156          TASK1_ID,
157          &Task1_STK[0u],
158          TASK_STACKSIZE,
159          0u,
160          (OS_TASK_OPT_STK_CHK | OS_TASK_OPT_STK_CLR),
161          TASK1_ARRIVAL,
162          TASK1_EXECUTION,
163          TASK1_PERIOD);
164  #endif // TASK1_ID
165
166
167  □ #ifndef TASK2_ID //假如task2有被定義的話 就創建task2工作
168      OSTaskCreateExt(task2,
169          0,
170          &Task2_STK[TASK_STACKSIZE - 1u],
171          TASK2_PRIORITY,
172          TASK2_ID,
173          &Task2_STK[0u],
174          TASK_STACKSIZE,
175          0u,
176          (OS_TASK_OPT_STK_CHK | OS_TASK_OPT_STK_CLR),
177          TASK2_ARRIVAL,
178          TASK2_EXECUTION,
179          TASK2_PERIOD);
180  #endif // TASK2_ID
181

```

```

182  □ #ifndef TASK3_ID //假如task3有被定義的話 就創建task3工作
183      OSTaskCreateExt(task3,
184          0,
185          &Task3_STK[TASK_STACKSIZE - 1u],
186          TASK3_PRIORITY,
187          TASK3_ID,
188          &Task3_STK[0u],
189          TASK_STACKSIZE,
190          0u,
191          (OS_TASK_OPT_STK_CHK | OS_TASK_OPT_STK_CLR),
192          TASK3_ARRIVAL,
193          TASK3_EXECUTION,
194          TASK3_PERIOD);
195  #endif // TASK3_ID
196
197      INT8U err;
198      R1 = Jack_OSMutexCreate(R1_PRIO, &err, R1_ID);
199      R2 = Jack_OSMutexCreate(R2_PRIO, &err, R2_ID);
200
201      OSTimeSet(0); //重新歸零timetick
202

```

```
250 void mywait(int tick)
251 {
252     #if OS_CRITICAL_METHOD == 3
253         OS_CPU_SR cpu_sr = 0;
254     #endif
255
256     int now, exit;
257     OS_ENTER_CRITICAL();
258     now = OSTCBCur->runtime; //now 為目前task執行多久的時間點
259     exit = now + tick; //exit 為now加等待多久tick
260     OS_EXIT_CRITICAL();
261     while (1)
262     {
263         //OSTCBCur->runtime會在只有在當前task在執行時才會加時間
264         //exit只要小於等於runtime時就會跳出迴圈
265         if (exit <= OSTCBCur->runtime)
266             break;
267     }
268 }
```

```

270 void task1(void* p_arg) //task1的執行程式
271 {
272     (void)p_arg;
273     INT8U err;
274
275     while (1)
276     {
277         //假如task開始執行時 還沒到達arrival time那就執行 OSTimeDly休息相差的時間
278         if (OSTCBCur->arrival > OSTimeGet())
279         {
280             OSTimeDly(OSTCBCur->arrival - OSTimeGet());
281         }
282         else
283         {
284             while (1)
285             {
286                 //第一小題的題目設定
287                 /*mywait(1);
288
289                 OSMutexPend(R1, 0, &err);
290                 mywait(3);
291
292                 OSMutexPost(R1);
293                 mywait(1);
294
295                 //printf("task 1 sleep %d\n", OSTCBCur->deadline - OSTimeGet());
296                 OSTimeDly(OSTCBCur->deadline - OSTimeGet());*/
297
298
299                 //第二小題的題目設定
300                 mywait(1);
301
302                 OSMutexPend(R1, 0, &err);
303                 mywait(2);
304
305                 OSMutexPend(R2, 0, &err);
306                 mywait(2);
307
308                 OSMutexPost(R2);
309                 OSMutexPost(R1);
310                 mywait(1);
311
312                 OSTimeDly(OSTCBCur->deadline - OSTimeGet());
313             }
314         }
315     }
316 }

```

```

317
318 void task2(void* p_arg) // task2的執行程式
319 {
320     (void)p_arg;
321     INT8U err;
322
323     while (1)
324     {
325         //假如task開始執行時 還沒到達arrival time那就執行 OSTimeDly休息相差的時間
326         if (OSTCBCur->arrival > OSTimeGet())
327         {
328             OSTimeDly(OSTCBCur->arrival - OSTimeGet());
329         }
330         else
331         {
332             while (1)
333             {
334                 //第一小題的題目設定
335                 /*mywait(3);
336
337                 OSTimeDly(OSTCBCur->deadline - OSTimeGet());*/
338
339                 //第二小題的題目設定
340                 mywait(1);
341
342                 OSMutexPend(R2, 0, &err);
343                 mywait(3);
344
345                 OSMutexPend(R1, 0, &err);
346                 mywait(2);
347
348                 OSMutexPost(R1);
349                 OSMutexPost(R2);
350                 mywait(1);
351
352                 OSTimeDly(OSTCBCur->deadline - OSTimeGet());
353             }
354         }
355     }
356 }
357
358
359

```

