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ENM 502-001

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## Assignment 3 Newton method and Arc-length continuation

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### Introduction

In this assignment, we would solve a non-linear boundary-value problem defined on the unit-square domain

$$\begin{aligned} D &= (0 \leq x \leq 1) \cup (0 \leq y \leq 1) \\ \nabla^2 u + \lambda u(1 + u) &= 0 \\ u(x, y) &= 0 \text{ on all boundaries,} \end{aligned}$$

with **newton method**. After we guess the initial solution on some typical  $\lambda$ , we track track and iterate  $\lambda$  from

$$0 \leq \lambda \leq 60$$

with **analytic continuation(AyC)** and **arc-length continuation(ARCLC)**.

### Problem Setup and Formulation

**Discretization and centered finite difference applied to this problem.**

We discretize the  $\Omega$  with finite difference method, in specifically a  $30 \times 30$  uniform grid.

#### Newton's Method

As a fixed-point iteration method, given a initial approximation at  $u_0$ , newton's method would approximate the solution in the derivative direction.

The iteration goes like

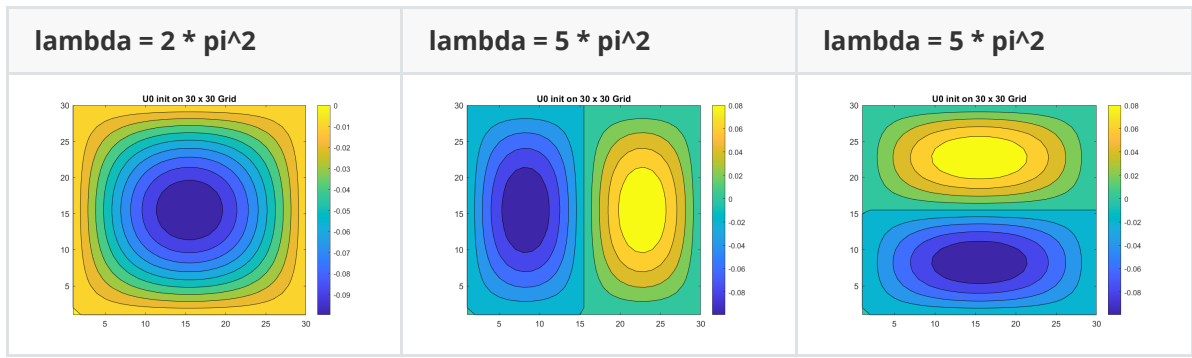
$$\mathbf{u}^{k+1} = \mathbf{u}^k + \delta \mathbf{u}^k$$

where  $\delta \mathbf{u}^k$  is calculated by

$$\mathbf{J}|_k (\partial \mathbf{u})_k = -(\partial \mathbf{R})_k$$

where  $\mathbf{J}$  is the Jacobin matrix.

For the initial value, when L2norm of  $\lambda$  is near to zero, it could be visualized as a eigen value problem. The initial value near is like



## Methods to generate first two non-trivial solutions (analytical continuation)

We would use newton's method to solve for  $u_0$  from first initial guess(see image above). To calculate  $u_1$ , we use **AyC** to calculate the initial guess  $u_{1\_guess}$ , then use newton's method to solve the solution at  $\lambda_{1\_1}$ .

## Arc-Length Continuation

During iterating the  $\lambda$ , the  $J$  would become nearly singular during turning point. To prevent this, we introduce a new independent variable  $s$ .

$$(\delta S)^2 = (\delta \lambda)^2 + \|\delta u\|_2^2$$

and start to iterate on  $s$  for the rest steps.

For each iteration, let's say we have  $u_{cur}$ ,  $\lambda_{cur}$ ,  $u_{prv}$ ,  $\lambda_{prv}$ , which is the solution of  $k - 1$ ,  $k - 2$  iteration(it's  $k$ th iteration)

during every iteration, we first use **arc-length initialization** to get initial guess, let's say it be  $u_{cur\_init}$ ,  $\lambda_{cur\_init}$ .

$$\begin{aligned} u_2^0 &= u_1 + (\delta s) \left( \frac{\partial u}{\partial s} \right)_1 \\ \lambda_2^0 &= \lambda_1 + (\delta s) \left( \frac{\partial \lambda}{\partial s} \right)_1 \end{aligned}$$

And during **arc-length initialization** \*\*, we would use  $u_{cur}$ ,  $\lambda_{cur}$  to create the Jacobin matrix.

