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Working Draft, Technical Specification for C++ Extensions for Parallelism

Note: this is an early draft. It's known to be incomplet and incorrekt, and it has lots of bad formatting.

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1 General

[parallel.general]

1.1 Scope

[parallel.general.scope]

This Technical Specification describes requirements for implementations of an interface that computer programs written in the C++ programming language may use to invoke algorithms with parallel execution. The algorithms described by this Technical Specification are realizable across a broad class of computer architectures.

- ² This Technical Specification is non-normative. Some of the functionality described by this Technical Specification may be considered for standardization in a future version of C++, but it is not currently part of any C++ standard. Some of the functionality in this Technical Specification may never be standardized, and other functionality may be standardized in a substantially changed form.
- ³ The goal of this Technical Specification is to build widespread existing practice for parallelism in the C++ standard algorithms library. It gives advice on extensions to those vendors who wish to provide them.

1.2 Normative references

[parallel.general.references]

The following referenced document is indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO/IEC 14882: $-^1$, Programming Languages — C++

- ² ISO/IEC 14882:— is herein called the *C++ Standard*. The library described in ISO/IEC 14882:— clauses 17-30 is herein called the *C++ Standard Library*. The C++ Standard Library components described in ISO/IEC 14882:— clauses 25 and, 26.7 and 20.7.2 are herein called the *C++ Standard Algorithms Library*.
- ³ Unless otherwise specified, the whole of the C++ Standard's Library introduction (C++14 §17) is included into this Technical Specification by reference.

1.3 Namespaces and headers

[parallel.general.namespaces]

- Since the extensions described in this Technical Specification are experimental and not part of the C++ Standard Library, they should not be declared directly within namespace std. Unless otherwise specified, all components described in this Technical Specification are declared in namespace std::experimental::parallel_v1.
 - [Note: Once standardized, the components described by this Technical Specification are expected to be promoted to namespace std. $end\ note$]
- ² Unless otherwise specified, references to such entities described in this Technical Specification are assumed to be qualified with std::experimental::parallel_v1, and references to entities described in the C++ Standard Library are assumed to be qualified with std::.
- Extensions that are expected to eventually be added to an existing header <meow> are provided inside the <experimental/meow> header, which shall include the standard contents of <meow> as if by

#include <meow>

§ 1.3

1. To be published. Section references are relative to N3797.

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1.3.1 Terms and definitions

[parallel.general.defns]

 1 For the purposes of this document, the terms and definitions given in the C++ Standard and the following apply.

² A *parallel algorithm* is a function template described by this Technical Specification declared in namespace std::experimental::parallel_v1 with a formal template parameter named ExecutionPolicy.

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2 Execution policies

[parallel.execpol]

2.1 In general

[parallel.execpol.general]

¹ This clause describes classes that represent *execution policies*. An *execution policy* is an object that expresses the requirements on the ordering of functions invoked as a consequence of the invocation of a standard algorithm. Execution policies afford standard algorithms the discretion to execute in parallel.

```
[ Example:
```

```
std::vector<int> v = ...
 // standard sequential sort
 std::sort(vec.begin(), vec.end());
 std::sort(std::begin(vec), std::end(vec));
 std::sort(vec.begin(), vec.end());
 using namespace std::experimental::parallel_v1;
 // explicitly sequential sort
 sort(seq, v.begin(), v.end());
 sort(seq, std::begin(v), std::end(v));
 sort(seq, v.begin(), v.end());
 // permitting parallel execution
 sort(par, v.begin(), v.end());
 sort(par, std::begin(v), std::end(v));
 sort(par, v.begin(), v.end());
 // permitting vectorization as well
 sort(vec, v.begin(), v.end());
 sort(vec, std::begin(v), std::end(v));
 sort(par vec, v.begin(), v.end());
 // sort with dynamically-selected execution
 size t threshold = ...
 execution_policy exec = seq;
 if (v.size() > threshold)
   exec = par;
 }
 sort(exec, v.begin(), v.end());
 sort(exec. std::begin(v). std::end(v));
 sort(exec, v.begin(), v.end());
— end example ]
```

