

李宏毅 (Hung-yi Lee) · HYLEE | Machine Learning (2021)

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GAN

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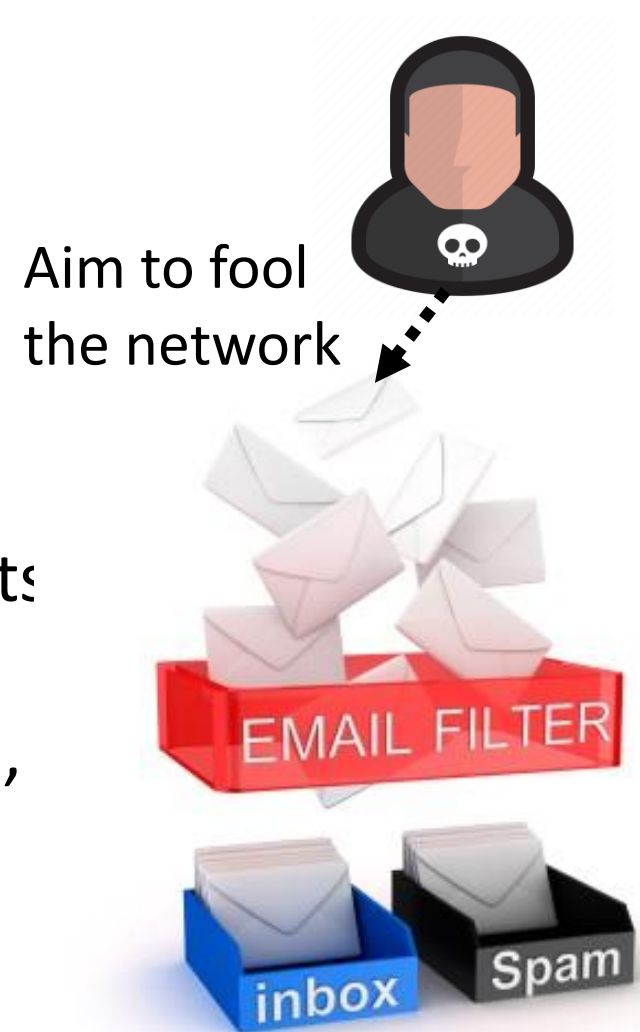
The background of the slide is a dynamic anime-style illustration. It depicts two characters in a close-quarters combat stance, their bodies tensed as they clash. A massive, brilliant white and yellow energy explosion erupts from the point of impact, radiating outwards in all directions. The scene is set against a dark, starry background, suggesting a cosmic or high-stakes battle environment. The overall color palette is dominated by the cool blues and greys of the characters' clothing, contrasted sharply with the intense, fiery colors of the energy release.

Adversarial Attack

Hung-yi Lee

Motivation


- You have trained many neural networks.
- We seek to deploy neural networks in the real world.
- Are networks robust to the inputs that are built to fool them?
 - Useful for spam classification, malware detection, network intrusion detection, etc.





人類不講武德 ...





How to Attack

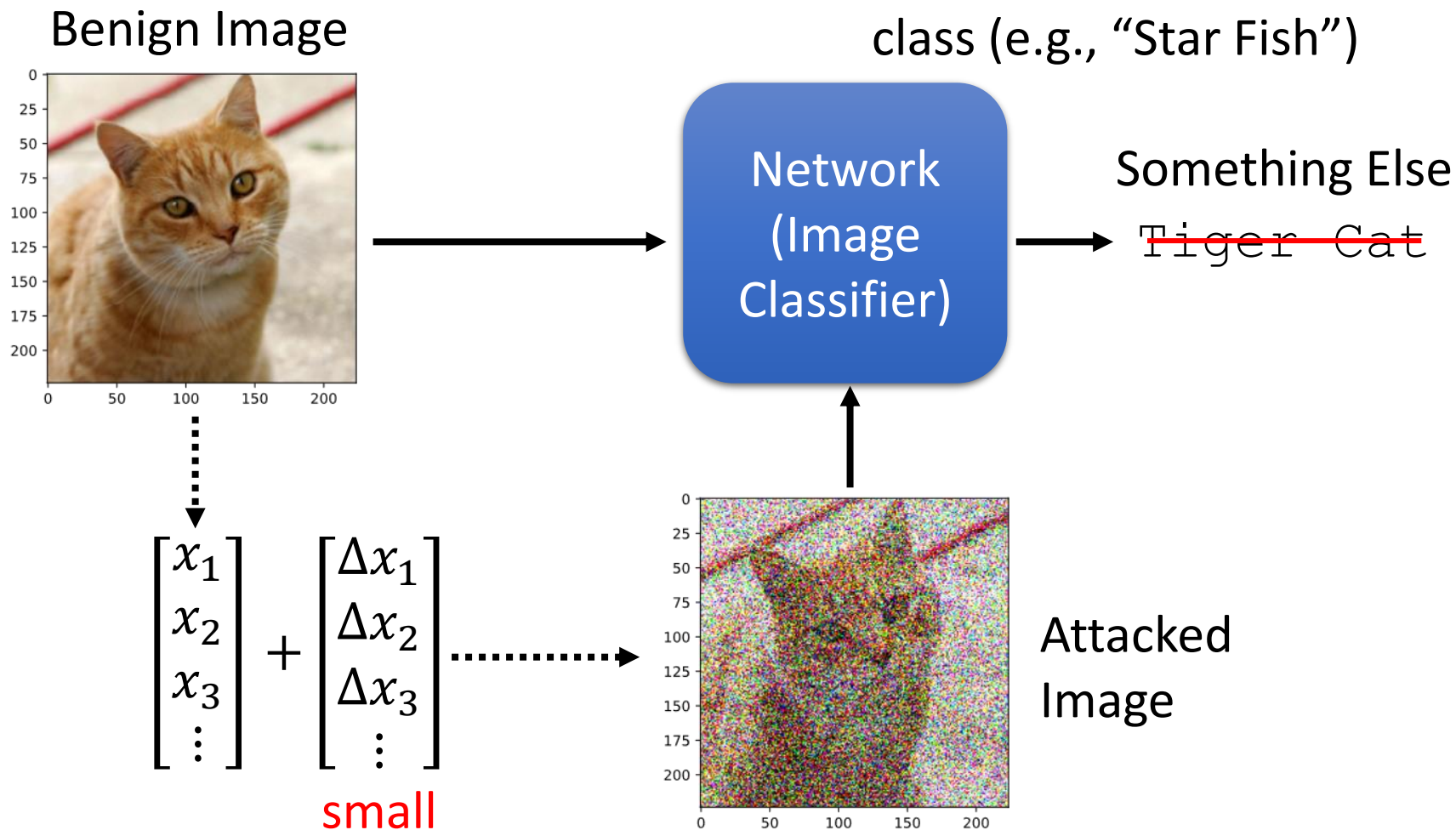
Example of Attack

Non-targeted

Anything other than “Cat”

Targeted

Misclassified as a specific class (e.g., “Star Fish”)

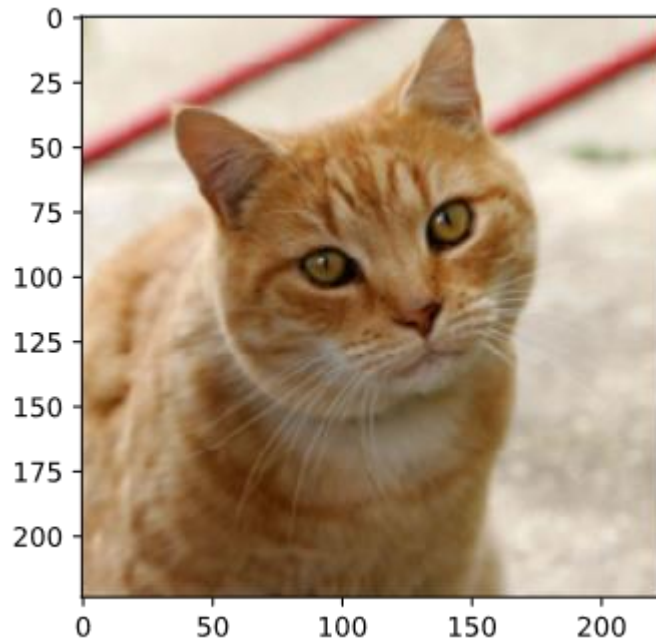


Example of Attack

Network = ResNet-50

The target is “Star Fish”