```

360 void task3(void* p_arg) //task3的執行程式
361 {
362     (void)p_arg;
363     INT8U err;
364
365     while (1)
366     {
367         //假如task開始執行時 還沒到達arrival time那就執行 OSTimeDly休息相差的時間
368         if (OSTCBCur->arrival > OSTimeGet())
369         {
370             OSTimeDly(OSTCBCur->arrival - OSTimeGet());
371         }
372         else
373         {
374             while (1)
375             {
376                 //第一小題的題目設定
377                 mywait(1);
378
379                 OSMutexPend(R2, 0, &err);
380                 mywait(5);
381
382                 OSMutexPost(R2);
383                 mywait(1);
384
385                 OSTimeDly(OSTCBCur->deadline - OSTimeGet());
386             }
387         }
388     }
389 }
390
391
392

```

ucos\_ii.h

```

639 //在OS_TCB內新增變數
640
641 INT32U begin_ready_time; //紀錄task變為ready的時間點
642 INT32U response; //反應時間
643 INT32U arrival; //到達時間
644 INT32U execution; //執行時間
645 INT32U period; //週期
646 INT32U job_id; //工作次數
647 INT32U deadline; //最後期限
648 INT32U runtime; //執行了多久
649 } OS_TCB;
650

```

```

711 OS_EXT INT32U      OSCtxSwCtr;           /* Counter of number of context switches */
712
713 #if (OS_EVENT_EN) && (OS_MAX_EVENTS > 0u)
714 OS_EXT OS_EVENT    *OSEventFreeList;     /* Pointer to list of free EVENT control blocks */
715 OS_EXT OS_EVENT    OSEventTbl[OS_MAX_EVENTS]; /* Table of EVENT control blocks */
716 OS_EXT OS_EVENT    *Jack_event_Tbl[OS_LOWEST_PRIO + 1u]; //新增一個Mutex event的table
717 #endif
718
719 #if (OS_EVENT_EN) && (OS_MAX_EVENTS > 0u)
720 typedef struct os_event {
721     INT8U  OSEventType;           /* Type of event control block (see OS_EVENT_TYPE_xxxx) */
722     void    *OSEventPtr;          /* Pointer to message or queue structure */
723     INT16U  OSEventCnt;           /* Semaphore Count (not used if other EVENT type) */
724     OS_PRIO OSEventGrp;           /* Group corresponding to tasks waiting for event to occur */
725     OS_PRIO OSEventTbl[OS_EVENT_TBL_SIZE]; /* List of tasks waiting for event to occur */
726     INT8U   id; //紀錄resource的id ex: R1的ID為1、F2的ID為2
727 } os_event;
728
729 #if OS_EVENT_NAME_EN > 0u
730 INT8U *OSEventName;
731 #endif
732 } OS_EVENT;
733 #endif
734
735
736
737
738
739
740

```

## os\_cfg.h

```

24
25 #ifndef OS_CFG_H
26 #define OS_CFG_H
27
28 #define CPP //設定要用什麼樣的排程方式 #define CPP 或 #define NPCS
29 /* ----- MISCELLANEOUS ----- */
30 #define OS_APP_HOOKS_EN 1u /* Application-defined hooks are called from the uC/OS-II hooks */
31 #define OS_ARG_CHK_EN 1u /* Enable (1) or Disable (0) argument checking */
32 #define OS_CPU_HOOKS_EN 1u /* uC/OS-II hooks are found in the processor port files */
33
34 #define OS_DEBUG_EN 1u /* Enable(1) debug variables */
35
36 #define OS_EVENT_MULTI_EN 1u /* Include code for OSEventPendMulti() */
37 #define OS_EVENT_NAME_EN 1u /* Enable names for Sem, Mutex, Mbox and Q */
38
39 #define OS_LOWEST_PRIO 63u /* Defines the lowest priority that can be assigned ... */
40 /* ... MUST NEVER be higher than 254! */
41
42 #define OS_MAX_EVENTS 10u /* Max. number of event control blocks in your application */
43 #define OS_MAX_FLAGS 5u /* Max. number of Event Flag Groups in your application */
44 #define OS_MAX_MEM_PART 5u /* Max. number of memory partitions */
45 #define OS_MAX_QS 4u /* Max. number of queue control blocks in your application */
46 #define OS_MAX_TASKS 20u /* Max. number of tasks in your application, MUST be >= 2 */
47
48 #define OS_SCHED_LOCK_EN 1u /* Include code for OSSchedLock() and OSSchedUnlock() */
49
50 #define OS_TICK_STEP_EN 1u /* Enable tick stepping feature for uC/OS-View */
51 #define OS_TICKS_PER_SEC 1u /* Set the number of ticks in one second */
52
53 #define OS_TLS_TBL_SIZE 0u /* Size of Thread-Local Storage Table */
54

```

## os\_task.c