The we would use  $u_{cur\_init}$ ,  $\lambda_{cur\_init}$  together with  $u_{prv}$ ,  $\lambda_{prv}$  to do the full newton iteration. The detailed iteration could be viewed as below.

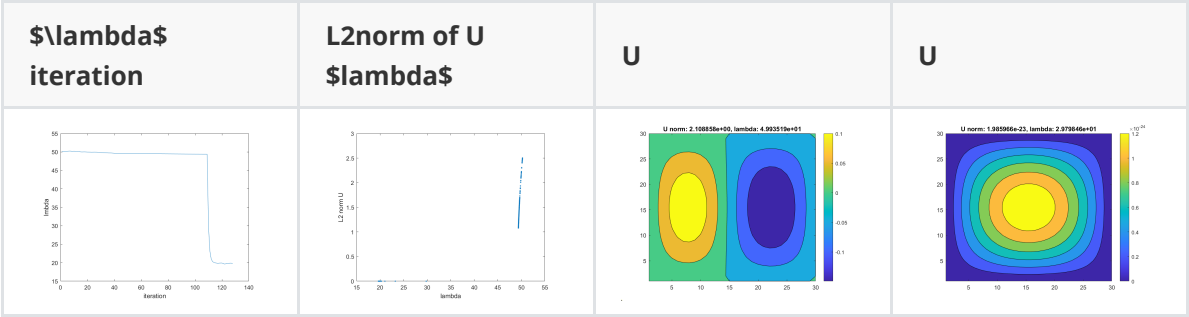
$$\begin{aligned} \left( \hat{J}^k \right) \Big|_{s2} \begin{pmatrix} \delta u^k \\ \delta \lambda^k \end{pmatrix} \Big|_{s2} &= - \left( \hat{R}^k \right) \Big|_{s2} \\ \lambda^{k+1} &= \lambda^k + \delta \lambda^k \\ u^{k+1} &= u^k + \delta u^k \end{aligned}$$

## Results and Discussion

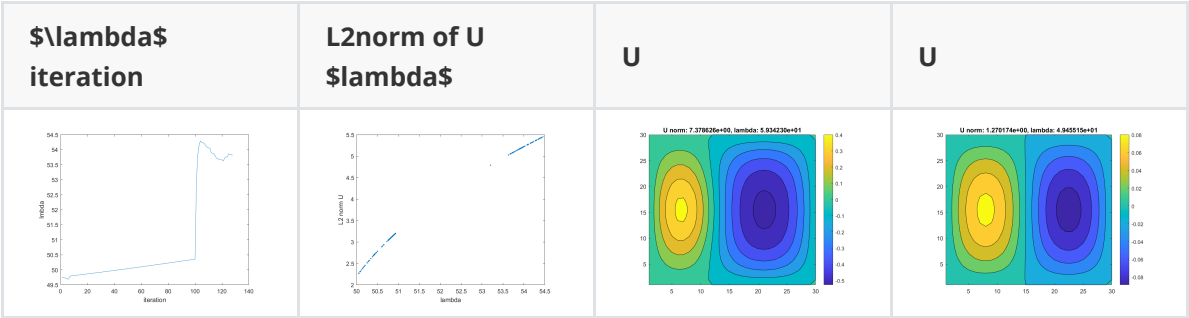
From my circumstances, I notice that with different mixture of parameters( **ARCLC** step size, initial point, etc), the results vary rapidly.