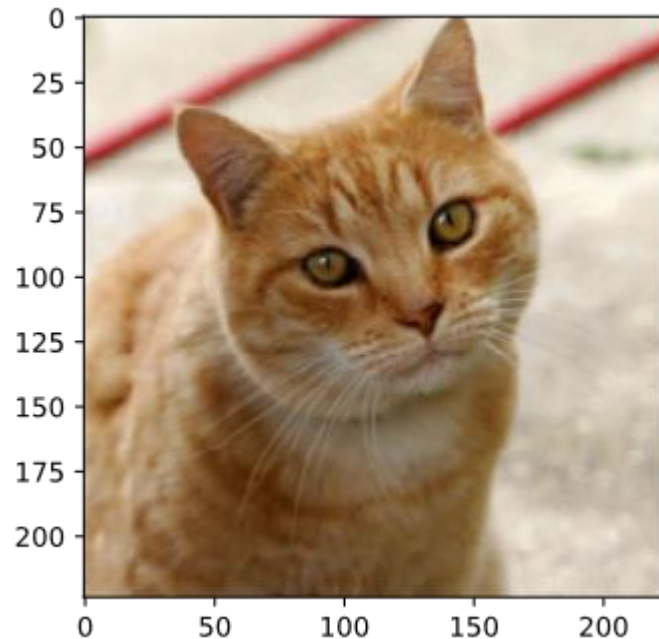
Benign Image



Tiger Cat

0.64

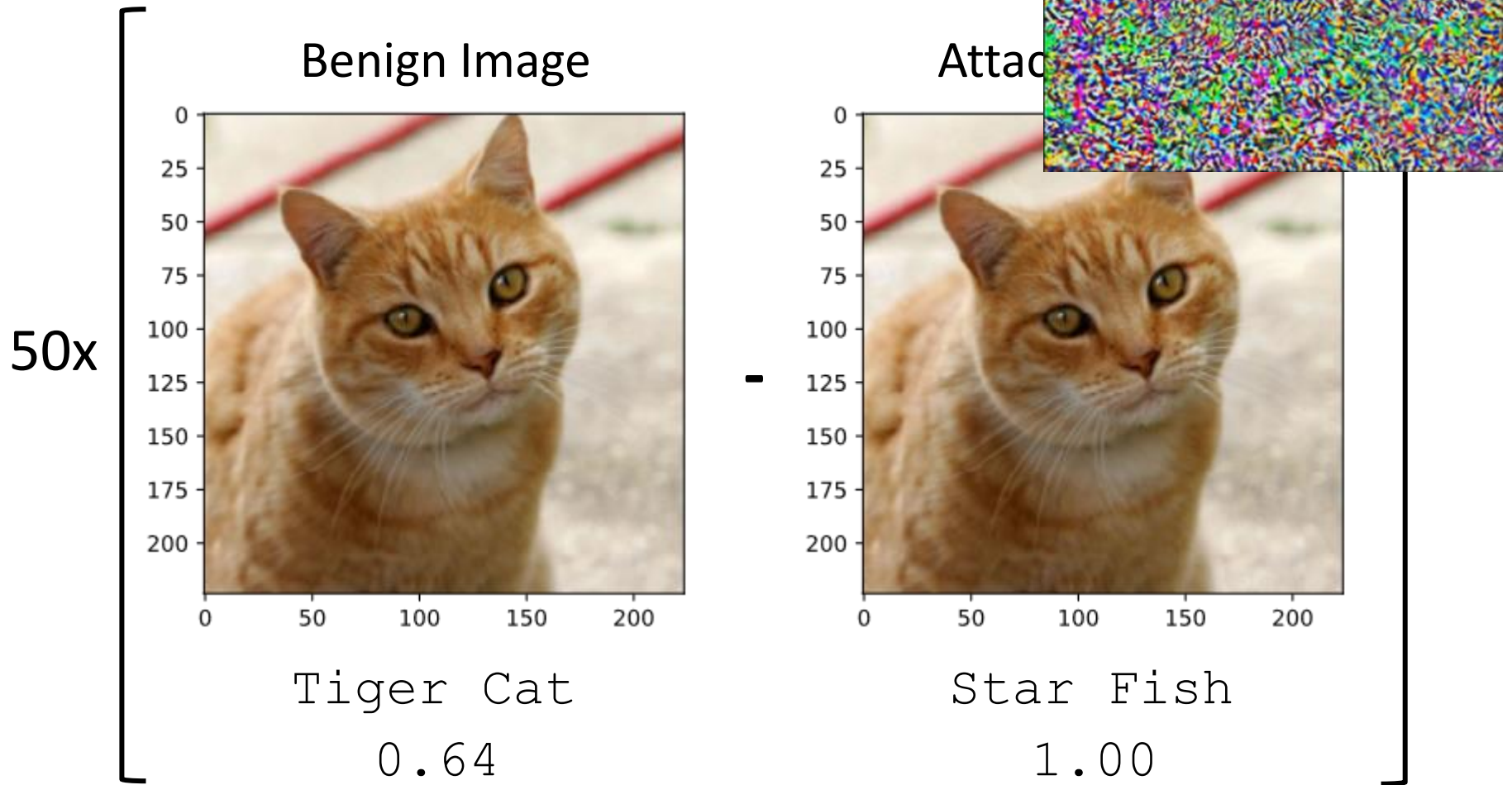
Attacked Image



Star Fish

1.00

Example of Attack

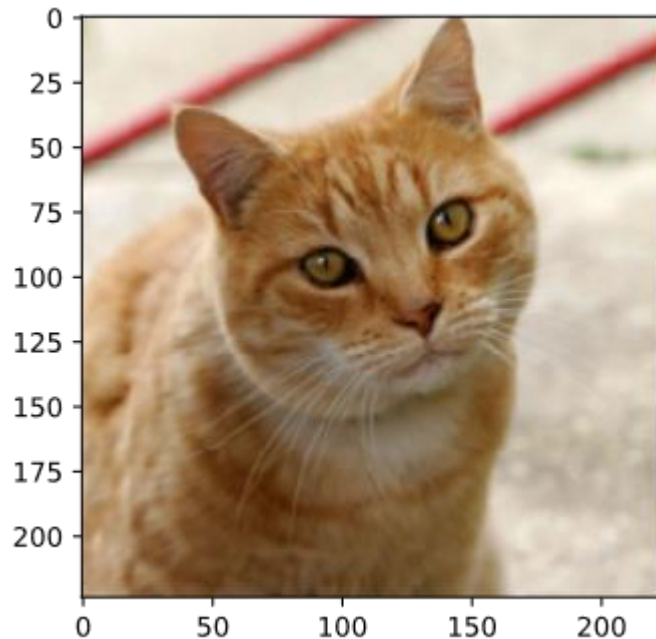


Example of Attack

Network = ResNet-50

The target is “Keyboard”