```
349 INT8U OSTaskCreateExt (void (*task)(void *p_arg),
350                        void *p_arg,
351                        OS_STK *pTos,
352                        INT8U prio,
353                        INT16U id,
354                        OS_STK *pTos,
355                        INT32U stk_size,
356                        void *pext,
357                        INT16U opt,
358                        INT32U arrival,
359                        INT32U execution,
360                        INT32U period) //在OSTaskCreateExt內新增變數 arrival\execution\period
361 {
362     OS_STK *psp;
363     INT8U err;
364     #if OS_CRITICAL_METHOD == 3u /* Allocate storage for CPU status register */
365     OS_CPU_SR cpu_sr = 0u;
366     #endif
367
368     #ifdef OS_SAFETY_CRITICAL_IEC61508
369     if (OSSafetyCriticalStartFlag == OS_TRUE) {
370         OSSafetyCriticalException();
371         return (OS_ERR_ILLEGAL_CREATE_RUN_TIME);
372     }
373     #endif
374
375     #if OS_ARG_CHK_EN > 0u
376     if (prio > OS_LOWEST_PRIO) { /* Make sure priority is within allowable range */
377         return (OS_ERR_PRIO_INVALID);
378     }
379     #endif
380
381     OS_ENTER_CRITICAL();
382     if (OSIntNesting > 0u) { /* Make sure we don't create the task from within an ISR */
383         OS_EXIT_CRITICAL();
384         return (OS_ERR_TASK_CREATE_ISR);
385     }
386
387     if (OSTCBPrioTbl[prio] == (OS_TCB *)0) { /* Make sure task doesn't already exist at this priority */
388         OSTCBPrioTbl[prio] = OS_TCB_RESERVED; /* Reserve the priority to prevent others from doing ... */
389         /* ... the same thing until task is created. */
390         OS_EXIT_CRITICAL();
391     }
392     #if (OS_TASK_STAT_STK_CHK_EN > 0u)
393     OS_TaskStkClr(pTos, stk_size, opt); /* Clear the task stack (if needed) */
394     #endif
395
396     psp = OSTaskStkInit(task, p_arg, pTos, opt); /* Initialize the task's stack */
397     err = OSTCBInit(prio, psp, pTos, id, stk_size, pext, opt, arrival, execution, period); //在OSTCBInit內新增變數 arrival\execution\period
```

## os\_core.c

```
938 void OSStart (void)
939 {
940     if (OSRunning == OS_FALSE) {
941         #ifdef NPCS
942         printf("Tick\tEvent\n");
943         #endif // NPCS
944
945         #ifdef CPP
946         printf("Tick\tEvent\t\t\tPrio_Inheritance\n");
947         #endif // CPP
948
949         OS_SchedNew(); /* Find highest priority's task priority number */
950         OSPrioCur = OSPrioHighRdy;
951         OSTCBHighRdy = OSTCBPrioTbl[OSPrioHighRdy]; /* Point to highest priority task ready to run */
952         OSTCBCur = OSTCBHighRdy;
953         OSStartHighRdy(); /* Execute target specific code to start task */
954     }
955 }
956
```

```

2231     INT8U  OS_TCBInit (INT8U   prio,
2232                      OS_STK *ptos,
2233                      OS_STK *pbos,
2234                      INT16U   id,
2235                      INT32U   stk_size,
2236                      void *pext,
2237                      INT16U   opt,
2238                      INT32U   arrival,
2239                      INT32U   execution,
2240                      INT32U   period) //在OS_TCBInit內新增變數 arrival~execution~period
2241 {
2242     OS_TCB *ptcb;
2243     #if OS_CRITICAL_METHOD == 3u /* Allocate storage for CPU status register */
2244     OS_CPU_SR cpu_sr = 0u;
2245     #endif
2246     #if OS_TASK_REG_TBL_SIZE > 0u
2247     INT8U i;
2248     #endif
2249     #if OS_TASK_CREATE_EXT_EN > 0u
2250     #if defined(OS_TL_S_TBL_SIZE) && (OS_TL_S_TBL_SIZE > 0u)
2251     INT8U j;
2252     #endif
2253     #endif
2254
2255     OS_ENTER_CRITICAL();
2256     ptcb = OSTCBFreeList; /* Get a free TCB from the free TCB list */
2257     if (ptcb != (OS_TCB *)0) {
2258         OSTCBFreeList = ptcb->OSTCBNext; /* Update pointer to free TCB list */
2259         OS_EXIT_CRITICAL();
2260
2261         ptcb->begin_ready_time = arrival; //初始化在OS_TCB內新增的變數
2262         ptcb->response = execution;
2263         ptcb->arrival = arrival;
2264         ptcb->execution = execution;
2265         ptcb->period = period;
2266         ptcb->job_id = 0;
2267         ptcb->deadline = arrival + period;
2268         ptcb->runtime = 0;
2269

```