[Note: Because different parallel architectures may require idiosyncratic parameters for efficient execution, implementations of the Standard Library shouldmay provide additional execution policies to those described in this Technical Specification as extensions. — end note]

2.2 Header <experimental/execution_policy> synopsis

[parallel.execpol.synopsis]

```
namespace std {
namespace experimental {
inline namespace parallel_v1 {
   // 2.3, Execution policy type trait
   template<class T> struct is_execution_policy;
```

§ 2.2

```
template<class T> constexpr bool is_execution_policy_v = is_execution_policy<T>::value;

// 2.4, Sequential execution policy
class sequential_execution_policy;

// 2.5, Parallel execution policy
class parallel_execution_policy;

// 2.6, Parallel+Vector execution policy
class vector_execution_policyparallel_vector_execution_policy;

// 2.7, Dynamic execution policy
class execution_policy;
}
```

2.3 Execution policy type trait

[parallel.execpol.type]

is_execution_policy can be used to detect parallel execution policies for the purpose of excluding function signatures from otherwise ambiguous overload resolution participation.

If T is the type of a standard or implementation-defined execution policy, is_execution_policy<T> shall be publicly derived from integral_constant<bool,true>, otherwise from integral_constant<bool,false>.

<u>is_execution_policy<T> shall be a UnaryTypeTrait with a BaseCharacteristic of true_type if T is the type of a standard or implementation-defined execution policy, otherwise false_type.</u>

The behavior of a program that adds specializations for is_execution_policy is undefined.

2.4 Sequential execution policy

[parallel.execpol.seq]

```
namespace std {
namespace experimental {
namespace parallel_v1 {
   class sequential_execution_policy{ unspecified };
}
}
```

¹ The class sequential_execution_policy is an execution policy type used as a unique type to disambiguate parallel algorithm overloading and require that a parallel algorithm's execution may not be parallelized.

§ 2.4

2.5 Parallel execution policy

[parallel.execpol.par]

```
namespace std {
namespace experimental {
namespace parallel_v1 {
   class parallel_execution_policy{ unspecified };
}
}
```

The class parallel_execution_policy is an execution policy type used as a unique type to disambiguate parallel algorithm overloading and indicate that a parallel algorithm's execution may be parallelized.

2.6 Parallel+Vector execution policy

[parallel.execpol.vec]

```
namespace std {
namespace experimental {
namespace parallel_v1 {
   class vector_execution_policyparallel_vector_execution_policy{ unspecified };
}
}
}
```

The class class vector_execution_policy is an execution policy type used as a unique type to disambiguate parallel algorithm overloading and indicate that a parallel algorithm's execution may be vectorized and parallelized.

2.7 Dynamic execution policy

[parallel.execpol.dynamic]

The class execution_policy is a container for execution policy objects. execution_policy allows dynamic control over standard algorithm execution.

[Example:

§ 2.7

```
std::vector<float> sort me = ...
    using namespace std::experimental::parallel;
    std::execution policy exec = std::seq;
    if(sort me.size() > threshold)
      exec = std::par;
    }
    std::sort(exec, sort me.begin(), sort me.end());
    std::sort(exec, std::begin(sort me), std::end(sort me));
  — end example ]
<sup>2</sup> Objects of type execution policy shall be constructible and assignable from objects of type T for
  which is execution policy<T>::value is true.
                                                                                [parallel.execpol.con]
  2.7.1 execution policy construct/assign
1 template<class T> execution_policy(const T& exec);
    <sup>2</sup> Effects: Constructs an execution_policy object with a copy of exec's state.
      Requires: is execution policy<T>::value is true.
      Remarks: This constructor shall not participate in overload resolution unless
      is_execution_policy<T>::value is true.
3 template<class T> execution policy& operator=(const T& exec);
    <sup>4</sup> Effects: Assigns a copy of exec's state to *this.
    5 Returns: *this.
      Requires: is execution policy<T>::value is true.
      Remarks: This operator shall not partipate in overload resolution unless
      is execution policy<T>::value is true.
  2.7.2 execution policy object access
                                                                            [parallel.execpol.access]
            const type info& type() const noexcept;
    <sup>2</sup> Returns: typeid(T), such that T is the type of the execution policy object contained by *this.
            template<class T> T* get() noexcept;
                template<class T> const T* get() const noexcept;
    4 Returns: If target type() == typeid(T), a pointer to the stored execution policy object;
      otherwise a null pointer.
      Requires: is execution policy<T>::value is true.
      Remarks: This function shall not participate in overload resolution unless
```

