
Table of Contents

.....	1
Question 1	1
Question 2	3
Question 3	5
Question 4	7
Question 5	9
Question 6	9
Question 7	10
Question 8	12
Question 9	12
Question 10	13
Question 11	14
Functions	17

```
%Jackson Bilello
%Final Exam
%MCEN 3030
%12-13-20
close all
clear
clc
```

Question 1

```
fprintf('Question 1\n');
x = linspace(-2,2,500);
f = -5.74*x.^3 - 4.33*x.^2 + 7.26*x - 1.05;
figure(1)
plot(x,f)
hold on
plot([-2 2],[0 0])
title('question 1')

%Bisection
xl = 0.5;
xu = 1;
iter = 1;
xr = xl;
maxi = 4;
Tl = zeros(3,5);
f = @(x) (-5.74*x.^3 - 4.33*x.^2 + 7.26*x - 1.05);

while(iter<maxi)
    Tl(iter,1) = iter;
    Tl(iter,2) = xl;
    Tl(iter,3) = xr;
    Tl(iter,4) = xu;
```

```

    T1(iter,5) = f(xr);
    xr = (xl + xu)/2;

    if(f(xl)*f(xr) < 0)
        xu = xr;
    elseif(f(xr)*f(xu) < 0)
        xl = xr;
    end
    iter=iter+1;
end
T1

%Newton-Raphson
xl = -2;
xu = -1;
xOld = -2;
iter = 1;
T2 = zeros(3,5);
syms x
f = @(x) (-5.74*x.^3 - 4.33*x.^2 + 7.26*x - 1.05);
df_dx = diff(f,x);
while(iter < maxi)
    fOrig = double(f(xOld));
    temp = subs(df_dx,x,xOld);
    fDer = double(temp);
    xNew = xOld - ((fOrig)/(fDer));
    T2(iter,1) = iter;
    T2(iter,2) = xl;
    T2(iter,3) = xNew;
    T2(iter,4) = xu;
    T2(iter,5) = f(xNew);
    xOld = xNew;
    iter = iter + 1;
end
T2

```

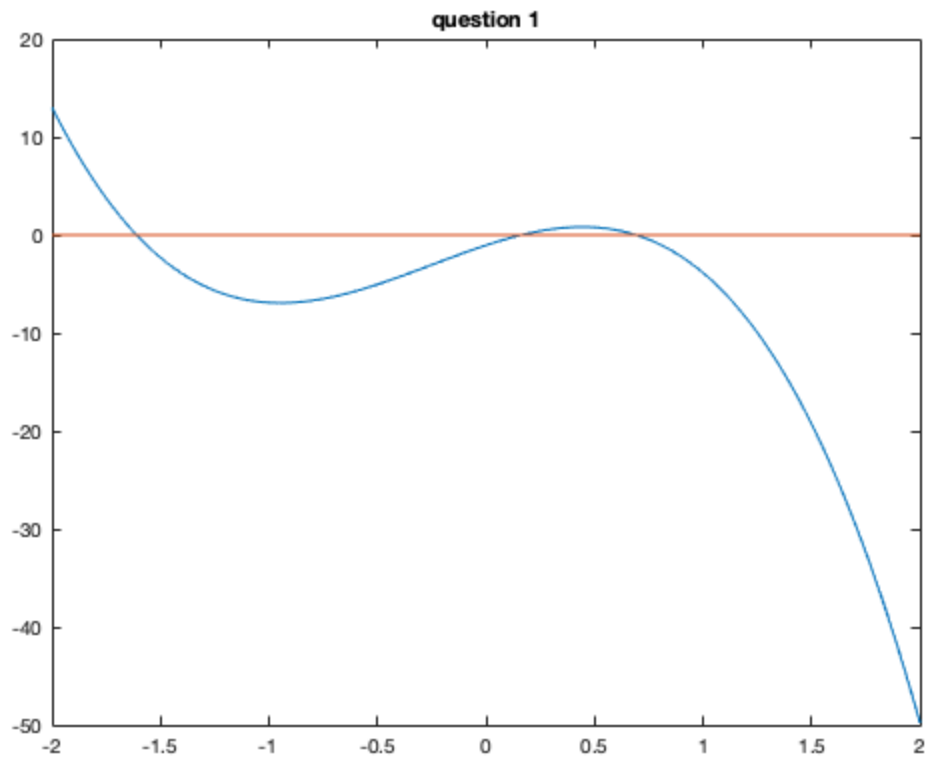
Question 1

T1 =

1.0000	0.5000	0.5000	1.0000	0.7800
2.0000	0.5000	0.7500	0.7500	-0.4622
3.0000	0.6250	0.6250	0.7500	0.3947