```

1061 //這段是加在OSTimeTick內
1062 //從ReadyTable得到目前正在Ready的task
1063 //把現在正在Ready但沒有在執行的task的反應時間加一
1064 for (INT8U y = 0; y < 8; y++) //jack
1065 {
1066     for (INT8U x = 0; x < 8; x++)
1067     {
1068         if ((OSRdyTbl[y] & (INT8U)1 << x) == (INT8U)1 << x) //確認是有有Ready
1069         {
1070             INT8U prio = (y << 3u) + x;
1071             if (prio != OS_TASK_IDLE_PRIO)
1072             {
1073                 if (OSTCBPrioTbl[prio] != OSTCBCur && OSTimeGet() > OSTCBPrioTbl[prio]->arrival)
1074                 {
1075                     OSTCBPrioTbl[prio]->response += 1;
1076
1077                     //假設反應時間 大於週期 表示說task已經missdeadline了
1078                     if (OSTCBPrioTbl[prio]->response > OSTCBPrioTbl[prio]->period)
1079                     {
1080                         printf("%d\t MissDeadline\t Task(%d)(%d)\t\t\t -----<div>
1081                         OSTCBPrioTbl[prio]->OSTCBId, OSTCBPrioTbl[prio]->job_id);
1082                         while (1) {}
1083                     }
1084                 }
1085             }
1086
1087             //只要是面前正在執行的task，runtime加1
1088             if (OSTCBPrioTbl[prio] == OSTCBCur)
1089             {
1090                 OSTCBCur->runtime += 1;
1091             }
1092         }
1093     }
1094 }
1095
1096

```

OSTimeTick()

```

1112 ptcb = OSTCBLst; /* Point at first TCB in TCB list */
1113 while (ptcb->OSTCBPrio != OS_TASK_IDLE_PRIO) { /* Go through all TCBs in TCB list */
1114     OS_ENTER_CRITICAL();
1115     if (ptcb->OSTCDBly != 0u) { /* No, Delayed or waiting for event with TO */
1116         ptcb->OSTCDBly--; /* Decrement nbr of ticks to end of delay */
1117         if (ptcb->OSTCDBly == 0u) { /* Check for timeout */
1118
1119             if ((ptcb->OSTCBStat & OS_STAT_PEND_ANY) != OS_STAT_RDY) {
1120                 ptcb->OSTCBStat &= (INT8U)~(INT8U)OS_STAT_PEND_ANY; /* Yes, Clear status flag */
1121                 ptcb->OSTCBStatPend = OS_STAT_PEND_TO; /* Indicate PEND timeout */
1122             } else {
1123                 ptcb->OSTCBStatPend = OS_STAT_PEND_OK;
1124             }
1125
1126             if ((ptcb->OSTCBStat & OS_STAT_SUSPEND) == OS_STAT_RDY) { /* Is task suspended? */
1127                 OSRdyGrp |= ptcb->OSTCBBitY; /* No, Make ready */
1128                 OSRdyTbl[ptcb->OSTCBY] |= ptcb->OSTCBBitX;
1129
1130                 //這段是加在OSTimeTick內
1131                 //當某個task轉變為Ready的時間 設定變數數值
1132                 ptcb->begin_ready_time = OSTimeGet(); //begin_ready_time是task轉變為Ready的時間點
1133                 ptcb->response = ptcb->execution;
1134                 ptcb->OSTCBctxSwCtr = 0; //context switch次數設為0
1135                 ptcb->deadline = (ptcb->job_id + 1) * ptcb->period + ptcb->arrival; //jack
1136                 ptcb->runtime = 0;
1137
1138                 OS_TRACE_TASK_READY(ptcb);
1139             }
1140         }
1141     }
1142     ptcb = ptcb->OSTCBNext; /* Point at next TCB in TCB list */
1143     OS_EXIT_CRITICAL();
1144 }
1145
1146
1147

```

OSTimeTick()