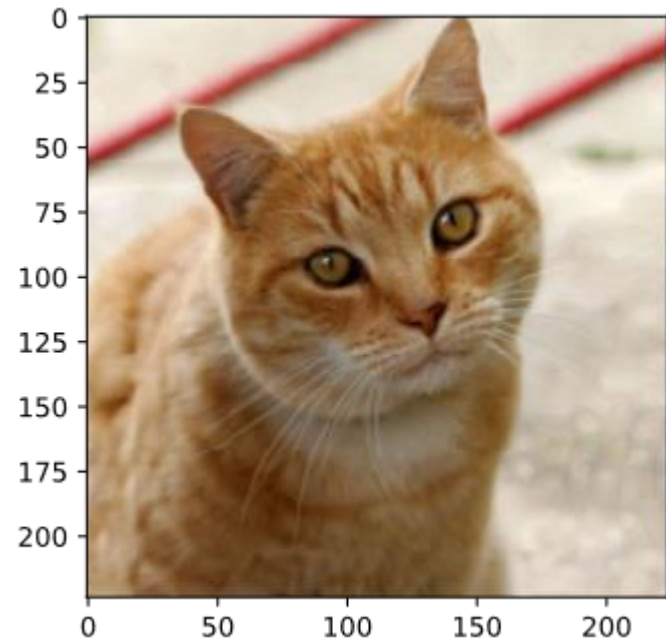
Benign Image



Tiger Cat

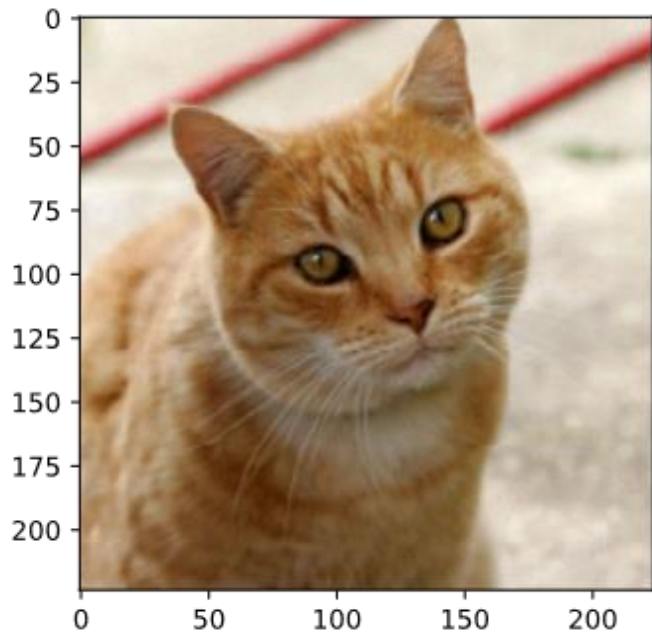
0.64

Attacked Image

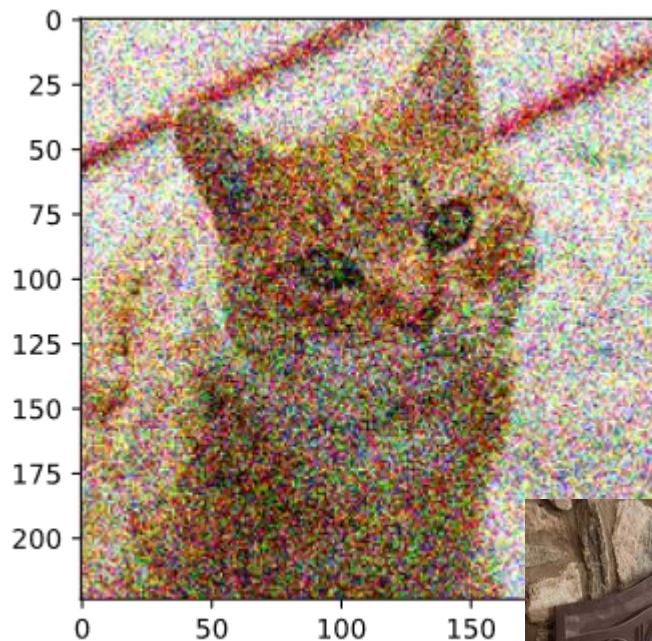


Keyboard

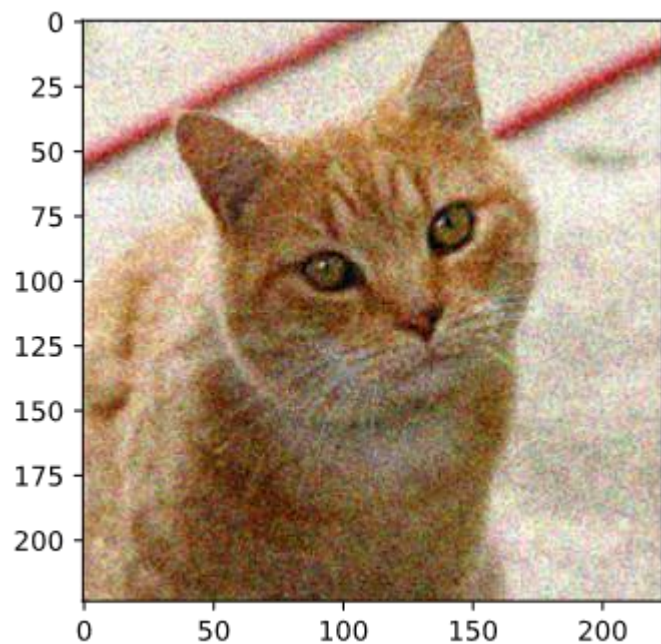
0.98



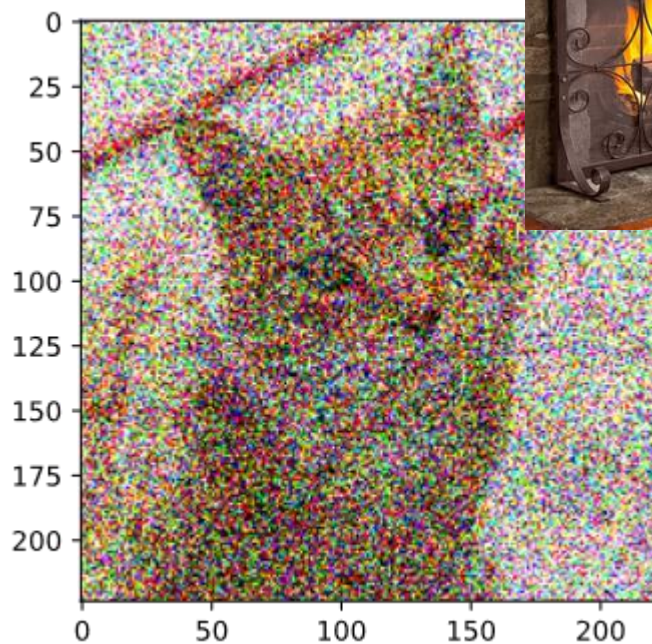
tiger
cat



Persian
cat



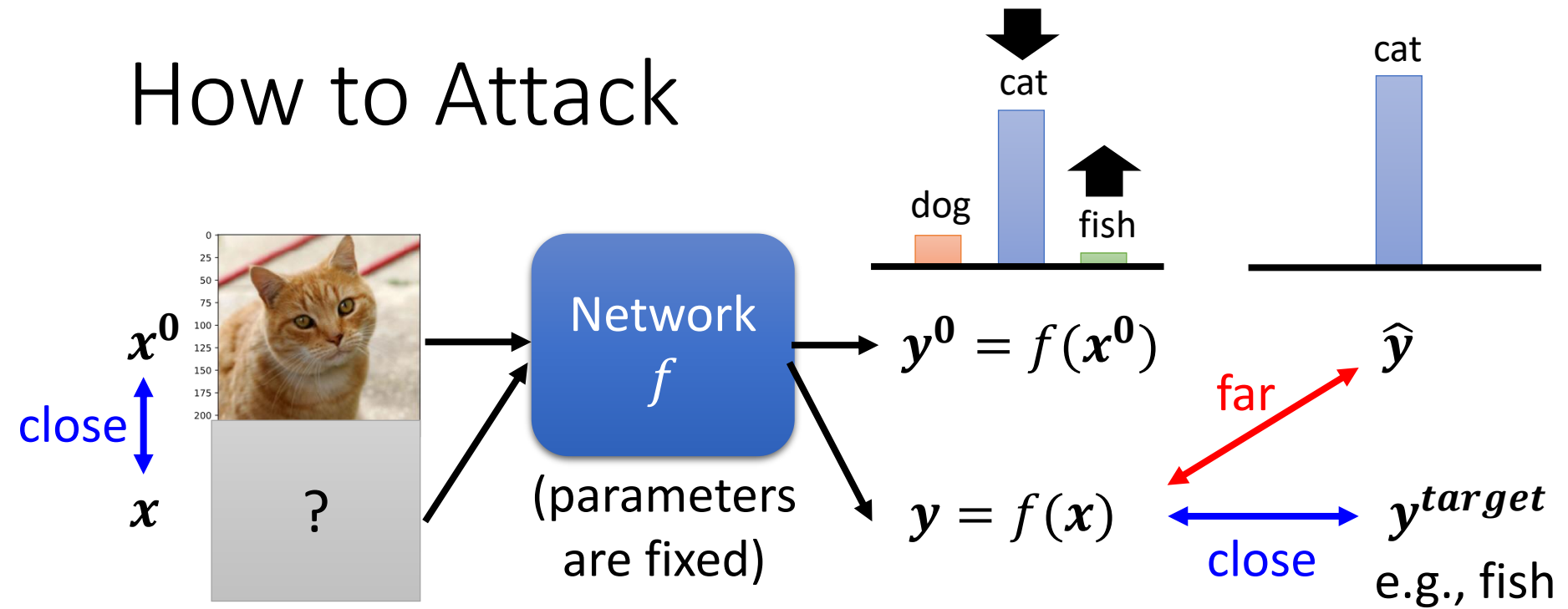
tabby
cat



fire
screen



How to Attack



Non-targeted

$$x^* = \arg \min L(x)$$

$$L(x) = -e(y, \hat{y})$$

not perceived
by humans

Targeted

$$L(x) = -e(y, \hat{y}) + e(y, y^{target})$$

Non-perceivable

$$d(\mathbf{x}^0, \mathbf{x}) \leq \varepsilon \quad \text{Need to consider human perception}$$

- L2-norm

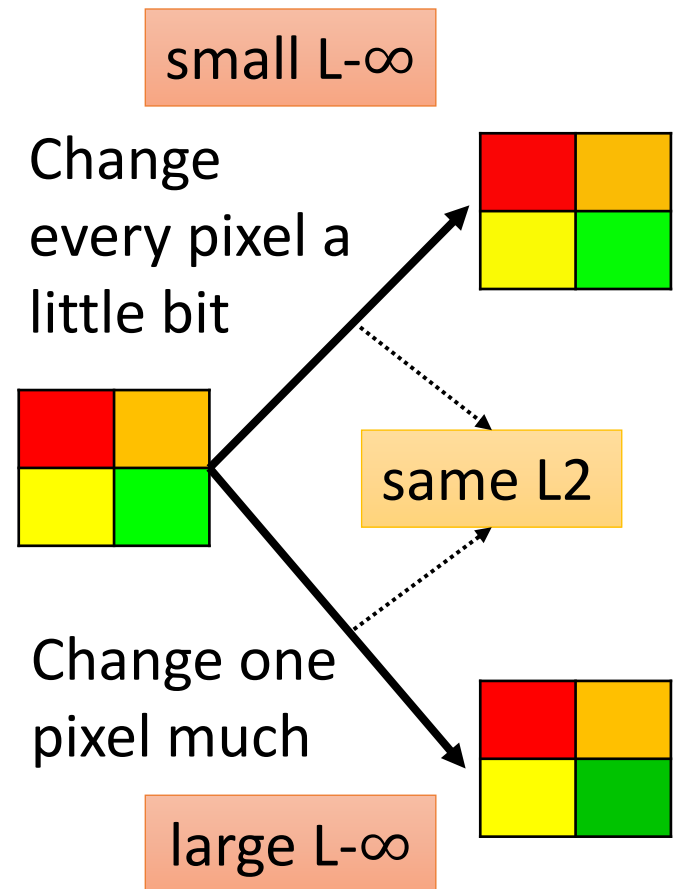
$$\begin{aligned} d(\mathbf{x}^0, \mathbf{x}) &= \|\Delta \mathbf{x}\|_2 \\ &= (\Delta x_1)^2 + (\Delta x_2)^2 + (\Delta x_3)^2 \dots \end{aligned}$$