1

is execution policy<T> is true.

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2.8 Execution policy objects

[parallel.execpol.objects]

¹ The header <experimental/execution_policy> declares a global object associated with each type of execution policy defined by this Technical Specification.

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3 Parallel exceptions

[parallel.exceptions]

3.1 Exception reporting behavior

[parallel.exceptions.behavior]

During the execution of a standard parallel algorithm, I temporary memory resources are required by the algorithm and none are available, the algorithm throws a std::bad_alloc exception.

During the execution of a standard parallel algorithm, if the application of a function object terminates with an uncaught exception, the behavior of the program is determined by the type of execution policy used to invoke the algorithm:

If the execution policy object is of type class vector_execution_policy.std::terminate shall be called.
If the execution policy object is of type sequential_execution_policy or parallel_execution_policy, the execution of the algorithm terminates with an exception_list exception. All uncaught exceptions thrown during the application of user-provided function objects shall be contained in the exception list.

[*Note:* For example, the number of invocations of the user-provided function object in for_each is unspecified. When for_each is executed sequentially, only one exception will be contained in the exception list object. — *end note*]

[Note: These guarantees imply that, unless the algorithm has failed to allocate memory and terminated with std::bad_alloc, all exceptions thrown during the execution of the algorithm are communicated to the caller. It is unspecified whether an algorithm implementation will "forge ahead" after encountering and capturing a user exception.

— end note]

[Note: The algorithm may terminate with the std::bad_alloc exception even if one or more user-provided function objects have terminated with an exception. For example, this can happen when an algorithm fails to allocate memory while creating or adding elements to the exception_list object. — end note]

If the execution policy object is of any other type, the behavior is implementation-defined.

3.2 Header <experimental/exception_list> synopsis

3

[parallel.exceptions.synopsis]

```
namespace std {
namespace experimental {
inline namespace parallel v1 {
 class exception_list : public exception
   public:
     typedef exception ptr
                                                                     value type;
    typedef const value type&
                                                                    reference;
     typedef const value type&
                                                                     const reference;
     typedef implementation-defined
                                                                     const iterator;
   typedef const iterator
                                                                   iterator;
   — typedef typename iterator_traits<const_iterator>::difference_type difference_type;
     typedef size t
     typedef unspecified
```

§ 3.2

```
size_t size() const noexcept;
iterator begin() const noexcept;
iterator end() const noexcept;

const char* what() const override noexcept;

private:
    std::list<exception_ptr> exceptions_; // exposition only
};
}
}
```

- ¹ The class exception_list is a container owns a sequence of exception_ptr objects .<u>The</u> parallel algorithms may use the exception_list to communicate uncaught exceptions encountered during parallel execution to the caller of the algorithm.
- ² The type exception list::iterator shall fulfill the requirements of ForwardIterator.
- 3 size_t size() const noexcept;
 - ⁴ Returns: The number of exception ptr objects contained within the exception list.
 - ⁵ Complexity: Constant time.
- - ⁷ Returns: An iterator referring to the first exception_ptr object contained within the exception_list.
- - ⁹ *Returns:* An iterator which is the past-the-end value for the exception_list that is past the end of the owned sequence.
- - 11 Returns: An implementation-defined NTBS.