```

1839 void OS_Sched (void)
1840 {
1841     #if OS_CRITICAL_METHOD == 3u /* Allocate storage for CPU status register
1842         OS_CPU_SR Cpu_sr = 0u;
1843     #endif
1844
1845     OS_ENTER_CRITICAL();
1846     if (OSIntNesting == 0u) { /* Schedule only if all ISRs done and ...
1847         if (OSLockNesting == 0u) { /* ... scheduler is not locked
1848             OS_SchedNew();
1849             OSTCBHighRdy = OSTCBPrioTbl[OSPrioHighRdy];
1850
1851             INT8U sw = 1; //紀錄是否要context switch
1852
1853             //遍歷所有Jack_event_Tbl表
1854             //查看是否有當前task使用的資源的優先權比OSTCBHighRdy還高
1855             for (int i = 0; i < 64; i++)
1856             {
1857                 if (Jack_event_Tbl[i] != (OS_EVENT*)0)
1858                 {
1859                     if ((Jack_event_Tbl[i]->OSEventCnt & 0x00FF) == OSPrioCur)
1860                     {
1861                         #ifdef NPCS
1862                         //排程為NPCS時執行這段
1863                         //只要有使用任一資源就不做context switch
1864                         if ((Jack_event_Tbl[i]->OSEventCnt >> 8) != 0x00)
1865                         {
1866                             sw = 0;
1867                             OSPrioHighRdy = OSPrioCur;
1868                             OSTCBHighRdy = OSTCBCur;
1869                         }
1870                     }
1871                 }
1872             }
1873             #endif // NPCS
1874             #ifdef CPP
1875             //排程為CPP時執行這段
1876             //只要當前task使用的資源的優先權比OSTCBHighRdy還高就不做context switch
1877             if ((Jack_event_Tbl[i]->OSEventCnt >> 8) <= OSPrioHighRdy)
1878             {
1879                 sw = 0;
1880                 OSPrioHighRdy = OSPrioCur;
1881                 OSTCBHighRdy = OSTCBCur;
1882             }
1883             #endif // CPP
1884         }
1885     }
1886

```

```

1887     if (sw == 1) //是否做context switch
1888     {
1889         if (OSPrioHighRdy != OSPrioCur) { /* No Ctx Sw if current task is highest rdy */
1890
1891             //顯示下個要執行的task
1892             if (OSPrioHighRdy == OS_TASK_IDLE_PRIO)
1893                 printf("%d\t\tTask %d\n", OSTimeGet(), OS_TASK_IDLE_PRIO);
1894             else if (OSTimeGet() >= OSTCBHighRdy->arrival)
1895                 printf("%d\t\tTask %d\n", OSTimeGet(), OSTCBHighRdy->OSTCBId);
1896
1897             if (OSTimeGet() > OSTCBCur->arrival)
1898             {
1899                 OSTCBCur->OSTCBCtxSwCtr++; //OSTCBCtxSwCtr加一
1900
1901                 //task完成之後會執行OS_Sched所以在這裡print完成
1902                 //假設是task完成後切入idle task，print的方式會不一樣
1903                 /*if(OSTCBHighRdy->OSTCBPrio == OS_TASK_IDLE_PRIO)
1904                     printf("%d\t\tCompletion\t task(%d)(%d)\t\t\t task(%d) \t\t %d\t\t\t\t %d\n", OSTimeGet(),
1905                             OSTCBCur->OSTCBId, OSTCBCur->job_id,
1906                             OS_TASK_IDLE_PRIO,
1907                             OSTimeGet() - OSTCBCur->begin_ready_time, OSTCBCur->OSTCBCtxSwCtr);
1908                 else
1909                     printf("%d\t\tCompletion\t task(%d)(%d)\t\t\t task(%d) \t\t %d\t\t\t\t %d\n", OSTimeGet(),
1910                             OSTCBCur->OSTCBId, OSTCBCur->job_id,
1911                             OSTimeGet() - OSTCBCur->begin_ready_time, OSTCBCur->OSTCBCtxSwCtr);
1912                 */
1913             }
1914         }
1915     }
1916 }

```

OS\_Sched()

