```
In [1]: from pulp import *
```

Question 1

```
1.1 c \le 0; a <= 0; b <= 0; all others free
```

A tableau is optimal if and only if all coefficients of the variables are nonpositive.

```
1.2 c > 0; d >= max(0, 5e/6); all others free
```

The selection of optimal exiting variables is based on the min ratio rule. By this rule, this means to exit on x3 the constraint $5 / d \ge 6$ /e must be sastified. We equalize the constraint by transforming it to $30/6d \ge 30/5e$ therefore it can be reduced to $6d \ge 5e$ and simplified to $d \ge 5e/6$. We add a 0 constraint in the event e is negative.

```
1.3\,\mathrm{c} > 0; e <= 0; d <= 0; all others free
```

A problem is unbounded if all coefficients of the entering variable column are nonpositive. We select entering variables which are positive.

Question 2

2.1

```
max z = x[1] + 2*x[2] + 3*x[3]

s.t.

x[1] + x[2] + x[3] + s[1] = 16

3*x[1] + 2*x[2] + 2*x[3] = 26

x[1] + x[3] - s[2] = 10

x[1], x[2], x[3], s[1], s[2] >= 0
```

2.2

min.
$$z = y[1] + y[2]$$

s.t.
 $x[1] + x[2] + x[3] + s[1] = 16$
 $3*x[1] + 2*x[2] + 2*x[3] + y[1] = 26$
 $x[1] + x[3] - s[2] + y[2] = 10$
 $x[1], x[2], x[3], s[1], s[2], y[1], y[2] >= 0$

2.3

Form initial tableau in canonical form

```
-z x1
          x2
              x3
                  s1
                      s2
                              y2
                                   RHS
                          y1
r1 1
       5
           3
               4
                   1
                      -1
                           0
                               0
                                    52
r2 0
       1
           1
               1
                   1
                       0
                           0
                               0
                                    16
r3 0
       3
           2
               2
                   0
                       0
                               0
                                    26
                           1
```

```
r4 0 1 0 1 0 -1 0 1
                                      10
enter x3; exit y2;
   -z x1
           x2
               xЗ
                   s1 s2
                           у1
                               y2
                                     RHS
        1
            3
                0
                    1
                        3
                            0
                               -4
                                      12 ; = r1 - 4*r4
r1
                                      6 ; = r2
r2
   0
        0
                0
                    1
                        1
                            0
                               -1
                                                - r4
                        2
                               -2
                                      6 ; = r3 - 2*r4
r3 0
        1
                0
                            1
        1
                    0 -1
                                1
                                      10
enter x1; exit y1;
   -z x1
           x2
               xЗ
                   s1 s2
                           у1
                               y2
                                    RHS
        0
                0
                    1
                        1
                               -2
                                       6 ; r1 = r1 - r3
r1
   1
            1
                           -1
r2
   0
                0
                    1
                        1
                               -1
        0
            1
                            0
                        2
            2
                               -2
r3 0
        1
                0
                    0
                            1
                                       6
r4 0
        0
          -2
                1
                    0 -3 -1
                                3
                                       4 : r4 = r4 - r3
enter x2; exit x1;
   -z
        x1
             x2
                  xЗ
                       s1
                            s2
                                 у1
                                       y2
                                             RHS
r1 1-0.5
              0
                   0
                        1
                             0 - 1.5
                                       -1
                                               3 ; r1 = r1 - 0.5*r3
r2 0 -0.5
                             0 -0.5
                                       0
                                               3 ; r2 = r2 - 0.5*r3
              0
                   0
                        1
r3 0 0.5
              1
                   0
                        0
                             1
                               0.5
                                      -1
                                               3 ; r3 = 0.5*r3
              0
                   1
                        0
                                       1
                                              10 ; r4 = r4 + r3
r4 0
         1
                            -1
                                  0
pivot s1;
             x2
                  xЗ
                            s2
                                             RHS
   -z
        x1
                       s1
                                 y1
                                       y2
                                               0 ; r1 = r1 - r2
                             0
r1 1
         0
              0
                   0
                        0
                                 -1
                                       -1
                             0 -0.5
r2 0 -0.5
              0
                   0
                        1
                                       0
                                               3;
r3 0 0.5
              1
                   0
                        0
                             1
                                0.5
                                       -1
                                               3;
```

Optimal solution reached, RHS = 0 for z-row, feasible basis achieved, proceed to phase 2.