§ 3.2

4 Parallel algorithms

[parallel.alg]

4.1 In general

[parallel.alg.general]

This clause describes components that C++ programs may use to perform operations on containers and other sequences in parallel.

4.1.1 Effect of execution policies on algorithm execution [parallel.alg.general.exec]

- Parallel algorithms have template parameters named ExecutionPolicy which describe the manner in which the execution of these algorithms may be parallelized and the manner in which they apply user-provided function objects.
- ² The applications of function objects in parallel algorithms invoked with an execution policy object of type sequential_execution_policy execute in sequential order in the calling thread.
- The applications of function objects in parallel algorithms invoked with an execution policy object of type parallel_execution_policy are permitted to execute in an unordered fashion in unspecified threads, and indeterminately sequenced within each thread. [*Note:* It is the caller's responsibility to ensure correctness, for example that the invocation does not introduce data races or deadlocks. *end note*]

[Example:

```
using namespace std::experimental::parallel;
int a[] = {0,1};
std::vector<int> v;
for_each(par, std::begin(a), std::end(a), [&](int i) {
   v.push_back(i*2+1);
});
for_bar
```

The program above has a data race because of the unsynchronized access to the container v. — $end\ example$

[Example:

```
using namespace std::experimental::parallel; std::atomic<int> x = 0; int a[] = {1,2}; for_each(par, std::begin(a), std::end(a), [&](int n) {    x.fetch_add(1, std::memory_order_relaxed);    // spin wait for another iteration to change the value of x while (x.load(std::memory_order_relaxed) == 1) { }});
```

The above example depends on the order of execution of the iterations, and is therefore undefined (may deadlock). — *end example*]

[Example:

```
using namespace std::experimental::parallel;
int x=0;
std::mutex m;
int a[] = {1,2};
for_each(par, std::begin(a), std::end(a), [&](int) {
    m.lock();
    ++x;
    m.unlock();
});
```

§ 4.1.1

The above example synchronizes access to object x ensuring that it is incremented correctly. — *end example*]

[Example:

```
using namespace std::experimental::parallel_v1;
int x=0;
std::mutex m;
int a[] = {1,2};
for_each(par_vec, std::begin(a), std::end(a), [&](int) {
    m.lock();
    ++x;
    m.unlock();
}.
```

The above program is invalid because the applications of the function object are not guaranteed to run on different threads. — *end example*]

[Note: The application of the function object may result in two consecutive calls to m.lock on the same thread, which may deadlock. — end note]

[*Note:* The semantics of the parallel execution policy or the

vector_execution_policyparallel_vector_execution_policy invocation allow the implementation to fall back to sequential execution if the system cannot parallelize an algorithm invocation due to lack of resources. — end note]

A parallel algorithm invoked with an execution policy object of type parallel_execution_policy or vector_execution_policymay apply iterator member functions of a stronger category than its specification requires, if such iterators exist. In this case, the application of these member functions are subject to provisions 3. and 4. above, respectively.

[Note: For example, an algorithm whose specification requires InputIterator but receives a concrete iterator of the category RandomAccessIterator may use operator[]. In this case, it is the algorithm caller's responsibility to ensure operator[] is race-free. — end note]

- Algorithms invoked with an execution policy object of type execution_policy execute internally as if invoked with instances of type sequential_execution_policy, parallel_execution_policy, or an implementation-defined execution policy type depending on the dynamic value of the execution_policy object. the contained execution policy object.
- ⁶ The semantics of parallel algorithms invoked with an execution policy object of implementation-defined type are <u>unspecifiedimplementation-defined</u>.