T2 =

1.0000	-2.0000	-1.7059	-1.0000	2.4588
2.0000	-2.0000	-1.6183	-1.0000	0.1882
3.0000	-2.0000	-1.6104	-1.0000	0.0015



Question 2

```
fprintf('Question 2\n')
fprintf('To be accurate to 7 figures, our stopping error criteria
would be 0.5*10^(2-7) which is %.2d \n',0.5*10^(-5));

xL=-1.5;
xU=-0.5;
Es=0.5*10^(-5);
maxi = 4;
iter = 1;
Ea = 100;
R = (sqrt(5)-1)/2;
d = R*(xU-xL);
x1 = xL+d;
x2 = xU-d;
xOpt = x1;
T3 = zeros(3,4);
while(Ea>Es && iter < maxi)
    T3(iter,1) = iter;
    T3(iter,2) = xOpt;
    T3(iter,3) = f(xOpt);
    T3(iter,4) = Ea;
    if(f(x1) < f(x2))
        xL = x2;
```

```

        d = R*(xU-xL);
        x1 = xL+d;
        x2 = xU-d;
        xOpt = x1;
        Ea = (1-R)*abs((xU-xL)/(xOpt));
    else
        xU = x1;
        d = R*(xU-xL);
        x1 = xL+d;
        x2 = xU-d;

        xOpt = x2;
        Ea = (1-R)*abs((xU-xL)/(xOpt));
    end
    iter = iter+1;
end
T3
x = linspace(-2,2,500);
f = -5.74*x.^3 - 4.33*x.^2 + 7.26*x - 1.05;
figure(2)
plot(x,f)
hold on
plot(T3(:,2),T3(:,3),'o')
legend('f(x)', 'x,f(x)')
title('question 2')

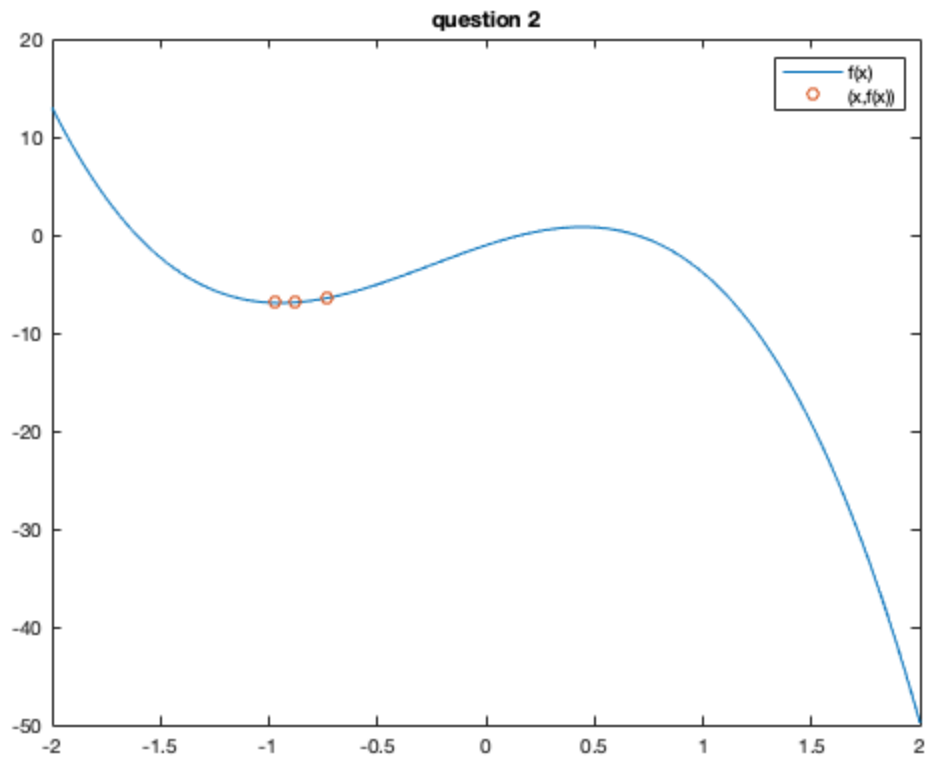
```

Question 2

To be accurate to 7 figures, our stopping error criteria would be $0.5 \cdot 10^{-(2-7)}$ which is $5.00e-06$

T3 =

1.0000	-0.8820	-6.8833	100.0000
2.0000	-0.7361	-6.4507	0.3207
3.0000	-0.9721	-6.9263	0.1501