```

696 void OSIntExit(void)
697 {
698     #if OS_CRITICAL_METHOD == 3u                      /* Allocate storage for CPU status register */
699         OS_CPU_SR Cpu_sr = 0u;
700     #endif
701
702     if (OSRunning == OS_TRUE) {
703         OS_ENTER_CRITICAL();
704         if (OSIntNesting > 0u) {                      /* Prevent OSIntNesting from wrapping */
705             OSIntNesting--;
706         }
707         if (OSIntNesting == 0u) {                      /* Reschedule only if all ISRs complete ... */
708             if (OSLockNesting == 0u) {                /* ... and not locked. */
709
710                 //加這行if判斷是為了迴避當有task已經快要完成時被其他優先權高的task給搶占
711                 //迴避掉這次切換讓原本的task先做完
712                 if (OSTimeGet() - OSTCBCur->begin_ready_time != OSTCBCur->response)
713                 {
714                     OS_SchedNew();
715                     OSTCBHighRdy = OSTCBPrioTbl[OSPrioHighRdy];
716
717                     INT8U sw = 1; //紀錄是否要Context switch
718
719                     //遍歷所有Jack_event_Tbl表
720                     //查看是否有當前task使用的資源的優先權比OSTCBHighRdy還高
721                     for (int i = 0; i < 64; i++)
722                     {
723                         if (Jack_event_Tbl[i] != (OS_EVENT*)0)
724                         {
725                             if ((Jack_event_Tbl[i]->OSEventCnt & 0x00FF) == OSPrioCur)
726                             {
727                                 //排程為NPCS時執行這段
728                                 //只要有使用任一資源就不做context switch
729                                 if ((Jack_event_Tbl[i]->OSEventCnt >> 8) != 0x00)
730                                 {
731                                     sw = 0;
732                                     OSPrioHighRdy = OSPrioCur;
733                                     OSTCBHighRdy = OSTCBCur;
734                                 }
735                             }
736                         }
737                     }
738                     #endif // NPCS
739
740                     //排程為CPP時執行這段
741                     //只要當前task使用的資源的優先權比OSTCBHighRdy還高就不做context switch
742                     if ((Jack_event_Tbl[i]->OSEventCnt >> 8) <= OSPrioHighRdy)
743                     {
744                         sw = 0;
745                         OSPrioHighRdy = OSPrioCur;
746                         OSTCBHighRdy = OSTCBCur;
747                     }
748                 }
749
750                 if (sw == 1) //確認是否要做context switch
751                 {
752                     if (OSPrioHighRdy != OSPrioCur) { /* No Ctx Sw if current task is highest rdy */
753
754                         //顯示下個要執行的task
755                         if (OSPrioHighRdy == OS_TASK_IDLE_PRIO)
756                             printf("%d\tTask %d\n", OSTimeGet(), OS_TASK_IDLE_PRIO);
757                         else
758                             printf("%d\tTask %d\n", OSTimeGet(), OSTCBHighRdy->OSTCBId);
759
760                         OSTCBCur->OSTCBCtxSwCtr++; //OSTCBCtxSwCtr加一
761
762                         //OSIntExit是在time tick中斷後會做，低優先權task會被高優先權task搶占，所以在這裡print搶占
763                         //假設是idle task被搶占，print的方式會不一樣
764                         /*if (OSTCBCur->OSTCBPrio == OS_TASK_IDLE_PRIO)
765                             printf("%d\t Preemption\t task(%d) \t\t task(%d)(%d)\n", OSTimeGet(),
766                                     OS_TASK_IDLE_PRIO,
767                                     OSTCBHighRdy->OSTCBId, OSTCBHighRdy->job_id);
768                         else
769                             printf("%d\t Preemption\t task(%d)(%d)\t\t task(%d)(%d)\n", OSTimeGet(),
770                                     OSTCBCur->OSTCBId, OSTCBCur->job_id,
771                                     OSTCBHighRdy->OSTCBId, OSTCBHighRdy->job_id);*/
772                     }
773                 }
774             }
775         }
776     }
777 }

```

## os\_time.c

```
55 void OSTimeDly (INT32U ticks)
56 {
57     INT8U    y;
58     #if OS_CRITICAL_METHOD == 3u           /* Allocate storage for CPU status register */
59     OS_CPU_SR Cpu_sr = 0u;
60     #endif
61
62     if (ticks > 0u && OSTCBCur->arrival < OSTimeGet())
63     {
64         //task初始化參數
65         OSTCBCur->begin_ready_time = OSTimeGet();
66         OSTCBCur->response = OSTCBCur->execution;
67         OSTCBCur->OSTCBCtxSwCtr = 0;
68
69         //工作次數+1
70         OSTCBCur->job_id += 1;
71
72         OSTCBCur->deadline = (OSTCBCur->job_id + 1) * OSTCBCur->period + OSTCBCur->arrival;
73     }
74 }
```

