# ZHIHAO ZHANG

+86 186-0056-4483  $\Rightarrow$  zzh\_jackfram@outlook.com

#### **EDUCATION**

#### Renmin University, China

2016.9 - 2020.7

B.S. in Computer Science

Overall GPA: 3.74/4.0 (5%)

• Academic achievement: Annually Academic Achievement Scholarship 2016-2018, Dean's Scholarship of RUC 2018, National Undergraduate Training Programs Scholarship for Innovation and Entrepreneurship

### University of Edinburgh, UK

2018.9 - 2019.6

Full year visiting student, major in computer science

Overall GPA: 4.0/4.0

Carnegie Mellon University, USA

2020.9 - Now

Master of Science in Robotics (MSR)

Overall GPA: 4.17/4.0

#### RESEARCH EXPERIENCES

### Carnegie Mellon University, Catalyst

Pittsburgh, U.S

Research Assistant, advised by Prof. Zhihao Jia

2021.3-now

• Deep learning theory guided model performance inference, network compression

### Carnegie Mellon University, Intelligent Control Lab

Pittsburgh, U.S

Research Assistant, advised by Prof. Changliu Liu

2020.9-2021.3

• Deep learning theory related topics, eg. Neural Tangent Kernel, Rademacher Complexity, Norm Based NN Capacity Measurement.

### University of California Berkeley, Mechanical Systems Control Lab

Berkeley, U.S.

Research Intern, advised by Prof. Masayoshi Tomizuka

2019.10-2020.3

- "Unsupervised Distance Learning of Dynamic Model in Latent Space", a model based goal conditioned unsupervised reinforcement learning algorithm
- "Social-WaGDAT: Interaction-aware Trajectory Prediction via Wasserstein Graph Double-Attention Network", an interactive trajectory prediction method using GNN framework

#### Carnegie Mellon University, Intelligent Control Lab

Research Intern, advised by Prof. Changliu Liu

Pittsburgh, U.S 2019.6-2019.10

- AutoEnv, an integrated platform for autonomous driving related tasks. Components include preprocessing, algorithm implementation(TRPO, PS-GAIL, RLS), simulation and evaluation. Now published as an open source code base v1.0 on GitHub. Link https://github.com/JackFram/Autoenv
- AGen, an online adaptive generative trajectory prediction algorithm. Using Recursive Least Square algorithm to optimize policy network's final layer weights, the initial policy weights are given by offline PS-GAIL algorithm.

### RUC Multimedia and Intelligence Lab

Beijing, China

Research Assistant, advised by Prof. Qin Jin

2018.6-2019.3

• Visual-dialog challenge 2018, design an encoder-decoder framework incorporate attention mechanism to achieve multiple round of Q&A. Encoder is consisted of a ResNet50 for image feature extraction and LSTM for question encoding, decoder is a LSTM for answering questions.

#### **PUBLICATIONS**

- GradSign: Model Performance Inference with Theoretical Insights, under review for ICLR Zhihao Zhang, Zhihao Jia
- Social-WaGDAT: Interaction-aware Trajectory Prediction via Wasserstein Graph Double-Attention Network, IEEE Transactions on Intelligent Transportation Systems Jiachen Li, Hengbo Ma, Zhihao Zhang, Masayoshi Tomizuka

## TECHNICAL STRENGTHS

 ${\bf Research\ background} \qquad \quad {\rm Machine\ Learning,\ Computer\ Vision,\ Reinforcement\ Learning,}$ 

Software & Tools Python, C, C++, Java, Pytorch, Tensorflow

Language TOEFL overall 112, speaking 25 GRE Best Score Verbal 158, Quant 170, AW 4.0