1

10;

0

In [2]: # verification of phase 1

1

0

-1

0

1

r4 0

```
prob = LpProblem("Phase 1",LpMinimize)
x1=LpVariable("x1", 0, None)
x2=LpVariable("x2", 0, None)
x3=LpVariable("x3", 0, None)
s1=LpVariable("s1", 0, None)
s2=LpVariable("s2", 0, None)
y1=LpVariable("y1", 0, None)
y2=LpVariable("y2", 0, None)
prob += y1 + y2
prob += x1 + x2 + x3 + s1 == 16
```

```
prob += 3*x1 + 2*x2 + 2*x3 + y1 == 26
                                x3 - s2 + y2 == 10
        prob += x1 +
        prob.solve()
        print("Optimal Value for Phase 1 Problem")
        print("z = {}".format(value(prob.objective)))
2.4
   -z
        x1
             x2
                  xЗ
                       s1
                            s2
                                  RHS
r1 1
              2
                        0
                             0
         1
                   3
                                    0;
r2 0 -0.5
                   0
                             0
              0
                        1
                                    3;
r3 0 0.5
              1
                   0
                        0
                             1
                                    3;
r4 0
              0
                   1
                        0
                            -1
         1
                                   10;
pivot x2;
   -z
        x1
             x2
                  xЗ
                       s1
                            s2
                                  RHS
                            -2
r1 1
             0
                   3
                        0
                                   -6; r1 = r1 - 2*r3
         0
r2 0 -0.5
              0
                   0
                        1
                             0
                                    3;
r3 0 0.5
              1
                   0
                        0
                             1
                                    3;
                            -1
r4 0
              0
                                   10;
pivot x3;
                       s1
   -z
        x1
             x2
                  xЗ
                            s2
                                  RHS
r1 1
        -3
             0
                   0
                        0
                             1
                                  -36; r1 = r1 - 3*r4
r2 0 -0.5
              0
                   0
                        1
                             0
                                    3;
r3 0 0.5
              1
                   0
                        0
                             1
                                    3;
              0
                   1
                        0
                            -1
r4 0
                                   10;
enter s2; exit x2;
   -z
        x1
             x2
                  x3
                       s1
                            s2
                                  RHS
r1 1 -3.5
                        0
                                  -39; r1 = r1 - r3
             -1
                   0
                             0
r2 0 -0.5
             0
                   0
                        1
                             0
                                    3;
r3 0 0.5
              1
                   0
                        0
                             1
                                    3;
r4 0 1.5
                   1
                        0
                             0
                                   13 ; r4 = r4 + 3
              1
Tableau is now optimal, the objective value is 39 and the optimal vector is (0, 0, 13, 3, 3)
In [9]: # verification for phase 2
        prob = LpProblem("Phase 2",LpMaximize)
                        + 2*x2 + 3*x3
        prob +=
                     x1
                         + 0*x2 + 0*x3 + 1*s1 + 0*s2 == 3
        prob += -0.5*x1
```

+ 1*x2 + 0*x3 + 0*s1 + 1*s2 == 3

prob += 0.5*x1

```
prob +=
                     x1 + 0*x2 + 1*x3 + 0*s1 - 1*s2 == 10
        prob.solve()
        phase2val = value(prob.objective)
        prob = LpProblem("Original Problem",LpMaximize)
        prob += x1 + 2*x2 + 3*x3
       prob += 1*x1 + 1*x2 + 1*x3 <= 16
        prob += 3*x1 + 2*x2 + 2*x3 == 26
       prob += 1*x1 + 0*x2 + 1*x3 >= 10
        prob.solve()
        val = value(prob.objective)
        print("Optimal value for phase 2 problem")
        print("z = {}".format(phase2val))
        print("Optimal value for original problem")
       print("z = {}".format(val))
        print("Is phase 2 equal original? {}".format(phase2val == val))
Optimal value for phase 2 problem
z = 39.0
Optimal value for original problem
z = 39.0
Is phase 2 equal original? True
```

Question 3

3.1

```
      v w = 0
      1
      2
      3
      4
      5
      6
      7
      8
      9
      10
      11

      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      0
      <td
```