```
95 //當發生直行 OSTimeDly(0) 的情況表示反應時間剛好是週期時間
96 //task已經完成這次週期的工作要做下個週期的工作
97 if (OSTCBCur->period == OSTCBCur->response)
98 {
99     //print這次週期的工作完成 輪到下個週期的工作開始
100     /*printf("Completion\t task(%d)(%d)\t\t task(%d)(%d)\t\t %d\t\t %d\n", OSTimeGet(),
101             OSTCBCur->OSTCBIId, OSTCBCur->job_id,
102             OSTCBCur->OSTCBIId, OSTCBCur->job_id + 1,
103             OSTimeGet() - OSTCBCur->begin_ready_time, OSTCBCur->OSTCBCtxSwCtr);*/
104
105     //初始化task的OS_TCB參數
106     OSTCBCur->begin_ready_time = OSTimeGet();
107     OSTCBCur->response = OSTCBCur->execution;
108     OSTCBCur->OSTCBCtxSwCtr = 0;
109
110     //工作次數+1
111     OSTCBCur->job_id += 1;
112 }
113 }
114 }
```

OSTimeDly()

## os\_cpu.c.c

```
624
625 #if (OS_MSG_TRACE > 0u)
626     //OS_Printf("Task[%3.id] created, Thread ID %5.0d\n", p_tcb->OSTCBPrio, p_stk->ThreadID); //因為作業不需要print這行 所以註解掉這行
627 #endif
628
```

## os\_mutex.c

```
306
307     pevent = OSEventFreeList;                                /* Get next free event control block */
308     if (pevent == (OS_EVENT*)0) {                             /* See if an ECB was available */
309         if (prio != OS_PRIO_MUTEX_CEIL_DIS) {
310             OSTCBPrioTbl[prio] = (OS_TCB*)0;                /* No, Release the table entry */
311         }
312         OS_EXIT_CRITICAL();
313         *perr = OS_ERR_PEVENT_NULL;
314         return (pevent);
315     }
316     OSEventFreeList = (OS_EVENT*)OSEventFreeList->OSEventPtr; /* Adjust the free list */
317     OS_EXIT_CRITICAL();
318     pevent->OSEventType = OS_EVENT_TYPE_MUTEX;
319     pevent->OSEventCnt = (INT16U)((INT16U)prio << 8u) | OS_MUTEX_AVAILABLE; /* Resource is avail. */
320     pevent->OSEventPtr = (void*)0;                             /* No task owning the mutex */
321     pevent->Id = Id;
322     Jack_event_Tbl[id] = pevent; //將mutex的記憶體位置放入Jack_event_Tbl中
323     #if OS_EVENT_NAME_EN > 0u
324     pevent->OSEventName = (INT8U*)(void*)"??";
325     #endif
326 }

327
328
329     pcp = (INT8U)(pevent->OSEventCnt >> 8u);                /* Get PCP from mutex */
330     /* Is Mutex available? */
331     if ((INT8U)(pevent->OSEventCnt & OS_MUTEX_KEEP_LOWER_8) == OS_MUTEX_AVAILABLE) {
332         pevent->OSEventCnt &= OS_MUTEX_KEEP_UPPER_8;        /* Yes, Acquire the resource */
333         pevent->OSEventCnt |= OSTCBCur->OSTCBPrio;           /* Save priority of owning task */
334         pevent->OSEventPtr = (void *)OSTCBCur;              /* Point to owning task's OS_TCB */
335         if ((pcp != OS_PRIO_MUTEX_CEIL_DIS) &&
336             (OSTCBCur->OSTCBPrio <= pcp)) {
337             OS_EXIT_CRITICAL();
338             *perr = OS_ERR_PCP_LOWER;
339             /* PCP 'must' have a SMALLER prio ...
340              * ... than current task! */
341         }
342         else {
343             OS_EXIT_CRITICAL();
344             *perr = OS_ERR_NONE;
345         }
346         OS_TRACE_MUTEX_PEND_EXIT(*perr);
347     }
348 }

