## Portable Multitasking Real- Time Kernel Design and Implementation on DSP Systems

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#### Outline

- Introduction
- Taunix System Architecture
- Task Management
- Device Drivers
- Inter Process Communication
- Communication Network SECS-I protocol
- Future Works
- Live Demo

#### Introduction

- Motivation
- The problems this thesis tries to solve

## Taunix System Architecture

Real-time Tasks

Unified Device Driver
Interface

Device Drivers

Task: Management Inter Process Communication

Hardware: TI 320F243 DSP







#### Task Management

- Portable context switch facility setjmp/longjmp
- Priority- based scheduling
   16/32- level fixed priority scheduling
- Periodical task
  - 1. one- shot or periodic
  - 2. with simple priority policy

#### **Portable Context Switch**

Use jumping buffer to form Task Control Block (TCB)

```
Jumping Buffer:
                           TCB:
   TOS
                               void (*ret_addr)();
                               void * stack_pointer;
   AR1
                               void * stack frame;
   AR0
   AR6
                                     AR6
                               int
   AR7
                               int
                                     AR7
                               char
                                      state:
                               char *
                                     caption;
```

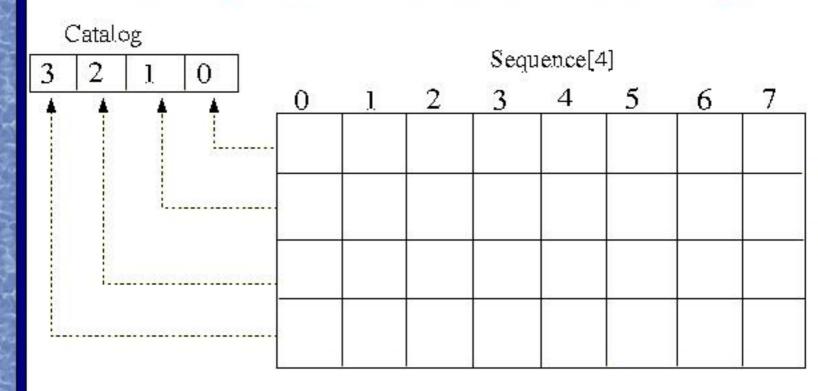
#### Portable Context Switch (cont.)

Use POSIX standard function calls to implement task switch

```
Task switching:
```

```
void task_switch(TCB * from, TCB * to)
{
   if(setjmp(from) == 0)
     tlongjmp(to, 1);
}
```

## **Priority-based Scheduling**



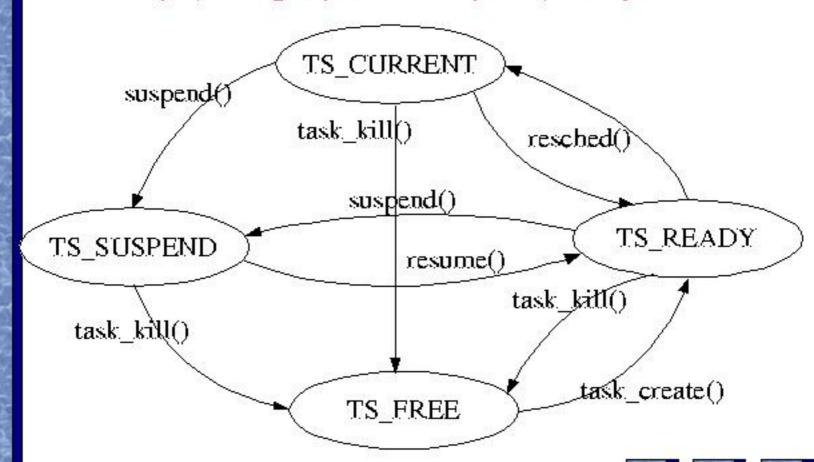
Use index mapping table to fast locate highest priority task.