Question 3

```
fprintf('Question 3\n')
%steepest ascent 1 step
syms x y
f = -x.^2 - y.^2 + 2.*x -4.*y -5;
df_dx=diff(f,x);
df_dy=diff(f,y);
Xg=2.09;
Yg=-1.93;

syms X Y h
df_dx = subs(df_dx,x,Xg);
df_dy = subs(df_dy,y,Yg);
X = Xg + df_dx*h;
Y = Yg + df_dy*h;
g = subs(f,x,X);
G = subs(g,y,Y);
dG_dh = diff(G,h);
hnew = double(solve(dG_dh==0,h));

syms x y
f = -x.^2 - y.^2 + 2.*x -4.*y -5;
df_dx=diff(f,x);
df_dy=diff(f,y);
```

```

df_dx = subs(df_dx,x,Xg);
df_dy = subs(df_dy,y,Yg);
xstep = double(df_dx*hnew);
ystep = double(df_dy*hnew);
vecnorm = sqrt(xstep^2 + ystep^2);
xunit = xstep/vecnorm;
yunit = ystep/vecnorm;
fprintf('First step will be in the direction of %.4fi + %.4fj
\n',xunit,yunit);

%b
syms x y
f = -x.^2 - y.^2 + 2.*x -4.*y -5;
df_dx=diff(f,x);
df_dy=diff(f,y);
Xg=2.09;
Yg=-1.93;

maxi = 100;
iter = 1;
Ea = 100;
Es = 0.05;

while(Ea > Es && iter < maxi)
    syms x y
    f = -x.^2 - y.^2 + 2.*x -4.*y -5;
    syms X Y h
    df_dx=diff(f,x);
    df_dy=diff(f,y);
    df_dx = subs(df_dx,x,Xg);
    df_dy = subs(df_dy,y,Yg);

    X = Xg + df_dx*h;
    Y = Yg + df_dy*h;
    g = subs(f,x,X);
    G = subs(g,y,Y);
    dG_dh = diff(G,h);
    hnew = double(solve(dG_dh==0,h));

    xNew = Xg + double(df_dx*hnew);
    yNew = Yg + double(df_dy*hnew);

    fOld = subs(f,x,Xg);
    fOld = subs(fOld,y,Yg);
    fOld = double(fOld);

    fNew = subs(f,x,xNew);
    fNew = subs(fNew,y,yNew);
    fNew = double(fNew);
    Ea = (fNew - fOld);
    Xg = xNew;

```

```

        Yg = yNew;
        iter = iter + 1;
    end
    xdist = 2.09 - xNew;
    ydist = -1.93 - yNew;
    totaldistance = sqrt(xdist^2 + ydist^2);
    fprintf('The total distance travelled from point 1 to the max: %.4f\n',totaldistance);

```

Question 3

First step will be in the direction of $-0.9979i + -0.0641j$

The total distance travelled from point 1 to the max: 1.0922

Question 4

```

fprintf('Question 4\n')

% LU by hand
a = [2.5 1.1 0.92; 0.54 0.83 0.91; 0.16 1.6 0.34];
[~,n] = size(a);
L = eye(n,n);

for k = 1:1:n-1
    for i = k+1:1:n
        factor = a(i,k)/a(k,k);
        L(i,k) = factor;
        for j = k:1:n
            a(i,j) = a(i,j) - factor*a(k,j);
        end
    end
end
fprintf('LU decomp by hand');
L
U = a

%Using lu
fprintf('LU Decomp using built in functions');
a = [2.5 1.1 0.92; 0.54 0.83 0.91; 0.16 1.6 0.34];
[L,U,P] = lu(a)

%Gauss seidel
fprintf('gauss Seidel method\n');
b = [0.75;2.8;0.79];

```

```

iter = 0;
maxi = 4;
[n,~] = size(a);
X = zeros(n,1);
T4 = zeros(3,3);
while(iter < maxi)
    iter = iter + 1;

```

```

T4(iter,1) = X(1,1);
T4(iter,2) = X(2,1);
T4(iter,3) = X(3,1);
for i = 1:n
    j = 1:n;
    j(i) = [];
    xTemp = X;
    xTemp(i) = [];

    X(i,1) = ( b(i,1) - sum(a(i,j)*xTemp) ) / a(i,i);
end