The optimal solution is 20 with the optimal vector (0, 0, 1, 0, 1)

```
In [4]: # verification for 3.1
    import pprint
    n = 5
    W = 11
    vs = [4, 9, 7, 6, 13]
```

```
ws = [5, 6, 4, 3, 7]
        V = [[0 \text{ for } i \text{ in } range(W + 1)] \text{ for } j \text{ in } range(n + 1)]
        for i in range(1, n + 1):
            v_i = vs[i - 1]
            w_i = ws[i - 1]
            for w in range(1, W + 1):
                if w < w_i:
                     V[i][w] = V[i - 1][w]
                else:
                     V[i][w] = max(V[i - 1][w], v_i + V[i - 1][w - w_i])
        pprint.pprint(V)
[[0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0],
 [0, 0, 0, 0, 0, 4, 4, 4, 4, 4, 4, 4],
 [0, 0, 0, 0, 0, 4, 9, 9, 9, 9, 13],
 [0, 0, 0, 0, 7, 7, 9, 9, 9, 11, 16, 16],
 [0, 0, 0, 6, 7, 7, 9, 13, 13, 15, 16, 16],
 [0, 0, 0, 6, 7, 7, 9, 13, 13, 15, 19, 20]]
In [5]: # solution for 3.1
        prob = LpProblem("Knapsack without Replacement", LpMaximize)
        x1=LpVariable("x1", 0, 1, LpInteger)
        x2=LpVariable("x2", 0, 1, LpInteger)
        x3=LpVariable("x3", 0, 1, LpInteger)
        x4=LpVariable("x4", 0, 1, LpInteger)
        x5=LpVariable("x5", 0, 1, LpInteger)
        prob += 4*x1 + 9*x2 + 7*x3 + 6*x4 + 13*x5
        prob += 5*x1 + 6*x2 + 4*x3 + 3*x4 + 7*x5 <= 11
        prob.solve()
        val = value(prob.objective)
        print("Optimal Value for Knapsack without Replacement")
        for v in prob.variables():
            print("{} = {}".format(v.name, v.varValue))
        print("z = {}".format(val))
Optimal Value for Knapsack without Replacement
x1 = 0.0
x2 = 0.0
x3 = 1.0
x4 = 0.0
x5 = 1.0
z = 20.0
```

```
3.2
v w = 0 1 2 3 4 5 6 7 8 9 10 11
      0 0 0
              0
                  0
                     0
                        0
                           0 0 0 0 0
1
      0
        0
           0
               0
                  0
                     4
                        4 4 4 4
2
                        9 9 9 9 13
      0 0
           0
               0
                  0 4
3
      0 0
            0
              0
                 7 7
                        9 9 14 14 16 16
4
      0 0 0 6
                 7
                    7 12 12 14 18 19 20
      0 0 0 6 7 7 12 13 14 18 19 20
The optimal solution is 20 with the optimal vector (0, 0, 1, 0, 1)
In [6]: # verification for 3.2
        n = 5
        W = 11
        vs = [4, 9, 7, 6, 13]
        ws = [5, 6, 4, 3, 7]
        V = [[0 \text{ for } i \text{ in } range(W + 1)] \text{ for } j \text{ in } range(n + 1)]
        for i in range(1, n + 1):
            v_i = vs[i - 1]
            w_i = ws[i - 1]
            for w in range(1, W + 1):
                k = 1
                while True:
                    if k*w_i > w:
                        V[i][w] = max(V[i][w], V[i-1][w])
                        break
                    else:
                        V[i][w] = \max(V[i][w], k*v_i + V[i-1][w - k*w_i])
                    k += 1
        pprint.pprint(V)
[[0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0],
 [0, 0, 0, 0, 0, 4, 4, 4, 4, 4, 8, 8],
 [0, 0, 0, 0, 0, 4, 9, 9, 9, 9, 13],
 [0, 0, 0, 0, 7, 7, 9, 9, 14, 14, 16, 16],
 [0, 0, 0, 6, 7, 7, 12, 13, 14, 18, 19, 20],
 [0, 0, 0, 6, 7, 7, 12, 13, 14, 18, 19, 20]]
In [7]: # solution for 3.2
        prob = LpProblem("Knapsack with Replacement", LpMaximize)
        x1=LpVariable("x1", 0, None, LpInteger)
        x2=LpVariable("x2", 0, None, LpInteger)
```

```
x3=LpVariable("x3", 0, None, LpInteger)
        x4=LpVariable("x4", 0, None, LpInteger)
        x5=LpVariable("x5", 0, None, LpInteger)
        prob += 4*x1 + 9*x2 + 7*x3 + 4*x4 + 13*x5
        prob += 5*x1 + 6*x2 + 4*x3 + 3*x4 + 7*x5 <= 11
        prob.solve()
        val = value(prob.objective)
        print("Optimal Value for Knapsack with Replacement")
        for v in prob.variables():
            print("{} = {}".format(v.name, v.varValue))
        print("z = {}".format(val))
Optimal Value for Knapsack with Replacement
x1 = 0.0
x2 = 0.0
x3 = 1.0
x4 = 0.0
x5 = 1.0
z = 20.0
```