- L-infinity

$$\begin{aligned} d(\mathbf{x}^0, \mathbf{x}) &= \|\Delta \mathbf{x}\|_\infty \\ &= \max\{|\Delta x_1|, |\Delta x_2|, |\Delta x_3|, \dots\} \end{aligned}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \end{bmatrix} - \begin{bmatrix} x_1^0 \\ x_2^0 \\ x_3^0 \\ \vdots \end{bmatrix} = \begin{bmatrix} \Delta x_1 \\ \Delta x_2 \\ \Delta x_3 \\ \vdots \end{bmatrix}$$

$\mathbf{x} \qquad \mathbf{x}^0 \qquad \Delta \mathbf{x}$



Attack Approach

$$w^*, b^* = \arg \min_{w, b} L \quad \text{Difference?}$$

Update *input*, not *parameters*

$$\mathbf{x}^* = \arg \min \quad L(\mathbf{x})$$

Gradient Descent

Start from original image \mathbf{x}^0

For $t = 1$ to T

$$\mathbf{x}^t \leftarrow \mathbf{x}^{t-1} - \eta \mathbf{g}$$

$$\mathbf{g} = \begin{bmatrix} \frac{\partial L}{\partial x_1} \big|_{\mathbf{x}=\mathbf{x}^{t-1}} \\ \frac{\partial L}{\partial x_2} \big|_{\mathbf{x}=\mathbf{x}^{t-1}} \\ \vdots \end{bmatrix}$$

$$w^*, b^* = \arg \min_{w, b} L \quad \text{Difference?}$$

Attack Approach

Update **input**, not **parameters**

$$x^* = \arg \min_{\substack{d(x^0, x) \leq \varepsilon}} L(x)$$

Different optimization methods

Different constraints

Gradient Descent

Start from original image x^0

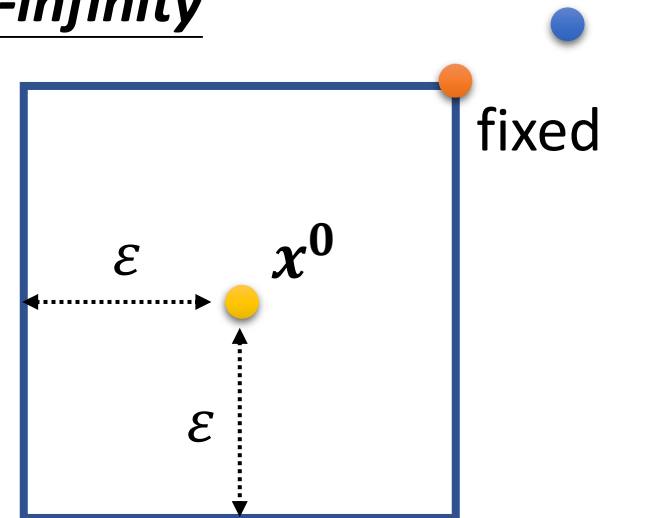
For $t = 1$ to T

$$x^t \leftarrow x^{t-1} - \eta g$$

$$\text{If } d(x^0, x) > \varepsilon$$

$$x^t \leftarrow \text{fix}(x^t)$$

L-infinity



Attack Approach

$$\mathbf{x}^* = \arg \min_{d(\mathbf{x}^0, \mathbf{x}) \leq \varepsilon} L(\mathbf{x})$$

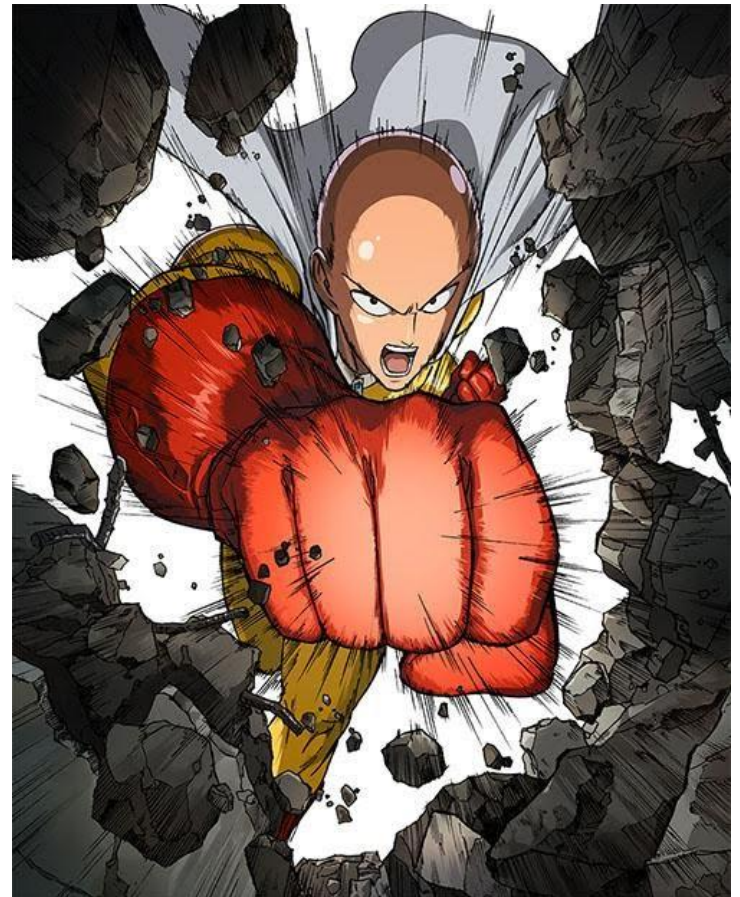
Fast Gradient Sign Method (FGSM)

<https://arxiv.org/abs/1412.6572>

Start from original image \mathbf{x}^0

For $t = 1$ ~~to~~ T

$$\mathbf{x}^t \leftarrow \mathbf{x}^{t-1} - \eta \mathbf{g}$$



Attack Approach

$$\mathbf{x}^* = \arg \min_{d(\mathbf{x}^0, \mathbf{x}) \leq \varepsilon} L(\mathbf{x})$$

Fast Gradient Sign Method (FGSM)

<https://arxiv.org/abs/1412.6572>

Start from original image \mathbf{x}^0

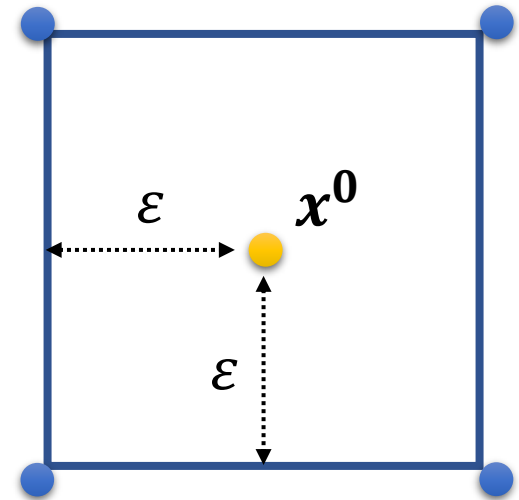
For $t = 1$ ~~to~~ T

$$\mathbf{x}^t \leftarrow \mathbf{x}^{t-1} - \eta \mathbf{g}$$

ε

$\begin{bmatrix} +1 \\ -1 \\ +1 \\ \vdots \end{bmatrix}$

L-infinity



$$\mathbf{g} = \begin{bmatrix} \pm 1 \cdot \text{sign} \left(\frac{\partial L}{\partial x_1} \Big|_{\mathbf{x}=\mathbf{x}^{t-1}} \right) \\ \pm 1 \cdot \text{sign} \left(\frac{\partial L}{\partial x_2} \Big|_{\mathbf{x}=\mathbf{x}^{t-1}} \right) \\ \vdots \end{bmatrix}$$

if $t > 0$, $\text{sign}(t) = 1$; otherwise, $\text{sign}(t) = -1$

Attack Approach

$$\mathbf{x}^* = \arg \min_{d(\mathbf{x}^0, \mathbf{x}) \leq \varepsilon} L(\mathbf{x})$$

