

AdaSociety: An Adaptive Environment with Social Structures for Multi-Agent Decision-Making

Yizhe Huang^{*2,1} Xingbo Wang^{*2} Hao Liu³ Fanqi Kong^{2,1} Aoyang Qin^{4,1} Min Tang^{5,1} Xiaoxi Wang¹
Song-Chun Zhu^{1,2} Mingjie Bi¹ Siyuan Qi¹ Xue Feng¹✉

¹State Key Laboratory of General Artificial Intelligence, BIGAI ²Peking University ³New York University

⁴Tsinghua University ⁵University of Science and Technology of China

The code is available at <https://github.com/bigai-ai/AdaSociety>

Motivation



Physical Complexity
An agent traverses various tasks

Social Complexity
Multiple agents collaborate to complete a task

Multi-Agent
WE WANT THEM ALL!
Adaptive Social Connections Diverse Tasks
Expanding Physical Surroundings

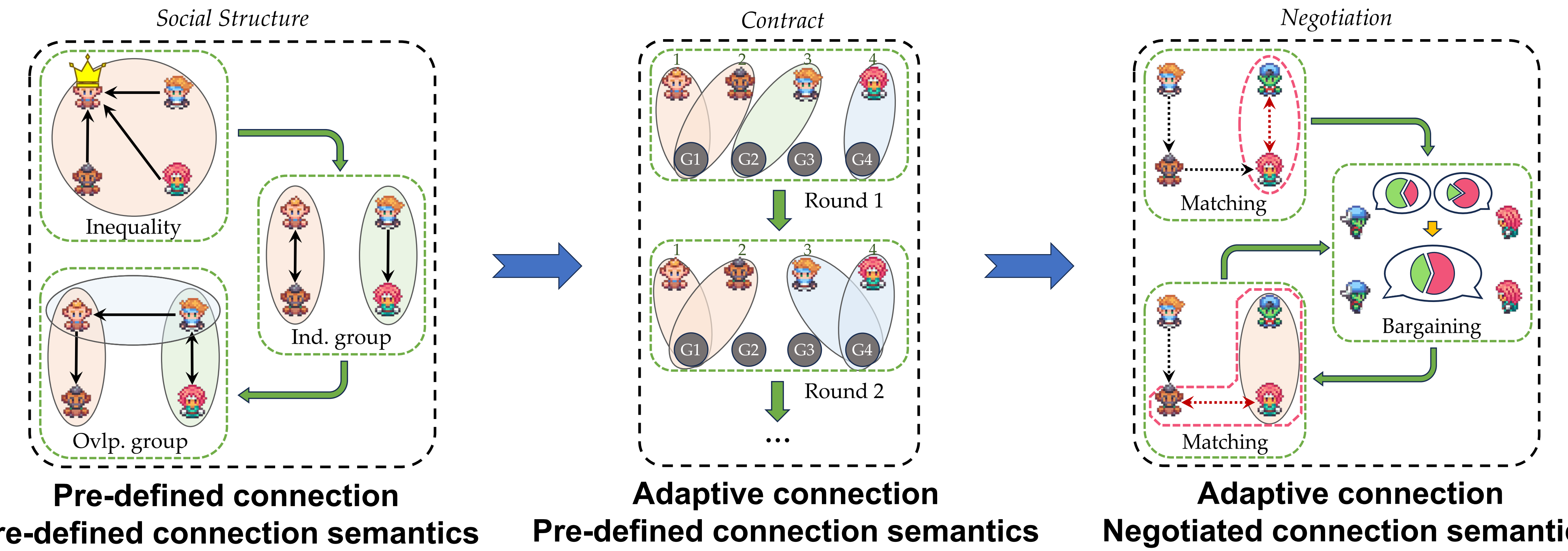
Novelty



- Introduce an environment featuring **expanding physical surroundings** and **adaptive social connections**
- Introduce **social states** to explicitly and quantitatively describe the dynamic connections between entities
- Offer a **customizable environment** with three built-in minigames supporting **tensor- and LLM-based methods**

Mini-games

The three mini-games are arranged in ascending order of the complexity of decision-making. All of the three mini-games share the same physical component, containing two basic events: *HammerCraft* and *TorchCraft*.