```

end

T4

Question 4

LU decomp by hand

L =

1.0000	0	0
0.2160	1.0000	0
0.0640	2.5820	1.0000

U =

2.5000	1.1000	0.9200
0	0.5924	0.7113
0	0	-1.5554

LU Decomp using built in functions

L =

1.0000	0	0
0.0640	1.0000	0
0.2160	0.3873	1.0000

U =

2.5000	1.1000	0.9200
0	1.5296	0.2811
0	0	0.6024

P =

1	0	0
0	0	1
0	1	0

gauss Seidel method

T4 =

0	0	0
0.3000	3.1783	-12.7744
3.6025	15.0354	-70.1264
19.4910	67.5782	-324.8639

Question 5

```
fprintf('Question 5\n')
A = [2.5 1.1 0.92; 0.54 0.83 0.91; 0.16 1.6 0.34];
B = [0.75;2.8;0.79];

L1A = norm(A,1);
L2A = norm(A,2);
FroA = norm(A,'fro');
InfA = norm(A,'Inf');

fprintf('A norms:   L1       L2       Frobenius       Infinite\n')
fprintf('           %.4f    %.4f    %.4f           %.4f\n')
fprintf('           \n',L1A,L2A,FroA,InfA);

L1B = norm(B,1);
L2B = norm(B,2);
InfB = norm(B,'Inf');

fprintf('B norms:   L1       L2       Infinite\n')
fprintf('           %.4f    %.4f    %.4f           \n',L1B,L2B,InfB);

Question 5
A norms:   L1       L2       Frobenius       Infinite
           3.5300    3.2620    3.5800    4.5200
B norms:   L1       L2       Infinite
           4.3400    3.0044    2.8000
```

Question 6

```
fprintf('Question 6\n')

I = [0.1, 1.3, 2.5, 3.7, 4.9, 6.1, 7.3, 8.5, 9.7, 11, 12];
V = [ 8.4, 3.6, 14, 23, 28, 43, 47, 56, 64, 70, 87];

figure(3)
plot(I,V)
hold on
title('question 6')
xlabel('I')
ylabel('V')
hold on

sum1 = sum(I.*V);
sum2 = sum(I);
```

```

sum3 = sum(V);
sum4 = sum(I.^2);

a1 = (11*sum1-sum2*sum3)/(11*sum4 - sum2.^2);
a0 = (sum(V)/11) - (a1*sum(I)/11);
Y_line=a1.*I+a0;
plot(I,Y_line)
fprintf('Using the slope of the regression line, resistance = %.4f
        ohms\n',a1);

Sr = sum((V - Y_line).^2);
Syx = sqrt(Sr/9)

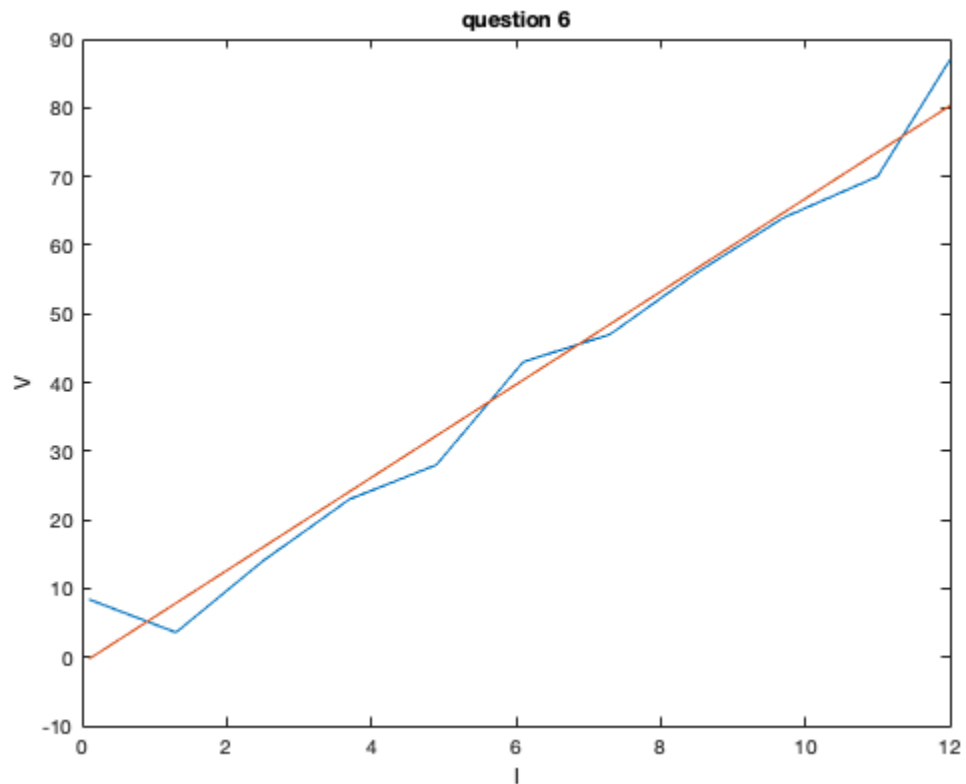
```