Iterative FGSM

<https://arxiv.org/abs/1607.02533>

Start from original image \mathbf{x}^0

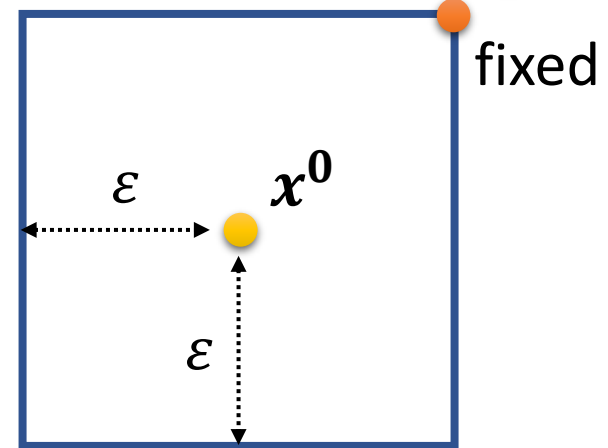
For $t = 1$ ~~to~~ T

$$\mathbf{x}^t \leftarrow \mathbf{x}^{t-1} - \eta \mathbf{g}$$

$$\text{If } d(\mathbf{x}^0, \mathbf{x}) > \varepsilon$$

$$\mathbf{x}^t \leftarrow \text{fix}(\mathbf{x}^t)$$

L -infinity



$$\mathbf{g} = \begin{bmatrix} \pm 1 \cdot \text{sign} \left(\frac{\partial L}{\partial x_1} \Big|_{\mathbf{x}=\mathbf{x}^{t-1}} \right) \\ \pm 1 \cdot \text{sign} \left(\frac{\partial L}{\partial x_2} \Big|_{\mathbf{x}=\mathbf{x}^{t-1}} \right) \\ \vdots \end{bmatrix}$$

White Box v.s. Black Box

- In the previous attack, we know the network parameters θ
 - This is called **White Box Attack**.
- You cannot obtain model parameters in most online API.
- Are we safe if we do not release model? ☺
- No, because **Black Box Attack** is possible. ☹

$$\mathbf{g} = \begin{bmatrix} \text{sign} \left(\frac{\partial L}{\partial x_1} \Big|_{x=x^{t-1}} \right) \\ \text{sign} \left(\frac{\partial L}{\partial x_2} \Big|_{x=x^{t-1}} \right) \\ \vdots \end{bmatrix}$$

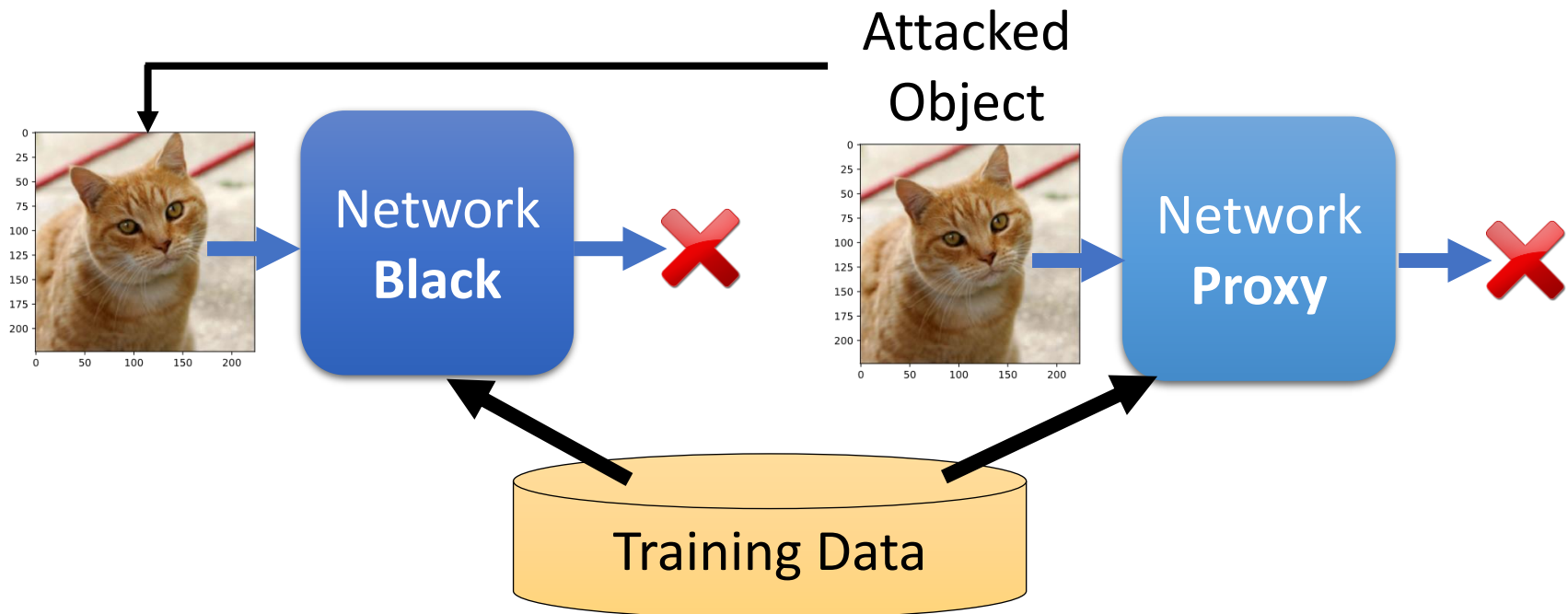


Black Box Attack

If you have the training data of the target network

Train a proxy network yourself

Using the proxy network to generate attacked objects



What if we do not know the training data?

Black Box Attack

<https://arxiv.org/pdf/1611.02770.pdf>

Be Attacked

Proxy

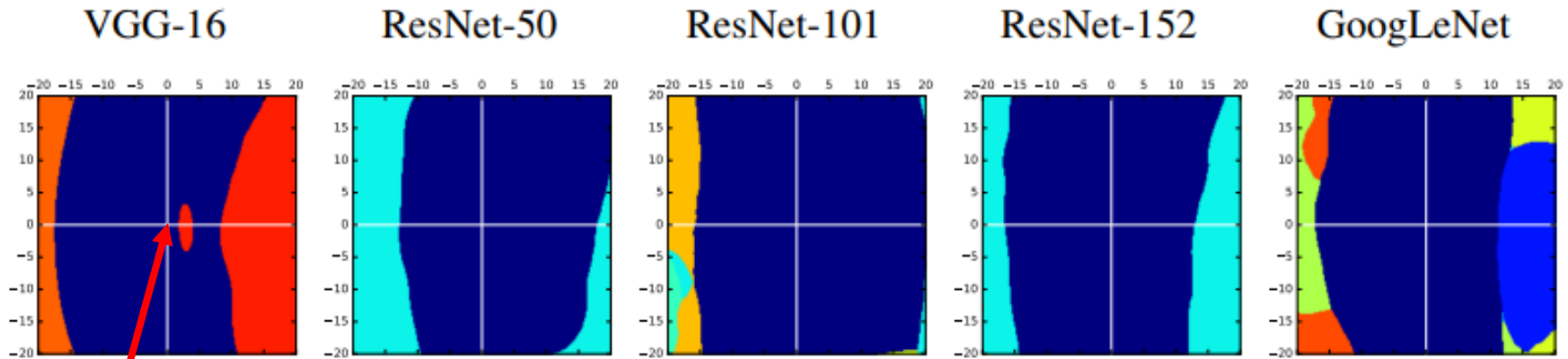
	ResNet-152	ResNet-101	ResNet-50	VGG-16	GoogLeNet
ResNet-152	0%	13%	18%	19%	11%
ResNet-101	19%	0%	21%	21%	12%
ResNet-50	23%	20%	0%	21%	18%
VGG-16	22%	17%	17%	0%	5%
GoogLeNet	39%	38%	34%	19%	0%

(lower accuracy → more successful attack)

Ensemble Attack

	ResNet-152	ResNet-101	ResNet-50	VGG-16	GoogLeNet
-ResNet-152	0%	0%	0%	0%	0%
-ResNet-101	0%	1%	0%	0%	0%
-ResNet-50	0%	0%	2%	0%	0%
-VGG-16	0%	0%	0%	6%	0%
-GoogLeNet	0%	0%	0%	0%	5%

The attack is so easy! Why?



<https://arxiv.org/pdf/1611.02770.pdf>

To learn more:

Adversarial Examples Are Not
Bugs, They Are Features

<https://arxiv.org/abs/1905.02175>



One pixel attack

Source of image:

<https://arxiv.org/abs/1710.08864>



joystick

Video: <https://youtu.be/tfpKIZIWidA>



Cup(16.48%)
Soup Bowl(16.74%)



Bassinet(16.59%)
Paper Towel(16.21%)