Environment

Physical Component

Natural resources (icons) ...
Synthetic resources (icons) ...
Resource

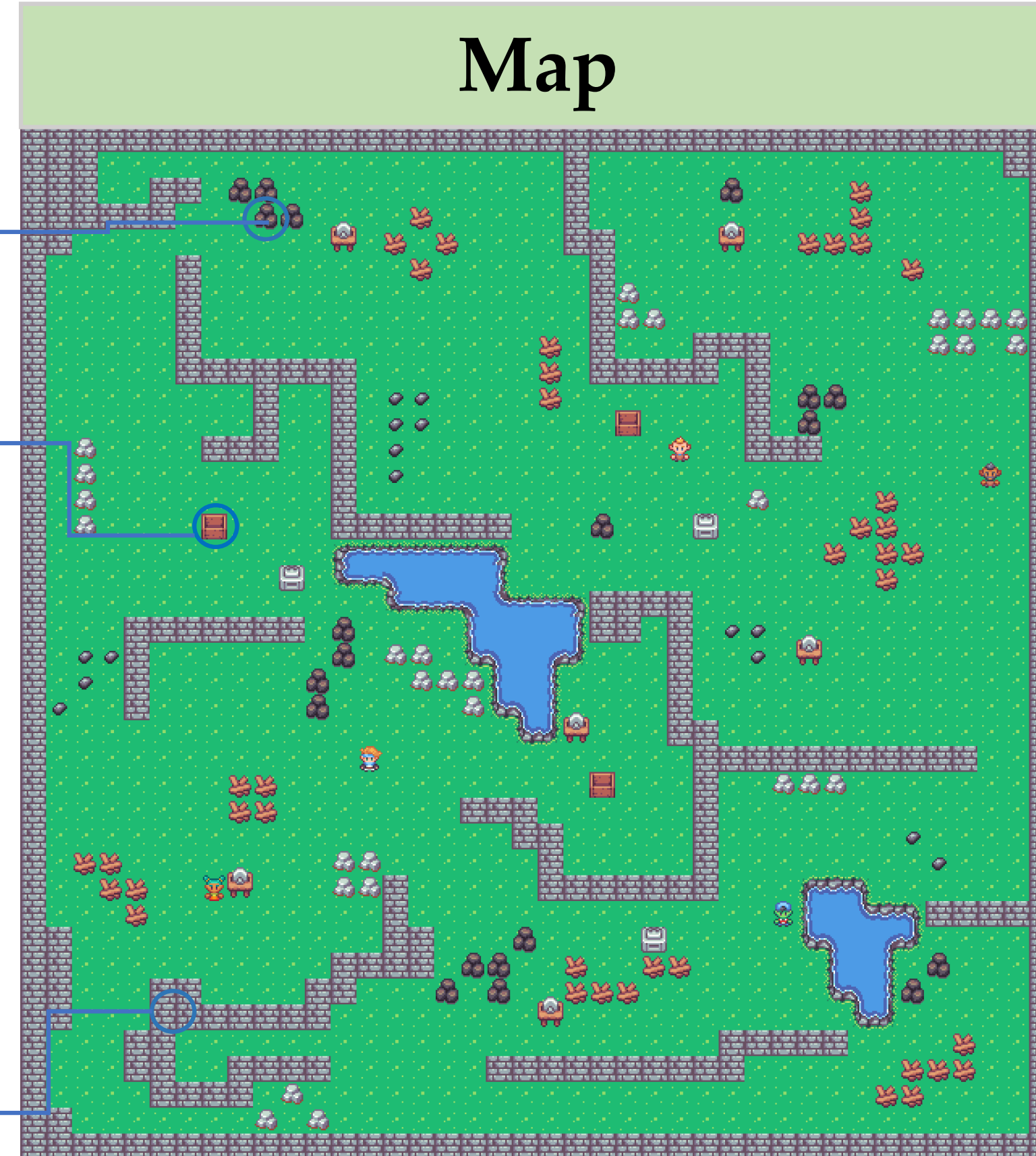
resources $\xrightarrow{\text{event}}$ resource
e.g. (icons) + (icons) \rightarrow (icon)
Event grid

Heterogeneous inv. capacity
Heterogeneous preference for resources in inv.
Agent's inventory