Question 6

Using the slope of the regression line, resistance = 6.7684 ohms

Syx =

4.5181



Question 7

```
fprintf('Question 7\n')
```

```
x = linspace(0,10,100);
y1 = (9 - 5.5.*x)/3;
y2 = (6 - 1.1.*x)/2;
y3 = (4 - 1.*x)/2.5;

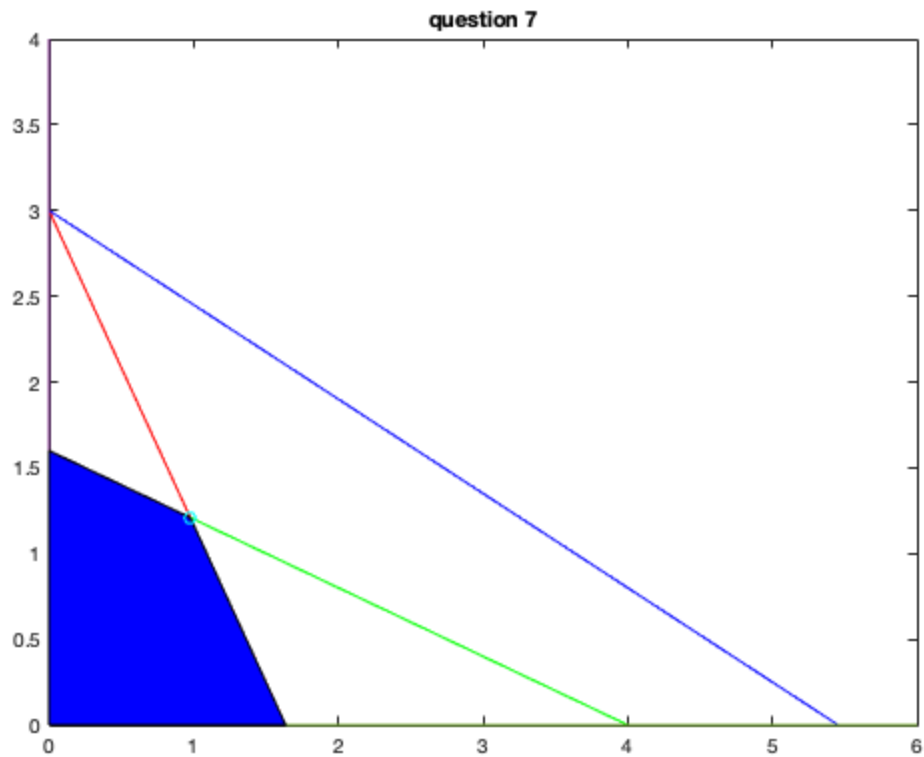
figure(4)
plot(x,y1,'r-')
hold on
plot(x,y2,'b-')
hold on
plot(x,y3,'g-')
hold on
plot([0 0],[0 20])
hold on
plot([0 20],[0 0])
xlim([0 6])
ylim([0,4])
title('question 7')
int = [5.5 3.0;1 2.5]\[9;4];
X = [0 1.636 int(1) 0];
Y = [0 0 int(2) 1.6];
patch(X,Y,'Blue')
hold on

f = -[2.2 3.3];
A = [5.5 3; 1.1 2; 1.0 2.5];
B = [9;6;4];
C = linprog(f,A,B);
F = 2.2*C(1) + 3.3*C(2);
fprintf('The maximum value of f(x,y) = %.4f is located at (%.4f, %.4f)\n',F,C(1),C(2))
plot(C(1),C(2),'co')
```

Question 7

Optimal solution found.