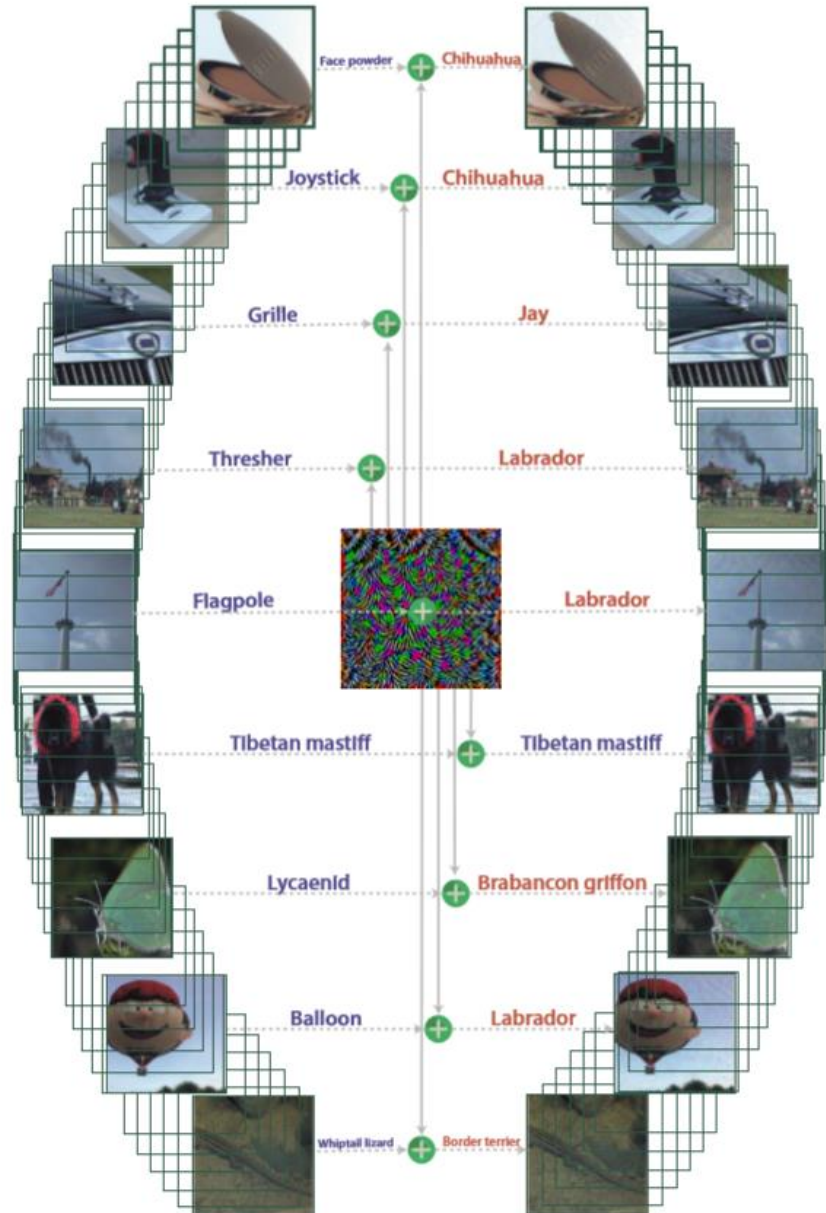
Teapot(24.99%)
Joystick(37.39%)



Hamster(35.79%)
Nipple(42.36%)

Universal Adversarial Attack

<https://arxiv.org/abs/1610.08401>



Black Box Attack is also possible!

Beyond Images

感謝吳海濱同學提供實驗結果

- Speech processing

Detect synthesized
speech

Synthesized!



Real!



- Natural language processing

<https://arxiv.org/abs/1908.07125>

Question: Why did he walk?

For exercise, Tesla walked between 8 to 10 miles per day. He squished his toes one hundred times for each foot every night, saying that it stimulated his brain cells. '

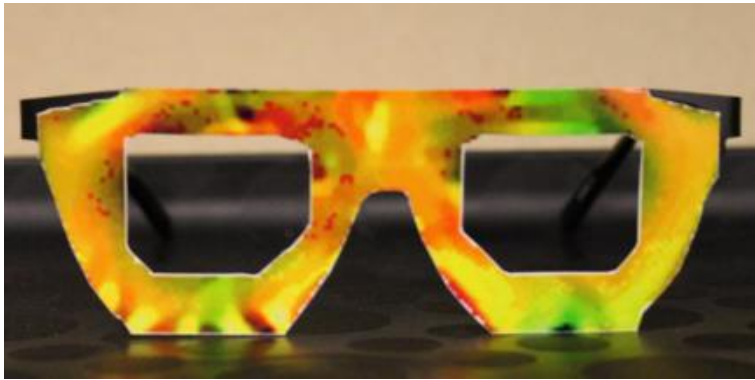
exercise

Question: Why did the university see a drop in applicants?


























In the early 1950s, student applications declined as a result of increasing crime and poverty in the Hyde Park neighborhood. In response, the university became a

crime and poverty

Attack in the Physical World



- An attacker would need to find perturbations that generalize beyond a single image.
- Extreme differences between adjacent pixels in the perturbation are unlikely to be accurately captured by cameras.
- It is desirable to craft perturbations that are comprised mostly of colors reproducible by the printer.

Distance/Angle	Subtle Poster	Subtle Poster Right Turn	Camouflage Graffiti	Camouflage Art (LISA-CNN)	Camouflage Art (GTSRB-CNN)
5' 0°					
5' 15°					
10' 0°					
10' 30°					
40' 0°					
Targeted-Attack Success	100%	73.33%	66.67%	100%	80%

<https://arxiv.org/abs/1707.08945>

Attack in the Physical World



read as an 85-mph sign

https://youtu.be/4uGV_fRj0UA

<https://www.mcafee.com/blogs/other-blogs/mcafee-labs/model-hacking-adas-to-pave-safer-roads-for-autonomous-vehicles/>

Adversarial Reprogramming

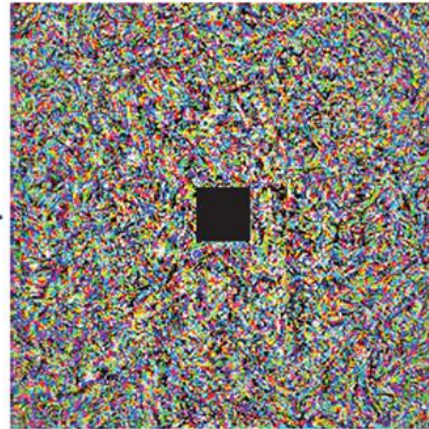


(a) counting ImageNet (b)

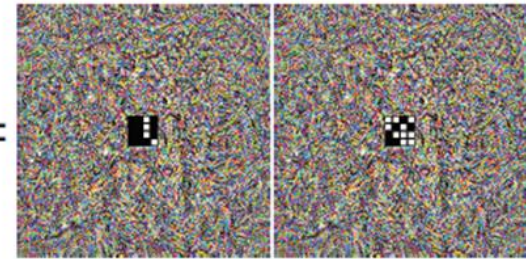
y_{adv}	y
1 square	tench
2 squares	goldfish
3 squares	white shark
4 squares	tiger shark
5 squares	hammerhead
6 squares	electric ray
7 squares	stingray
8 squares	cock
9 squares	hen
10 squares	ostrich



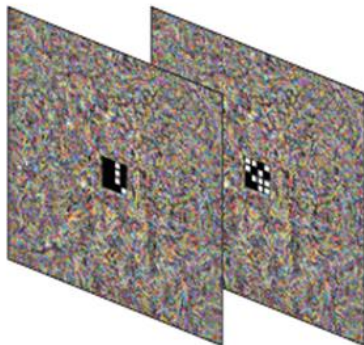
Adversarial Program



=



(c)