Movement (icons)
Pick (icons), Dump (icons) ...
Physical action

Impassable wall or water
Block

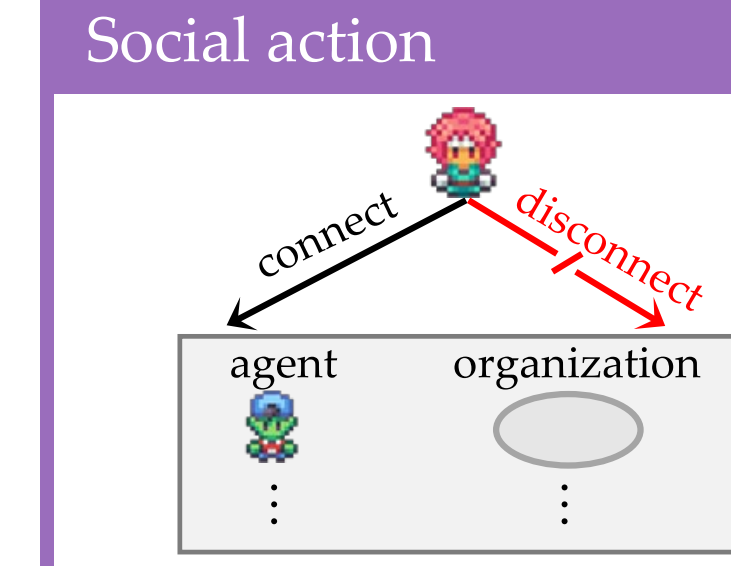
Map



Social Component

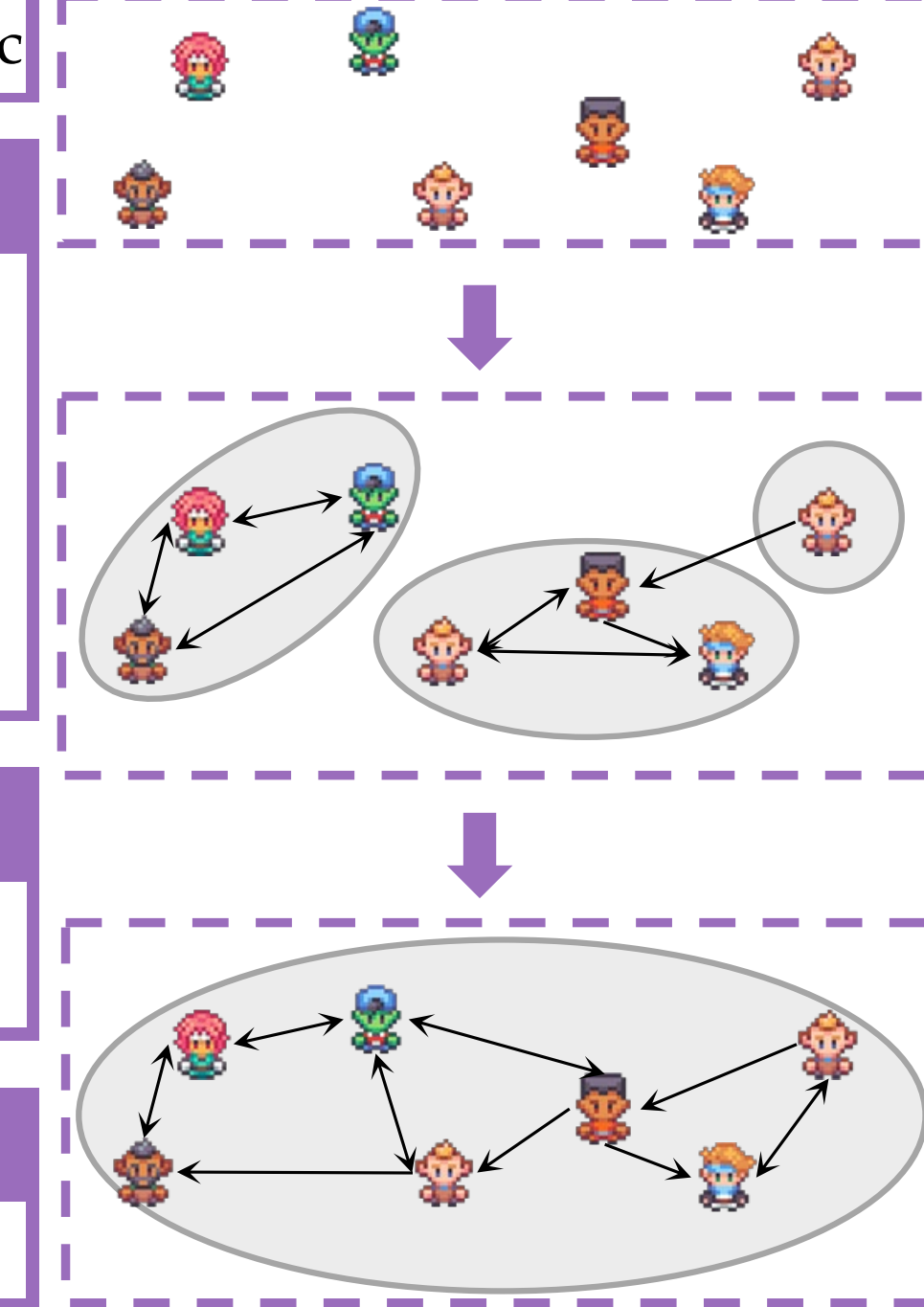
Social connection
non-deterministic & dynamic