The maximum value of $f(x,y) = 6.1395$ is located at $(0.9767, 1.2093)$



Question 8

```
fprintf('Question 8\n')
t1 = [0 3 6];
t2 = [7.5 8.5];
v1 = [13.698 12.358 12.109];
v2 = [13.06 12.612];
Int1 = trapz(t1,v1);
Int2 = trapz(t2,v2);
Int3 = (6-3)*(12.109 + 3*12.723 + 3*12.551 + 13.06)/8;
totD = Int1 + Int2 + Int3;
avgV = totD/8.5;
fprintf('Total distance flown: %.4f m, average velocity: %.4f m/s\n',totD,avgV)
```

Question 8

Total distance flown: 126.4921 m, average velocity: 14.8814 m/s

Question 9

```
fprintf('Question 9\n')
x0 = [0.1 -0.4];
t = [0,5];
[t,x] = ode23(@myODE,t,x0);
figure(5)
```

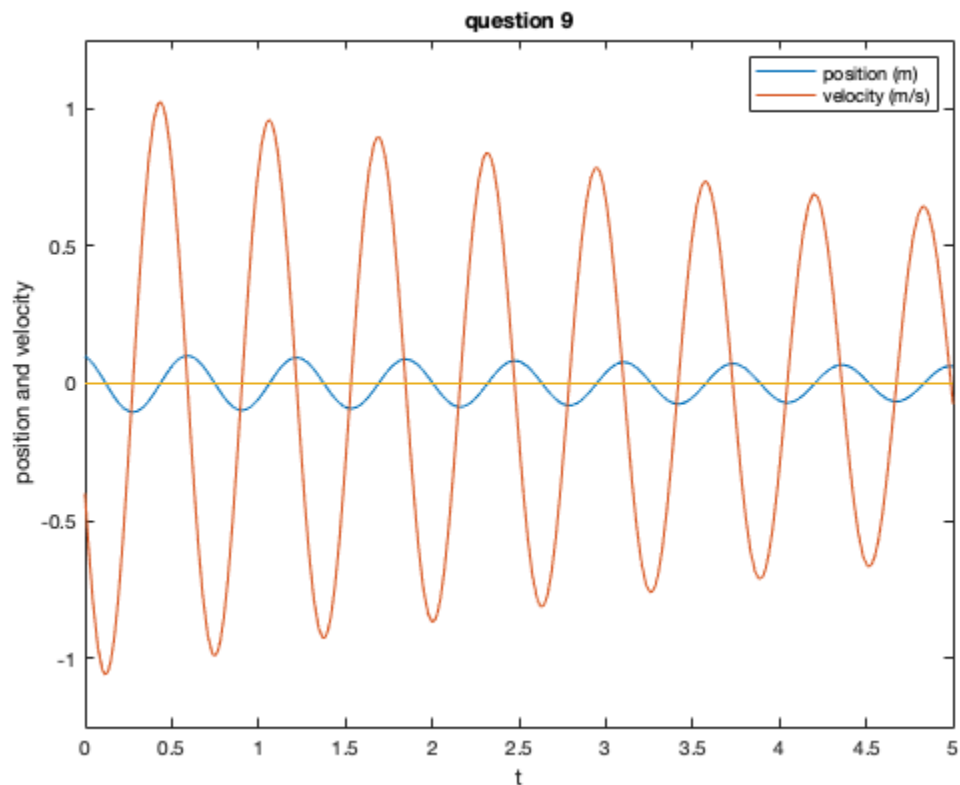
```

plot(t,x(:,1))
hold on
plot(t,x(:,2))
hold on
plot([0 5],[0 0])
title('question 9')
xlabel('t')
ylabel('position and velocity')
legend('position (m)', 'velocity (m/s)')
ylim([-1.25 1.25])

```

```
%function @myODE is at EOF
```

Question 9



Question 10

```

%1
%a 101101 = 45
%b 101.011 = 5.375
%c 0.01101 = 0.40625

% 2. when multiplying two numbers like 0.12*0.12, a floating point
    will spit
% out 0.0144 while two fixed point numbers will spit out 0.014 because
    of

```

```
% rounding errors. Float points have much more range than a fixed
point.
```

```
%3
%a m=1.5, b=2, exp=6 = 1.5*2^6 = 96
%b m=1.5, b=3.7, exp=2.5 = 1.5*3.7^2.5 = 39.49998
```