ImageNet Classifier

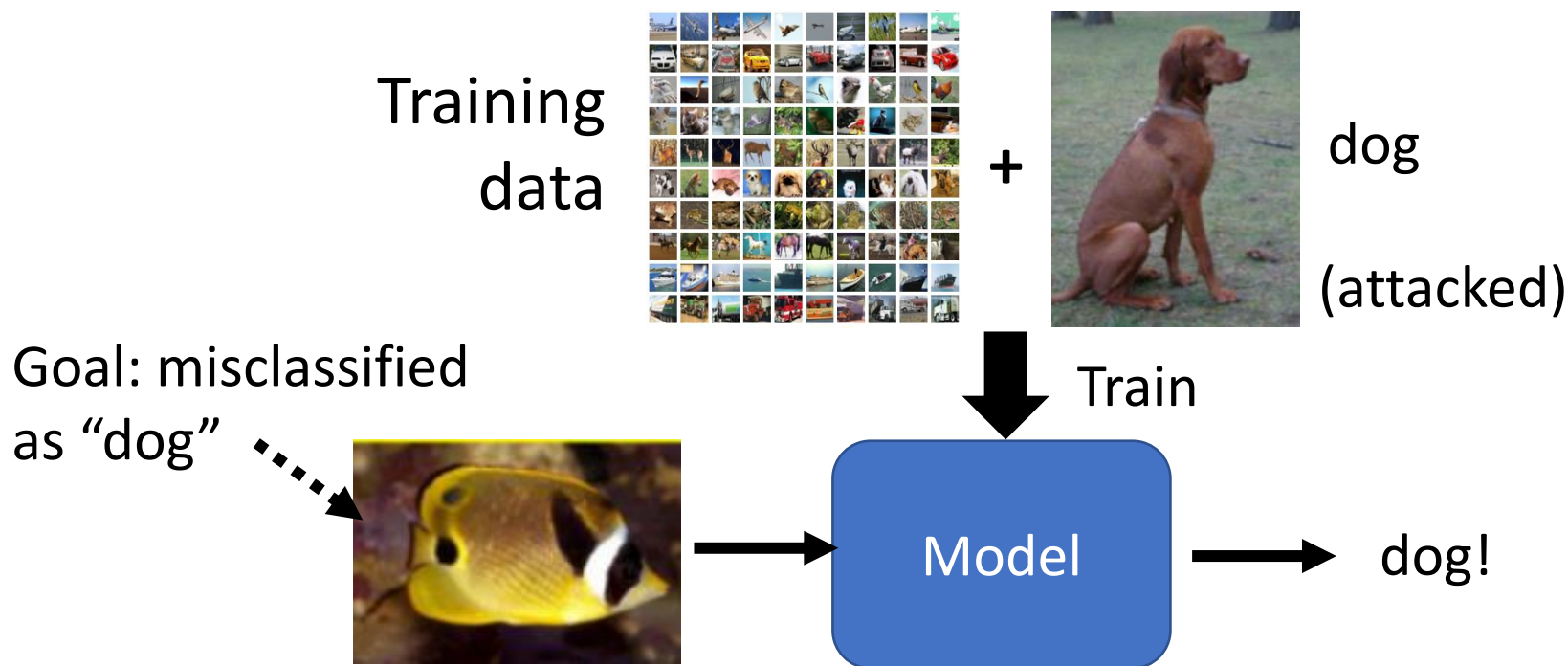


tiger shark, ostrich
≡
4 squares, 10 squares


“Backdoor” in Model

<https://arxiv.org/abs/1804.00792>

- Attack happens at the training phase



be careful of unknown dataset

The background of the slide is a close-up, slightly angled view of Captain America's shield. It features concentric circles of red and silver, with a blue center containing a white five-pointed star. The text is centered over the star.

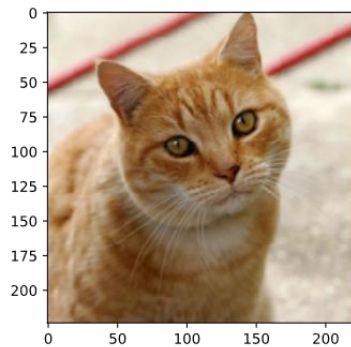
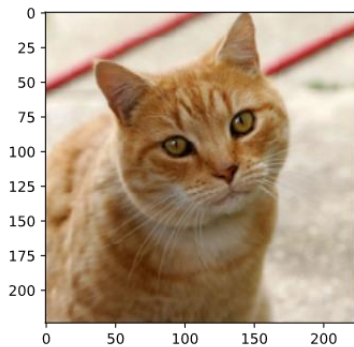
Defense

Passive v.s. Proactive

Passive Defense

Do not influence
classification

Original



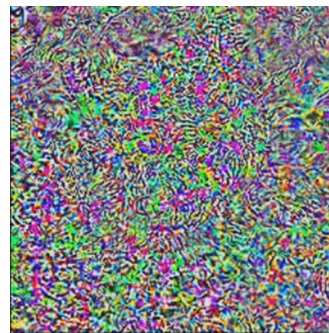
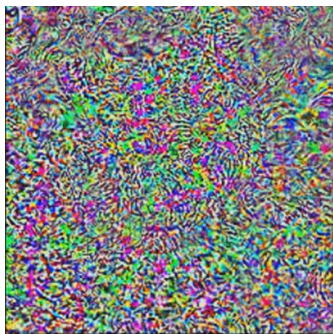
+

Filter

+

Network

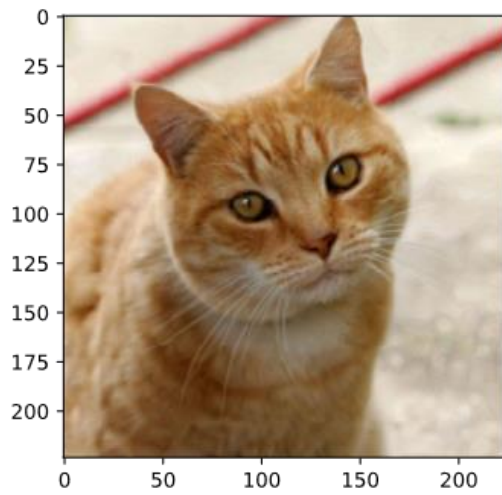
Tiger Cat
~~Keyboard~~



e.g.
Smoothing

Attack signal

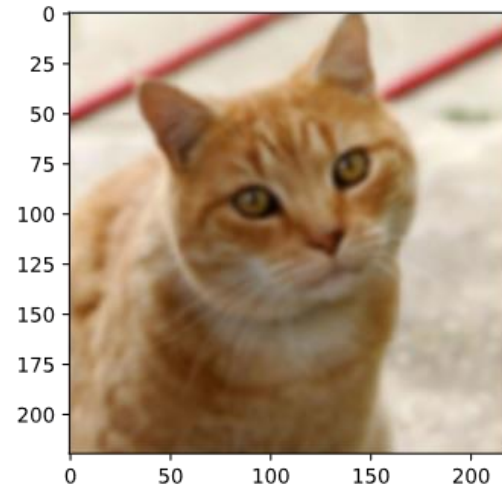
Less harmful



Keyboard

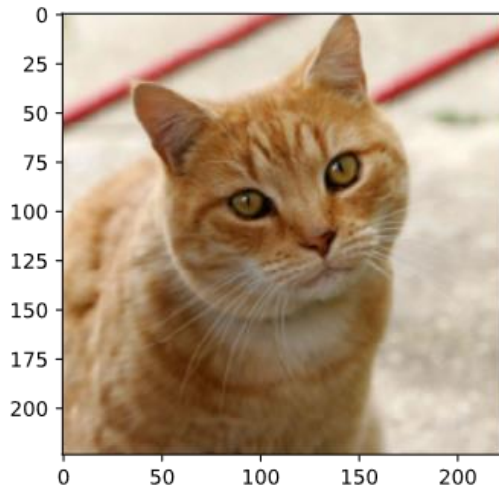
0.98

→
Smoothing



tiger cat

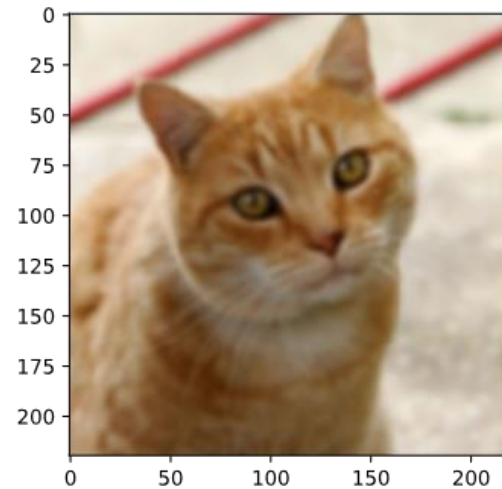
0.37



tiger cat

0.64

→
Smoothing



tiger cat

0.45

Side Effect!