Example: dynamic connections



Hierarchy
agent-agent & agent-organization connections

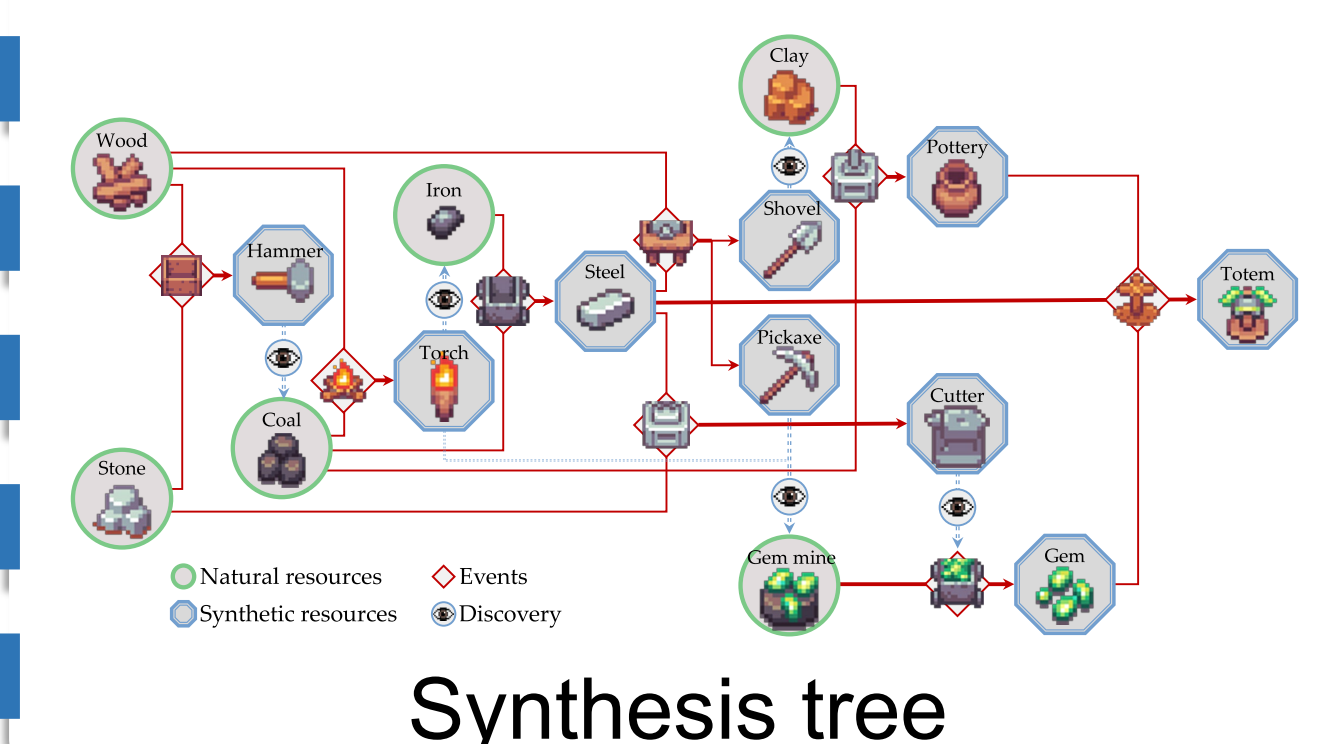
Connection semantics
share information / reward



Agents can:

- move
- pick up / discard resources
- synthesize new resources in event grids

As the synthesis progresses, agents will gradually discover resources that have not appeared before.