Question 11

```
fprintf('Question 11\n')

conductivity = 204.3;
specificHeat = 910;
Density = 2700;

Lx= 0.5;
Ly= 0.5;
Nx=25;
Ny=25;
T_initial= 0 ;
T_east    = 20 ;
T_west    = 0 ;
T_north   = 100 ;
T_south   = 0 ;
t_end=50 ;
dt=0.6 ;
tolerence = 0.5;
tolerence_ss= 0.001;

k=1;
err_SS_max(k)=1;
err_SS_min(k)=1;
dx=Lx/Nx;
dy=Ly/Ny;
n_time=round(t_end/dt);
alpha = conductivity/(specificHeat*Density);
T_max=max([T_east T_west T_north T_south T_initial]);
T_min=min([T_east T_west T_north T_south T_initial]);

Tss2=zeros(Nx+2,Ny+2);
Tss2(2:25,Ny+1)=T_north;
Tss2(2:25,Ny+2)=T_north; % Redundant, it has no effect in
    calculations but is required in plotting section
Tss2(Nx+1,2:25)=T_east;
Tss2(Nx+2,2:25)=T_east;

T=zeros(Nx+2,Ny+2,75000);
T(2:25,Ny+1,:)= T_north;
T(2:25,Ny+2,:)= T_north;
T(Nx+1,2:25,:)= T_east;
```

```

T(Nx+2,2:25,:) = T_east;

k=1;
err_E_max(k)=100;
err_E_min(k)=100;
Specnode = zeros(79135,1);
while err_E_max(k)>=tolerence
    for i=2:Nx
        for j=2:Ny

            if i == 2 %west
                T(i,j,k+1) =T(i,j,k)+dt*alpha*((( -2*T(i,j,k)+2*T(i
+1,j,k)))/dx^2)+((T(i,j-1,k)-2*T(i,j,k)+T(i,j+1,k))/dy^2));
            elseif j == 2 %south
                T(i,j,k+1)
                =T(i,j,k)+dt*alpha*(((T(i-1,j,k)-2*T(i,j,k)+T(i+1,j,k)))/
dx^2)+((-2*T(i,j,k)+2*T(i,j+1,k))/dy^2));
            else %center nodes
                T(i,j,k+1)
                =T(i,j,k)+dt*alpha*(((T(i-1,j,k)-2*T(i,j,k)+T(i+1,j,k)))/
dx^2)+((T(i,j-1,k)-2*T(i,j,k)+T(i,j+1,k))/dy^2));
                if(i==19 && j==6)
                    Specnode(k,1) = T(i,j,k+1);
                end
            end
        end
    end

    end
    k=k+1;
    err_E_max(k)=abs(max(max(T(:, :, k)-Tss2))); %calculate error
    err_E_min(k)=abs(min(min(T(:, :, k)-Tss2))); %calculate error

end
T=T(:, :, 1:k);
SStime=k*dt;
SSsteps=k;

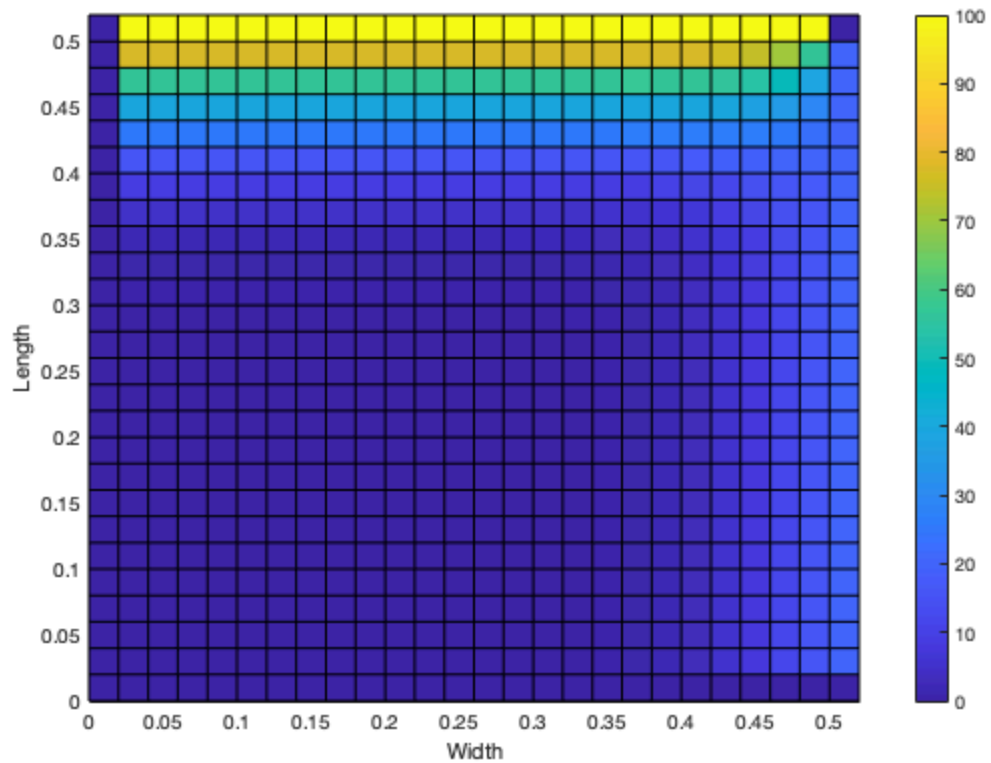
x=zeros(1,Nx+2);
y=zeros(1,Ny+2);
for i = 1:Nx+2
    x(i) =(i-1)*dx;
end
for i = 1:Ny+2
    y(i) =(i-1)*dy;
end

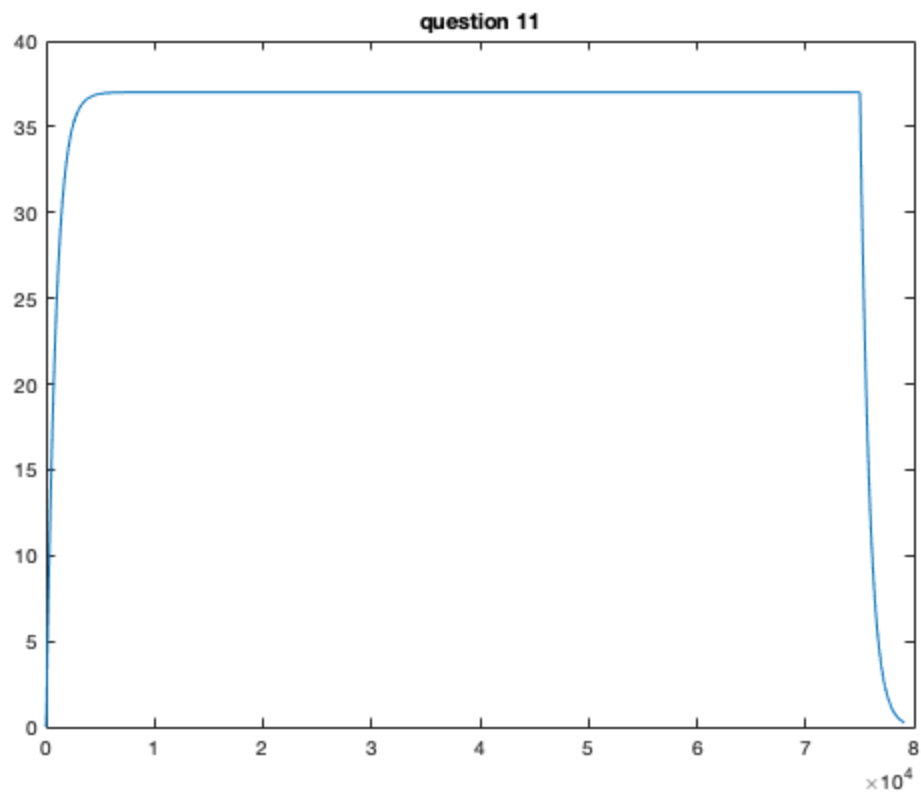
figure(6);
title('question 11 @ 50s');
surf(x,y,T(:, :, 50))
colorbar
caxis([T_min T_max]);
view(90,-90);
xlim([0 Lx+dx]); xlabel('Length');