Passive Defense

Image Compression

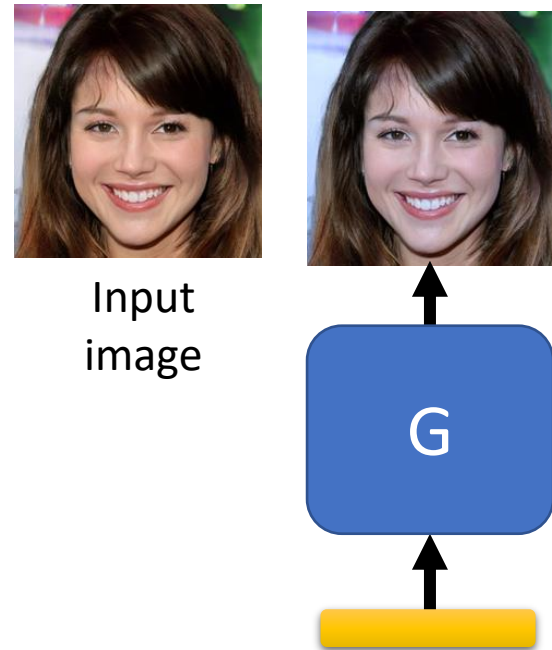


<https://arxiv.org/abs/1704.01155>

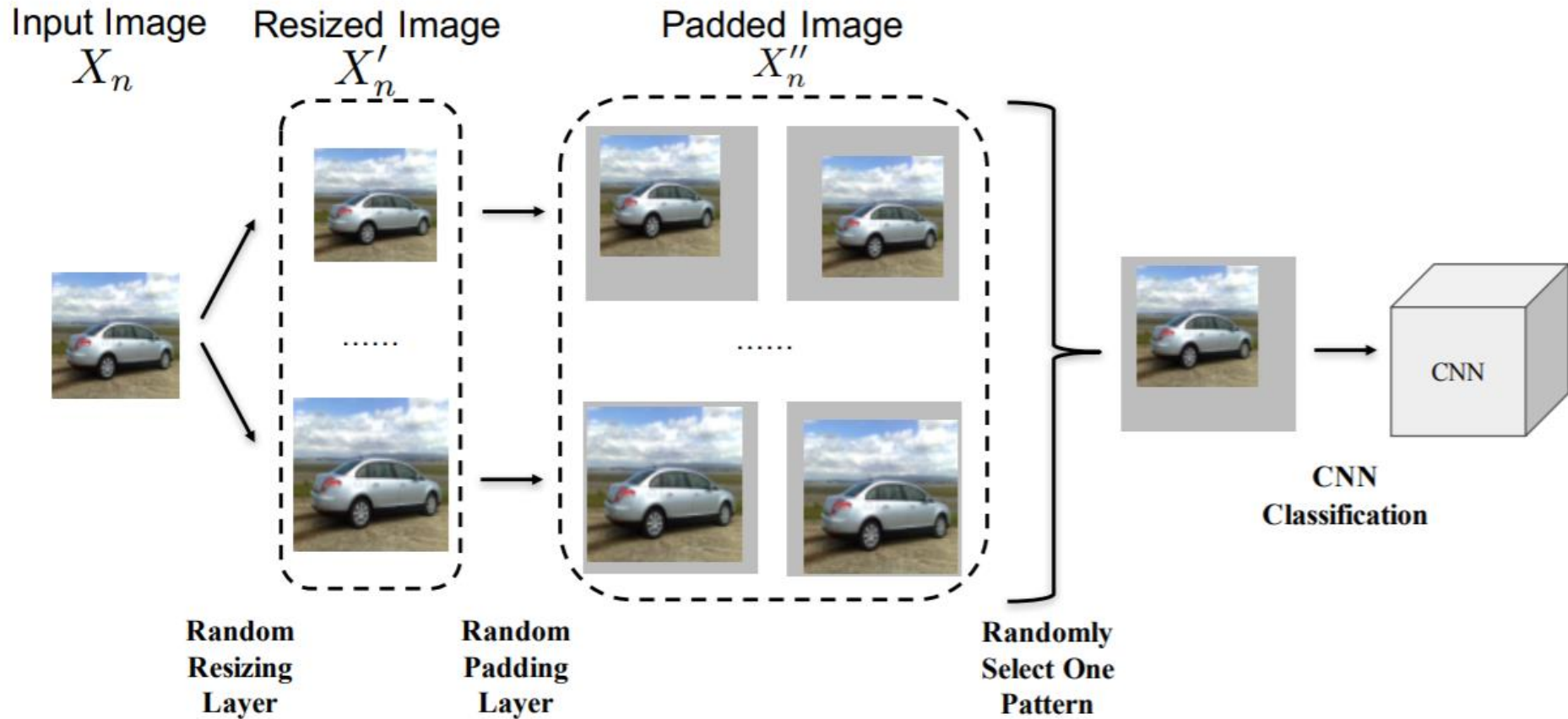
<https://arxiv.org/abs/1802.06816>

Generator

<https://arxiv.org/abs/1805.06605>



Passive Defense - Randomization



Proactive Defense

Adversarial Training

Training a model that is robust to adversarial attack.

Given training set $\mathcal{X} = \{(\mathbf{x}^1, \hat{y}^1), (\mathbf{x}^2, \hat{y}^2), \dots, (\mathbf{x}^N, \hat{y}^N)\}$

Using \mathcal{X} to train your model

For $n = 1$ to N

Can it deal with new algorithm?

Find adversarial input $\tilde{\mathbf{x}}^n$ given \mathbf{x}^n by an attack algorithm

Find the problem

We have new training data

$$\mathcal{X}' = \{(\tilde{\mathbf{x}}^1, \hat{y}^1), (\tilde{\mathbf{x}}^2, \hat{y}^2), \dots, (\tilde{\mathbf{x}}^N, \hat{y}^N)\}$$

Using both \mathcal{X} and \mathcal{X}' to update your model Fix it!

Data Augmentation



Concluding Remarks

- Attack: given the network parameters, attack is very easy.
- Even black box attack is possible
- Defense: Passive & Proactive
- Attack / Defense are still evolving.

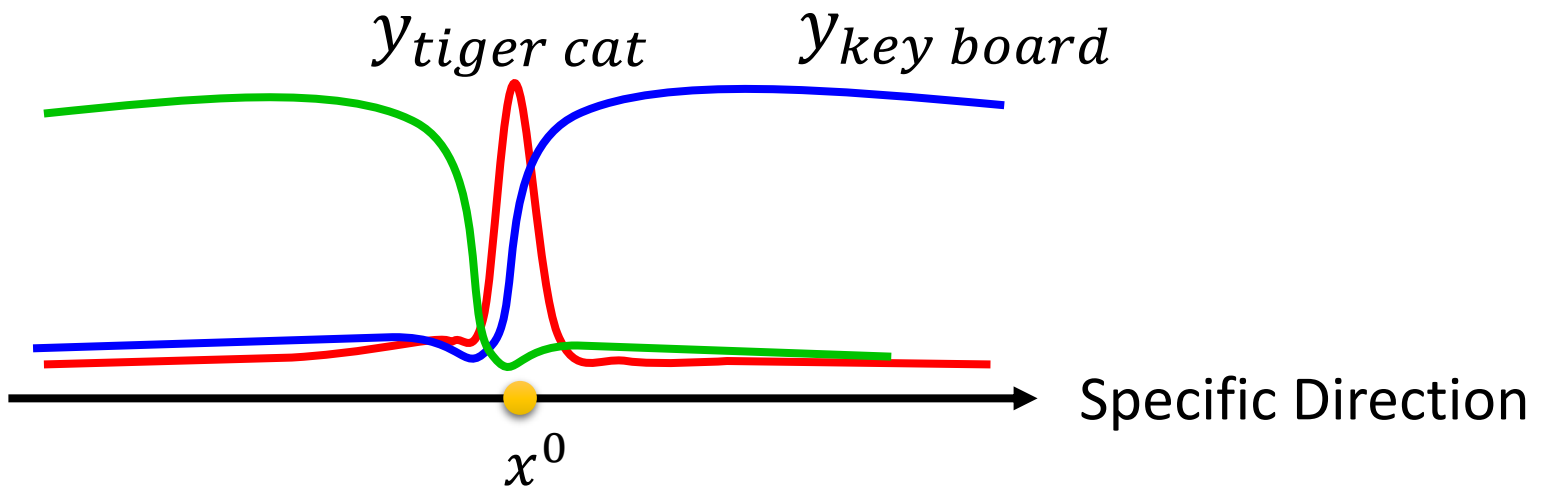
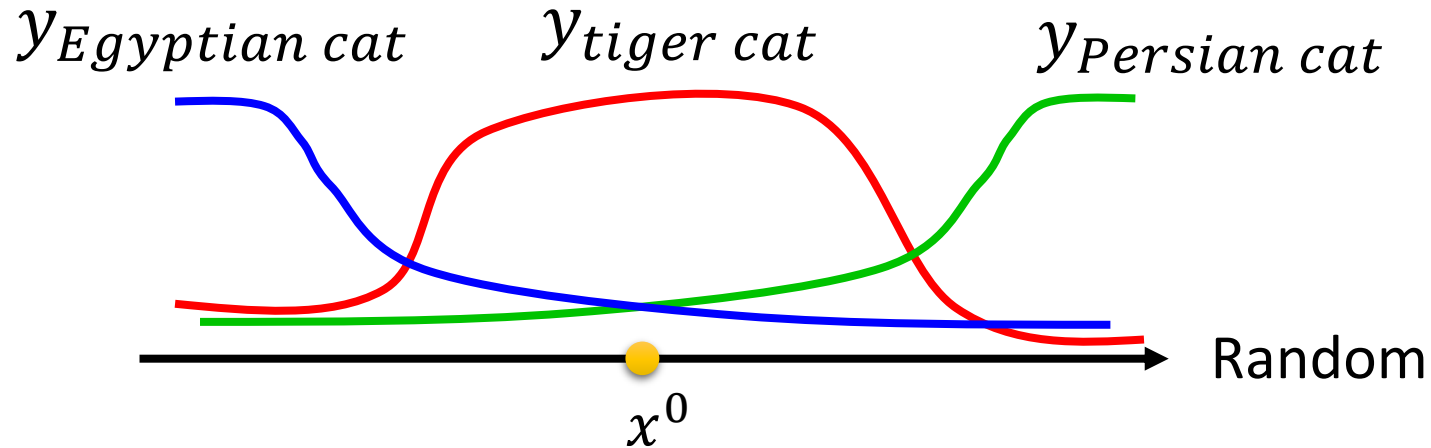
Acknowledgement

- 感謝作業十助教團隊林毓宸同學、黃啟斌同學幫忙蒐集參考

Attack Approaches

- FGSM (<https://arxiv.org/abs/1412.6572>)
- Basic iterative method (<https://arxiv.org/abs/1607.02533>)
- L-BFGS (<https://arxiv.org/abs/1312.6199>)
- Deepfool (<https://arxiv.org/abs/1511.04599>)
- JSMA (<https://arxiv.org/abs/1511.07528>)
- C&W (<https://arxiv.org/abs/1608.04644>)
- Elastic net attack (<https://arxiv.org/abs/1709.04114>)
- Spatially Transformed (<https://arxiv.org/abs/1801.02612>)
- One Pixel Attack (<https://arxiv.org/abs/1710.08864>)
- only list a few

What happened?



李宏毅 (Hung-yi Lee) · HYLEE | Machine Learning (2021)

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<http://blog.showmeai.tech/ntu-hylee-ml>

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自监督

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批次标准化

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