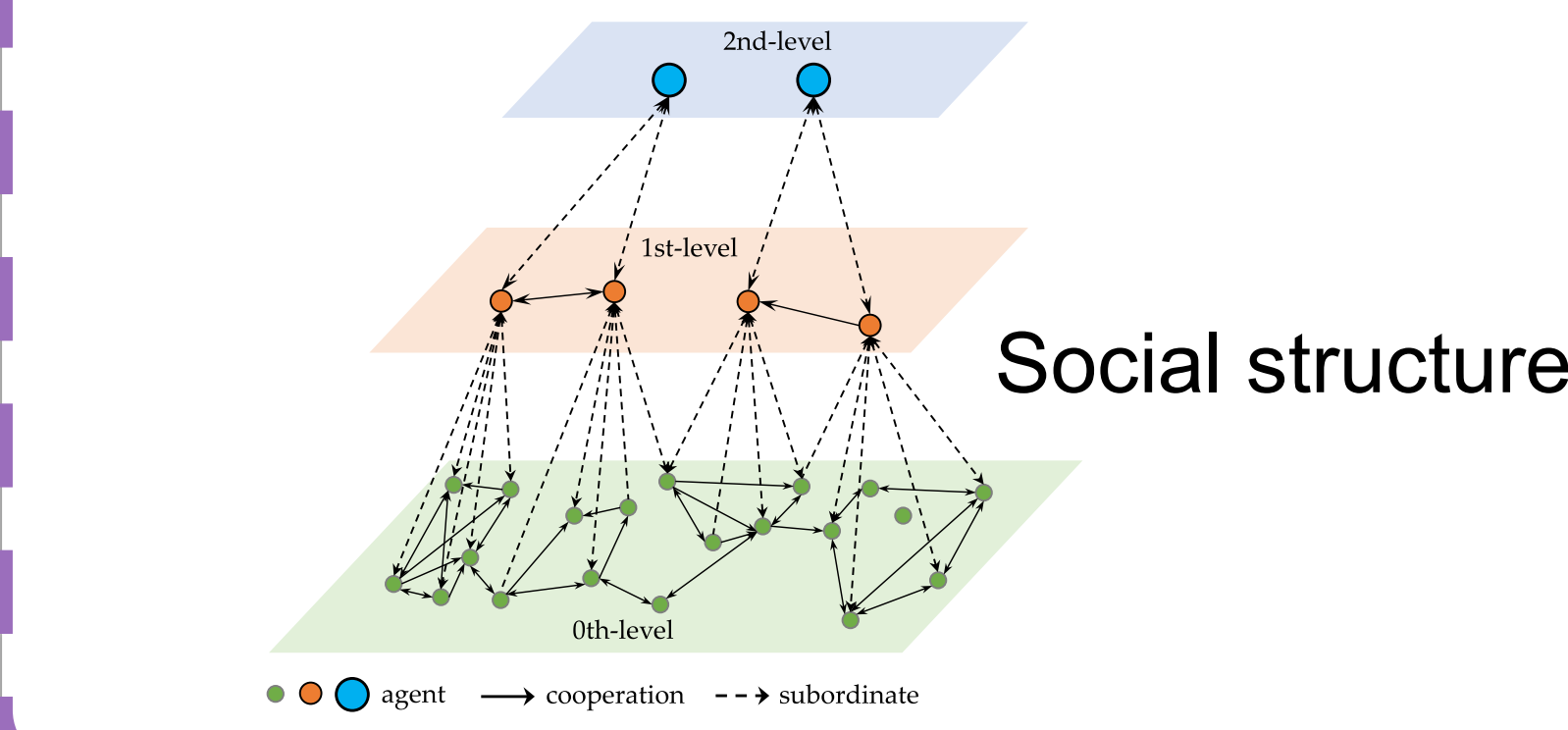


Characteristics

- ✓ Multi-agent general-sum game
- ✓ Dynamically expanding state and action spaces
- ✓ Dynamic social connection
- ✓ Massive and diverse tasks
- ✓ Partial observation
- ✓ Communication
- ✓ Customization
- ✓ LLM- and tensor-based APIs
- ✓ ...

Agents can:

- share observation by links to other agent nodes
 - share reward by links to organization nodes
 - autonomously connect / disconnect with other nodes
 - establish new organization nodes
- Social structures are included in observations.



Experiments

Setup and Baseline

The **Easy** mode involves a single event, while the **Hard** mode is more complex, including six resources and two events. We take *PPO*, *RecurrentPPO(RecPPO)*, *MAPPO* and *Rainbow* as our baselines. We also design a *curriculum learning(CL)* algorithm and a *large language model planner + rule-based controller (LLM-C)* framework.