```

```
ylim([0 Ly+dy]); ylabel('Width');  
zlim([T_min T_max]); zlabel('Temprature');  
  
figure(7)  
i = 1:79135;  
plot(i,Specnode)  
hold on  
title('question 11')
```

Question 11





Functions

```
function xd = myODE(~,x)
    k = 100; m = 1; c = 0.2;
    xd(1)=x(2);
    xd(2)=1/m*(-k.*x(1) - c.*x(2));
    xd = xd';
end
```

Published with MATLAB® R2020a

ATTACH TO QUESTION 9

$$m = 1 \text{ kg} \quad v_0 = -0.4 \text{ m/s} \quad x_0 = 0.1 \text{ m}$$

$$k = 100 \quad c = 0.2$$

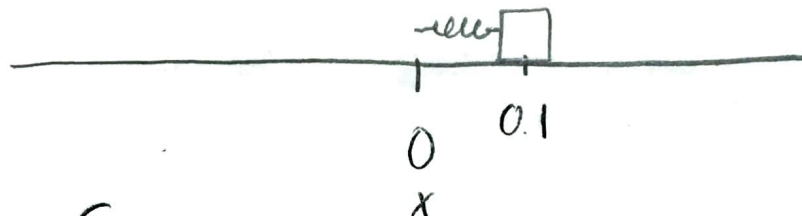
Find

v_0
←

x = Position

\dot{x} = Velocity

\ddot{x} = Acceleration



$$\sum F_x = 0$$

$$m\ddot{x} = -kx - c\dot{x}$$

$$\ddot{x} = -\frac{k}{m}x - \frac{c}{m}\dot{x}$$