349
350
351 #ifdef NIOS
352 //排程為NIOS時print
353 printf("%d\tTask %d get R%d\n", OSTimeGet(), OSTCBCur->OSTCBId, pevent->Id);
354 #endif
355
356 #ifdef CPP
357 //排程為CPP時
358 //遍歷所有Jack_event_Tbl表，查看當前task使用的資源的最高優先權
359 INT8U highestPrio = OSPrioCur;
360 for (int i = 0; i < 64; i++)
361 {
362     if (Jack_event_Tbl[i] != (OS_EVENT*)0 && Jack_event_Tbl[i] != pevent) //((OS_EVENT*)0)和當前event不判斷
363     {
364         if ((Jack_event_Tbl[i]->OSEventCnt & 0x00FF) == OSPrioCur)
365         {
366             if ((Jack_event_Tbl[i]->OSEventCnt >> 8) <= highestPrio)
367             {
368                 highestPrio = (Jack_event_Tbl[i]->OSEventCnt >> 8);
369             }
370         }
371     }
372 }
373 if((pevent->OSEventCnt >> 8) < highestPrio) //當前event的優先權比較大時
374     printf("%d\tTask %d get R%d\t\t%d>>%d\n", OSTimeGet(), OSTCBCur->OSTCBId, pevent->Id, highestPrio, pevent->OSEventCnt >> 8);
375 else if(highestPrio < OSPrioCur)
376     printf("%d\tTask %d get R%d\t\t%d>>%d\n", OSTimeGet(), OSTCBCur->OSTCBId, pevent->Id, highestPrio, highestPrio);
377 else
378     printf("%d\tTask %d get R%d\t\t%d>>%d\n", OSTimeGet(), OSTCBCur->OSTCBId, pevent->Id, OSTCBCur->OSTCBPrio, pevent->OSEventCnt >> 8);
379 #endif // CPP
380
381 return;
382 }
```

```

804 pevent->OSEventCnt != OS_MUTEX_AVAILABLE; /* No, Mutex is now available */
805 pevent->OSEventPtr = (void *)0;
806 OS_EXIT_CRITICAL();
807 OS_TRACE_MUTEX_POST_EXIT(OS_ERR_NONE);
808
809 #ifdef NPCS
810 //排程為NPCS時print
811 printf("Task %d release R%d\n", OSTimeGet(), OSTCBCur->OSTCBId, pevent->id);
812 OS_Sched();
813 #endif
814 #ifdef CPP
815 //排程為CPP時
816 //遍歷所有Jack_event_Tbl表，查看當前task使用的資源的最高優先權
817 INT8U highestPrio = OSPrCur;
818 for (int i = 0; i < 64; i++)
819 {
820     if (Jack_event_Tbl[i] != (OS_EVENT*)0 && Jack_event_Tbl[i] != pevent) //((OS_EVENT*)0 和 當前event 不判斷
821     {
822         if ((Jack_event_Tbl[i]->OSEventCnt & 0x00FF) == OSPrCur)
823         {
824             if ((Jack_event_Tbl[i]->OSEventCnt >> 8) <= highestPrio)
825             {
826                 highestPrio = (Jack_event_Tbl[i]->OSEventCnt >> 8);
827             }
828         }
829     }
830 }
831 if ((pevent->OSEventCnt >> 8) < highestPrio) //當前event的優先權比較大時
832     printf("Task %d release R%d\n", OSTimeGet(), OSTCBCur->OSTCBId, pevent->id, pevent->OSEventCnt >> 8, highestPrio);
833 else if (highestPrio < OSPrCur)
834     printf("Task %d release R%d\n", OSTimeGet(), OSTCBCur->OSTCBId, pevent->id, highestPrio, highestPrio);
835 else
836     printf("Task %d release R%d\n", OSTimeGet(), OSTCBCur->OSTCBId, pevent->id, pevent->OSEventCnt >> 8, OSTCBCur->OSTCBPrio);
837
838 OS_Sched();
839 #endif // CPP
840
841 return (OS_ERR_NONE);
842

```

## OSMutexPost()

## [ PART III] Performance Analysis [50%]

- Compare the scheduling behaviors between NPCS and CPP with the results of PART I and PART II. (5%)

[PART1]

NPCS 跟 CPP 都是根據 RM 的方式，CPP 因為資源都只有自己的 task 在用所以排程的結果就是單純以 RM 排程的結果，而 NPCS 不同的是當 task 使用到資源時直到釋放掉才可以切換到其他的 task。

[PART2]

比較看結果 NPCS 與 CPP 的結果相同，因為 CPP 兩個 task 都有用到兩個資源所以當有 task 在使用資源時就不會被其他 task 中斷，結果就如同 NPCS 一樣只要在使用資源時直到釋放掉資源才可以切換到其他 task。

- Explain how NPCS and CPP avoid the deadlock problem. (5%)

NPCS 因為當有 task 在使用到資源時就會等到他做完才能切換到其他 task，所以不會有其他 task 能夠同時想使用資源就不會發生 deadlock。

CPP 因為當 task 在使用資源時會繼承會使用到這個資源的最高 task 高一點點的優先權，只有比這個資源優先權還高的 task 才能中斷，但這些中斷的 task 不會用到同個資源，而會使用到同個資源的 task 因為無法中斷所以不會搶到同個資源，所以不會發生 deadlock。