JACK MACKINNON

University of Waterloo | ID# 20682183 | 2A Mechatronics Engineering jack.mackinnon@edu.uwaterloo.ca | (519) 222-5395

	OIII	jack.mackinnon@e		0 0	,	
SKILLS & SUI	MMARY OF	QUALIFICATIONS				
C++	MatLab	Git, GitHub, GitLab	Data Analysis	Automation	Leadership	
Python	HTML	Physics	Debugging	Computer Vision	Project Management	
 Proficier 	nt in Python a	nd object-oriented progra	mming language C-	++		
 Automat 	ed systems de	eveloper				
 Prototyp 	ing, debuggir	ng and testing of robotic s	ystems and software	e		
WORK EXPE	RIENCE					
Teledyne DA	LSA, Waterle	00 ON				
Research and	Developmen	t Engineer				
	-	of an infrared sensor auto			ntal steps	
 Paired Universal Robots' UR3 and a Dino-lite for image acquisition of the sensors 						
• Used OpenCV's Python computer vision API to locate identifying labels on infrared sensors						
•	•	code to optimize paramete	•			
		he project's code reposito			04/40 04/40	
		_			01/18 – 04/18	
Analytical and	`		that musaassas and :		imatan data	
• •		at/breath detector in C++ meter and an Arduino to	•		imeter data	
•	-	out of an electrical motor	-		Zaro	
•		machine learning softwar	-	process of the STAC 2	æ10	
	•	•			05/16 – 09/16	
Team Member		zang cumum, cumerag				
• Lexus R	X350 produc	t quality insurance				
 Exercise 	d time manag	gement and attention to de	etail through vehicle	inspection		
Fundraiser for Project Lead	or Pancreation	c Cancer, Resurrection (C.S.S., Kitchener O	N	04/15 – 05/15	
 Managed 	d 26 people ir	the production and exec	ution of a school-wi	de fundraiser under str	rict time constraints	
DESIGN PRO	JECTS					
UW REACT,	, University (of Waterloo, Waterloo O	N		01/19 – Present	
Planning Sub-	-Team					
 Aiding r 	obots in decis	sion making by creating a	strategy and reacting	ng to interference in Py	rthon	
		y of Waterloo, Waterloo	ON			
Sub-Team Lea						
• General Motors AutoDrive Challenge, hosted by SAE, the Student Association of Engineering						
• Developed a recursive C++ algorithm to map the velocity of an autonomous vehicle along a local path						
 Wrote a Python script to extract self-acquired vehicle data from a ROS bag file Lead a team of 5 engineers in preparation of the first challenge, held in Yuma, AZ 						
	•		•		10/17 12/17	
Autonomous (10/17 – 12/17	
	-	ped an autonomous check	rers-playing robot v	with 3 associates		
_		mized robotic movements			EV3	
_	-	nd hardware issues	5 III CTT 101 a LLO		1 13	
Debugge	o boil wait al					

EDUCATION

University of Waterloo, Waterloo ON, Candidate for BASc, Honors Mechatronics Engineering09/17 – Preser	ıt
University of Waterloo, Waterloo ON, Candidate for BSc, Honors Physics	7