Failed cases

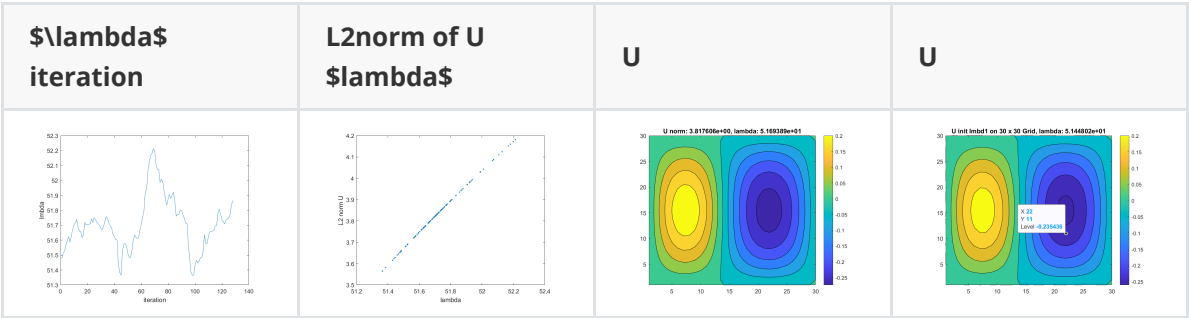
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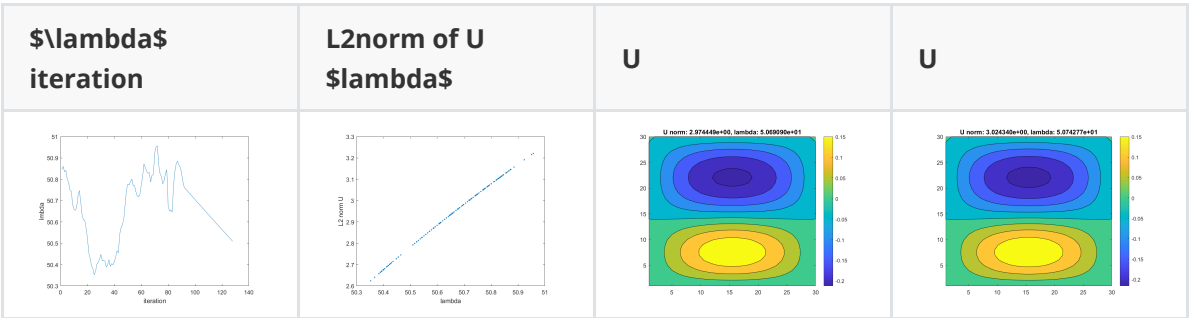
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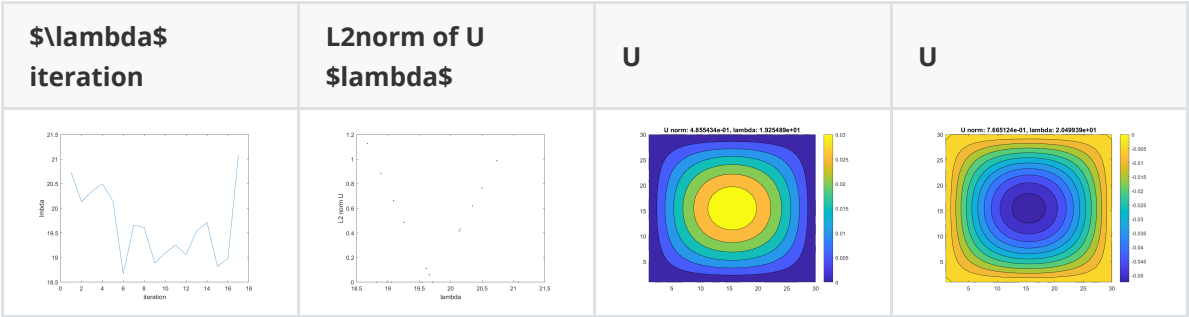
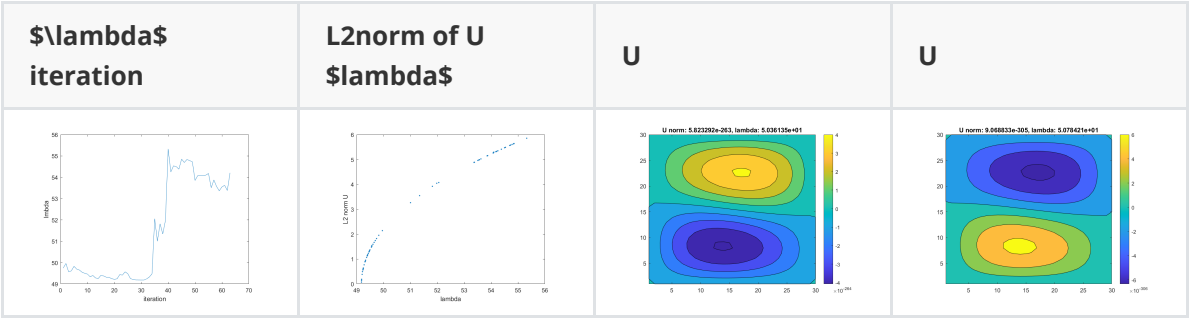
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Up and down