4.1.2 ExecutionPolicy algorithm overloads

[parallel.alg.overloads]

Parallel algorithms coexist alongside their sequential counterparts as overloads distinguished by a formal template parameter named ExecutionPolicy. This template parameter corresponds to the parallel algorithm's first function parameter, whose type is ExecutionPolicy is the first template parameter and corresponds to the parallel algorithm's first function parameter, whose type is ExecutionPolicy&&. The Parallel Algorithms Library provides overloads for each of the algorithms named in Table 1, corresponding to the algorithms with the same name in the C++ Standard Algorithms Library. For each algorithm in Table 1, if there are overloads for

 $\S~4.1.2$

corresponding algorithms with the same name in the C++ Standard Algorithms Library, the overloads shall have an additional template type parameter named ExecutionPolicy&&, which shall be the first template parameter.

- ² Unless otherwise specified, the semantics of ExecutionPolicy algorithm overloads are identical to their overloads without.
- ³ Parallel algorithms have the requirement is_execution_policy<ExecutionPolicy>::value is true shall not participate in overload resolution unless is_execution_policy<decay_t<ExecutionPolicy>>::value is true.

The algorithms listed in Table 1 shall have ExecutionPolicy overloads.

Table 1 — Table of parallel algorithms

rable i — rable of parallel algorithms						
adjacent_difference	adjacent_find	all_of	any_of			
сору	copy_if	copy_n	count			
count_if	equal	exclusive_scan	fill			
fill_n	find	find_end	find_first_of			
find_if	find_if_not	for_each	for_each_n			
generate	generate_n	includes	inclusive_scan			
<u>inner_product</u>	inplace_merge	is_heap	is_heap_until			
is_partitioned	is_sorted	is_sorted_until	lexicographical_compare			
max_element	merge	min_element	minmax_element			
mismatch	move	none_of	nth_element			
partial_sort	partial_sort_copy	partition	partition_copy			
reduce	remove	remove_copy	remove_copy_if			
remove_if	replace	replace_copy	replace_copy_if			
replace_if	reverse	reverse_copy	rotate			
rotate_copy	search	search_n	set_difference			
set_intersection	${\tt set_symmetric_difference}$	set_union	sort			
stable_partition	stable_sort	swap_ranges	transform			
uninitialized_copy	uninitialized_copy_n	$uninitialized_fill$	uninitialized_fill_n			
unique	unique_copy					

[Note: Not all algorithms in the Standard Library have counterparts in Table 1. — end note]

4.2 Definitions

4

[parallel.alg.defns]

```
<sup>1</sup> Define \textit{GENERALIZED\_SUM}(op, a1, ..., aN) as follows:
```

```
al—when N is 1 op(\mbox{\it GENERALIZED\_SUM}(op, b1, ..., bMK), \mbox{\it GENERALIZED\_SUM}(op, bM, ..., bN)) where b1—..., bN may be any permutation of a1, ..., aN and 0 < M < N.  
1 < K+1 = M <math>\leq N.
```

Define <code>GENERALIZED_NONCOMMUTATIVE_SUM(op, a1, ..., aN)</code> as follows:

```
al-when N is 1 op(GENERALIZED_NONCOMMUTATIVE_SUM(op, al, ..., aMK), GENERALIZED_NONCOMMUTATIVE_SUM(op, aM, ..., aN) where \frac{0}{N} < \frac{N}{N} < \frac{N}{N} < \frac{N}{N}...
```

§ 4.2

4.3 Non-Numeric Parallel Algorithms

[parallel.alg.ops]

4.3.1 Header <experimental/algorithm> synopsis

[parallel.alg.ops.synopsis]

4.3.2 For each

[parallel.alg.foreach]

- ² Effects: Applies f to the result of dereferencing every iterator in the range [first,last). [Note: If the type of first satisfies the requirements of a mutable iterator, f may apply nonconstant functions through the dereferenced iterator. end note]
- ³ Complexity: Applies f exactly last first times.
- ⁴ *Remarks:* If f returns a result, the result is ignored.
- ⁵ *Notes:* Unlike its sequential form, the parallel overload of for_each does not return a copy of its Function parameter, since parallelization may not permit efficient state accumulation.
- Requires: Unlike its sequential form, the parallel overload of for_each requires Function to meet the requirements of CopyConstructible, but not MoveConstructible.

