

Reinforcement Learning

HW 1-2

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Problem 1

(a) Q-value and discounted state visitation

$$\nabla_{\theta} V^{\pi_{\theta}}(\mu) = \frac{1}{1-\gamma} E_{s \sim d^{\pi_{\theta}}} E_{a \sim \pi_{\theta}(\cdot|s)} [Q^{\pi_{\theta}}(s, a) \nabla_{\theta} \log \pi_{\theta}(a|s)]$$

subtract a baseline function $B(s)$ from the policy gradient

$$E_{s \sim d^{\pi_{\theta}}} E_{a \sim \pi_{\theta}(\cdot|s)} [(Q^{\pi_{\theta}}(s, a) - B(s)) \nabla_{\theta} \log \pi_{\theta}(a|s)]$$

$$E_{s \sim d^{\pi_{\theta}}} E_{a \sim \pi_{\theta}(\cdot|s)} [B(s) \nabla_{\theta} \log \pi_{\theta}(a|s)]$$

$$= \sum_s d^{\pi_{\theta}}(s) \sum_a \pi_{\theta}(a|s) \nabla_{\theta} \log \pi_{\theta}(a|s) B(s)$$

$$= \sum_s d^{\pi_{\theta}}(s) B(s) \nabla_{\theta} \sum_a \pi_{\theta}(a|s) = 0$$

(b) REINFORCE

$$\nabla_{\theta} V^{\pi_{\theta}}(\mu) = E_{\tau \sim p_{\mu}^{\pi_{\theta}}} \left[\sum_{t=0}^{\infty} \gamma^t Q^{\pi_{\theta}}(s_t, a_t) \nabla_{\theta} \log \pi_{\theta}(a_t|s_t) \right]$$

subtract a baseline function $B(s)$ from the policy gradient

$$E_{\tau \sim p_{\mu}^{\pi_{\theta}}} \left[\sum_{t=0}^{\infty} \gamma^t (Q^{\pi_{\theta}}(s_t, a_t) - B(s_t)) \nabla_{\theta} \log \pi_{\theta}(a_t|s_t) \right]$$

$$E_{\tau \sim p_{\mu}^{\pi_{\theta}}} [B(s_t) \nabla_{\theta} \log \pi_{\theta}(a_t|s_t)]$$

$$= \sum_s P(s_t=s) \sum_a \pi_{\theta}(a|s) \nabla_{\theta} \log \pi_{\theta}(a|s) B(s)$$

$$= \sum_s P(s_t=s) B(s) \nabla_{\theta} \sum_a \pi_{\theta}(a|s) = 0$$

(c)

$$V[(G(t) - B(s)) \frac{d}{ds} \log \pi_0(a|s)]$$

$$= \sum_s P(s) (E[(G(t) - B(s)) \frac{d}{ds} \log \pi_0(a|s)] | s)$$

$$- (\sum_s P(s) E[(G(t) - B(s)) \frac{d}{ds} \log \pi_0(a|s) | s])^2$$

$$= \sum_s P(s) (\sum_a \pi_0(a|s) (E[(G(t) - B(s)) \frac{d}{ds} \log \pi_0(a|s)] | s, a))$$

$$- (\sum_s P(s) \sum_a \pi_0(a|s) E[(G(t) - B(s)) \frac{d}{ds} \log \pi_0(a|s) | s, a])^2$$

$$= \sum_s P(s)$$

$$= \sum_s P(s) (\sum_a \pi_0(a|s) (\frac{d}{ds} \log \pi_0(a|s))^2 E[(G(t) - B(s))^2 | s, a])$$

$$- (\sum_s P(s) \sum_a \pi_0(a|s) \frac{d}{ds} \log \pi_0(a|s) E[G(t) | s, a])^2$$

$$= \sum_s P(s) \sum_a C_a (E[G(t) - B(s) | s, a])$$

Problem 2

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12/12/22

(a) Show that $E_{\text{emp}}^{\pi_0} \left[\sum_{t=0}^{\infty} \gamma^t f(s_t, a_t) \right] = \frac{1}{1-\gamma} E_{\pi_0} E_{\pi_0(\cdot|s)} [f(s, a)]$

pf:

$$\text{RHS} = \frac{1}{1-\gamma} \sum_s d^{\pi_0}(s) \sum_a \pi_0(a|s) f(s, a)$$

$$= \frac{1}{1-\gamma} \sum_s \left(\sum_a \mu(s) (1-\gamma) \sum_{t=0}^{\infty} \gamma^t p(s_t=s | s_0, \pi_0) \right) \cdot \sum_a \pi_0(a|s) f(s, a)$$

$$= \sum_{s_0} \mu(s_0) \sum_s \sum_a \pi_0(a|s) \sum_{t=0}^{\infty} \gamma^t p(s_t=s | s_0, \pi_0) f(s, a)$$

$$= \sum_{s_0} \mu(s_0) \sum_s \sum_a \sum_{t=0}^{\infty} \gamma^t p(s_t=s, a_t=a | s_0, \pi_0) f(s, a)$$

$$= \sum_{s_0} \mu(s_0) \sum_z p(z|s_0) \sum_{t=0}^{\infty} \gamma^t f(s_t, a_t)$$

$$= \sum_z p(z) \sum_{t=0}^{\infty} \gamma^t f(s_t, a_t)$$

$$= E_{\text{emp}}^{\pi_0} \left[\sum_{t=0}^{\infty} \gamma^t f(s_t, a_t) \right]$$

$$= \text{LHS}$$

(b)

For episodic environments, show that

$$V^{\pi_0}(\mu) = \mathbb{E}_{\pi \sim p_{\pi_0}^{\mu}} \left[\sum_{t=0}^{T(\tau)-1} \gamma^t A^{\pi_0}(s_t, a_t) \nabla_{\theta} \log \pi_0(a_t | s_t) \right]$$

pf:

The major different between episodic and continuing environments is the existence of "terminate state"

Let s_* be the terminate state of an episodic environments

Once the agent reaches state s_* , it will stay at s_* forever (and hence the episode ends)

Moreover, $Q^{\pi}(s_*, a) = 0$, $V^{\pi}(s_*) = 0$, $A^{\pi}(s_*, a) = 0$, for all a and all π

Let $T(\tau)$ be the episode length of a trajectory τ ,

then, we have

$$V^{\pi_0}(\mu) = \mathbb{E}_{\pi \sim p_{\pi_0}^{\mu}} \left[\sum_{t=0}^{T(\tau)-1} \gamma^t A^{\pi_0}(s_t, a_t) \nabla_{\theta} \log \pi_0(a_t | s_t) \right]$$

~~$$\sum_{t=0}^{T(\tau)-1} \gamma^t A^{\pi_0}(s_t, a_t) \nabla_{\theta} \log \pi_0(a_t | s_t)$$~~

~~$$\sum_{t=0}^{T(\tau)-1} \gamma^t A^{\pi_0}(s_t, a_t) \nabla_{\theta} \log \pi_0(a_t | s_t)$$~~
$$= \mathbb{E}_{\pi \sim p_{\pi_0}^{\mu}} \left[\sum_{t=0}^{T(\tau)-1} \gamma^t A^{\pi_0}(s_t, a_t) \nabla_{\theta} \log \pi_0(a_t | s_t) \right]$$

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