Relatively make sense cases



## Performance with sparse matrix

Here we test the running time during solving the

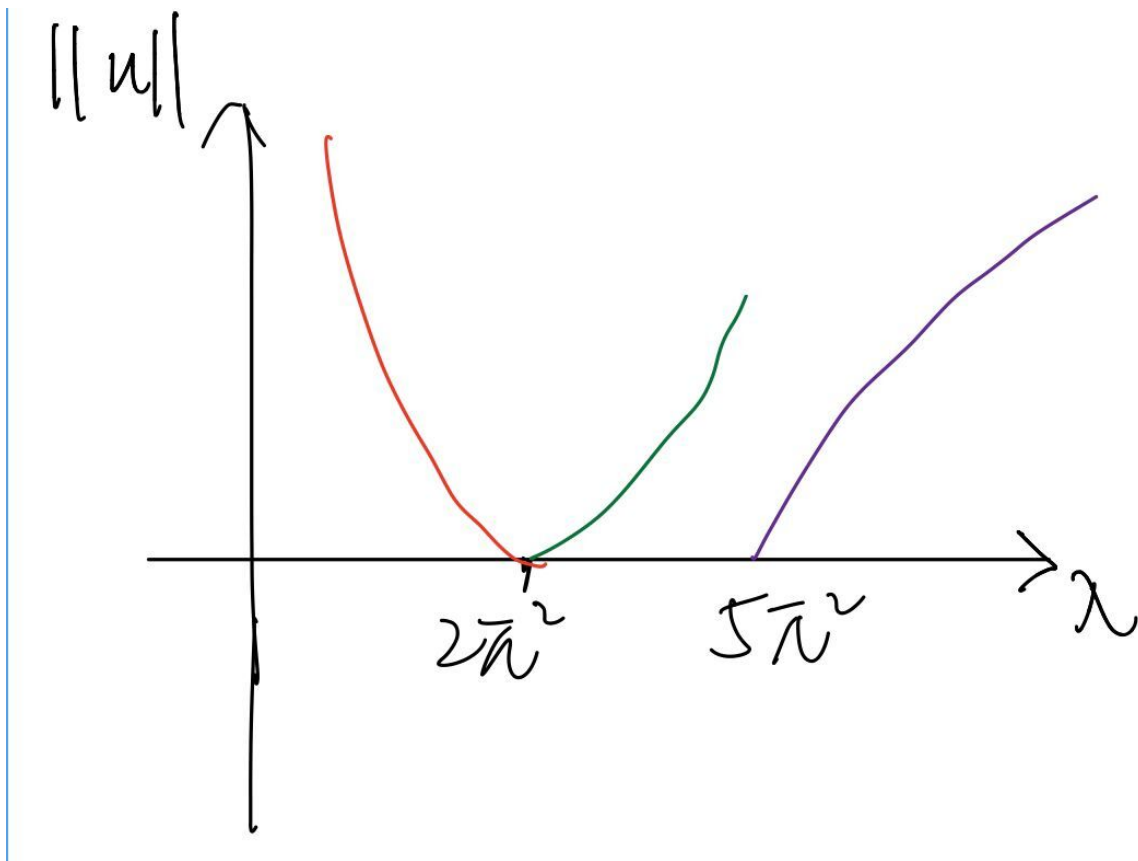
$$\mathbf{J}|_k(\partial \mathbf{u})_k = -(\partial \mathbf{R})_k$$

	Sparse	Full
time(seconds) spent in 64 iterations	2.158603	2.75824

Here  $\mathbf{J}$  is a banded matrix with bandwidth  $2n$  (the whole matrix  $\mathbf{J}$  is  $(n+1)^2$ ). As expected, matrix solving under this setting could benefit greatly from sparse matrix.

## Conclusion

This is the expected whole graph of L2 norm of U vs iteration.



In my current version of ARCLC, the full newton's method (with  $\hat{J}$ ) could hardly converge. I think that's the reason why the  $\lambda$  vs iteration is not stable and smooth.

Despite, we still manage to see that the  $u$  could jump on another branch. As in last two examples, the hill-like and bowl-like solutions change signs when we are moving along the curve.

In some circumstances (the first results), the  $u$  could sometimes move to  $2\pi^2$  branch.

## Code

Code repository is [here](#).