- ⁸ Requires: Function shall meet the requirements of MoveConstructible [Note: Function need not meet the requirements of CopyConstructible. end note]
- ⁹ Effects: Applies f to the result of dereferencing every iterator in the range [first,first + n), starting from first and proceeding to first + n 1. [Note: If the type of first satisfies the requirements of a mutable iterator, f may apply nonconstant functions through the dereferenced iterator. end note]
- 10 Returns: first + n for non-negative values of n and first for negative values.
- 11 *Remarks:* If f returns a result, the result is ignored.

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Effects: Applies f to the result of dereferencing every iterator in the range [first,first + n), starting from first and proceeding to first + n - 1. [Note: If the type of first satisfies the requirements of a mutable iterator, f may apply nonconstant functions through the dereferenced iterator. — end note]

Returns: first + n for non-negative values of n and first for negative values.

Remarks: If f returns a result, the result is ignored.

Notes: Unlike its sequential form, the parallel overload of for_each_n requires Function to meet the requirements of CopyConstructible, but not MoveConstructible.

4.4 Numeric Parallel Algorithms

[parallel.alg.numeric]

4.4.1 Header <experimental/numeric> synopsis

[parallel.alg.numeric.synopsis]

```
namespace std {
namespace experimental {
inline namespace parallel_v1 {
  template<class InputIterator>
   typename iterator_traits<InputIterator>::value type
      reduce(InputIterator first, InputIterator last);
 template<class InputIterator, class T>
   T reduce(InputIterator first, InputIterator last_ T init);
  template<class InputIterator, class T, class BinaryOperation>
   T reduce(InputIterator first, InputIterator last, T init,
             BinaryOperation binary_op);
template<class InputIterator, class OutputIterator>
   OutputIterator
     exclusive scan(InputIterator first, InputIterator last,
                    OutputIterator result);
 template<class InputIterator, class OutputIterator,
          class T>
   OutputIterator
      exclusive_scan(InputIterator first, InputIterator last,
                     OutputIterator result,
                     T init);
 template<class InputIterator, class OutputIterator,
           class T, class BinaryOperation>
   OutputIterator
      exclusive scan(InputIterator first, InputIterator last,
                     OutputIterator result,
                     T init, BinaryOperation binary_op);
 template<class InputIterator, class OutputIterator>
   OutputIterator
      inclusive_scan(InputIterator first, InputIterator last,
                     OutputIterator result);
 template<class InputIterator, class OutputIterator,
           class BinaryOperation>
   OutputIterator
```

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```
inclusive scan(InputIterator first, InputIterator last,
                      OutputIterator result,
                      BinaryOperation binary op);
   template<class InputIterator, class OutputIterator,
            class T, class BinaryOperation, class T>
     OutputIterator
       inclusive scan(InputIterator first, InputIterator last,
                      OutputIterator result.
                      T init, BinaryOperation binary_op, T init);
 }
}
4.4.2 Reduce
                                                                             [parallel.alg.reduce]
         template<class InputIterator>
               typename iterator traits<InputIterator>::value type
                 reduce(InputIterator first, InputIterator last);
 2 Effects: Same as reduce(first, last, typename iterator_traits<InputIterator>::value_type{}).
    Returns: reduce(first, last, typename iterator_traits<InputIterator>::value_type{})
    Requires: typename iterator_traits<InputIterator>::value_type{} shall be a valid expression.
    The operator+ function associated with iterator traits<InputIterator>::value type shall not
    invalidate iterators or subranges, nor modify elements in the range [first,last].
    Complexity: O(last - first) applications of operator+.
    Notes: The primary difference between reduce and accumulate is that the behavior of reduce
    may be non-deterministic for non-associative or non-commutative operator+.
         template<class InputIterator, class T>
               T reduce(InputIterator first, InputIterator last, T init);
```

4 Effects: Same as reduce(first, last, init, plus<>()).

Returns: reduce(first, last, init, plus<>())

3

Requires: The operator+ function associated with T shall not invalidate iterators or subranges, nor modify elements in the range [first, last].

Complexity: O(last - first) applications of operator+.

Notes: The primary difference between reduce and accumulate is that the behavior of reduce may be non-deterministic for non-associative or non-commutative operator+.

§ 4.4.2

- 6 Returns: GENERALIZED_SUM(binary_op, init, *first, ..., *(first + last first 1)*(first + (last first) 1)).
- ⁷ Requires: binary_op shall not invalidate iterators or subranges, nor modify elements in the range [first,last).
- ⁸ Complexity: O(last first) applications of binary op.
- ⁹ *Notes:* The primary difference between reduce and accumulate is that the behavior of reduce may be non-deterministic for non-associative or non-commutative operator+binary op.

4.4.3 Exclusive scan

[parallel.alg.exclusive.scan]

2 Effects: Same as exclusive_scan(first, last, result, init, plus<>()).

