

4-valued coalgebraic modal logic

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28 January 2015

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.



4-valued logics

1. true
2. false
3. ?
4. .

4-valued logics

\perp = Not enough information

1. true
2. false
3. \perp
4.
 - ▶ At the beginning of a computation.
 - ▶ Program hangs (example: trying to evaluate halting problem).

4-valued logics

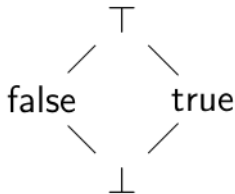
1. true
2. false
3. \perp
4. \top

\top = Inconsistent information

- ▶ Obtained information from database don't make any sense.
- ▶ Different threads returning contradicting results.

4-valued logics

1. true
2. false
3. \perp
4. \top



$$\text{true} \sqcup \text{false} = \top$$

$$\text{true} \sqcap \text{false} = \perp$$

4-valued coalgebraic modal logic

✓ ? ? ? ?

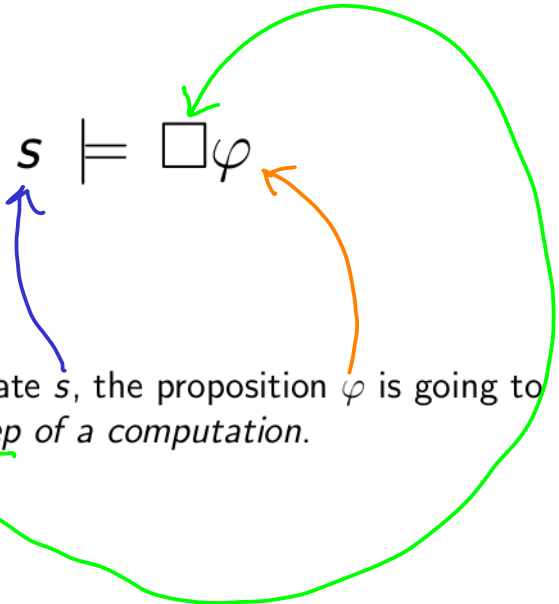


Modal logics

$$s \models \Box \varphi$$

Starting in the state s , the proposition φ is going to hold *after one step of a computation*.

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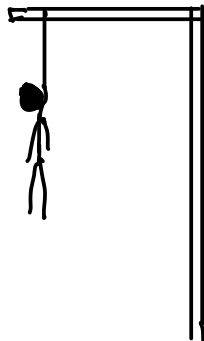
✓ ??? ✓



What are coalgebras?

Simple answer:

They are just algebras in the opposite category.



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They are just algebras in the opposite category.

More useful answer:

Any state based system is a coalgebra. For example

- ▶ streams of bytes, single thread computation,
- ▶ concurrent computation,
- ▶ complex intelligent networks (brain, internet, financial systems),
- ▶ ...

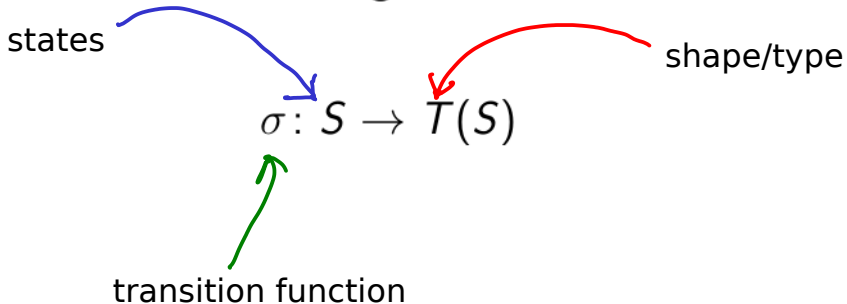
Coalgebras

states

shape/type

$$\sigma: S \rightarrow T(S)$$

transition function



Coalgebras

$$\sigma: S \rightarrow T(S)$$

- Printing coalgebra ($T(S) = A$):

$$\sigma: S \longrightarrow A$$

$$\sigma: s \in S \longmapsto \sigma(s) \in A$$

Coalgebras

$$\sigma: S \rightarrow T(S)$$

- ▶ Printing coalgebra ($T(S) = A$):

$$\sigma: S \longrightarrow A$$

$$\sigma: s \in S \longmapsto \sigma(s) \in A$$

- ▶ Changing-states coalgebra ($T(S) = S$):

$$\sigma: S \longrightarrow S$$

Coalgebras of combined shapes

- Choice:

$$\sigma: S \rightarrow T_1(S) \cup T_2(S)$$

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- Reading input:

$$\sigma: S \rightarrow T(S)^B$$

where

$$T(S)^B = \{f \mid f: B \rightarrow T(S)\}$$

Coalgebras of combined shapes

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- Parallel composition:

$$\sigma: S \rightarrow T_1(S) \times T_2(S)$$

- Reading input:

$$\sigma: S \rightarrow T(S)^B$$

- Nondeterminism:

$$\sigma: S \rightarrow \mathcal{P}(T(S)) = \{X \mid X \subseteq T(S)\}$$



Example

An automaton is: $(S, \delta: S \times \Sigma \rightarrow S, F \subseteq S)$.

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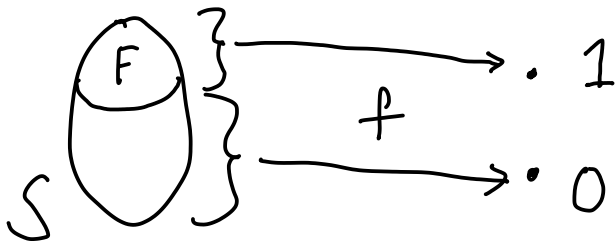
$$\tilde{\delta}: s \in S \mapsto \lambda x. \delta(s, x)$$

Example

An automaton is: $(S, \delta: S \times \Sigma \rightarrow S, F \subseteq S)$.

- ▶ $\tilde{\delta}: S \rightarrow S^\Sigma$
- ▶ $f: S \rightarrow \{0, 1\}$

$$f^{-1}(1) = F$$



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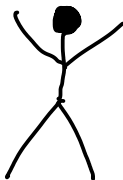
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Similarly, nondeterministic automata are coalgebras

$$S \rightarrow \{0, 1\} \times (\mathcal{P}(S))^\Sigma.$$

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= a suitable logic for systems!



Thank

you!