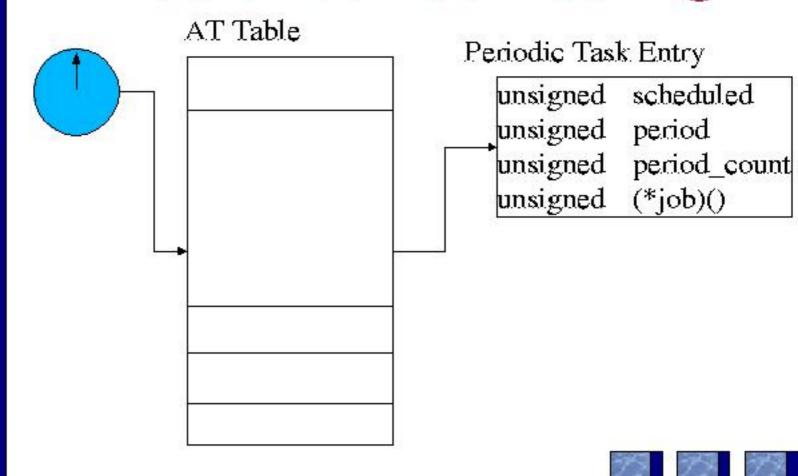




#### **Task State Transition**



#### Periodic Task Scheduling



#### **Device Drivers**

- Device Switch
   Unified device driver interface
- •Blocking/Non- Blocking I/O

  Efficiency and CPU utilization
- Supported Devices

#### **Device Switch**

☐ Unified Device Driver Interface Device Switch:

```
open() close()
read() write() ioctl()
```

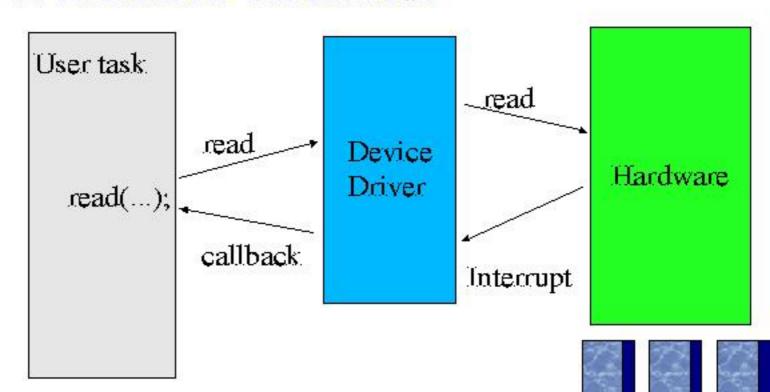






## Blocking/Non-Blocking I/O

□ Block/non-block mode



#### **Supported Devices**

- Supported devices
  - 1. Analog- to- digital convertor
  - 2. Capture unit
  - 3. General purpose timers
  - 4. PWM
  - 5. Serial communication with SECS-I
  - 6. Watch-dog

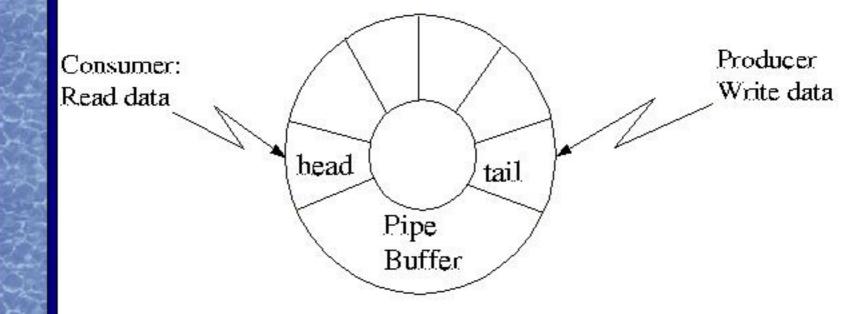
# Inter Process Communication

- Counting Semaphore
- ☐ Message Pipe/Queue

## IPC - Semaphore

- Counting semaphore plus:
  - 1. Limited priority- based pending list
  - 2. Non-blocking pending