```
Returns: exclusive_scan(first, last, result, init, plus<>())
```

Requires: The operator+ function associated with iterator_traits<InputIterator>::value_type shall not invalidate iterators or subranges, nor modify elements in the ranges [first,last) or [result,result + (last - first)).

Complexity: O(last - first) applications of operator+.

Notes: The primary difference between exclusive_scan and inclusive_scan is that exclusive_scan excludes the ith input element from the ith sum. If the operator+ function is not mathematically associative, the behavior of exclusive scan may be non-deterministic.

§ 4.4.3

- 4 Effects: Assigns through each iterator i in [result, result + (last first)) the value of GENERALIZED_NONCOMMUTATIVE_SUM(binary_op, init, *first, ..., (*first + i - result - 1)*(first + (i - result) - 1)).
- ⁵ *Returns:* The end of the resulting range beginning at result.
- ⁶ Requires: binary_op shall not invalidate iterators or subranges, nor modify elements in the ranges [first,last) or [result,result + (last first)).
- ⁷ Complexity: O(last first) applications of binary op.
- ⁸ Notes: The primary difference between exclusive_scan and inclusive_scan is that exclusive_scan excludes the ith input element from the ith sum. If binary_op is not mathematically associative, the behavior of exclusive_scan may be non-deterministic.

4.4.4 Inclusive scan

[parallel.alg.inclusive.scan]

² Effects: Same as inclusive scan(first, last, result, plus<>()).

```
Returns: inclusive_scan(first, last, result, plus<>())
```

Requires: The operator+ function associated with iterator_traits<InputIterator>::value_type shall not invalidate iterators or subranges, nor modify elements in the ranges [first,last) or [result,result + (last - first)).

Complexity: O(last - first) applications of operator+.

Notes: The primary difference between exclusive_scan and inclusive_scan is that exclusive_scan excludes the ith input element from the ith sum. If the operator+ function is not mathematically associative, the behavior of inclusive scan may be non-deterministic.

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- 4 Effects: Assigns through each iterator i in [result, result + (last first)) the value of GENERALIZED_NONCOMMUTATIVE_SUM(binary_op, *first, ..., (*first + i result)*(first + (i result))) or GENERALIZED_NONCOMMUTATIVE_SUM(binary_op, init, *first, ..., (*first + i result)*(first + (i result))) if init is provided.
- ⁵ Returns: The end of the resulting range beginning at result.
- ⁶ Requires: binary_op shall not invalidate iterators or subranges, nor modify elements in the ranges [first,last) or [result,result + (last first)).
- ⁷ Complexity: O(last first) applications of binary_op.
- ⁸ Notes: The primary difference between exclusive_scan and inclusive_scan is that inclusive_scan includes the ith input element in the ith sum. If binary_op is not mathematically associative, the behavior of inclusive_scan may be non-deterministic.

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