Results

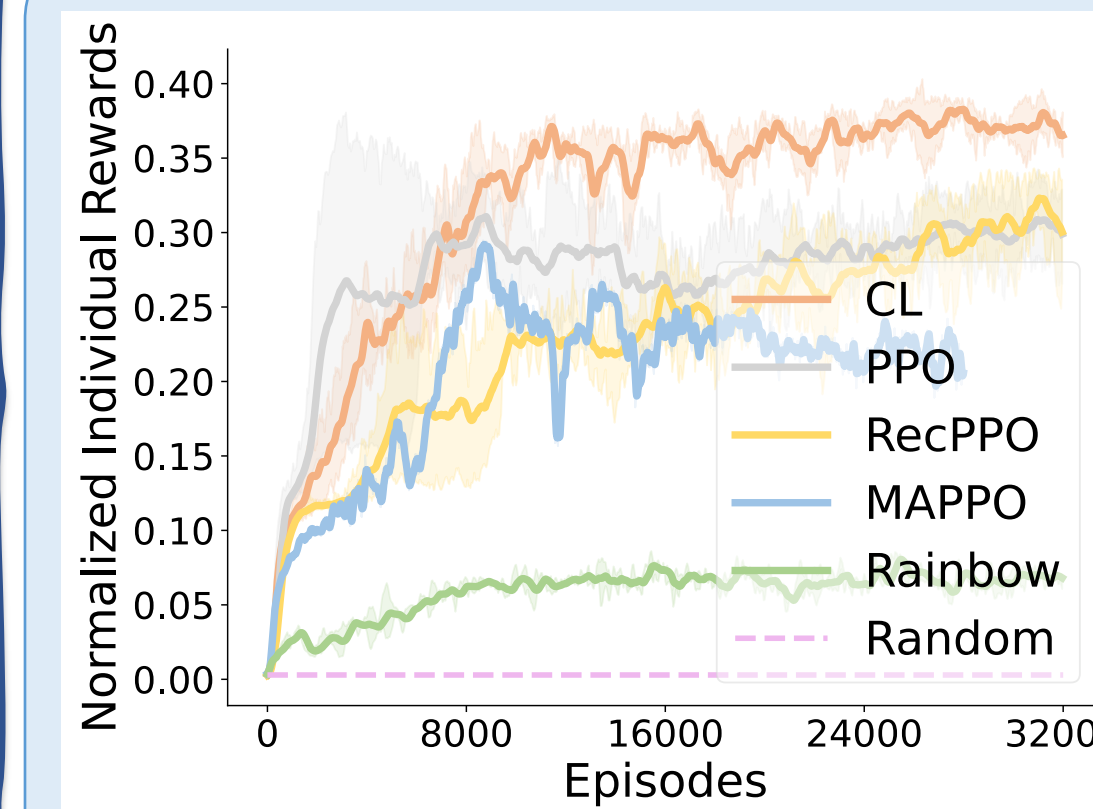


Figure 1: The training curves of tensor-based agents in **Social Structure - Dynamic**. *CL* agents demonstrates better performance than popular RL methods. *Rainbow* performs the worst, likely because of its general ineffectiveness in exploration.

Table 1: The normalized rewards of tensor-based methods in **Contract** and **Negotiation**. Popular RL methods often fall into local optima. While *CL* enhances tensor-based agents, its training efficiency and effectiveness decline as the scale of the environment increases.

		CL	PPO	RecPPO	MAPPO	Rainbow
Con.	Easy	0.9136±0.0023	0.2286±0.0003	0.2276±0.0015	0.2271±0.0003	0.1987±0.0127
	Hard	0.2773±0.0466	0.1151±0.0002	0.1149±0.0000	0.1137±0.0005	0.0868±0.0033
Neg.	Easy	0.3543±0.0229	0.2276±0.0006	0.2278±0.0004	0.2147±0.0001	0.1969±0.0105
	Hard	0.1945±0.0109	0.1093±0.0027	0.1107±0.0019	0.0946±0.0032	0.0905±0.0024

Table 2: The normalized rewards of *LLM-C* in **Contract** and **Negotiation**. Due to the rich prior knowledge, *LLM-C* achieves significantly high rewards. However, these results still fall short of the optimal rewards achieved by an Oracle.

	Social Structure	Contract	Negotiation
Easy	-	0.8433±0.1312	0.8733±0.1116
Hard	0.7894±0.0444	0.6499±0.1716	0.6862±0.1027

AdaSociety maintains a rational complexity level for popular decision-making methods.

These methods fails to utilize social structure provided in **AdaSociety** to form effective cooperation.

Prior knowledge can be of great help to the algorithm.