## IPC - Message Pipe/Queue

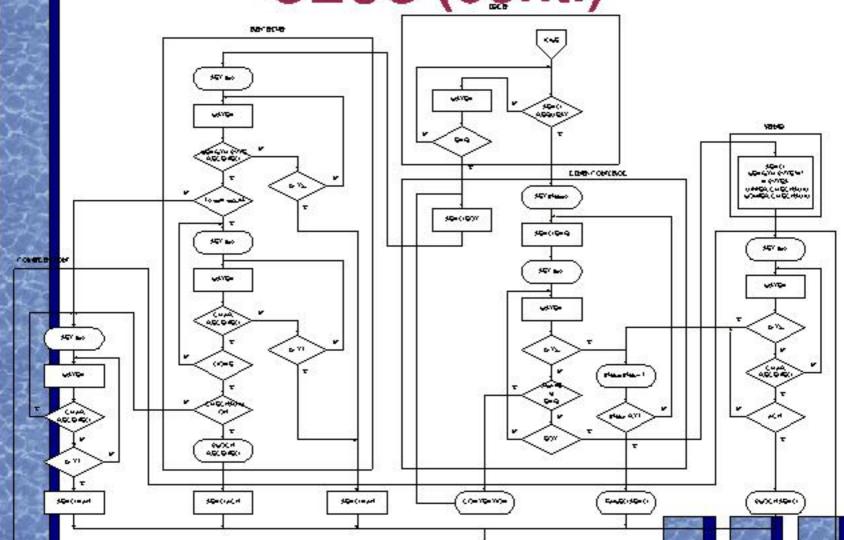


#### SECS

□ Point- to- Point Communication

□ Master/Slave Protocol

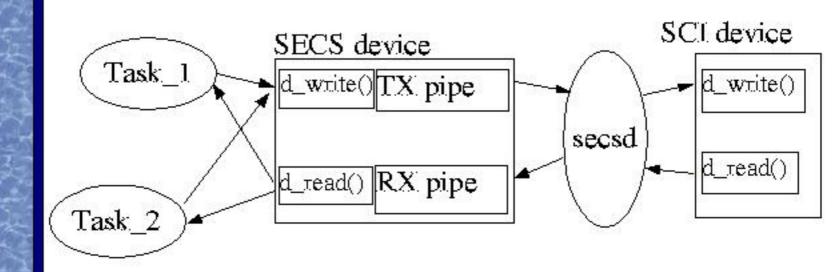
# SECS (cont.)



MATCHINETTO DECR

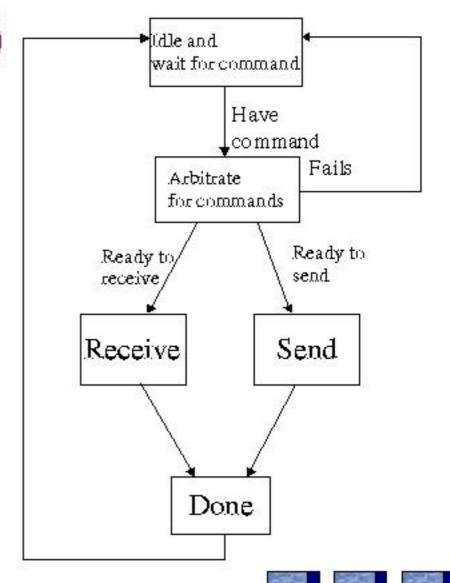
#### SECS (cont.)

Relation between Tasks, SECS virtual device and SECSd:



## SECS (cont.)

SECSd Event Flow Chart:



#### **Future Works**

- □ Taunix Virtual File System
- System Call Library
- Installable Scheduling System
- □ Architecture Porting
- □ Going to GPL

## **Live Demo**







## THANK YOU VERY MUSH